

ARTICULATED TOTAL BODY MODEL ENHANCEMENTS  
VOLUME 3: PROGRAMMER'S GUIDE

Harry G. Armstrong Aerospace Medical Research Laboratory  
Wright-Patterson AFB, OH

Jan 88

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ARTICULATED TOTAL BODY MODEL ENHANCEMENTS,  
Volume 3: Programmer's Guide



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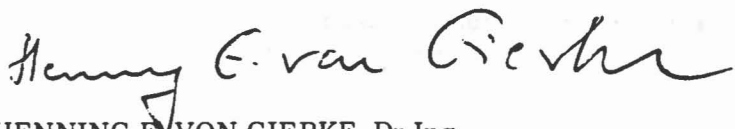
## TECHNICAL REVIEW AND APPROVAL

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This report has been reviewed by the Office of Public Affairs (PA) and is releasable to the National Technical Information Service (NTIS). At NTIS, it will be available to the general public, including foreign nations.

This technical report has been reviewed and is approved for publication.

**FOR THE COMMANDER**



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Director  
Biodynamics and Bioengineering Division  
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<p>The Articulated Total Body (ATB) Model is used at the Armstrong Aerospace Medical Research Laboratory (AAMRL) to study human body biomechanics in various dynamic environments, especially aircraft ejection with windblast exposure. In order to improve the model's predicted results and capabilities, a number of modifications have been made. These modifications include the capability to have segment contact ellipsoids block the wind from other segments, an option to prescribe velocity dependent wind forces, a correction to prevent angular drift in the joints, improved contact force calculations for segment contact near a plane's edge, the capability to specify as input multi-axis angular displacements to describe the vehicle motion, a sliding joint capability and a hyperellipsoid option. Along with these major changes, a number of minor corrections and clarifications have been included to form the ATB-IV version. The results of these modifications have been documented in three volumes of which this is Volume 3, the</p>					
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Programmer's Guide. It contains a complete listing of the ATB-IV program with designation of coding modifications from previous versions. Volume 1 contains a technical description of the ATB-IV modifications and Volume 2 is an updated User's Guide containing the new input description.

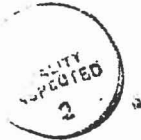
PREFACE

This report incorporates the work done in a number of different efforts to improve the Articulated Total Body (ATB) model's capability to simulate human body biomechanics in various dynamic environments, especially aircraft ejection with windblast exposure.

The majority of modifications to the model fall into six categories:

- wind force option
- joint drift correction
- edge effect option
- multi-axis angular displacement vehicle motion prescription
- slip joint option
- hyperellipsoid option

These improvements have been combined to form the ATB-IV version on the Armstrong Aerospace Medical Research Laboratory's (AAMRL) Concurrent computer system at Wright Patterson Air Force Base. AAMRL, Systems Research Laboratories, Inc. and J&J Technologies Inc. and the National Highway Traffic Safety Administration have all contributed to the technical work described herein.



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Dear Mr. [Name],  
I have your letter of [Date] regarding [Subject].  
I am sorry that I cannot give you a more definite answer at this time.  
I will be glad to discuss this matter with you if you wish.

Very truly yours,  
[Name]  
[Title]

Enclosed for you are [Number] copies of [Document Name].  
I am sure you will find them of interest.

I am sure you will find them of interest.

I am sure you will find them of interest.



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## 1.0 INTRODUCTION

The Articulated Total Body (ATB) Model is used at the Armstrong Aerospace Medical Research Laboratory (AAMRL) for predicting gross human body response in various dynamic environments, especially aircraft ejection with windblast exposure. Aerodynamic force application and a harness belt capability were added to the Crash Victim Simulation (CVS) Program (Ref 1) by Calspan Corporation in 1975 for AMRL (Ref 2), and the resulting program became known as the ATB model. In 1980, Calspan made a number of modifications to the ATB model combining it with the then current 3-D Crash Victim Simulation program to form the ATB-II model (Ref 3). Complete documentation of the ATB-II program was performed by Calspan Corp. (Ref 4). A new version, ATB-III, was generated which included the improvements made by J&J Technologies Inc to model the body response to windblast for AMRL (Ref 5).

A number of efforts have been made to improve various aspects of the ATB-III model, with emphasis on its capability to simulate aircraft ejection with windblast exposure and complex automobile accidents.

This volume, Programmer's Guide, contains a complete listing of the ATB-IV.0 source code and other information about the FORTRAN program. Much of this volume is a reprinting with modifications and updates of Volume 4 of Calspan's report on the CVS (Ref 4).

A list of the variables contained in the labeled COMMON blocks and a brief description of each variable are in section Two of this volume. Cross reference charts for the subroutines and COMMON blocks are in Section Three, while a list of all the subroutines is in Section Four. Section Five contains a complete listing of the ATB-IV.0 source code.

Faint, illegible text covering the majority of the page, likely bleed-through from the reverse side. The text is too light to transcribe accurately.

## 2.0 COMMON BLOCK VARIABLES

This section contains a list of all of the variables contained in the labeled COMMON blocks of the ATB program. They are listed in the alphabetical order of the COMMON block names. Following each variable is its dimension, if any, and a short definition. If the variable is supplied as ATB program input, references are indicated to the input card number and a more complete definition may be found in the input description contained in Volume 2.

<u>COMMON</u>	<u>/AB DATA/</u>	
ZDEP	(3,5)	Deployment point of airbag in local reference of 1st reaction panel (Card D.4.c)
DBR	(3,3,5)	Direction cosine matrix of airbag relative to vehicle
DPVCTR	(3,5)	Vector along which airbag c.g. lies during bag inflation
DEPLOY	(3,5)	Location of deployment point
AB	(3,5)	Semiaxes of fully inflated ellipsoid airbag (Cards D.4.b)
B	(9,4,5)	3 X 3 matrix defining ellipsoid $X^T B X = 1$ for reaction panel
ZR	(3,4,5)	Location of panel c.g. in vehicle reference (Card D.4.h)
BFB	(3,4,5)	c.g. offset of reaction panel (Card D.4.g)
DRR	(9,4,5)	Direction cosine matrix of reaction panel relative to inertial reference
VBAGG	(5)	Geometric volume of fully inflated airbag
VSCS	(5)	Coefficient of sliding friction of the airbag (Card D.4.f)
SPRK	(5)	Spring constant of a linear spring used to stipulate attachment of the airbag at the deployment point (Card D.4.f)

CK	(5)	Parameter used to stabilize airbag numerical integration (Card D.4.f)
CMASS	(5)	Multiplier to increase or decrease the mass of the airbag to artificially dampen the integrated airbag motion (Card D.4.f)
CYMIN	(5)	Mass flow into the airbag
CYMOUT	(5)	Mass flow out of the airbag
BAGPV	(5)	Undeformed airbag volume
PD	(5)	Airbag pressure differential
VBAG	(5)	Airbag volume
VOLBP	(5)	Total volume of intersection of airbag with contacting segments and panels
PCYV	(5)	Volume of mass flow into airbag at atmospheric pressure at time of initial inflation
PCYMIN	(5)	Mass flow into airbag at time of initial full inflation
PVBAG	(5)	Airbag volume at time of initial inflation
TV1	(3,4,5)	Memory for Subroutines INTERS and EDEPTH for airbag-panel ellipsoid contacts
TV2	(3,10,5)	Memory for Subroutines INTERS and EDEPTH for airbag-segment ellipsoid contacts
SWITCH	(5)	Reciprocal density of airbag at time of initial full inflation

**PYMOUT**           (5)       **Mass flow out of airbag at time of initial full inflation**

**SCALE**            (5)       **Ratio (0-1) of linear dimensions of airbag to fully inflated airbag**

**PREVT**            Value of **TIME** at previous airbag integration step

**IFULL**            (6)       **Indicates that airbag is fully inflated**

COMMON    /CDINT/

**UU**               (4)       }       **Constants computed by Subroutine TRIGFS**

**GH**              (3,4)     }       **valid for the upcoming integrator time step**

**E**                (3,240)    }

**FF**              (5,240)    }       **Intermediate storage of function**

**GG**              (5,240)    }       **evaluations in Subroutine DINT**

**Y**               (5,240)    }

**U**               (5,240)    }

**H**                **Current value of the independent variable step size in Subroutine DINT**



HPRINT		Saved value of H while integrating to print point only
TSAVE		Set to zero or H to reset integrator
TPRINT		Value of next print time point
TSTART		Start time of an integration step
ICNT		Count of successive integration steps for which convergence has been successful
IDBL		Maximum value for ICNT before test to double step size is performed
IFLAG		Currently not used by program

COMMON     /CEULER/

IEULER	(30)	Current lock-unlock conditions for an Euler joint (see identification under IPIN on Cards B.2)
HIR	(3,3,90)	Direction cosine matrix defining orientation of axes of an Euler joint
ANG	(3,30)	Angles of orientation of an Euler joint
ANGD	(3,30)	Time derivative of orientation angles of an Euler joint
FE	(3,30)	Components of torque acting on an Euler joint in joint reference

TQE (3,30) Components of torque acting on an Euler joint  
in inertial reference

CONST (5,30) Memory of previous angles of orientation of an  
Euler joint

COMMON /CMATRIX/

V1 (3,30) Right hand side of system of equations  
 $B_{11}\ddot{x} + B_{12}\dot{w} + B_{13} f = V_1$

V2 (3,30) Right hand side of system of equations  
 $B_{22}\ddot{x} + B_{24} t = v_2$

V3 (3,12) Right hand side of system of equations  
 $B_{31} \ddot{x} + B_{32}\dot{w} + B_{35} q = V_3$

B12 (3,3,60) Subarray elements of B12

A22 (3,3,60) Subarray elements of A22

F (3,30) Components of force acting on the joints from  
the solution of system equations

TQ (3,30) Components of torque acting on the joints from  
the solution of system equations

WJ (30) Relative angular velocity of each joint

All (3,3,30) Subarray elements of A11

COMMON /CNSNTS/

PI   FORTRAN Subroutine Library value for Pi,  
  computed by  $PI = \text{DATAN2}(0.0\text{D}0, -1.0\text{D}0)$

RADIAN                                    Number of radians per degree ( $PI/180$ )

G   Resultant of gravity vector (Card A.3)

THIRD                                    Double precision value for  $1/3$

EPS                                      (24)         Values of negative powers of ten, computed  
  by  $\text{EPS}(I) = 10.0\text{D}0^{*(-I)}$

UNITL                                    I/O unit of length (Card A.3)

UNITM                                    I/O unit of force of mass (Card A.3)

UNITT                                    I/O unit of time (Card A.3)

GRAVITY                                 (3)         Components of gravity vector (Card A.3)

TWOPI                                     $2.0*PI$

COMMON /CNTSRF/

PL                                       (24,30)     Array of parameters that define each plane  
  (See Table 1 in Volume 1)

BELT                                     (20,8)     Array of parameters that define each belt  
  (Cards D.3.b-D.3.c)

TPTS                                     (6,8)     Location of belt tangent points in inertial  
  reference

BD (24,40) Array of parameters that define each ellipsoid

COMMON /COMAIN/

VAR (240) Integrated function values supplied by Subroutine DINT to Subroutine PDAUX

DER (240) Function derivatives supplied by Subroutine PDAUX to Subroutine DINT

DT Time interval for main program output time points (Card A.4)

HO Initial integrator step size (Card A.4)

HMAX Maximum integrator step size (Card A.4)

HMIN Minimum integrator step size (Card A.4)

RSTIME Restart time (Card A.1.a)

ISTEP Current integration step number

NSTEPS No. of integration steps for duration of simulation (Card A.4)

NDINT No. of iterations for convergence test for Subroutine DINT (Card A.4)

NEQ Total number of functions integrated by Subroutine DINT

IRSIN                      Restart input unit no. (Card A.1.a)

IRSOUT                     Restart output unit no. (Card A.1.a)

COMMON     /CONTRL/

TIME                        Current simulation time

NSEG                        Number of body segments of crash victim,  
 max=30 (Card B.1)

NJNT                        Number of joints, max=30 (Card B.1)

NPL                         Number of plane definitions supplied on  
 Cards D.2, max=30 (Card D.1)

NBLT                        Number of belt definitions supplied on  
 Cards D.3, max=8 (Card D.1)

NBAG                        Number of airbag definitions supplied  
 Cards D.4, max=5 (Card D.1)

NVEH                        Segment identification number for the vehicle  
 (NVEH=NSEG+number of vehicles)

NGRND                      Segment identification number for the ground  
 (NGRND=NSEG+NBAG+number of vehicles+1)

NS                          Number of singular segments, i.e., W or at  
 least one component of PHI is zero

NQ                          Number of constraints supplied on Cards D.6,  
 final max = 12 (Card D.1)

NSD                                Number of spring dampers supplied on Cards  
D.8, max=20 (Card D.1)

NFLX                                Total number of interior segments of all  
flexible elements.

NHRNSS                              Number of harness-belt systems supplied on  
Cards F.8, max=5 (Card D.1)

NWINDF                              Number of wind force functions supplied on  
Cards E.6 (Card D.1)

NJNTF                                Number of joint restoring force functions  
supplied on Cards E.7 (Card D.1)

NPRT                                (36)                              Indicators that control optional output of  
the program (Card A.5)

NPG                                    Current page number of main output

COMMON        /CSTRNT/

A13                    (3,3,24)                    Subarray elements of  $A_{13}$  for system of  
equations  
 $M\ddot{x} + A_{11}f + A_{13}q - U_1$

A23                    (3,3,24)                    Subarray elements of  $A_{23}$  for system of  
equations  
 $\phi\dot{w} + A_{21}f + A_{22}t + A_{23}q = U_2$

B31                    (3,3,24)                    Subarray elements of  $B_{31}$  for system of  
equations defining constraints

B32	(3,3,24)	Subarray elements of $B_{32}$ for system of equations defining constraints
HHT	(3,3,12)	Array $hh^T$ or $I-hh^T$ for each constraint
RK1	(3,12)	Specified point on segment number KQ1 (Card D.6)
RK2	(3,12)	Specified point on segment number KQ2 (Card D.6)
QQ	(3,12)	Computed force necessary to maintain each constraint
TQQ	(3,12)	Normal vector at the point of contact for each constraint
RQQ	(3,12)	R dot term for constraint equation
HQQ	(3,12)	Reference vector at point of constraint
SQQ	(3,12)	R term for constraint equation
CFQQ	(12)	Coefficient of friction for each constraint
KQ1	(12)	Segment identification number of the 1st specified point (Card D.6)
KQ2	(12)	Segment identification number of the 2nd specified point (Card D.6)
KQTYPE	(12)	Constraint type number (Card D.6)

COMMON/CYDATA/

CYTD	(5)	Gas supply actuator firing time (Card D.4.d)
CYPA	(5)	Atmospheric pressure (Card D.4.d)
CYSP	(5)	Initial gas supply pressure (Card D.4.d)
CYTO	(5)	Initial gas supply temperature (Card D.4.d)
CYVO	(5)	Gas supply reservoir volume (Card D.4.d)
CYCD	(5)	Sonic throat discharge coefficient (Card D.4.e)
CYK	(5)	Ratio of specific heats of supply gas (Card D.4.e)
CYR	(5)	Specific gas constant (Card D.4.e)
CYAT	(5)	Sonic throat area (Card D.4.e)
CYPV	(5)	Vent pressure of the exhaust orifice
CYCDO	(5)	Exhaust orifice discharge coefficient (Card D.4.e.)
CYAO	(5)	Exhaust orifice area (Card D.4.f)
CYPO	(5)	Initial air cylinder gauge supply pressure
CYSS	(5)	Speed of sound
CYLO	(5)	Characteristic length



CYC	(5)	Air cylinder gas constant
CYRHO	(5)	Initial air cylinder density
CYVMAX	(5)	Air cylinder maximum volume
CYORFC	(5)	Air cylinder exhaust orifice constant
CYRHO	(5)	Density of air cylinder gas supply
CYT	(5)	Temperature of air cylinder gas supply
CYP	(5)	Pressure of air cylinder gas supply
CYV	(5)	Volume of air cylinder gas supply at standard atmospheric pressure

COMMON      /DAMPER/

APSDM	(3,20)	Attachment point in local reference of segment M for spring dampers (Card D.8)
APSDN	(3,20)	Attachment point in local reference of segment N for spring dampers (Card D.8)
ASD	(5,20)	Spring and viscous force function coefficients (Card D.8)
MSDM	(20)	Identification number of segment M (Card D.8)
MSDN	(20)	Identification number of segment N (Card D.8)

<u>COMMON</u>	<u>/DESCRP/</u>	
PHI	(3,30)	Segment principal moments of inertia (Cards B.2)
W	(30)	Segment weight (Cards B.2)
RW	(30)	Reciprocal mass (g/w) for each segment
SR	(4,60)	Joint locations in local reference of adjacent segments (Cards B.3)
HA	(3,60)	Principal line of joint from which flexure angle is measured
HB	(4,60)	Perpendicular to HA (pin axis if joint is pinned)
RPHI	(3,30)	Reciprocal moments of inertia for each segment
HT	(3,3,60)	Principal axes of the joints
SPRING	(5,90)	Flexural and torsional spring characteristics (Cards B.4)
VISC	(7,90)	Flexural and torsional viscous characteristics (Cards B.5)
JNT	(30)	Magnitude indicates the segment identification number that is connected to segment J+1 by joint J (Cards B.3)
IPIN	(30)	Indicator of joint type (Card B.3)

ISING (30) Indicator (value=1) that segment is singular

IGLOB (30) Input indicator (Card F.4.a) to signify that joint J is to use the globalgraphic option. A nonzero value will be set to index of function to be used.

JOINTF (30) The function identification number used to compute the joint restoring force (Card F.5)

COMMON /FLXBLE/

HF (4,12,8) Coefficients of quadratic function defining relative orientation of interior segments of flexible elements

B42 (3,3,24) Subarray elements of matrix  $B_{42}$  in the constraint equations for flexible elements

V4 (3,8) Right hand side of the constraint equations for flexible elements.

NFLEX (3,8) The identification numbers of reference, interior and terminating segments for each interior segment.

COMMON/FORCES/

PSF	(7,70)	Array of output values for plane-segment contacts
BSF	(4,20)	Array of output values for belt-segment contacts
SSF	(10,40)	Array of output values for segment-segment contacts
BAGSF	(3,20)	Array of output values for airbag-segment contacts
PRJNT	(7,30)	Output arrays for joint parameters
NPANEL	(5)	Number of reaction panels for each airbag (J=1, NBAG)
NPSF		Number of plane-segment contact (Max=70)
NBSF		Number of belt-segment contacts (Max=20)
NSSF		Number of segment-segment contacts (Max=40)
NBGSF		Number of items to be printed for airbag-segment contacts (Max=20)

COMMON    /HRNESS/

BAR	(15,100)	Coordinates of points in local reference (Cards F.8.d)
BB	(100)	Lengths of individual belt segments between reference points
BBDOT	(100)	Time derivative of belt segment lengths
FLOSS	(2,100)	Energy loss of individual belt segments
XLONG	(20)	The initial slack of each belt (Cards F.8.c)
HTIME	(2)	Previous value of TIME for Subroutine HPTURB
IBAR	(5,100)	Array of indicators containing KS, KE, NF index, NPD and NPR (Cards F.8.d) for each point
NL	(2,100)	Pointers to the IBAR and NTHRNS arrays for each point in play
NPTSPB	(20)	Number of points per belt (Cards F.8.b)
NPTPLY	(20)	Number of points in play per belt
NTHRNS	(20)	Index to NTAB array defining the force deflection functions for each belt
NBLTPH	(5)	Number of belts per harness (Card F.8.a)

COMMON    /INTEST/

SGTEST    (3,4,30)    Integrator convergence test input numbers  
                        (Cards B.6)

XTEST      (3,120)    Integrator convergence test numbers setup  
                        by PDAUX for DINT

SEGT        (120)        Segment identification of integrator variable

REGT        (120)        Identification (ANG VEL, ANG ACC, LIN VEL  
                        or LIN ACC) of type of integrator variable

COMMON    /JBARTZ/

MNPL        (30)        Number of segments to contact each plane  
                        (Card F.1.a)

MNBLT       (8)        Number of segments to contact each belt  
                        (Card F.2.a)

MNSEG       (30)        Number of segments to contact each segment  
                        (Card F.3.a)

MNBAG       (6)        Number of segments to contact each airbag

MPL         (3,5,30)    Segment and ellipsoid identification numbers  
                        for each plane-segment contact

MBLT        (3,5,8)    Segment and ellipsoid identification numbers  
                        for each belt-segment contact

MSEG	(3,5,30)	Segment and ellipsoid identification numbers for each segment-segment contact
MBAG	(3,10,6)	Segment and ellipsoid identification numbers for each airbag-segment contact (Cards F.4)
NTPL	(5,30)	Index to NTAB array for each plane-segment contact
NTBLT	(5,8)	Index to NTAB array for each belt-segment contact
NTSEG	(5,30)	Index to NTAB array for each segment-segment contact
<u>COMMON</u>	<u>/RSAVE/</u>	
XSG	(3,20,3)	Points in local segment reference for first three types of time history output (Cards H.1-H.3)
DPMI	(3,3,30)	Direction cosine matrix of principal moment of inertia to local geometric reference coordinate system for each segment
LPMI	(30)	Indicator that local geometric does not correspond to principal moment of inertia reference coordinate system for each segment (Cards B.2.il)
NSG	(9)	Number of segments for each type of time history output (Max=20) (Cards H.1-H.9)

MSG	(20,9)	The segment identification numbers for each type of time history output (Cards H.1-H.9)
MCG		Number of bodies for body property time history output (Max=5) (Cards H.10)
MCGIN	(24,5)	Body characteristics for body property time history output (Cards H.10)
KREF	(20,9)	The reference segment numbers for each time history output (Cards H.1-H.9)

COMMON /SGMNTS/

D	(3,3,30)	Segment direction cosine matrix
WMEG	(3,30)	Segment angular velocity in local reference
WMEGD	(3,30)	Segment angular acceleration in local reference
U1	(3,30)	Total external forces on each segment
U2	(3,30)	Total external torques on each segment
SEGLP	(3,30)	Segment c.g. linear position in inertial reference
SEGLV	(3,30)	Segment c.g. linear velocity in inertial reference



SEGLA (3,30) Segment c.g. linear acceleration in inertial reference

NSYM (30) Indicators that control the symmetry options for body segments (Cards D.7)

COMMON /TABLES/

MXNTI Dimension (50) of NTI array

MXNTB Number of elements in the NTAB array

MXTB1 Number of elements in TAB array used to define functions

MXTB2 Total number of elements in TAB array

NTI (50) Index pointers to the TAB array for data defining function no. 1.

NTAB (1250) Index pointers to TAB array for each function used for allowed contacts

TAB (4500) Subdivided into arrays containing function definitions and update information for each allowed contact

COMMON /TEMPVI/

CREST Coefficient of restitution for current impulse

TTI (3) Value of U1 array for impulse

R1I	(3)	Value of RK1 for current constraint or impulse
R2I	(3)	Value of RK2 for current constraint or impulse
JSTOP	(4,2,30)	Indicators to signify joint is in joint stop

COMMON    /TEMPVS/

Variables in this labeled common block are temporary for each subroutine that refers to it.

COMMON    /TITLES/

DATE	(3)	Date of computer run in 12 alphanumeric characters (Card A.1.a)
COMENT	(40)	160 character description of the run (Cards A.1.b- A.1.c)
VPSTTL	(20)	80 character description of the crash vehicle deceleration (Card C.1)
BDYTTL	(5)	20 character description of the crash victim (Card B.1)
BLTTTL	(5,8)	20 character description of each belt (Cards D.3)
PLTTTL	(5,30)	20 character description of each plane (Cards D.2)

BAGTTL (5,6) 20 character description of each airbag  
(Cards D.4)

SEG (30) 4 character segment nomenclature (Cards B.2)

JOINT (30) 4 character joint nomenclature (Cards B.3)

CGS (30) 1 character plot symbol of the segment C.G.  
(Cards B.2)

JS (30) 1 character plot symbol of the joint location  
(Cards B.3)

COMMON /VPOSTN/

ZPLT (3) Printer plot coordinates of the vehicle  
reference origin (Card G.1.a)

SPLT (3) Scale factors for the printer plot axes  
(Card G.1.b)

AXV (3,6) Unit vector of deceleration impulse  
direction

VATAB (6,501,6) Tables of computed or supplied (Cards C.3  
or C.4) values of linear (1-3) and angular  
accelerations (4-6) of vehicle motion

VTO (6) Beginning time point of the deceleration table  
input (Card C.2)

VDT (6) Fixed time interval for deceleration table  
input (Card C.2)

**TIMEV** (6) Time duration of the deceleration impulse  
 (Card C.2)

**OMEGAV** (6) Frequency of the half-sine wave deceleration  
 type (Card C.2)

**NVTAB** (6) Number of points in deceleration table.  
 Sign determines type (Card C.2)

**INDXV** (6) Segment identification number for each  
 specified motion definition (MSEG on Card  
 C.2.a or NVEH)

COMMON    /WINDFR/

**WTIME** (30) Initial time that segment penetrates wind

**QFU** (3,5) Unit vector for force application

**QFV** (3,5) Vector for torque application

**WF** (3,30) Wind force vectors applied to segments (local)

**IWIND** (30) Indicator that wind has been penetrated

**MWSEG** (7,30) Identification numbers for the application  
 of wind forces on each segment (Cards F.7)

**NFVSEG** (6) Segment identification number for each force  
 function (Cards D.9)

NFVNT	(5)	Function identification number for each force function (Cards D.9)
MOWSEG	(30,30)	Contact ellipsoid numbers and segment identification numbers of blocking segments (Cards F.7)

The following table shows the results of the experiment. The values are given in the units indicated in the column headings. The values in parentheses are the values calculated from the theoretical equation.

Temperature (°C)	Observed $\log k$	Calculated $\log k$
25	1.25	1.25
30	1.45	1.45
35	1.65	1.65
40	1.85	1.85
45	2.05	2.05
50	2.25	2.25
55	2.45	2.45
60	2.65	2.65
65	2.85	2.85
70	3.05	3.05
75	3.25	3.25
80	3.45	3.45
85	3.65	3.65
90	3.85	3.85
95	4.05	4.05
100	4.25	4.25

2



### 3.0 CROSS REFERENCE CHARTS

The first two cross reference charts list the COMMON blocks used by each subroutine. The remaining ten charts list the subroutines called by each subroutine.





CALLING SUBROUTINES

```

:HHHHHHHHHHHHHHHHH:IIII:KLLL:MMOO:PPPPPPPPP:QRRRR:SSSSSSSSS:TUUU:VVVV:WKY:
:YYYYYYYYYYYYYYYYY:MMNN:IIOT:AARU:ADLLLLLORR:SUCOOS:EEEEILOOPP:RNPP:EIII:IDP:
:ABBDEFLLLNPBSVVV:PPIT:NNGI:TTTT:NAERSTSI:EARTTT:AGTTNPLLDL:IIDD:HNSS:NYR:
:BNASCIPPTTEEOABF:LUTE:PAAM:33HP:EUDLEEXTNP:TTT AA:RSUPLVVAI:GTAF:PPCP:D D:
:FDXDTNMRXRNALLXN:SLAR:UXXE:13OU:LXGPAGYPTL:TR:CEPPUOARMN:FITD:OUOR:Y E:
:                :2SLS:TSS:   T:   FZR T:   ET:HG12TT  PE:S EC:STS:  G:

```

31

	ABDATA	5						*												
	CDINT	7						*		*										
	CEULER	14		*			*	*	**	*		*		*						
	CMATRX	20		**		*		*	*	**		*		*						
C	CNSNTS	45		**	*	*		**	*	*	*	**		*		**	*	*	*	*
A	CNTSRF	19					*	*	**	*	*	*		*		*		*		*
L	COMAIN	6				*			*											
E	CONTRL	57		***	*	*	**	****	**	***	*	**	***	*	**	***	*	*	*	*
D	CSTRNT	19		**			*	*	*	**	*	**		*		*		*		*
	CYDATA	5							*											
C	DAMPER	7				*		*	**	*	*	*		*		*		*		*
O	DESCRP	33		***		*	*	**	**	**	**	*	*	*	*	*	*	*	*	*
M	FLXBLE	9		**			*		*		*			*		*		*		*
O	FORCES	18				*	*	*	*	*	*	*	*	*	*	*	*	*	*	*
N	HRNESS	13				*		*	*	**		*		*		*		*		*
	INTEST	6					*		*		*			*		*		*		*
B	JBARTZ	15		*		*		*	*	**	**	**		**		**		**		**
L	RSAVE	13				*	*	**	**	*	*	*		*		*		*		*
O	SGMNTS	45		***		*	**	*	**	**	**	**	****	*	**	***	*	**	***	**
K	TABLES	25		*	*			*	*	*	*	*	*	*	**	*	*	*	*	*
S	TEMPVI	7		*				*		*		*		*		*		*		*
	TEMPVS	57	*	**	*	*	*	****	*****	*	*	****	*	*	*	*	*	*	*	*
	TITLES	17		*	*	*	*	*	***	*	*	*		*		*		*		*
	VPOSTN	5		*				*		*		*		*		**		*		*
	WINDFR	7				*		*		**	*	*		*		*		*		*

SUBROUTINE CROSS REFERENCE

CALLING SUBROUTINES

:MAAAAA:BBBBB:CCCCC:DDDDDDDD:DDDDDDDDDDDDDD:EEEEEEEE:FFFFFFG:HHHHHHH:  
 :ADIII:EEGIL:FHIMOR:AAAAAAAAA:HIOOOORRRSSSZ:DFJLLQUV:DILNRSL:BBEEIIPS:  
 :IJRRRR:LLGNK:AANPNO:UUUUUUUU:HNTTTTCCCIEMP:EUOOTULA:INXTCMO:EPDRCNTE:  
 :NUBBBB:TT PD:CIPUTS:XXXXXXXXXX:PT33TTIQYFTTS :PNINIIRL:NPSEDSB:LLIRCPUT:  
 :ASAGGG:GR UT:TNUCTS: 11233345:I 1333JUPTDQO :TCNGMLAF:IUERFOA:TANOSURC:  
 :TG13G: T TA:T TET : 12212345:N 13KAR L :HTT EBDD:TTGPLLL: YGNITB :

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MAINA									
ADJUST	1				*				
AIRBAG	1			*					
AIRBG1	1								
AIRBG3	1								
AIRBGG	2	*	*						
BELTG	1			*					
BELTRT	1				*				
BGG	1		*						
BINPUT	1	*							
BLKDTA	1	*							
CFACTT	3						***		
CHAIN	3				*			*	
CINPUT	1	*							
CMPUTE	1					*			
CONTCT	1				*				
CROSS	28	*	***	*			*	*	*
DAUX	5							*	
DAUX11	1				*				
DAUX12	1				*				
DAUX22	1				*				
DAUX31	1				*				
DAUX32	1				*				
DAUX33	1				*				
DAUX44	1				*				
DAUX55	1				*				

CALLING SUBROUTINES

```

:MAAAAA:BBBBB:CCCCCC:DDDDDDDD:DDDDDDDDDDDDDD:EEEEEEEE:FFFFFFG:HHHHHHHH:
:ADIIII:EEGIL:FHIMOR:AAAAAAAAA:HIOOOORRRSSSZ:DFJLLQUV:DILNRSL:BBEEIIPS:
:IJRRRR:LLGNK:AANPNO:UUUUUUUU:HNTTTTCCCIEMP:EUOOTULA:INXTCMO:EPDRCNTE:
:NUBBBB:TT PD:CIPUTS:XXXXXXXXXX:PT33TTIQYFTTS :PNINIIRL:NPSEDSB:LLIRCPUT:
:ASAGGG:GR UT:TNUTCS: 11233345:I 1333JUPTDQO :TCNGMLAF:IUERFOA:TANOSURC:
:  TG13G: T TA:T TET : 12212345:N 13KAR L :HTT EBDD:TTGPLLL: YGNITB :
  
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DHHPIN	1												
DINT	1	*											
DOT31	34	****	**	*	*	*	*	*	*	*	**	**	
DOT33	10	*					*		*	*			
DOTT31	1												
DOTT33	9									*			
DRCIJK	2								*				
DRCQUA	1												
DRCYPR	6	*	*				*			*			
DRIFT	1			*									
DSETD	1												
DSETQ	1												
DSMSOL	4								*				
DZP	1			*									
EDEPTH	1		*										
EFUNCT	2								*				
EJOINT	5					*		*					
ELONG	1		*										
ELTIME	40	* * *	* *	* *	*	*****	*	*	*	*	*	*	*
EQUILB	1												
EULRAD	1								*				
EVALFD	7									*	*	*	
FDINIT	2									*		*	
FINPUT	1			*									
FLXSEG	1				*								
FNTERP	1												
FRCDFL	7		*						*	*	*	*	*
FSMSOL	2					*						*	
GLOBAL	2								*				

CALLING SUBROUTINES

```

:MAAAAA:BBBBB:CCCCCC:DDDDDDDD:DDDDDDDDDDDDDD:EEEEEEEE:FFFFFFG:HHHHHHHH:
:ADIIII:EEGIL:FHIMOR:AAAAAAAAA:HI000ORRRSSSZ:DFJLLQUV:DILNRSL:BBEEIIPS:
:IJRRRR:LLGNK:AANPNO:UUUUUUUU:HNTTTCCCIEMP:EUOOTULA:INXTCMO:EPDRCNTE:
:NUBBBB:TT PD:CIPUTS:XXXXXXXXX:PT33TTIQYFTS:PNINIIRL:NPSEDSB:LLIRCPUT:
:ASAGGG:GR UT:TNUCTS: 11233345 I 1333JUPTDQO:TCNGMLAF:IUERFOA:TANOSURC:
:TG13G: T TA:T TET: 12212345 N 13KAR L:HTT EBD:TTGPLLL: YGNITB:

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HBELT	2		*				*
HBPLAY	2						*
HEDING	2						
HERRON	1					*	
HICCSI	1						
HINPUT	1		*				
HPTURB	1						
HSETC	1						*
HYABF	2						
HYBND	1						
HYBOX	1						
HYDAD	1						
HYEST	1						
HYFCN	3						
HYLIM	1						
HYLPR	1						
HYLPX	1						
HYNTR	1						
HYPEN	1						
HYREA	1						
HYSOL	1						
HYVAL	1						
HYVBX	1						
HYVFN	1						
IMPLS2	1						
IMPULS	1						
INITAL	1	*					
INTERS	2		*				



CALLING SUBROUTINES

```

:MAAAAA:BBBBB:CCCCC:DDDDDDDD:DDDDDDDDDDDDDD:EEEEEEE:FFFFFFG:HHHHHHHH:
:ADIIII:EEGIL:FHIMOR:AAAAAAAAA:HI000ORRRRSSSZ:DFJLLQUV:DILNRSL:BBEEIIPS:
:IJRRRR:LLGNK:AANPNO:UUUUUUUU:HNTTTTCCCIEMP:EUOOTULA:INXTCMO:EPDRCNTE:
:NUBBBB:TT PD:CIPUTS:XXXXXXXXXX:PT33TTIQYFTTS:PNINIIRL:NPSEDSB:LLIRCPUT:
:ASAGGG:GR UT:TNUCTS: 11233345:I 1333JUPTDQO:TCNGMLAF:IUERFOA:TANOSURC:
:TG13G: T TA:T TET: 12212345:N 13KAR L:HTT EBDD:TTGPLLL: YGNITB

```

SEARCH	1							
SEGSEG	2		*					
SETUP1	1			*				
SETUP2	2			*				
SINPUT	1	*						
SLPLOT	1							
SOLVA	1							
SOLVR	1							
SPDAMP	1		*					
SPLINE	1							
TRIGFS	1				*			
UNIT1	2	*						
UPDATE	1				*			
UPDFDC	1							
VEHPOS	2			*				
VINPUT	1	*						
VISCOS	2					*		
VISPR	2			*				
WINDY	1		*					
XDY	8					*	*	* **
YPRDEG	5	*						

36 CALLED SUBROUTINES













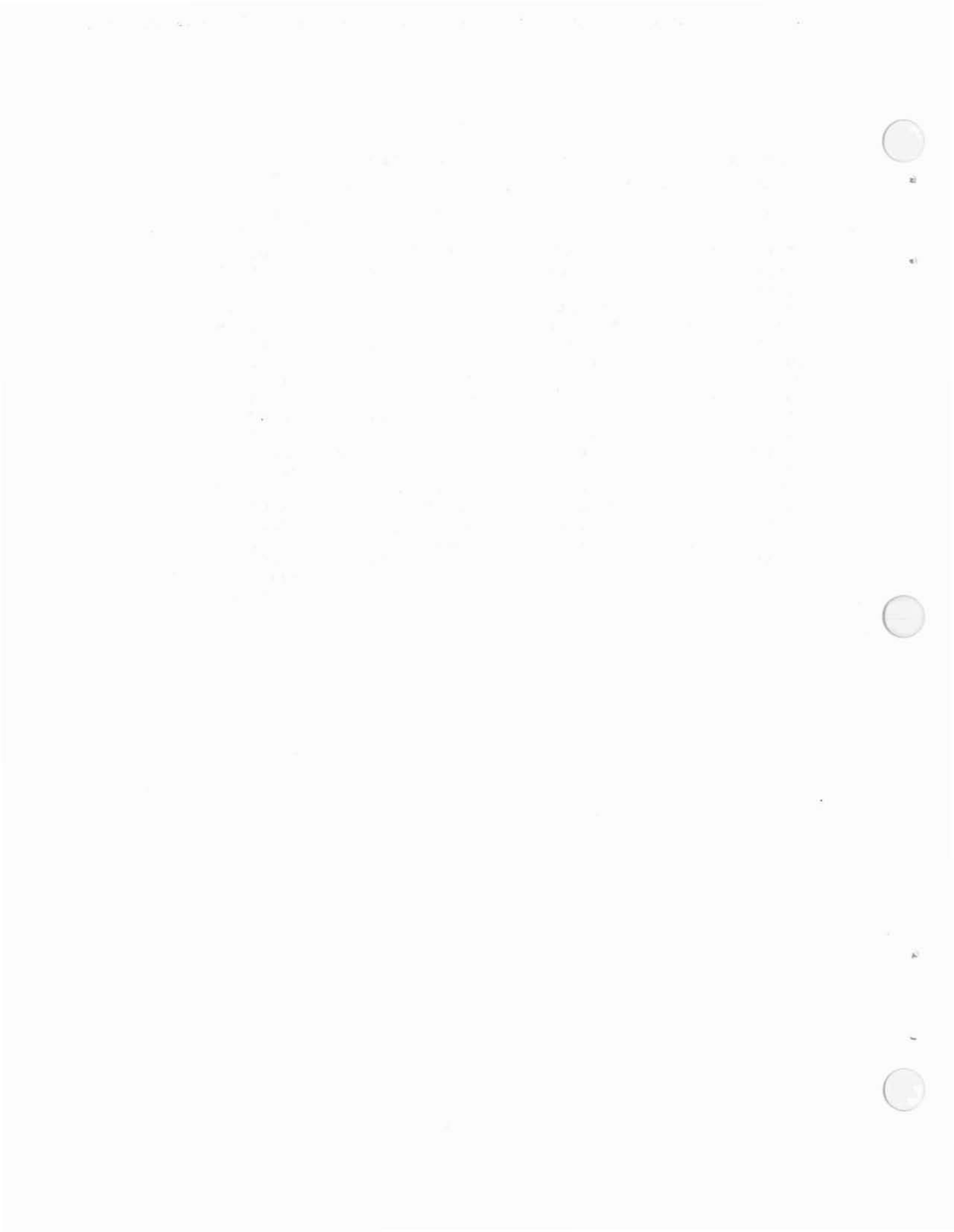


**4.0 LIST OF 130 SUBROUTINES  
THAT COMPRISE THE ATB-IV MODEL COMPUTER PROGRAM**

The first subroutine is a list of the common blocks used by the program, the second is the main program followed by all of the remaining subroutines in alphabetical order. Each subroutine name is appended with its revision number followed by the date of the latest change to the subroutine. This same data and revision number appears on the second line of each subroutine in Section 5.

SUBPROGRAM & REV. NO.			SUBPROGRAM & REV. NO.		
		DATE			DATE
BDATA	IV	07/23/86	MAIN	IV	07/23/86
ADJUST	IV	07/23/86	AIRBAG	IV	07/24/86
AIRBGG	III.5	10/17/85	AIRBG1	IV	07/24/86
AIRBG3	IV	07/23/86	BELTG	IV	07/23/86
BELTRT	IV	07/23/86	BGG	IV	07/23/86
BINPUT	IV	07/24/86	BLKDTA	IV	07/23/86
CFACTT	3	05/31/73	CHAIN	IV	07/24/86
CINPUT	III.2	08/08/84	CMPUTE	III.2	08/08/84
CONCTC	III.2	08/08/84	CROSS	3	05/31/73
DAUX	IV	07/24/86	DAUX11	IV	07/24/86
DAUX12	IV	07/24/86	DAUX22	IV	07/24/86
DAUX31	IV	07/24/86	DAUX32	IV	07/24/86
DAUX33	IV	07/24/86	DAUX44	IV	07/24/86
DAUX55	IV	07/24/86	DHHPIN	IV	07/24/86
DINT	IV	07/23/86	DOTT31	17	12/20/76
DOTT33	17	01/03/77	DOT31	17	01/03/77
DOT33	17	01/03/77	DRCIJK	18	02/24/78
DRCQUA	III.5	07/31/85	DRCYPR	IV	07/23/86
DRIFT	IV	07/24/86	DSETD	IV	07/23/86
DSETQ	IV	07/23/86	DSMSOL	3	07/08/74
DZP	IV	07/23/86	EDEPTH	IV	07/23/86
EFUNCT	20	04/29/80	EJOINT	IV	07/24/86
ELONG	1	10/05/72	ELTIME	III.2	08/08/84
EQUILB	IV	02/01/88	EULRAD	IV	07/23/86
EVALFD	IV	07/23/86	FDINIT	III.2	08/08/84
FINPUT	IV	02/01/88	FLXSEG	IV	07/23/86
FENTERP	IV	04/10/87	FRCDFL	III.2	08/08/84
FSMSOL	III.2	08/08/84	GLOBAL	IV	07/24/86
HBELT	IV	02/01/88	HBPLAY	III.5	10/17/85
HEDING	IV	02/01/88	HERRON	IV	07/23/86
HICCSI	IV	10/08/87	HINPUT	IV	07/23/86
HPTURB	IV	07/23/86	HSETC	III.2	08/08/84
HYABF	IV	02/07/87	HYBND	IV	02/07/87
HYBOX	IV	02/07/87	HYDAD	IV	02/07/87
HYEST	IV	02/07/87	HYFCN	IV	02/07/87
HYLIM	IV	12/11/87	HYLPR	IV	02/07/87
HYLPX	IV	02/07/87	HYNTR	IV	02/07/87
HYPEN	IV	02/07/87	HYREA	IV	12/11/87
HYSOL	IV	02/01/88	HYVAL	IV	12/11/87
HYVBX	IV	02/07/87	HYVFN	IV	12/11/87
IMPLS2	IV	07/24/86	IMPULS	IV	07/24/86
INITIAL	IV	07/24/86	INTERS	IV	02/23/86
KINPUT	IV	07/23/86	LINAXS	18	02/28/78

SUBPROGRAM & REV NO.			DATE	SUBPROGRAM & REV NO.			DATE
LOGAXS	19		09/18/79	LTIME	III.2		08/08/84
MAT31	17		01/03/77	MAT33	17		01/03/77
ORTHO	3		05/31/73	OUTPUT	IV		02/01/88
PANEL	III.2		08/08/84	PDAUX	IV		07/24/86
PLEDG	IV		02/07/87	PLELP	IV		02/07/87
PLREA	IV		12/11/87	PLSEGF	III.5		09/03/85
PLTXYZ	III.5		05/30/85	POSTPR	IV		02/01/88
PRINT	IV		07/24/86	PRIPLT	IV		07/24/86
QSET	III.3		10/01/84	QUAT	IV		07/23/86
RCRT	3		07/19/73	ROT	IV		07/23/86
ROTATE	IV		02/20/87	RSTART	IV		07/24/86
SEARCH	IV		07/24/86	SEGSEG	IV		02/07/87
SETUP1	IV		07/24/86	SETUP2	IV		07/24/86
SINPUT	IV		02/20/87	SLPLOT	III.2		08/08/84
SOLVA	III.2		08/08/84	SOLVR	III.2		08/08/84
SPDAMP	IV		07/24/86	SPLINE	19		05/14/79
SPRNGF	IV		07/23/86	TRIGFS	19		08/05/78
UNIT1	IV		02/20/87	UPDATE	IV		07/24/86
UPDFDC	III.2		08/08/84	VEHPOS	IV		07/23/86
VINPUT	IV		07/24/86	VISCOS	19		10/23/78
VISPR	IV		02/01/88	WINDY	IV		07/23/86
XDY	IV		07/23/86	YPRDEG	IV		11/26/86





5.0 FORTRAN SOURCE CODE OF  
THE ATB-IV.0 PROGRAM

Each of the 130 ATB-IV subroutines are listed in this section. The second line of each subroutine contains the subroutine revision number and the date of the latest change to the subroutine. Columns 72-80 of each line contain the subroutine name unless the line is a new or changed line from the listing in Ref. 4. In these cases the name of the latest change is in columns 72-80. The first subroutine is the BLOCKDATA containing the COMMON blocks used by the program. The second routine is the MAIN program which controls the flow of the program. The remaining subroutines are listed alphabetically.

## BLOCK DATA

REV IV 07/23/86TWOPI

	IMPLICIT REAL*8 (A-H,O-Z)	DECKA
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	DECKA
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),	DECKA
*	UNITL,UNITM,UNITT,GRAVITY(3),TWOPI	TWOPI
	COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6),	DECKA
*	MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6),	DECKA
*	NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30)	DECKA
	COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5),	DECKA
*	BLTTTL(5,8),PLTTL(5,30),BAGTTL(5,6),SEG(30),	DECKA
*	JOINT(30),CGS(30),JS(30)	DECKA
	REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,SEG,JOINT	DECKA
	LOGICAL*1 CGS,JS	DECKA
	COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),	NCFORC
*	PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF	DECKA
	COMMON/RSAVE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30),	ATBII I
*	NSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9)	TTHKREF
	COMMON/CDINT/ UU(4),GH(3,4),	DECKA
*	E(3,240),FF(5,240),GG(5,240),Y(5,240),U(5,240),	DECKA
*	H,HPRINT,TSAVE,TPRINT,TSTART,ICNT,IDBL,IFLAG	DECKA
	COMMON/DAMPER/ APSDM(3,20),APSDN(3,20),ASD(5,20),MSDM(20),MSDN(20)	DECKA
	COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100),	DECKA
*	XLONG(20),HTIME(2),IBAR(5,100),NL(2,100),	DECKA
*	NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5)	DECKA
C	NOTE: FF REPLACES F.	DECKA
	LOGICAL*1 FREE	SLIP
	COMMON/TEMPVS/ JTMPVS(24000),FREE(30)	SLIP
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),	DECKA
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)	DECKA
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),	SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),	DECKA
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)	DECKA
	COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)	EDGE
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)	BUTLER2
	COMMON/VPOSTN/ ZPLT(3),SPLT(3),AXV(3,6),VATAB(6,501,6),	VEHICL
*	VTO(6),VDT(6),TIMEV(6),OMEGV(6),NVTAB(6),INDXV(6)	DECKA
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),	DECKA
*	F(3,30),TQ(3,30),WJ(30),A11(3,3,30)	SLIP
	COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30),	JDRIFT
*	FE(3,30),TQE(3,30),CONST(5,30)	JDRIFT
	COMMON/FLXBLE/ HF(4,12,8),B42(3,3,24),V4(3,8),NFLEX(3,8)	DECKA
	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),	DECKA
*	HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),	DECKA
*	RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),	DECKA
*	KQ1(12),KQ2(12),KQTYPE(12)	DECKA
	COMMON/TEMPVI/ CREST,TTI(3),RII(3),R2I(3),JSTOP(4,2,30)	DECKA
	COMMON/INTEST/ SGTEST(3,4,30),XTEST(3,120),SEGT(120),REGT(120)	DECKA
	REAL SEG	DECKA

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COMMON/COMAIN/ VAR(240),DER(240),DT,HO,HMAX,HMIN,RSTIME, DECKA
* ISTEP,NSTEPS,NDINT,NEQ,IRSIN,IRSOUT DECKA
COMMON/ABDATA/ ZDEP(3,5),DBR(3,3,5),DPVCTR(3,5),DEPLOY(3,5), DECKA
* AB(3,5),B(9,4,5),ZR(3,4,5),BFB(3,4,5),DRR(9,4,5), DECKA
* VBAGG(5),VSCS(5),SPRK(5),CK(5),CMASS(5),CYMIN(5), DECKA
* CYMOUT(5),BAGPV(5),PD(5),VBAG(5),VOLBP(5), DECKA
* PCYV(5),PCYMIN(5),PVBAG(5),TV1(3,4,5),TV2(3,10,5), DECKA
* SWITCH(5),PYMOUT(5),SCALE(5),PREVT,IFULL(6) DECKA
COMMON/CYDATA/ CYTD(5),CYP(5),CYSP(5),CYTO(5),CYVO(5),CYCD(5), DECKA
* CYK(5),CYR(5),CYAT(5),CYPV(5),CYCDO(5),CYAO(5), DECKA
* CYP0(5),CYSS(5),CYLO(5),CYC(5),CYRHO0(5),CYVMAX(5),DECKA
* CYORFC(5),CYRHO(5),CYT(5),CYP(5),CYV(5) DECKA
COMMON/WINDFR/ WTIME(30),QFU(3,5),QFV(3,5),WF(3,30),IWIND(30), WINDOP
* MWSEG(7,30),NFVSEG(6),NFVNT(5),MOWSEG(30,30) WINDOP
END DECKA

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C		MAINA
C	AAMRL ARTICULATED TOTAL BODY (ATBIV) MODEL COMPUTER PROGRAM	ATBIV
C	DEVELOPED BY CALSPAN CORP. AND J&J TECHNOLOGIES INC.	BUTLER1
C		REV IV 07/23/86TWOPI
C	MAIN PROGRAM	MAINA
C		MAINA
C	PERFORMS CARD INPUT, PROGRAM INITIALIZATION,	MAINA
C	CONTROL OF INTEGRATION LOOP AND OPTIONAL OUTPUT.	MAINA
C		MAINA
	IMPLICIT REAL*8(A-H,O-Z)	MAINA
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	MAINA
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5),	MAINA
*	BLTTTL(5,8),PLTTL(5,30),BAGTTL(5,6),SEG(30),	MAINA
*	JOINT(30),CGS(30),JS(30)	MAINA
	REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,SEG,JOINT	MAINA
	LOGICAL*1 CGS,JS	MAINA
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),	MAINA
*	UNITL,UNITM,UNITT,GRAVITY(3),TWOPI	TWOPI
	COMMON/COMAIN/ VAR(240),DER(240),DT,HO,HMAX,HMIN,RSTIME,	MAINA
*	ISTEP,NSTEPS,NDINT,NEQ,IRSI,IRSOUT	MAINA
	LOGICAL NPRT1,NPRT2,NPRT3	MAINA
	CALL ELTIME(1, 1)	MAINA
C		PECONV
C	MAKE THE OUTPUT FILES PRINTER CONTROL FILES FOR THE P&E	PECONV
C		PECONV
	CALL CARCON(6,1)	PECONV
	CALL CARCON(2,1)	PECONV
C		MAINA
C	WRITE PROLOGUE ON PRIMARY OUTPUT UNIT.	MAINA
C		MAINA
	NPG=2	PAGE
	WRITE(6,11)	MAINA
11	FORMAT(1H1,30X,'AAMRL ARTICULATED TOTAL BODY (ATB) MODEL',52X,	ATBIV
*	'PAGE 1'////	PAGE
*	31X,'DEVELOPED BY CALSPAN CORP., P.O. BOX 400, BUFFALO NY 14225' /	BUTLER1
*	31X,'AND BY J&J TECHNOLOGIES INC., ORCHARD PARK, NY 14127' //	EDGE
*	31X,'FOR THE AIR FORCE ARMSTRONG AEROSPACE MEDICAL RESEARCH ' /	VEHICL
*	31X,'LABORATORY, WRIGHT PATTERSON AIR FORCE BASE ' /	ATBIV
*	31X,'UNDER CONTRACTS F33615-75C-5002,-78C-0516 AND -80C-05117' //	BUTLER1
*	31X,'AND FOR THE NATIONAL HIGHWAY TRAFFIC SAFETY ADMINISTRATION,'	BUTLER1
*/31X,	'U.S. DEPARTMENT OF TRANSPORTATION, UNDER CONTRACTS' /	BUTLER1
*	31X,'FH-11-7592, HS-053-2-485, HS-6-01300 AND HS-6-01410.' ////	BUTLER1
*	31X,'PROGRAM DOCUMENTATION: NHTSA REPORT NOS. DOT-HS-801-507' /	BUTLER1
*	31X,'THROUGH 510 (FORMERLY CALSPAN REPORT NO. ZQ-5180-L-1),' /	BUTLER1
*	31X,'AVAILABLE FROM NTIS (ACCESSION NOS. PB-241692,3,4 AND 5),' /	BUTLER1
*	31X,'APPENDIXES A-J TO THE ABOVE (AVAILABLE FROM CALSPAN),' /	BUTLER1
*	31X,'AND REPORT NOS. AMRL-TR-75-14 (NTIS NO. AD-A014 816), /	ATBIV
*	31X,'AFAMRL-TR-80-14 (NTIS NO. AD-A088 029), AND' /	ATBIV
*	31X,'AFAMRL-TR-83-073 (NTIS NO. AD-B079 184).' ////	

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* 31X,'PROGRAM ATB-IV, EXECUTED ON THE AAMRL/BB CONCURRENT'/
* 31X,'3250 COMPUTER, WRIGHT-PATTERSON AFB, OHIO'/////
C
C INPUT CARDS A.1 AND A.2, TEST FOR RESTART.
C
CALL BLKDTA
READ(5,12) DATE,IRSIN,IRSOUT,RSTIME,COMENT
12 FORMAT(3A4,2I4,F8.0/20A4/20A4)
WRITE(6,13) DATE,IRSIN,IRSOUT,RSTIME,COMENT
13 FORMAT(/////4X,3A4,' IRSIN=',I4,' IRSOUT=',I4,' RSTIME =',F8.4,
* 61X,'CARDS A'//1X,20A4/1X,20A4//)
IF (IRSIN.NE.0) GO TO 18
C
C INPUT CARDS A.3,A.4 AND A.5.
C
READ(5,14) UNITL,UNITM,UNITT,GRAVTY,G
14 FORMAT(3A4,4F12.0)
IF (G.EQ.0.0) G = DSQRT(GRAVTY(1)**2+GRAVTY(2)**2+GRAVTY(3)**2)
READ(5,15) NDINT,NSTEPS,DT,HO,HMAX,HMIN,NPRT
15 FORMAT(2I4,4F8.0/36I2)
WRITE(6,16) UNITL,UNITM,UNITT,GRAVTY,G,
* NDINT,NSTEPS,DT,HO,HMAX,HMIN
16 FORMAT(5X,'UNITL = ',A4,5X,'UNITM = ',A4,5X,'UNITT = ',A4,
* 5X,'GRAVITY VECTOR = (' ,F9.4,',',F9.4,',',F9.4,')',5X,'G = '
*F9.4,/,5X,'NDINT = ',I4,5X,'NSTEPS = ',I5,5X,'DT = ',F8.6,
* 5X,'HO = ',F8.6,5X,'HMAX = ',F8.6,5X,'HMIN = ',F8.6)
WRITE(6,17) (I,I=1,36),NPRT
17 FORMAT('O NPRT ARRAY'/3X,36I3/3X,36I3)
NPRT4 = NPRT(4)
IF(NPRT(26).GT.6) STOP 93
IF (NPRT(4).LT.0) GO TO 50
C
C CALL INPUT ROUTINES
C
CALL BINPUT
CALL VINPUT
CALL SINPUT
CALL CINPUT
C
C PROGRAM INITIALIZATION
C
TIME = 0.0
CALL INITAL
GO TO 19
C
C READ INPUT DATA FROM RESTART TAPE AND WRITE NEW TAPE.
C THE FIVE FUNCTIONS OF SUBROUTINE RSTART ARE:
C 1. READ INPUT & INITIALIZATION RECORD FROM OLD RESTART TAPE.
C 2. WRITE INPUT & INITIALIZATION RECORD ONTO NEW RESTART TAPE.
C 3. READ TIME POINT RECORD FROM OLD RESTART TAPE.

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C	4. READ NEW INPUT DATA FROM INPUT STREAM FOR RESTART.	MAINA
C	5. WRITE TIME POINT RECORD ONTO NEW RESTART TAPE.	MAINA
C		MAINA
	18 CALL RSTART(1,IRSIN)	MAINA
	CALL RSTART(4,5)	MAINA
	NPRT4 = NPRT(4)	MAINA
	19 IF (IRSOUT.NE.0) CALL RSTART(2,IRSOUT)	MAINA
C		MAINA
C	INTEGRATION LOOP - ADVANCE TIME BY EITHER INTEGRATING THROUGH	MAINA
C	SUBROUTINE DINT OR BY FETCHING TIME POINT RECORD FROM RESTART TAPE	MAINA
C		MAINA
	TIME = 0.0	MAINA
	ISTEP = 0	MAINA
	20 IF (IRSIN.EQ.0) GO TO 23	MAINA
	IF (TIME.GT.RSTIME+0.5*DT) GO TO 23	MAINA
	IF (DABS(TIME-RSTIME).LT.0.5*DT) GO TO 21	MAINA
	CALL RSTART(3,IRSIN)	MAINA
	GO TO 24	MAINA
	21 CALL RSTART(4,5)	MAINA
	IF (NPRT(4).LT.0) GO TO 50	MAINA
	23 CALL DINT	MAINA
C		MAINA
C	OPTIONAL OUTPUT	MAINA
C	1. PRINTER PLOT ON OUTPUT UNIT 2 CONTROLLED BY NPRT(5) & (6).	MAINA
C		MAINA
	24 CALL PRIPLT	MAINA
C		MAINA
C	2. RESTART DATA ON UNIT IRSOUT CONTROLLED BY IRSOUT # 0.	MAINA
C		MAINA
	IF (IRSOUT.NE.0) CALL RSTART(5,IRSOUT)	MAINA
C		MAINA
C	3. SUBROUTINE PRINT ON PRIMARY OUTPUT UNIT CONTROLLED BE NPRT(3).	MAINA
C		MAINA
	NPRT3 = (NPRT(3).EQ.1)	MAINA
	IF (NPRT(3).GT.1) NPRT3 = (MOD(ISTEP,NPRT(3)).EQ.0)	MAINA
	IF (NPRT3) CALL PRINT(6HMAIN3D)	MAINA
C		MAINA
C	4. PROGRAM VIEW PLOT DATA ON UNIT 1 CONTROLLED BY NPRT(1).	MAINA
C		MAINA
	NPRT1 = (NPRT(1).EQ.1)	MAINA
	IF (NPRT(1).GT.1) NPRT1 = (MOD(ISTEP,NPRT(1)).EQ.0)	MAINA
	IF (NPRT1) CALL UNIT1(0)	MAINA
C		MAINA
C	5. SUBROUTINE ELTIME ON PRIMARY OUTPUT UNIT CONTROLLED BY NPRT(2).	MAINA
C		MAINA
	NPRT2 = (NPRT(2).EQ.1)	MAINA
	IF (NPRT(2).GT.1) NPRT2 = (MOD(ISTEP,NPRT(2)).EQ.0)	MAINA
	IF (NPRT2) CALL ELTIME(NPG,1)	PAGE
C		MAINA
C	END OF INTEGRATION LOOP.	MAINA

C	ISTEP = ISTEP+1	MAINA
	IF (ISTEP.LE.NSTEPS) GO TO 20	MAINA
C		MAINA
C	6. SUBROUTINE POSTPR ON PRIMARY OUTPUT UNIT CONTROLLED BY NPRT(4).	MAINA
C		MAINA
	50 IF (NPRT4.GT.0) END FILE 8	MAINA
	IF (NPRT(4).EQ.0 .OR. NPRT(4).EQ.4) GO TO 60	MAINA
	PRDT = 1000.0*DT	MAINA
	CALL POSTPR (PRDT)	MAINA
	IF (NPRT2) CALL ELTIME(NPG,1)	PAGE
C		MAINA
C	7. END OF RUN - CALL ELTIME IF NOT CALLED ABOVE.	MAINA
C		MAINA
	60 IF (.NOT.NPRT2) CALL ELTIME(NPG,1)	PAGE
	STOP 1	MAINA
	END	MAINA

	SUBROUTINE ADJUST (M,D1)	ADJUST
		REV IV 07/23/86TWOPI
C	IMPLICIT REAL*8 (A-H,O-Z)	ADJUST
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),	ADJUST
	* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI	TWOPI
	COMMON/CDINT/ UU(4),GH(3,4),	ADJUST
	* E(3,240), F(5,240),GG(5,240),Y(5,240),U(5,240),	ADJUST
	* H,HPRINT,HS,TPRINT,TSTART,ICNT,IDBL,IFLAG	ADJUST
	COMMON/COMAIN/ VAR(240),DER(240),DT,HO,EMAX,HMIN,RSTIME,	ADJUST
	* ISTEP,NSTEPS,MDINT,NEQ,IRSI,IRSOUT	ADJUST
	IF (M.NE.1) GO TO 12	ADJUST
C		ADJUST
C	M = 1:	ADJUST
C		ADJUST
	DO 11 I=1,NEQ	ADJUST
	W = VAR(I) - GG(1,I)	ADJUST
	Z = DER(I) - GG(2,I)	ADJUST
	ZZ = Z - GG(5,I)*W - GG(3,I)*UU(3) - GG(4,I)*UU(4)	ADJUST
	GG(3,I) = GG(3,I) + ZZ*UU(1)	ADJUST
	GG(4,I) = GG(4,I) + ZZ*UU(2)	ADJUST
	Y(1,I) = VAR(I)	ADJUST
11	Y(2,I) = DER(I)	ADJUST
	GO TO 99	ADJUST
12	IF (M.EQ.3) GO TO 23	ADJUST
C		ADJUST
C	M = 2,4,5:	ADJUST
C		ADJUST
	H1 = EPS(1)/H	ADJUST
	N2 = NEQ/2	ADJUST
	DO 20 I=1,NEQ,3	ADJUST
	ZA = 0.0	ADJUST
	IF (I.LE.N2) GO TO 20	ADJUST
	IF (M.EQ.4) GO TO 16	ADJUST
	VARX = VAR(I) - Y(1,I)	ADJUST
	VARY = VAR(I+1) - Y(1,I+1)	ADJUST
	VARZ = VAR(I+2) - Y(1,I+2)	ADJUST
	DERX = DER(I) - Y(2,I)	ADJUST
	DERY = DER(I+1) - Y(2,I+1)	ADJUST
	DERZ = DER(I+2) - Y(2,I+2)	ADJUST
	GO TO 17	ADJUST
16	VARX = VAR(I) - U(1,I)	ADJUST
	VARY = VAR(I+1) - U(1,I+1)	ADJUST
	VARZ = VAR(I+2) - U(1,I+2)	ADJUST
	DERX = DER(I) - U(2,I)	ADJUST
	DERY = DER(I+1) - U(2,I+1)	ADJUST
	DERZ = DER(I+2) - U(2,I+2)	ADJUST
17	U(3,I) = U(3,I) + VARX*DERX + VARY*DERY + VARZ*DERZ	ADJUST
	U(4,I) = U(4,I) + VARX**2 + VARY**2 + VARZ**2	ADJUST
	IF (U(4,I).EQ.0.0) GO TO 18	FIXADJ
	ZA = H1	FIXADJ



	IF (U(3,I).LT.H1*U(4,I)) ZA = U(3,I)/U(4,I)	FIXADJ
18	GG(5,I+2) = ZA	FIXADJ
	GG(5,I+1) = ZA	ADJUST
20	GG(5,I ) = ZA	ADJUST
	GO TO (99,21,99,23,25),M	ADJUST
C		ADJUST
C	M = 2:	ADJUST
C		ADJUST
21	DO 22 I=1,NEQ	ADJUST
	ZA = GG(5,I)	ADJUST
	Y1 = Y(4,I) - ZA*Y(3,I)	ADJUST
	Y2 = GG(2,I) - ZA*GG(1,I)	ADJUST
	Y3 = DER(I) - ZA*VAR(I)	ADJUST
	GG(3,I) = -Y1*GH(1,1) + Y2*GH(2,1) + Y3*GH(3,1)	ADJUST
	GG(4,I) = Y1*GH(1,2) - Y2*GH(2,2) + Y3*GH(3,2)	ADJUST
	Y(1,I) = 0.5*(Y(1,I)+VAR(I))	ADJUST
22	Y(2,I) = 0.5*(Y(2,I)+DER(I))	ADJUST
	GO TO 99	ADJUST
C		ADJUST
C	M = 3,4:	ADJUST
C		ADJUST
23	DO 24 I=1,NEQ	ADJUST
	ZA = GG(5,I)	ADJUST
	Y1 = GG(2,I) - ZA*GG(1,I)	ADJUST
	Y2 = Y(2,I) - ZA*Y(1,I)	ADJUST
	Y3 = DER(I) - ZA*VAR(I)	ADJUST
	GG(3,I) = -Y1*GH(1,3) + Y2*GH(2,3) - Y3*GH(3,3)	ADJUST
	GG(4,I) = Y1*GH(1,4) - Y2*GH(2,4) + Y3*GH(3,4)	ADJUST
	U(1,I) = VAR(I)	ADJUST
24	U(2,I) = DER(I)	ADJUST
	GO TO 99	ADJUST
C		ADJUST
C	M = 5:	ADJUST
C		ADJUST
25	DO 26 I=1,NEQ	ADJUST
	ZA = GG(5,I)	ADJUST
	Y1 = GG(2,I) - ZA*GG(1,I)	ADJUST
	Y2 = DER(I) - ZA*VAR(I)	ADJUST
	Y3 = U(2,I) - ZA*U(1,I)	ADJUST
	GG(3,I) = -Y1*GH(1,3) + Y2*GH(2,3) - Y3*GH(3,3)	ADJUST
	GG(4,I) = Y1*GH(1,4) - Y2*GH(2,4) + Y3*GH(3,4)	ADJUST
	Y(1,I) = VAR(I)	ADJUST
26	Y(2,I) = DER(I)	ADJUST
99	RETURN	ADJUST
	END	ADJUST

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SUBROUTINE AIRBAG                                AIRBAG
C                                               REV IV 07/24/86SLIP
C AIRBAG ROUTINE CALLED BY SUBROUTINE CONTCT TO DETERMINE THE INTER-AIRBAG
C ACTION OF THE BAG WITH REACTION PANELS AND BODY SEGMENTS BY USE OFAIRBAG
C SUBROUTINE BGG. THE DIFFERENTIAL PRESSURE, FORCE AND TORQUE ON THE AIRBAG
C BAG IS EVALUATED AND THE RESULTING FORCE AND TORQUE ON THE BODY AIRBAG
C SEGMENTS ARE ADDED TO THE U1 AND U2 ARRAYS. AIRBAG
C
IMPLICIT REAL*8 (A-H,O-Z) AIRBAG
COMMON/CONTRL/ TIME, NSEG, NJNT, NPL, NBLT, NBAG, NVEH, NGRND, AIRBAG
* NS, NQ, NSD, NFLX, NHRNSS, NWINDF, NJNTF, NPRT(36), NPG PAGE
COMMON/SGMNTS/ D(3,3,30), WMEG(3,30), WMEGD(3,30), U1(3,30), U2(3,30), AIRBAG
* SEGLP(3,30), SEGLV(3,30), SEGLA(3,30), NSYM(30) AIRBAG
COMMON/DESCRP/ PHI(3,30), W(30), RW(30), SR(4,60), HA(3,60), HB(3,60), SLIP
* RPHI(3,30), HT(3,3,60), SPRING(5,90), VISC(7,90), AIRBAG
* JNT(30), IPIN(30), ISING(30), IGLOB(30), JOINTF(30) AIRBAG
COMMON/JBARTZ/ MNPL( 30), MNBLT( 8), MNSEG( 30), MNBAG( 6), AIRBAG
* MPL(3,5,30), MBLT(3,5,8), MSEG(3,5,30), MBAG(3,10,6), AIRBAG
* NTPL( 5,30), NTBLT( 5,8), NTSEG( 5,30) AIRBAG
COMMON/FORCES/PSF(7,70), BSF(4,20), SSF(10,40), BAGSF(3,20), NCFORC
* PRJNT(7,30), NPANEL(5), NPSF, NBSF, NSSF, NBGSF AIRBAG
COMMON/CNTRSF/ PL(24,30), BELT(20,8), TPTS(6,8), BD(24,40) EDGE
COMMON/CNSNTS/ PI, RADIANT, G, THIRD, EPS(24), AIRBAG
* UNITL, UNITM, UNITT, GRAVITY(3), TWOPI TWOPI
COMMON/ABDATA/ ZDEP(3,5), DBR(3,3,5), DPVCTR(3,5), DEPLOY(3,5), AIRBAG
* AB(3,5), B(9,4,5), ZR(3,4,5), BFB(3,4,5), DRR(9,4,5), AIRBAG
* VBAGG(5), VSCS(5), SPRK(5), CK(5), CMASS(5), CYMIN(5), AIRBAG
* CYMOUT(5), BAGPV(5), PD(5), VBAG(5), VOLBP(5), AIRBAG
* PCYV(5), PCYMIN(5), PVBAG(5), TV1(3,4,5), TV2(3,10,5), AIRBAG
* SWITCH(5), PYMOUT(5), SCALE(5), PREVT, IFULL(6) AIRBAG
COMMON/CYDATA/ CYTD(5), CYPA(5), CYSP(5), CYT0(5), CYV0(5), CYCD(5), AIRBAG
* CYK(5), CYR(5), CYAT(5), CYPV(5), CYCD0(5), CYAO(5), AIRBAG
* CYP0(5), CYSS(5), CYL0(5), CYC(5), CYRH00(5), CYVMAX(5), AIRBAG
* CYORFC(5), CYRHO(5), CYT(5), CYP(5), CYV(5) AIRBAG
COMMON/TEMPVS/ TMP(9), TMP1(3), TORQ(3), FORCE(3,5), TORA(3,5), AIRBAG
* TQB(3,10), FRB(3,10), VOL(10), DELF(3), VOLP(4,5), FRA(4,5) AIRBAG
C NOTE: THIS COMMON/TEMPVS/ IS SHARED BY AIRBAG AND AIRBGG. AIRBAG
CALL ELTIME(1,24) AIRBAG
DELT = TIME-PREVT AIRBAG
NBGSF = 0 AIRBAG
DO 70 J=1, NBAG AIRBAG
IF (MNBAG(J).EQ.0) GO TO 70 AIRBAG
IF (IFULL(J).LE.0) GO TO 69 AIRBAG
CALL AIRBGG(J) AIRBAG
C
C COMPUTE CMOUT: MASS FLOW OUT OF BAG AIRBAG
C BAGPV: UNDISTORTED BAG VOLUME AIRBAG
C
IF (PD(J).GT.CYPV(J)) CYMOUT(J) = PYMOUT(J) AIRBAG
* + DELT*CYORFC(J)*DSQRT(PD(J)) AIRBAG

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      BAGPV(J) = CYPA(J)*((CYMIN(J)-CYMOUT(J))*SWITCH(J))*CYK(J)
C
C      BAG IS FULLY INFLATED, COMPUTE DIFFERENTIAL PRESSURE
C
      PD(J) = BAGPV(J)/(VBAG(J)-VOLBP(J))*CYK(J) - CYPA(J)
      JB = NVEH + J
      KP = NPANEL(J)
      KBAG = MNBAG(J)
C
C      OPTIONAL DIAGNOSTIC OUTPUT
C
      IF (NPRT(21).NE.0) WRITE(6,41)
      * ((FRB(I,K),I=1,3),(TQB(I,K),I=1,3),K=1,KBAG),(FORCE(I,J),I=1,3),
      * (TORA(I,J),I=1,3),TORQ,((FRA(I,K),I=1,3),VOLP(K,J),K=1,KP),
      * (VOL(K),K=1,KBAG),VOLBP(J),CYMOUT(J),BAGPV(J),PD(J)
41  FORMAT ('OAIRBAG CONTCT'/(1X,9G14.6))
      IF (PD(J).LT.0.0) PD(J) = 0.0
      IF (PD(J).EQ.0.0) GO TO 46
C
C      SET UP BAGSF ARRAY FOR OUTPUT ROUTINE
C
      KBGSF = NBGSF+5
      DO 42 K=1,KP
      KBGSF = KBGSF+1
      DO 42 I=1,3
42  BAGSF(I,KBGSF) = PD(J)*FRA(I,K)
      DO 45 I=1,KBAG
      KBGSF = KBGSF+1
      IF (VOL(I).EQ.0.0) GO TO 45
      M = MBAG(2,I,J)
C
C      FINAL COMPUTATIONS OF FORCE AND TORQUE ON AIRBAG
C
      DO 44 K=1,3
      FRB(K,I) = PD(J)*FRB(K,I)
      BAGSF(K,KBGSF) = FRB(K,I)
      U1(K,M) = U1(K,M) - FRB(K,I)
44  U2(K,M) = U2(K,M) + PD(J)*TQB(K,I)
45  CONTINUE
46  DO 47 K=1,3
      FORCE(K,J) = PD(J)*FORCE(K,J)
47  TORA (K,J) = PD(J)*TORA (K,J)
      IF (VOLP(1,J).NE.0.0) GO TO 55
C
C      AIRBAG IS NOT INTERSECTING PRIMARY REACTION PANEL.
C      COMPUTE ARTIFICIAL FORCE AND TORQUE WITH A LINEAR SPRING FUNCTION
C      IN AN ATTEMPT TO TIE +X SEMIAXIS ENDPOINT OF AIRBAG TO DEPLOYMENT
C      POINT ON REACTION PANEL.
C
      DO 51 K=1,3

```

51	TMP(K) = BFB(K,1,J) + ZDEP(K,J)	AIRBAG
	CALL DOT31 (D(1,1,NVEH),TMP,TMP1)	AIRBAG
	DO 52 K=1,3	AIRBAG
	DELFF(K) = TMP1(K) + SEGLP(K,NVEH) - SEGLP(K,JB)	AIRBAG
52	TMP(K) = BD(K+3,JB)	AIRBAG
	TMP(1) = TMP(1) + BD(1,JB)	AIRBAG
	CALL DOT31 (D(1,1,JB),TMP,TMP1)	AIRBAG
	DO 53 K=1,3	AIRBAG
	DELFF(K) = SPRK(J)*(DELFF(K)-TMP1(K))	AIRBAG
	BAGSF(K,NBGSF+5) = DELFF(K)	AIRBAG
53	FORCE(K,J) = FORCE(K,J) + DELFF(K)	AIRBAG
	CALL MAT31 (D(1,1,JB),DELFF,TMP1)	AIRBAG
	CALL CROSS (TMP,TMP1,DELFF)	AIRBAG
	DO 54 K=1,3	AIRBAG
54	TORA(K,J) = TORA(K,J) + DELFF(K)	AIRBAG
55	XDD = CYMIN(J) - CYMOUT(J) + W(JB)	AIRBAG
	FMASS = CMASS(J)*XDD/G	AIRBAG
	TMASS = CMASS(J)*(XDD+W(JB)*2.0/3.0)/G	AIRBAG
	DO 56 I=1,3	AIRBAG
56	TMP(I) = WMEG(I,JB)*PHI(I,JB)	AIRBAG
	CALL CROSS (WMEG(1,JB),TMP,TMP1)	AIRBAG
	DO 57 I=1,3	AIRBAG
	SEGLA(I,JB) = FORCE(I,J)/FMASS + GRAVITY(I)	AIRBAG
57	WMEGD(I,JB) = (TORA(I,J)/TMASS-TMP1(I))*RPHI(I,JB)	AIRBAG
69	NBGSF = NBGSF + 5 + NPANEL(J) + MNBAG(J)	AIRBAG
70	CONTINUE	AIRBAG
	CALL ELTIME(2,24)	AIRBAG
	RETURN	AIRBAG
	END	AIRBAG

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SUBROUTINE AIRBGG(J)
C                                     REV III.5 10/17/85EDGE
C                                     AIRBGG
C CALLED BY SUBROUTINES AIRBAG AND AIRBG3 TO COMPUTE VOLUMES OF AIRBGG
C INTERSECTION BETWEEN AIRBAGS AND PANELS AND SEGMENTS. AIRBGG
C                                     AIRBGG
C IMPLICIT REAL*8 (A-H,O-Z) AIRBGG
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND, AIRBGG
* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG PAGE
COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30), AIRBGG
* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30) AIRBGG
COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6), AIRBGG
* MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6), AIRBGG
* NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30) AIRBGG
COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20), NCFORC
* PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBSGF AIRBGG
COMMON/CNTSRF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40) EDGE
COMMON/ABDATA/ ZDEP(3,5),DBR(3,3,5),DPVCTR(3,5),DEPLOY(3,5), AIRBGG
* AB(3,5),B(9,4,5),ZR(3,4,5),BFB(3,4,5),DRR(9,4,5), AIRBGG
* VBAGG(5),VSCS(5),SPRK(5),CK(5),CMASS(5),CYMIN(5), AIRBGG
* CYMOUT(5),BAGPV(5),PD(5),VBAG(5),VOLBP(5), AIRBGG
* PCYV(5),PCYMIN(5),PVBAG(5),TV1(3,4,5),TV2(3,10,5), AIRBGG
* SWITCH(5),PYMOUT(5),SCALE(5),PREVT,IFULL(6) AIRBGG
COMMON/CYDATA/ CYTD(5),CYPA(5),CYSP(5),CYTO(5),CYVO(5),CYCD(5), AIRBGG
* CYK(5),CYR(5),CYAT(5),CYPV(5),CYCDO(5),CYAO(5), AIRBGG
* CYPO(5),CYSS(5),CYLO(5),CYC(5),CYRHO0(5),CYVMAX(5), AIRBGG
* CYORFC(5),CYRHO(5),CYT(5),CYP(5),CYV(5) AIRBGG
COMMON/TEMPVS/ TMP(9),TMP1(3),TORQ(3),FORCE(3,5),TORA(3,5), AIRBGG
* TQB(3,10),FRB(3,10),VOL(10),DELF(3),VOLP(4,5),FRA(4,5) AIRBGG
C NOTE: THIS COMMON/TEMPVS/ IS SHARED BY AIRBAG AND AIRBGG. AIRBGG
C JB = NVEH + J AIRBGG
C VOLBP(J) = 0.0 AIRBGG
C                                     AIRBGG
C COMPUTE THERMODYNAMIC PROPERTIES OF AIRBAG AIRBGG
C     CYRHO : DENSITY AIRBGG
C     CYT   : TEMPERATURE AIRBGG
C     CYP   : PRESSURE AIRBGG
C     CYMIN : MASS FLOW INTO BAG AIRBGG
C     VBCALC : CALCULATED VOLUME AIRBGG
C                                     AIRBGG
C     Q = 1.0 AIRBGG
C     Q1 = 1.0 AIRBGG
C     Q2 = 1.0 AIRBGG
C     IF (TIME.LE.CYTD(J)) GO TO 13 AIRBGG
C     Q = 1.0 + CYC(J)*(TIME-CYTD(J)) AIRBGG
C     CYK1 = 2.0/(CYK(J)-1.0) AIRBGG
C     Q1 = 1.0/Q**CYK1 AIRBGG
C     Q2 = 1.0/Q** (CYK(J)*CYK1) AIRBGG
13 CYRHO(J) = CYRHO0(J)*Q1 AIRBGG
C     CYT(J) = CYTO(J)/Q**2 AIRBGG
C     CYP(J) = CYPO(J)*Q2 AIRBGG

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CYMIN(J) = CYVO(J)*(CYRHO0(J)-CYRHO(J))
CYV(J)   = CYVMAX(J)*(1.0-Q2)
IF (TIME.LT.CYTD(J)) GO TO 31
IF (BD(1,JB).EQ.0.0) GO TO 31
IF (TIME.LE.0.0)     GO TO 31
VOLB = 0.0
C
C COMPUTE AIRBAG ELLIPSOID MATRIX AND ZERO BAG FORCE AND TORQUE.
C
IF (IFULL(J).NE.0) GO TO 21
SAB = SCALE(J)*AB(1,J)
DO 19 I=1,3
19 TMP(I) = DEPLOY(I,J) + SAB*DPVCTR(I,J)
CALL DOT31 (D(1,1,NVEH),TMP,SEGLP(1,JB))
DO 20 I=1,3
20 SEGLP(I,JB) = SEGLP(I,JB) + SEGLP(I,NVEH)
21 DO 23 I=1,3
FORCE(I,J) = 0.0
23 TORA (I,J) = 0.0
C
C COMPUTE FORCE,TORQUE AND VOLUME OF INTERSECTION
C OF AIRBAG WITH REACTION PANEL ELLIPSOIDS.
C
KP = NPANEL(J)
DO 26 K=1,KP
CALL BGG(
*   BD(7,JB),SEGLP(1,JB),D(1,1,JB),BD(4,JB),SEGLV(1,JB),WMEG(1,JB),
*   B(1,K,J),SEGLP(1,NVEH),D(1,1,NVEH),BFB(1,K,J),SEGLV(1,NVEH),
*   WMEG(1,NVEH),VSCS(J),IFULL(J),TV1(1,K,J),
*   FRA(1,K),TORQ,TQB,VOLP(K,J))
VOLBP(J) = VOLBP(J) + VOLP(K,J)
DO 26 I=1,3
FORCE(I,J) = FORCE(I,J) + FRA(I,K)
26 TORA (I,J) = TORA (I,J) + TORQ(I)
C
C COMPUTE FORCE,TORQUE AND VOLUME OF INTERSECTION
C OF AIRBAG WITH CONTACTING SEGMENT ELLIPSOIDS.
C
KBAG = MNBAG(J)
DO 30 I=1,KBAG
M = MBAG(2,I,J)
MM = MBAG(3,I,J)
CALL BGG(
*   BD(7,JB),SEGLP(1,JB),D(1,1,JB),BD(4,JB),SEGLV(1,JB),WMEG(1,JB),
*   BD(7,MM),SEGLP(1,M),D(1,1,M),BD(4,MM),SEGLV(1,M),WMEG(1,M),
*   VSCS(J),IFULL(J),TV2(1,I,J),FRB(1,I),TORQ,TQB(1,I),VOL(I))
IF (VOL(I).EQ.0.0) GO TO 30
VOLB = VOLB + VOL(I)
DO 28 K=1,3
FORCE(K,J) = FORCE(K,J) + FRB(K,I)

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28 TORA (K,J) = TORA (K,J) + TORQ(K)  
30 CONTINUE  
VOLBP(J) = VOLBP(J) + VOLB  
31 RETURN  
END

AIRBGG  
AIRBGG  
AIRBGG  
AIRBGG  
AIRBGG

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SUBROUTINE AIRBG1                                AIRBG1
C                                                    REV IV 07/24/86SLIP
C READS AND PRINTS THE INPUT CARDS THAT DESCRIBE THE PHYSICAL AIRBG1
C DIMENSIONS AND GAS DYNAMICS OF THE AIRBAG RESTRAINTS AND AIRBG1
C PERFORMS INITIALIZATION REQUIRED BY THE AIRBAG ROUTINE. AIRBG1
C                                                    AIRBG1
IMPLICIT REAL*8 (A-H,O-Z)                        AIRBG1
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND, AIRBG1
* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG PAGE
COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30), AIRBG1
* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30) AIRBG1
COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60), SLIP
* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90), AIRBG1
* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30) AIRBG1
COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20), NCFORC
* PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF AIRBG1
COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5), AIRBG1
* BLTTTL(5,8),PLTTTL(5,30),BAGTTL(5,6),SEG(30), AIRBG1
* JOINT(30),CGS(30),JS(30) AIRBG1
REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTTL,BAGTTL,SEG,JOINT AIRBG1
LOGICAL*1 CGS,JS AIRBG1
COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24), AIRBG1
* UNITL,UNITM,UNITT,GRAVTY(3),TWOPI TWOPI
COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40) EDGE
COMMON/INTEST/ SGTEST(3,4,30),XTEST(3,120),SEGT(120),REGT(120) AIRBG1
REAL SEGT AIRBG1
COMMON/ABDATA/ ZDEP(3,5),DBR(3,3,5),DPVCTR(3,5),DEPLOY(3,5), AIRBG1
* AB(3,5),B(9,4,5),ZR(3,4,5),BFB(3,4,5),DRR(9,4,5), AIRBG1
* VBAGG(5),VSCS(5),SPRK(5),CK(5),CMASS(5),CYMIN(5), AIRBG1
* CYMOUT(5),BAGPV(5),PD(5),VBAG(5),VOLBP(5), AIRBG1
* PCYV(5),PCYMIN(5),PVBAG(5),TV1(3,4,5),TV2(3,10,5), AIRBG1
* SWITCH(5),PYMOUT(5),SCALE(5),PREVT,IFULL(6) AIRBG1
COMMON/CYDATA/ CYTD(5),CYP(5),CYSP(5),CYTO(5),CYVO(5),CYCD(5), AIRBG1
* CYK(5),CYR(5),CYAT(5),CYPV(5),CYCDO(5),CYAO(5), AIRBG1
* CYPO(5),CYSS(5),CYLO(5),CYC(5),CYRHO0(5),CYVMAX(5),AIRBG1
* CYORFC(5),CYRHO(5),CYT(5),CYP(5),CYV(5) AIRBG1
COMMON/TEMPVS/ TMP(9),TMP1(3) AIRBG1
DIMENSION YB(3),YP(3),IDYPR(3) AIRBG1
REAL BAG(6) AIRBG1
DATA BAG/4HBAG1,4HBAG2,4HBAG3,4HBAG4,4HBAG5,4HBAG / AIRBG1
DATA IDYPR/3,2,1/ AIRBG1
DATA MAXNPL/4/,MAXSEG/30/ CHGIII
C MAKE ROOM FOR BAG DATA IN SEGMENT ARRAYS BETWEEN VEH AND GRND. AIRBG1
C AIRBG1
C MSEG = 0 CHGIII
IF (NVEH.GT.NSEG) MSEG = NVEH - NSEG CHGIII
L = NSEG + NBAG + MSEG + 1 CHGIII
K = NSEG + MSEG + 1 CHGIII
W(L) = W(K) AIRBG1

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	RW(L) = RW(K)	AIRBG1
	SEG(L) = SEG(K)	AIRBG1
	ISING(L) = ISING(K)	AIRBG1
	IF (L-1.GT.NJNT) JNT (L-1) = 0	AIRBG1
	IF (L-1.GT.NJNT) IPIN(L-1) = 0	AIRBG1
	DO 19 I=1,3	AIRBG1
	SEGLP(I,L) = SEGLP(I,K)	AIRBG1
	SEGLV(I,L) = SEGLV(I,K)	AIRBG1
	SEGLA(I,L) = SEGLA(I,K)	AIRBG1
	WMEG (I,L) = WMEG (I,K)	AIRBG1
	WMEGD(I,L) = WMEGD(I,K)	AIRBG1
	PHI (I,L) = PHI (I,K)	AIRBG1
	RPHI (I,L) = RPHI (I,K)	AIRBG1
	DO 18 J=1,3	AIRBG1
	D(I,J,L) = D(I,J,K)	AIRBG1
18	SGTEST(I,J,L) = SGTEST(I,J,K)	AIRBG1
19	SGTEST(I,4,L) = SGTEST(I,4,K)	AIRBG1
	NGRND = NSEG + NBAG + MSEG + 1	CHGIII
	IF (NGRND.GT.MAXSEG) STOP 75	CHGIII
	DO 40 J=1,NBAG	AIRBG1
	JB = NVEH + J	AIRBG1
C		AIRBG1
C	READ AND PRINT CARDS D.4.A -D.4.F FOR THE JTH AIRBAG.	AIRBG1
C		AIRBG1
	READ(5,13) (BAGTTL(I,J),I = 1,5),NPANEL(J),	AIRBG1
	* (AB(I,J),I=1,3) , (BD(I,JB),I=4,6) ,	AIRBG1
	* YB,(ZDEP(I,J),I=1,3) ,	AIRBG1
	* W(JB),CYTD(J),CYP A(J),CYSP(J),CYTO(J),CYVO(J),	AIRBG1
	* CYCD(J),CYK(J),CYR(J),CYAT(J),CYPV(J),CYCDO(J),	AIRBG1
	* CYAO(J),SPRK(J),VSCS(J),CK(J),CMASS(J)	AIRBG1
13	FORMAT (5A4,I4/(6F12.0))	AIRBG1
	IF (NPANEL(J).GT.MAXNPL) STOP 76	CHGIII
	IF (MOD(J,2).EQ.1) WRITE(6,15) NPG	PAGE
	IF (MOD(J,2).EQ.1) NPG=NPG+1	PAGE
15	FORMAT('1',122X,'PAGE',I5/' AIRBAG INPUTS',105X,'CARDS D.4')	PAGE
	WRITE(6,14) J,(BAGTTL(I,J),I = 1,5) ,	AIRBG1
	* (AB(I,J),I=1,3) , (BD(I,JB),I=4,6) ,	AIRBG1
	* YB,(ZDEP(I,J),I=1,3) ,	AIRBG1
	* W(JB),CYTD(J),CYP A(J),CYSP(J),CYTO(J),CYVO(J),	AIRBG1
	* CYCD(J),CYK(J),CYR(J),CYAT(J),CYPV(J),CYCDO(J),	AIRBG1
	* CYAO(J),SPRK(J),VSCS(J),CK(J),CMASS(J)	AIRBG1
14	FORMAT('0 AIRBAG NO.',I4,4X,5A4//	AIRBG1
	* 29X,'AIR BAG SEMIAXES',46X,'C.G. OFFSET'/6X,6G20.9//	AIRBG1
	* 15X,'YAW',16X,'PITCH',15X,'ROLL',30X,'DEPLOYMENT POINT'	AIRBG1
	* /6X,6G20.9//	AIRBG1
	* 15X,'XBM',16X,'CYTD',16X,'CYP A',16X,'CYSP',16X,'CYTO',16X,'CYVO'	AIRBG1
	* /6X,6G20.9//	AIRBG1
	* 14X,'CYCD',17X,'CYK',17X,'CYR',16X,'CYAT',16X,'CYPV',16X,'CYCDO'	AIRBG1
	* /6X,6G20.9//	AIRBG1
	* 14X,'CYAO',16X,'SPRK',16X,'VSCS',17X,'CK',17X,'CMASS'/6X,5G20.9)	AIRBG1

	KP = NPANEL(J)	AIRBG1
	DO 25 K=1,KP	AIRBG1
C		AIRBG1
C	READ AND PRINT CARDS D.4.G AND D.4.H FOR THE KTH PANEL TO	AIRBG1
C	CONTACT THE JTH AIRBAG. THESE PANELS ARE APPROXIMATED BY	AIRBG1
C	ELLIPSOIDS. THE FIRST PANEL (K=1) IS THE REACTION PANEL THAT	AIRBG1
C	INCLUDES THE DEPLOYMENT POINT.	AIRBG1
C		AIRBG1
	READ(5,11) (B(I,K,J),I=1,3),(BFB(I,K,J),I=1,3),	AIRBG1
	* (ZR(I,K,J),I=1,3),YP	AIRBG1
	11 FORMAT(6F12.0)	AIRBG1
	WRITE(6,12) K,(B(I,K,J),I=1,3),(BFB(I,K,J),I=1,3),	AIRBG1
	* (ZR(I,K,J),I=1,3),YP	AIRBG1
	12 FORMAT('0 PANEL NO.',I4//	AIRBG1
	* 24X,'PANEL ELLIPSOID SEMIAXES',43X,'C.G. OFFSET'/6X,6G20.9//	AIRBG1
	* 29X,'PANEL LOCATION',32X,'YAW',16X,'PITCH',15X,'ROLL'/6X,6G20.9)	AIRBG1
C		AIRBG1
C	CONVERT B FROM ELLIPSOID SEMIAXES TO MATRIX	AIRBG1
C		AIRBG1
	DO 21 I=1,3	AIRBG1
	21 TMP(I) = B(I,K,J)	AIRBG1
	DO 22 I=1,9	AIRBG1
	22 B(I,K,J) = 0.0	AIRBG1
	DO 23 I=1,3	AIRBG1
	23 B(4*I-3,K,J) = 1.0/TMP(I)**2	AIRBG1
	CALL DRCYPR (DRR(1,K,J),YP,IDYPR)	AIRBG1
	CALL MAT33 (B(1,K,J),DRR(1,K,J),TMP)	AIRBG1
	CALL DOT33 (DRR(1,K,J),TMP,B(1,K,J))	AIRBG1
	CALL DOT31 (DRR(1,K,J),BFB(1,K,J),TMP)	AIRBG1
	DO 24 I=1,3	AIRBG1
	24 BFB(I,K,J) = TMP(I) + ZR(I,K,J)	AIRBG1
	25 CONTINUE	AIRBG1
C		AIRBG1
C	COMPUTE GEOMETRY OF DEPLOYMENT POINT ON FIRST PANEL.	AIRBG1
C		AIRBG1
	CALL DRCYPR (DBR(1,1,J),YB,IDYPR)	AIRBG1
	CALL DOT31 (DRR(1,1,J),ZDEP(1,J),DEPLOY(1,J))	AIRBG1
	DO 31 I=1,3	AIRBG1
	DPVCTR(I,J) = -DBR(1,I,J)	AIRBG1
	31 DEPLOY(I,J) = DEPLOY(I,J) + BFB(I,1,J)	AIRBG1
	CALL PANEL (DBR(1,1,J),DEPLOY(1,J),JB)	AIRBG1
C		AIRBG1
C	INITIALIZATION OF AIRBAG GEOMETRY.	AIRBG1
C		AIRBG1
	VBAGG(J) = 4.0/3.0*PI*AB(1,J)*AB(2,J)*AB(3,J)	AIRBG1
	PHI(1,JB) = (AB(2,J)**2+AB(3,J)**2)/5.0	AIRBG1
	PHI(2,JB) = (AB(3,J)**2+AB(1,J)**2)/5.0	AIRBG1
	PHI(3,JB) = (AB(1,J)**2+AB(2,J)**2)/5.0	AIRBG1
	JNT(JB-1) = 0	AIRBG1
	IPIN(JB-1) = 0	AIRBG1

	SEG(JB) = BAG(J)	AIRBG1
	IF (NBAG.EQ.1) SEG(JB) = BAG(6)	AIRBG1
	ISING(JB) = -1	AIRBG1
	RW(JB) = G/W(JB)	AIRBG1
	DO 36 I=1,3	AIRBG1
	BD(I,JB) = 0.0	AIRBG1
	RPHI(I,JB) = 1.0/PHI(I,JB)	AIRBG1
	DO 36 K=1,4	AIRBG1
36	SGTEST(I,K,JB) = 0.0	AIRBG1
	DO 35 I=7,24	AIRBG1
35	BD(I,JB) = 0.0	AIRBG1
	IFULL(J) = 0	AIRBG1
	CYMOUT(J) = 0.0	AIRBG1
	PYMOUT(J) = 0.0	AIRBG1
	DO 38 I=1,3	AIRBG1
	DO 37 K=1,4	AIRBG1
37	TV1(I,K,J) = 0.0	AIRBG1
	DO 38 K=1,10	AIRBG1
38	TV2(I,K,J) = 0.0	AIRBG1
C		AIRBG1
C	AIR CYLINDER INITIALIZATION	AIRBG1
C		AIRBG1
	CYPO(J) = CYSP(J)+CYPA(J)	AIRBG1
	CYSS(J) = DSQRT(CYK(J)*CYR(J)*CYTO(J)*G)	AIRBG1
	CYLO(J) = CYVO(J)/CYAT(J)	AIRBG1
	CYK1 = CYK(J)-1.0	AIRBG1
	CYK2 = 0.5*(CYK(J)+1.0)	AIRBG1
	CYK3 = CYK2**(-CYK2/CYK1)	AIRBG1
	CYC(J) = 0.5*CYK1*CYSS(J)*CYCD(J)/CYLO(J)*CYK3	AIRBG1
	CYRH00(J) = CYP0(J)/(CYR(J)*CYTO(J))	AIRBG1
	CYVMAX(J) = CYVO(J)/CYK(J)*CYP0(J)/CYPA(J)	AIRBG1
	CYORFC(J) = CYCDO(J)*CYAO(J)*G*DSQRT(2.0*CYPA(J)*CYK(J))/CYSS(J)	AIRBG1
	IF (NPRT(22).NE.0) WRITE(6,39)	AIRBG1
	* (SEGLP(I,JB), I=1,3), (SEGLV(I,JB), I=1,3), (WMEG(I,JB), I=1,3),	AIRBG1
	* VBAGG(J), CYP0(J), CYSS(J), CYC(J), CYRH00(J), CYVMAX(J), CYORFC(J)	AIRBG1
39	FORMAT('0 AIRBAG SINPUT'/(1X,9G14.6))	AIRBG1
40	CONTINUE	AIRBG1
	PREVT = 0.0	AIRBG1
	RETURN	AIRBG1
	END	AIRBG1

C  
C  
C  
C  
C  
C

SUBROUTINE AIRBG3(IRESET)

REV IV 07/23/86TWOPI

AIRBG3

AIRBG3

THIS SUBROUTINE IS CALLED BY SUBROUTINE UPDATE AT START (IRESET=1) AND END (IRESET=2) OF EACH INTEGRATION STEP TO DETERMINE IF EACH AIRBAG HAS BEEN FULLY INFLATED.

AIRBG3

AIRBG3

AIRBG3

AIRBG3

AIRBG3

IMPLICIT REAL\*8 (A-H,O-Z)

AIRBG3

COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,

AIRBG3

\* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG

PAGE

COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),

AIRBG3

\* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)

AIRBG3

COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6),

AIRBG3

\* MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6),

AIRBG3

\* NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30)

AIRBG3

COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),

NCFORC

\* PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF

AIRBG3

COMMON/CNTRSRF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)

EDGE

COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),

AIRBG3

\* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI

TWOPI

COMMON/ABDATA/ ZDEP(3,5),DBR(3,3,5),DPVCTR(3,5),DEPLOY(3,5),

AIRBG3

\* AB(3,5),B(9,4,5),ZR(3,4,5),BFB(3,4,5),DRR(9,4,5),

AIRBG3

\* VBAGG(5),VSCS(5),SPRK(5),CK(5),CMASS(5),CYMIN(5),

AIRBG3

\* CYMOUT(5),BAGPV(5),PD(5),VBAG(5),VOLBP(5),

AIRBG3

\* PCYV(5),PCYMIN(5),PVBAG(5),TV1(3,4,5),TV2(3,10,5),

AIRBG3

\* SWITCH(5),PYMOUT(5),SCALE(5),PREVT,IFULL(6)

AIRBG3

COMMON/CYDATA/ CYTD(5),CYPA(5),CYSP(5),CYTO(5),CYVO(5),CYCD(5),

AIRBG3

\* CYK(5),CYR(5),CYAT(5),CYPV(5),CYCDO(5),CYAO(5),

AIRBG3

\* CYPO(5),CYSS(5),CYLO(5),CYC(5),CYRHO(5),CYVMAX(5),

AIRBG3

\* CYORFC(5),CYRHO(5),CYT(5),CYP(5),CYV(5)

AIRBG3

COMMON/TEMPVS/ TMP(9),TMP1(3)

AIRBG3

CALL ELTIME(1,29)

AIRBG3

JRESET = IRESET

AIRBG3

IF (JRESET.EQ.1) PREVT = TIME

AIRBG3

NBGSF = 0

AIRBG3

DO 50 J=1,NBAG

AIRBG3

IF (MNBAG(J).EQ.0) GO TO 50

AIRBG3

JB = NVEH + J

AIRBG3

JFULL = IFULL(J) + 2

AIRBG3

IF (JFULL.LT.1 .OR. JFULL.GT.3) GO TO 11

AIRBG3

IF (JRESET-1) 13,13,14

BUTLER1

11 WRITE(6,12) TIME

AIRBG3

12 FORMAT ('0 ERROR IN SUBROUTINE AIRBG3 AT TIME =',F10.6)

AIRBG3

STOP 32

AIRBG3

13 IF (JFULL-2) 41,49,49

BUTLER1

14 IF (JFULL-2) 11,21,31

BUTLER1

C  
C  
C

END OF INTEGRATION STEP WHEN IFULL=0. TEST FOR FULL INFLATION.

AIRBG3

AIRBG3

21 PD(J) = 0.0

AIRBG3

	PCYV(J) = CYV(J)	AIRBG3
	PCYMIN(J) = CYMIN(J)	AIRBG3
	PVBAG(J) = VBAG(J)	AIRBG3
22	CALL AIRBGG(J)	AIRBG3
	VBAG(J) = CYV(J) + VOLBP(J)	AIRBG3
	IF (SCALE(J).EQ.1.0) GO TO 23	AIRBG3
	SCALE(J) = (VBAG(J)/VBAGG(J))**THIRD	AIRBG3
	IF (SCALE(J).LT.1.0) GO TO 24	AIRBG3
	SCALE(J) = 1.0	AIRBG3
	GO TO 22	AIRBG3
23	IFULL(J) = -1	AIRBG3
	CYMOUT(J) = 0.0	AIRBG3
	PSW1 = (VBAG(J)-VBAGG(J))*PCYV(J)/PCYMIN(J)	AIRBG3
	PSW2 = (VBAGG(J)-PVBAG(J))*CYV(J)/CYMIN(J)	AIRBG3
	SWITCH(J) = (PSW1+PSW2)/(VBAG(J)-PVBAG(J))	AIRBG3
	BAGPV(J) = CYP(A(J))*(CYMIN(J)*SWITCH(J))**CYK(J)	AIRBG3
	PD(J) = BAGPV(J)/(CYV(J)**CYK(J)) - CYP(A(J))	AIRBG3
24	DO 25 K=1,3	AIRBG3
	BD(K,JB) = SCALE(J)*AB(K,J)	AIRBG3
	IF (SCALE(J).EQ.0.0) GO TO 25	AIRBG3
	BD(4*K+12,JB) = BD(K,JB)**2	AIRBG3
	BD(4*K+ 3,JB) = 1.0/BD(4*K+12,JB)	AIRBG3
25	TMP(K) = DEPLOY(K,J) + BD(1,JB)*DPVCTR(K,J)	AIRBG3
	CALL PANEL (DBR(1,1,J),TMP,JB)	AIRBG3
C		AIRBG3
C	SET UP BAGSF ARRAY FOR OUTPUT.	AIRBG3
C		AIRBG3
31	BAGSF(1,NBGSF+1) = CYP(J)	AIRBG3
	BAGSF(2,NBGSF+1) = CYT(J)	AIRBG3
	BAGSF(3,NBGSF+1) = PD(J)	AIRBG3
	CALL DOT31 (D(1,1,JB),BD(4,JB),TMP)	AIRBG3
	DO 32 K=1,3	AIRBG3
	BAGSF(K,NBGSF+3) = BD(K,JB)	AIRBG3
32	TMP(K) = TMP(K) + SEGLP(K,JB) - SEGLP(K,NVEH)	AIRBG3
	CALL MAT31 (D(1,1,NVEH),TMP,BAGSF(1,NBGSF+2))	AIRBG3
	CALL YPRDEG (D(1,1,JB),BAGSF(1,NBGSF+4))	AIRBG3
	NBGSF = NBGSF + 5 + NPANEL(J) + MNBAG(J)	AIRBG3
	GO TO 50	AIRBG3
C		AIRBG3
C	START OF INTEGRATION STEP WITH IFULL = -1, RESET INTEGRATOR.	AIRBG3
C		AIRBG3
41	IFULL(J) = 1	AIRBG3
	IRESET = -1	AIRBG3
49	PYMOUT(J) = CYMOUT(J)	AIRBG3
50	CONTINUE	AIRBG3
	CALL ELTIME(2,29)	AIRBG3
	RETURN	AIRBG3
	END	AIRBG3

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SUBROUTINE BELTG (ZA,ZB,ZC,BD)                                BELTG
C                                                            REV IV 07/23/86TWOPI
C COMPUTE TANGENT POINTS, UNIT VECTORS FROM TANGENT POINTS TO BELTG
C ANCHOR POINTS AND LENGTHS OF THE BELT SEGMENTS.          BELTG
C                                                            BELTG
C ARGUMENTS:                                                BELTG
C                                                            BELTG
C    ZA,ZB - ANCHOR POINTS RELATIVE TO ELLIPSOID CENTER.    BELTG
C    ZC    - FIXED POINT OF BELT ON SEGMENT ELLIPSOID.      BELTG
C    BD    - SEGMENT ELLIPSOID SEMIAXES AND CENTER.        BELTG
C                                                            BELTG
C RESULTS ARE RETURNED TO CALLING ROUTINE VIA COMMON/TEMPVS/. BELTG
C                                                            BELTG
C IMPLICIT REAL*8 (A-H,O-Z)                                  BELTG
C DIMENSION ZA(3),ZB(3),ZC(3),BD(24)                        BELTG
C COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND.    BELTG
C * NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG         PAGE
C COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),                BELTG
C * UNITL,UNITM,UNITT,GRAVTY(3),TWOPI                      TWOPI
C NOTE: BELTRT AND BELTG SHARE FIRST PART OF TEMPVS        BELTG
C COMMON/TEMPVS/ APA(3),UVA(3),DLGA,UAA,APB(3),UVB(3),DLGB,UBB BELTG
C * ,TA(3),TB(3),TC(3),UP(3),B(3)                          BELTG
C * ,UC(3),AX(3),XE(3),BX(3),ACA(3),ACB(3)                 BELTG
C                                                            BELTG
C COMPUTE                                                    BELTG
C    TC: NORMALIZED VECTOR OF BELT PLANE DETERMINED        BELTG
C    BY ANCHOR POINTS AND FIXED POINT.                     BELTG
C                                                            BELTG
C    DO 10 K=1,3                                            BELTG
C    TA(K) = ZC(K)-ZA(K)                                     BELTG
C 10 TB(K) = ZC(K)-ZB(K)                                     BELTG
C    CALL CROSS(TB,TA,TC)                                    BELTG
C    S = DSQRT(TC(1)**2 + TC(2)**2 + TC(3)**2)              BELTG
C    TC(1) = TC(1)/S                                        BELTG
C    TC(2) = TC(2)/S                                        BELTG
C    TC(3) = TC(3)/S                                        BELTG
C                                                            BELTG
C GET DISTANCE OF BELT PLANE TO CENTER OF ELLIPSIOD.      BELTG
C                                                            BELTG
C    BET = TC(1)*ZC(1)+TC(2)*ZC(2)+TC(3)*ZC(3)            BELTG
C                                                            BELTG
C COMPUTE                                                    BELTG
C    XE: CENTER OF ELLIPSE DETERMINED BY INTERSECTION      BELTG
C    OF BELT PLANE AND SEGMENT ELLIPSOID.                 BELTG
C                                                            BELTG
C CALL MAT31 (BD(16),TC,XE)                                  BELTG
C GG = BET/(TC(1)*XE(1)+TC(2)*XE(2)+TC(3)*XE(3))          BELTG
C DLGA = 0.0                                                 BELTG
C DLGB = 0.0                                                 BELTG
C DO 15 K=1,3                                               BELTG

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	B(2) = B(2) + UC(1)*BD(K)*UP(J)	BELTG
22	B(3) = B(3) + UP(1)*BD(K)*UP(J)	BELTG
	B(1) = B(1)/YAY1	BELTG
	B(2) = B(2)/YAY1	BELTG
	B(3) = B(3)/YAY1	BELTG
C		BELTG
C	COMPUTE ANGLES FROM FIXED POINT TO POSSIBLE TANGENT POINTS.	BELTG
C		BELTG
	UCUVA = UC(1)*UVA(1) + UC(2)*UVA(2) + UC(3)*UVA(3)	BELTG
	UCUVB = UC(1)*UVB(1) + UC(2)*UVB(2) + UC(3)*UVB(3)	BELTG
	UCACA = UC(1)*ACA(1) + UC(2)*ACA(2) + UC(3)*ACA(3)	BELTG
	UCACB = UC(1)*ACB(1) + UC(2)*ACB(2) + UC(3)*ACB(3)	BELTG
	UPUVA = UP(1)*UVA(1) + UP(2)*UVA(2) + UP(3)*UVA(3)	BELTG
	UPUVB = UP(1)*UVB(1) + UP(2)*UVB(2) + UP(3)*UVB(3)	BELTG
	UPACA = UP(1)*ACA(1) + UP(2)*ACA(2) + UP(3)*ACA(3)	BELTG
	UPACB = UP(1)*ACB(1) + UP(2)*ACB(2) + UP(3)*ACB(3)	BELTG
	TH1 = DATAN2(UPUVA-UPACA,UCUVA-UCACA)	BELTG
	TH2 = DATAN2(UPUVA+UPACA,UCUVA+UCACA)	BELTG
	TH3 = DATAN2(UPUVB-UPACB,UCUVB-UCACB)	BELTG
	TH4 = DATAN2(UPUVB+UPACB,UCUVB+UCACB)	BELTG
	IF (TH1.LT.0.0) TH1 = TWOPI + TH1	BELTG
	IF (TH2.LT.0.0) TH2 = TWOPI + TH2	BELTG
	IF (TH3.LT.0.0) TH3 = TWOPI + TH3	BELTG
	IF (TH4.LT.0.0) TH4 = TWOPI + TH4	BELTG
C		BELTG
C	CHOOSE PROPER TANGENT POINTS AND BELT ARC LENGTHS.	BELTG
C		BELTG
	THMIN = DMIN1(TH1,TH2,TH3,TH4)	BELTG
	IF (THMIN.EQ.TH1.AND.DMIN1(TH2,TH3,TH4).NE.TH4) GO TO 61	BELTG
	IF (THMIN.EQ.TH2.AND.DMAX1(TH1,TH3,TH4).EQ.TH4) GO TO 61	BELTG
	IF (THMIN.EQ.TH3.AND.DMIN1(TH1,TH2,TH4).NE.TH2) GO TO 63	BELTG
	IF (THMIN.EQ.TH4.AND.DMAX1(TH1,TH2,TH3).EQ.TH2) GO TO 63	BELTG
	GO TO 70	BELTG
61	THA = TH1	BELTG
	THB = TWOPI-TH4	BELTG
	DO 62 K=1,3	BELTG
	APA(K) = UVA(K)-ACA(K)	BELTG
62	APB(K) = UVB(K)+ACB(K)	BELTG
	GO TO 65	BELTG
63	THA = TWOPI-TH2	BELTG
	THB = TH3	BELTG
	DO 64 K=1,3	BELTG
	APA(K) = UVA(K)+ACA(K)	BELTG
64	APB(K) = UVB(K)-ACB(K)	BELTG
65	CONTINUE	BELTG
	EPS1 = EPS(1)	BELTG
	DLGA = DABS(ELONG(B(1),B(2),B(3),EPS1,THA))	BELTG
	DLGB = DABS(ELONG(B(1),B(2),B(3),EPS1,THB))	BELTG
C		BELTG
C	CALCULATE BELT LENGTHS AND UNIT VECTORS	BELTG



C	FROM TANGENT POINTS TO ANCHOR POINTS.	BELTG
C		BELTG
70	UAA=0.	BELTG
	UBB=0.	BELTG
	DO 80 K=1,3	BELTG
	APA(K) = APA(K)+XE(K)	BELTG
	APB(K) = APB(K)+XE(K)	BELTG
	UVA(K)=ZA(K)-APA(K)	BELTG
	UVB(K)=ZB(K)-APB(K)	BELTG
	APA(K)=APA(K)+BD(K+3)	BELTG
	APB(K)=APB(K)+BD(K+3)	BELTG
	UAA=UAA+UVA(K)**2	BELTG
	UBB=UBB+UVB(K)**2	BELTG
80	CONTINUE	BELTG
	UAA=DSQRT(UAA)	BELTG
	UBB=DSQRT(UBB)	BELTG
	DO 90 K=1,3	BELTG
	UVA(K)=UVA(K)/UAA	BELTG
	UVB(K)=UVB(K)/UBB	BELTG
90	CONTINUE	BELTG
C		BELTG
C	OPTIONAL OUTPUT	BELTG
C		BELTG
	IF (NPRT(15).EQ.0) GO TO 99	BELTG
	WRITE(6,50)	BELTG
50	FORMAT(1X,'BELT RESTRAINT')	BELTG
	WRITE(6,60) APA,UVA,DLGA,UAA	BELTG
	WRITE(6,60) APB,UVB,DLGB,UBB	BELTG
60	FORMAT(1X,1P8D15.5)	BELTG
99	CONTINUE	BELTG
	RETURN	BELTG
	END	BELTG

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SUBROUTINE BELTRT(I,II,MM,M,NT)                                BELTRT
C                                                                    REV IV   07/23/86TWOPI
C THE ROUTINE CALLS SUBROUTINE BELTG TO COMPUTE THE TANGENT POINTS BELTRT
C AND BELT LENGTHS AND APPLIES THE RESTRAINT FORCES TO THE U1 ARRAY BELTRT
C AND BELT TORQUES TO THE U2 ARRAY FOR ELLIPSOID(II) ATTACHED TO BELTRT
C BODY SEGMENT (I) BY BELT (M) ATTACHED TO SEGMENT (MM).      BELTRT
C                                                                    BELTRT
C IMPLICIT REAL*8(A-H,O-Z)                                    BELTRT
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,      BELTRT
* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG          PAGE
COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),BELTRT
* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)            BELTRT
COMMON/CNTRSRF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)   EDGE
COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)DIMENB
COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),  NCFORC
* PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF             BELTRT
COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),                BELTRT
* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI                    TWOPI
COMMON/RSAVE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30),          TGMOD4
* NSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9)            TTHKREF
C NOTE: BELTRT AND BELTG SHARE FIRST PART OF TEMPVS        BELTRT
COMMON/TEMPVS/ APA(3),UVA(3),DLGA,UAA,APB(3),UVB(3),DLGB,UBB BELTRT
DIMENSION TA(3),TB(3),ZA(3),ZB(3),TT(3),TTT(3),TA1(3),TB1(3) TGMOD4
C                                                                    BELTRT
CALL ELTIME(1,22)                                           BELTRT
C                                                                    BELTRT
C CONVERT SEGMENT POSITION TO SEGMENT REFERENCE.            BELTRT
C                                                                    BELTRT
MA = MOD(MM,100)                                           JTF984
MB = MM/100                                               JTF984
IF (MB.EQ.0) MB=MA                                       JTF984
CALL DOT31 (D(1,1,MA),BELT(1,M),TA)                     BELTRT
CALL DOT31 (D(1,1,MB),BELT(4,M),TB)                     BELTRT
DO 10 K=1,3                                               BELTRT
TA(K) = SEGLP(K,MA) + TA(K) - SEGLP(K,I)                BELTRT
10 TB(K) = SEGLP(K,MB) + TB(K) - SEGLP(K,I)             BELTRT
CALL MAT31 (D(1,1,I),TA,ZA)                              BELTRT
CALL MAT31 (D(1,1,I),TB,ZB)                              BELTRT
DO 13 K=1,3                                               BELTRT
ZA(K) = ZA(K) - BD(K+3,II)                               BELTRT
13 ZB(K) = ZB(K) - BD(K+3,II)                             BELTRT
C                                                                    BELTRT
C COMPUTE NEW BELT LENGTHS AND EXPANSION.                BELTRT
C                                                                    BELTRT
CALL BELTG (ZA, ZB, BELT(7,M), BD(1,II))                BELTRT
TLA = DLGA+UAA                                           BELTRT
TLB = DLGB+UBB                                           BELTRT
TL = TLA+TLB                                             BELTRT
IF (TIME.NE.0.0) GO TO 11                                BELTRT
C                                                                    BELTRT

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C      IF TIME=0, COMPUTE INITIAL BELT LENGTHS
C      AND STORE RESULTS IN BELT ARRAY.
C
      IF (BELT(11,M).LT.0.0) BELT(11,M) = -BELT(11,M)-TL
      IF (BELT(11,M).LT.0.0) BELT(11,M) = 0.0
      BELT(12,M) = TLA+TLA/TL*BELT(11,M)
      BELT(13,M) = TLB+TLB/TL*BELT(11,M)
      B1213 = BELT(12,M) + BELT(13,M)
      BELT(10,M) = B1213
      DO 305 LL=1,3
      TA1(LL) = APA(LL)
305   TB1(LL) = APB(LL)
      IF(LPMI(I).EQ.0) GO TO 306
      CALL DOT31(DPMI(1,1,I),APA,TA1)
      CALL DOT31(DPMI(1,1,I),APB,TB1)
306   CONTINUE
      WRITE (6,14) M, B1213, BELT(12,M), BELT(13,M), UNITL,I,TA1, TB1
14   FORMAT('0 INITIAL LENGTHS OF BELT NO.',I3,' AND ITS SEGMENTS ARE',
*          '3F12.4,1X,A4/'0 INITIAL TANGENT POINTS IN LOCAL REFERENCE
*OF SEGMENT ',I2,' ARE:',/,2(3X,3F12.3))
C
C      CONVERT TANGENT POINTS TO INERTIAL REFERENCE AND STORE.
C
11   CALL DOT31 (D(1,1,I),APA,TPTS(1,M))
      CALL DOT31 (D(1,1,I),APB,TPTS(4,M))
      DO 12 K=1,3
      TPTS(K ,M) = TPTS(K ,M) + SEGLP(K,I)
12   TPTS(K+3,M) = TPTS(K+3,M) + SEGLP(K,I)
      SDOT = 0.0
      NCF = NTAB(NT+5)
      IF (NCF.NE.0) GO TO 15
C
C      ZERO BELT FRICTION, COMPUTE STRAIN AND FORCE OF ENTIRE BELT.
C
      B1213 = BELT(12,M)+BELT(13,M)
      S = (TL-B1213)/B1213
      SA = S
      SB = S
      IF (S.LT.0.0) S = 0.0
      CALL FRCDL (S,SDOT,NT,1,FA,ELOSS)
      FB = FA
      GO TO 17
C
C      FULL BELT FRICTION, COMPUTE STRAIN AND FORCE OF EACH PART OF BELT.
C
15   IF (TL.GT.BELT(10,M)) GO TO 16
      FA = 0.0
      FB = 0.0
      SA = (TL-BELT(10,M))/BELT(10,M)
      SB = SA

```

BELT(12,M) = TLA	BELTRT
BELT(13,M) = TLB	BELTRT
GO TO 17	BELTRT
16 S = (TLA-BELT(12,M))/BELT(12,M)	BELTRT
SA = S	BELTRT
IF (S.LT.0.0) S = 0.0	BELTRT
CALL FRCDL(S,SDOT,NT,1,FA,ELOSS)	BELTRT
S = (TLB-BELT(13,M))/BELT(13,M)	BELTRT
SB = S	BELTRT
IF (S.LT.0.0) S = 0.0	BELTRT
CALL FRCDL(S,SDOT,NT+6,1,FB,ELOSS)	BELTRT
BELT(10,M) = 0.0	BELTRT
17 BSF(1,NBSF) = SA	BELTRT
BSF(2,NBSF) = FA	BELTRT
BSF(3,NBSF) = SB	BELTRT
BSF(4,NBSF) = FB	BELTRT
IF (FA+FB.LE.0.0) GO TO 31	BELTRT
C	BELTRT
C COMPUTE FORCE VECTORS.	BELTRT
C	BELTRT
DO 20 K=1,3	BELTRT
UVA(K) = FA*UVA(K)	BELTRT
20 UVB(K) = FB*UVB(K)	BELTRT
C	BELTRT
C CONVERT FORCES TO INERTIAL REFERENCE AND ADD TO U1 ARRAY.	BELTRT
C	BELTRT
CALL DOT31(D(1,1,I),UVA,TT)	BELTRT
CALL DOT31(D(1,1,I),UVB,TTT)	BELTRT
DO 30 K=1,3	BELTRT
U1(K,MA) = U1(K,MA) - TT(K)	JTF984
U1(K,MB) = U1(K,MB) - TTT(K)	JTF984
30 U1(K,I) = U1(K,I)+TTT(K) + TT(K)	JTF984
C	BELTRT
C CONVERT TORQUES TO LOCAL REFERENCE AND ADD TO U2 ARRAY.	BELTRT
C	BELTRT
CALL MAT31(D(1,1,MA),TT,ZA)	JTF984
CALL MAT31(D(1,1,MB),TTT,ZB)	JTF984
CALL CROSS(BELT(1,M),ZA,TA)	JTF984
CALL CROSS(BELT(4,M),ZB,TB)	JTF984
CALL CROSS(APA,UVA,TT)	BELTRT
CALL CROSS(APB,UVB,TTT)	BELTRT
DO 40 K=1,3	BELTRT
U2(K,MA) = U2(K,MA) - TA(K)	JTF984
U2(K,MB) = U2(K,MB) - TB(K)	JTF984
40 U2(K,I) = U2(K,I)+(TT(K)+TTT(K))	BELTRT
31 CONTINUE	BELTRT
CALL ELTIME(2,22)	BELTRT
RETURN	BELTRT
END	BELTRT

```

SUBROUTINE BGG(A,ZA,DA,BFA,VA,WA,          BGG
*      B,ZB,DB,BFB,VB,WB,                BGG
*      VSCS,IFULL,TV,FRA,TORQ,TQB,VOL)    BGG
C
C                                     REV IV 07/23/86TWOPI
C
C COMPUTES THE VOLUME OF INTERSECTION OF AN ELLIPSOIDAL AIRBAG BGG
C WITH AN ELLIPSOIDAL BODY SEGMENT OR REACTION PANEL. BGG
C ALSO COMPUTES THE FORCE PER UNIT PRESSURE AND TORQUE PER UNIT BGG
C PRESSURE ON BOTH THE BAG AND THE INTERSECTING OBJECT. BGG
C
C ARGUMENTS: BGG
C AIRBAG INPUTS : A(3,3) - ELLIPSOID MATRIX BGG
C                  ZA(3) - C.G. BGG
C                  DA(3,3) - DIRECTION COSINE MATRIX BGG
C                  BFA(3) - OFFSET BGG
C                  VA(3) - CG VELOCITY(INERTIAL REF.) BGG
C                  WA(3) - ANGULAR VELOCITY (LOCAL REF.) BGG
C
C CONTACT SURFACE B(3,3) - ELLIPSOID MATRIX BGG
C                  ZB(3) - C.G. BGG
C                  DB(3,3) - DIRECTION COSINE MATRIX BGG
C                  BFB(3) - OFFSET BGG
C                  VB(3) - CG VELOCITY (INERTIAL REF.) BGG
C                  WB(3) - ANGULAR VELOCITY (LOCAL REF.) BGG
C                  VSCS - COEFFICIENT OF SLIDING FRICTION BGG
C                  IFULL - IF ZERO, COMPUTE VOL ONLY. BGG
C                  TV(3) - MEMORY FOR SUBROUTINES INTERS & EDEPTH. BGG
C
C OUTPUT : FRA(3) - FORCE ON BAG BGG
C           TORQ(3) - TORQUE ON BAG BGG
C           TOB(3) - TORQUE ON CONTACT SURFACE BGG
C           VOL - VOLUME OF INTERSECTION BGG
C
C IMPLICIT REAL*8 (A-H,O-Z) BGG
C DIMENSION A(3,3),ZA(3),DA(3,3),BFA(3),VA(3),WA(3),B(3,3),ZB(3), BGG
*          DB(3,3),BFB(3),VB(3),WB(3),FRA(3),TORQ(3),TQB(3),TV(3) BGG
C COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24), BGG
*          UNITL,UNITM,UNITT,GRAVITY(3),TWOPI TWOPI
C COMMON/TEMPVS/ DUMMY(200),DAB(3,3),BA(3,4),TEMP(3,3),Y(3),CPA(3), BGG
*          CPB(3),PLANE(4,3),FORCE(3),CBB(3),VLM(3),FRB(3), BGG
*          YFA(3),YFB(3),ZBB(3),T1(3),T2(3),T3(3),T4(3),T5(3),T6(3) BGG
C NOTE: DUMMY IS USED BY SUBROUTINES AIRBAG AND AIRBGG. BGG
C
C INITIALIZATION BGG
C
C S3TEST = 10.0 BGG
C VOL=0. BGG
C DO 5 I=1,3 BGG
C FRA(I) = 0.0 BGG
C TORQ(I) = 0.0 BGG
C TQB(I) = 0.0 BGG
C BA(I,4)=-BFA(I) BGG

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```

DO 5 J=1,3                                BGG
BA(I,4)=BA(I,4)+DA(I,J)*(ZB(J)-ZA(J))    BGG
DAB(I,J)=0.                                BGG
DO 5 K=1,3                                BGG
5 DAB(I,J)=DAB(I,J)+DA(I,K)*DB(J,K)      BGG
C                                           BGG
C COMPUTE DISTANCE BETWEEN ELLIPSOID CENTERS AND BGG
C CONVERT ELLIPSOID MATRIX OF OBJECT TO AIRBAG REFERENCE. BGG
C                                           BGG
DO 10 I=1,3                                BGG
DO 10 J=1,3                                BGG
TEMP(I,J) = 0.0                            BGG
BA(I,4)=BA(I,4)+DAB(I,J)*BFB(J)          BGG
DO 10 K=1,3                                BGG
10 TEMP(I,J) = TEMP(I,J) + B(I,K)*DAB(J,K) BGG
CALL MAT33(DAB,TEMP,BA)                   BGG
C                                           BGG
C CHECK FOR INTERSECTION AND DETERMINE POINTS OF MAXIMUM PENETRATION BGG
C                                           BGG
TB = 1.0                                    BGG
CALL INTERS (A,BA,BA(1,4),TB,Y,TV(1),T1)  BGG
IF (TB.GT.1.0) RETURN                      BGG
CALL EDEPTH (A,BA,BA(1,4),TB,Y,CPA,CPB,TV(2),TV(3)) BGG
C                                           BGG
C SET UP ORTHOGONAL SYSTEM USING VECTOR BETWEEN POINTS BGG
C OF MAXIMUM PENETRATION AS ONE AXIS.      BGG
C                                           BGG
P = 0.                                       BGG
DO 20 I=1,3                                BGG
PLANE(I,3) = CPA(I)-CPB(I)                 BGG
20 P = PLANE(I,3)**2+P                      BGG
IF (P.LT.EPS(6)) GO TO 99                 BGG
PP = DSQRT(P)                              BGG
DO 25 I=1,3                                BGG
25 TEMP(I,1) = PLANE(I,3)/PP              BGG
CALL ORTHO(PLANE,TEMP,4)                   BGG
C                                           BGG
C DEFINE PLANES AT MAXIMUM PENETRATION POINTS. BGG
C                                           BGG
DO 40 I=1,3                                BGG
PLANE(4,I) = 0.0                          BGG
DO 40 J=1,3                                BGG
40 PLANE(4,I) = PLANE(4,I)+PLANE(J,I)*CPB(J) BGG
DO 45 K=1,3                                BGG
45 CBB(K)=CPB(K)-BA(K,4)                  BGG
C                                           BGG
C ESTIMATES OF VOLUME AND AREA BASED ON RADII OF CURVATURE BGG
C AND PENETRATION.                         BGG
C                                           BGG
IP=2                                        BGG

```

	AREA=PI	BGG
	DO 70 L=1,2	BGG
	RA=RCRT(A,PLANE,CPA,L)	BGG
	RB=RCRT(BA,PLANE,CBB,L)	BGG
	IF (PP.GT.RA) RA=PP	BGG
	R=(RA-RB)*.5	BGG
	RC=(RA+RB)*.5	BGG
	VP=PP/(RA+RB)	BGG
	VD=VP	BGG
	ALP=RC*DSQRT(VP*(2.-VP))	BGG
	IF(R.GE.0.)GO TO 60	BGG
	AB=RA+RB-PP	BGG
	BET=(RA**2-RB**2+AB**2)*.5/AB	BGG
	ALP=DSQRT(RA**2-BET**2)	BGG
	R=0.	BGG
	VD=1.-BET/RA	BGG
	VP=(PP+BET-RA)/RB	BGG
60	VLM(L)=RB*(RB*VP)**2*(1.-VP/3.)+RA*(RA*VD)**2*(1.-VD/3.)	BGG
	IF(R.GT.0.)VLM(L)=VLM(L)-ALP*R*R*(PI-2.*(DASIN(1.-VP)+	BGG
	* (1.-VP)*ALP/RC))	BGG
	VLM(L)=VLM(L)*PI	BGG
	AREA=AREA*ALP	BGG
70	IP=1	BGG
	VOL=(VLM(1)+VLM(2))*5	BGG
	IF (IFULL.EQ.0) GO TO 99	BGG
C		BGG
C	SET UP FORCE VECTOR ALONG LINE OF MAXIMUM PENETRATION.	BGG
C		BGG
	CALL DOT31(DAB,CBB,ZBB)	BGG
	DO 76 K=1,3	BGG
	YFA(K)=CPB(K)+BFA(K)	BGG
	YFB(K)=ZBB(K)+BFB(K)	BGG
	FORCE(K) = -AREA*PLANE(K,3)	BGG
76	T1(K) = VA(K)-VB(K)	BGG
C		BGG
C	COMPUTE ANGULAR VELOCITY COMPONENTS,RELATIVE VELOCITY, COMPONENTS	BGG
C	OF RELATIVE VELOCITY ALONG MAX PENETRATION LINE AND MAGNITUDE OF	BGG
C	FORCE.	BGG
C		BGG
	CALL MAT31(DA,T1,T2)	BGG
	CALL CROSS(WA,YFA,T1)	BGG
	CALL CROSS(WB,YFB,T3)	BGG
	CALL MAT31(DAB,T3,T4)	BGG
	FM = 0.0	BGG
	SUM = 0.0	BGG
	DO 77 K=1,3	BGG
	T5(K) = T2(K)+T1(K)-T4(K)	BGG
	SUM = SUM+T5(K)*PLANE(K,3)	BGG
77	FM = FM+FORCE(K)**2	BGG
C		BGG

```

C      COMPUTE COMPONENTS OF RELATIVE VELOCITY IN TANGENT PLANE,      BGG
C      FRICTION FORCE AND TOTAL FORCE VECTOR.                          BGG
C                                                                 BGG
      S3 = 0.0                                                         BGG
      DO 78 K=1,3                                                     BGG
      T6(K) = T5(K)-SUM*PLANE(K,3)                                     BGG
78     S3 = S3+T6(K)**2                                              BGG
      SQ3 = DSQRT(S3)                                                BGG
      IF (SQ3.LT.S3TEST) SQ3=S3TEST/(2.0-SQ3/S3TEST)                BGG
      FF = VSCS*DSQRT(FM)/SQ3                                         BGG
      DO 79 K=1,3                                                     BGG
79     FORCE(K) = FORCE(K)-FF*T6(K)                                     BGG
C                                                                 BGG
C      COMPUTE FRB: FORCE ON REACTION SURFACE IN ITS LOCAL REFERENCE.  BGG
C      TORQ: TORQUE ON AIRBAG IN AIRBAG REFERENCE.                   BGG
C      TQB: TORQUE ON REACTION SURFACE IN ITS LOCAL REFERENCE.      BGG
C      FRA: FORCE ON AIRBAG IN INERTIAL REFERENCE.                    BGG
C                                                                 BGG
      CALL DOT31(DAB,FORCE,FRB)                                       BGG
      CALL CROSS(YFA,FORCE,TORQ)                                       BGG
      CALL CROSS(FRB,YFB,TQB)                                         BGG
      CALL DOT31(DA,FORCE,FRA)                                         BGG
99     RETURN                                                         BGG
      END                                                             BGG

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SUBROUTINE BINPUT                                     BINPUT
C                                                     REV IV   07/24/86SLIP
C READS THE INPUT CARDS THAT CONTAINS THE PHYSICAL DIMENSIONS AND BINPUT
C CHARACTERISTICS OF THE CRASH VICTIM'S BODY SEGMENTS AND JOINTS. BINPUT
C                                                     BINPUT
  IMPLICIT REAL*8(A-H,O-Z)                             BINPUT
  COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND, BINPUT
  * NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG PAGE
  COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60), SLIP
  * RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90), BINPUT
  * JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30) BINPUT
  COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40) EDGE
  COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5), BINPUT
  * BLTTTL(5,8),PLTTL(5,30),BAGTTL(5,6),SEG(30), BINPUT
  * JOINT(30),CGS(30),JS(30) BINPUT
  REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,SEG,JOINT BINPUT
  LOGICAL*1 CGS,JS BINPUT
  COMMON/INTEST/ SGTEST(3,4,30),XTEST(3,120),SEGT(120),REGT(120) BINPUT
  REAL SEGT BINPUT
  COMMON/FLXBLE/ HF(4,12,8),B42(3,3,24),V4(3,8),NFLEX(3,8) BINPUT
  COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30), JDRIFT
  * FE(3,30),TQE(3,30),CONST(5,30) JDRIFT
  COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24), BINPUT
  * UNITL,UNITM,UNITT,GRAVITY(3),TWOPI TWOPI
  COMMON/RSAVE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30), ATBIII
  * NSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9) TTHKREF
  LOGICAL*1 EULER,SLIP SLIP
  COMMON/TEMPVS/ YPR1(3,30),YPR2(3,30),YPR3(3,30),YPRPMI(3,30), BINPUT
  * T1(6),TMP1(3,3),TMP2(3,3),KNT(30),IDYPR(6,30), SLIP
  * EULER(30) SLIP
  DATA MXNSEG/30/,MXNJNT/30/,MNFLX/8/ MISC
  CALL ELTIME(1,2) BINPUT
  IDYPRT = 0 TGMOD5
C                                                     BINPUT
C INPUT CARD B.1 BINPUT
C                                                     BINPUT
  READ (5,11) NSEG,NJNT,BDYTTL BINPUT
11 FORMAT (2I6,8X,5A4) BINPUT
  IF (NSEG.GT.MXNSEG) STOP 77 MISC
  IF (NJNT.GT.MXNJNT) STOP 78 MISC
C                                                     BINPUT
C INPUT CARDS B.2.I FOR EACH SEGMENT. BINPUT
C                                                     BINPUT
  DO 12 I=1,NSEG BINPUT
  READ (5,13) SEG(I),CGS(I),W(I),(PHI(J,I),J=1,3), BINPUT
  * (BD(J,I),J=1,6),LPMI(I) BINPUT
13 FORMAT(A4,1X,A1,10F6.0,I4) BINPUT
  DO 81 J=1,3 BINPUT
  IDYPR(J,I) = 4-J BINPUT
81 YPRPMI(J,I) = 0.0 BINPUT

```

	IF (LPMI(I).EQ.0) GO TO 12	BINPUT
	READ (5,82) (YPRPMI(J,I),J=1,3)	BINPUT
82	FORMAT(12X,3F6.0)	BINPUT
12	CALL DRCYPR (DPMI(1,1,I),YPRPMI(1,I),IDYPR(1,I))	BINPUT
C		BINPUT
C	INPUT CARDS B.3.J FOR EACH JOINT.	BINPUT
C		BINPUT
	NFLX = 0	BINPUT
	IF (NJNT.EQ.0) GO TO 27	BINPUT
	SLIP = .FALSE.	SLIP
	DO 14 J=1,NJNT	BINPUT
	READ (5,15) JOINT(J),JS(J),JNT(J),IPIN(J), (SR(I,2*J-1),I=1,3),	BINPUT
*	(SR(I,2*J),I=1,3),IEULER(J),CONST(1,J),CONST(2,J),	SLIP
*	(YPR1(I,J),I=1,3),(YPR2(I,J),I=1,3),	SLIP
*	(YPR3(I,J),I=1,3),(IDYPR(I,J),I=1,6)	BINPUT
	ID1 = IDYPR(1,J)	BINPUT
	ID4 = IDYPR(4,J)	BINPUT
	EULER(J) = .FALSE.	SLIP
	IF (IPIN(J).EQ.4) EULER(J) = .TRUE.	SLIP
	IF (IEULER(J).EQ.0.AND.IPIN(J).LE.-4) EULER(J) = .TRUE.	SLIP
	IF (.NOT.EULER(J).AND.IABS(IPIN(J)).GE.5) SLIP = .TRUE.	SLIP
	IF(ID1.NE.0.OR.ID4.NE.0) IDYPRT = 1	TGMOD5
	DO 479 II=1,6	TGMOD5
479	IF(IABS(IDYPR(II,J)).GT.3) STOP 101	TGMOD5
	DO 14 I=1,3	BINPUT
	IF (ID1.EQ.0) IDYPR(I ,J) = 4-I	BINPUT
14	IF (ID4.EQ.0) IDYPR(I+3,J) = 4-I	BINPUT
15	FORMAT(A4,1X,A1,2I4,6F6.0,I4,2F6.0/14X,9F6.0,6I2)	SLIP
C		BINPUT
C	COMPUTE NFLX AND NFLEX ARRAY FROM NEGATIVE VALUES OF JNT(J).	BINPUT
C	NFLX WILL BE NUMBER OF CONSTRAINT TORQUES FOR FLEXIBLE SEGMENTS.	BINPUT
C	NFLEX(1, ) REFERENCE SEGMENT (LOWEST NUMBERED SEGMENT OF CHAIN)	BINPUT
C	NFLEX(2, ) INTERIOR SEGMENT NUMBERS	BINPUT
C	NFLEX(3, ) TERMINATING SEGMENT (HIGHEST NUMBERED SEGMENT IN CHAIN)	BINPUT
C	VALUES OF NFLEX NEED NOT BE SEQUENTIAL BUT MUST BE ORDERED.	BINPUT
C	FLEXIBLE SEGMENT MUST BE SIMPLE CHAIN, I.E., BRANCHING SEGMENTS	BINPUT
C	CANNOT BE ATTACHED TO INTERIOR SEGMENTS BUT MAY BE ATTACHED TO	BINPUT
C	REFERENCE OR TERMINATING SEGMENTS.	BINPUT
C		BINPUT
	DO 16 J=1,NJNT	BINPUT
16	KNT(J) = JNT(J)	BINPUT
	DO 22 J=1,NJNT	BINPUT
	IF (KNT(J).GE.0) GO TO 22	BINPUT
	NFA = NFLX+1	BINPUT
	IT = J+1	BINPUT
	IF (IT.GT.NJNT) GO TO 18	BINPUT
	JP1 = J+1	BINPUT
	DO 17 L=JP1,NJNT	BINPUT
	IF (IABS(KNT(L)).NE.IT) GO TO 17	BINPUT
	KL = KNT(L)	BINPUT

	KNT(L) = 0	BINPUT
	IF (KL.GT.0) GO TO 18	BINPUT
	NFLX = NFLX+1	BINPUT
	NFLEX(1,NFLX) = IABS(KNT(J))	BINPUT
	NFLEX(2,NFLX) = IT	BINPUT
	IT = L+1	BINPUT
	17 CONTINUE	BINPUT
	18 IF (NFLX.GE.NFA) GO TO 20	BINPUT
	WRITE (6,19)	BINPUT
	19 FORMAT('OERROR IN DEFINING FLEXIBLE SEGMENTS, ONLY ONE NEGATIVE JN	BINPUT
	*T IN STRING. PROGRAM TERMINATED.')	BINPUT
	STOP 3	BINPUT
	20 DO 21 K=NFA,NFLX	BINPUT
	21 NFLEX(3,K) = IT	BINPUT
	22 CONTINUE	BINPUT
C		BINPUT
C	INPUT CARDS B.4.J FOR EACH JOINT.	BINPUT
C		BINPUT
	DO 23 J=1,NJNT	BINPUT
	READ (5,24) (SPRING(I,3*J-2),I=1,5), (SPRING(I,3*J-1),I=1,5)	BINPUT
	23 IF (EULER(J)) READ(5,24) (SPRING(I,3*J),I=1,5), (ANG(I,J),I=1,3)	SLIP
	24 FORMAT(2(4F6.0,F12.0))	BINPUT
C		BINPUT
C	INPUT CARDS B.5.J FOR EACH JOINT.	BINPUT
C		BINPUT
	DO 25 J=1,NJNT	BINPUT
	READ (5,26) (VISC(I,3*J-2),I=1,7)	BINPUT
	IF (.NOT.EULER(J)) GO TO 25	SLIP
	READ (5,26) (VISC(I,3*J-1),I=1,7)	BINPUT
	READ (5,26) (VISC(I,3*J),I=1,7)	BINPUT
	25 CONTINUE	BINPUT
	26 FORMAT(5F6.0,18X,2F6.0)	BINPUT
C		BINPUT
C	INPUT CARDS B.6.I FOR EACH SEGMENT.	BINPUT
C		BINPUT
	27 DO 28 I=1,NSEG	BINPUT
	28 READ (5,29) ((SGTEST(J,K,I),J=1,3),K=1,4)	BINPUT
	29 FORMAT(12F6.0)	BINPUT
C		BINPUT
C	PRINT CARD B.1	BINPUT
C		BINPUT
	WRITE (6,30) BDYTTL,NSEG,NJNT,NPG,UNITM,UNITT,UNITL,UNITL,	PAGE
	* UNITL,UNITM	PAGE
	NPG=NPG+1	PAGE
	30 FORMAT('1 CRASH VICTIM',5X,5A4,15,' SEGMENTS',15,' JOINTS',58X,	PAGE
	* 'PAGE',15/120X,'CARD B.1'/25X,'PRINCIPAL MOMENTS OF INERTIA',	PAGE
	* 14X,'SEGMENT CONTACT ELLIPSOID',28X,'CARDS B.2'/	BINPUT
	* 3X,'SEGMENT',6X,'WEIGHT',7X,'(',A4,'-',A4,'**2-',A4,')',	BINPUT
	* 11X,'SEMIAXES (' ,A4,')',12X,'CENTER (' ,A4,')',	BINPUT
	* 11X,'PRINCIPAL AXES (DEG)'/	BINPUT

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*       ' I SYM PLOT (' ,A4,')' ,7X,'X',8X,'Y',8X,'Z' ,          BINPUT
*       2(9X,'X',7X,'Y',7X,'Z') ,8X,'YAW',5X,'PITCH',5X,'ROLL' /) BINPUT
C       PRINT CARDS B.2.I FOR EACH SEGMENT.                        BINPUT
C       DO 31 I=1,NSEG                                             BINPUT
31 WRITE (6,32) I,SEG(I),CGS(I),W(I), (PHI(J,I),J=1,3),          BINPUT
*       (BD(J,I),J=1,6), (YPRMI(J,I),J=1,3)                     BINPUT
32 FORMAT(I3,1X,A4,2X,A1,F11.3,2X,3F9.4,2(2X,3F8.3),1X,3F9.2)  BINPUT
IF (NJNT.EQ.0) GO TO 50                                          BUTLER1
C       PRINT CARDS B.3.J FOR EACH JOINT.                          BINPUT
C       IF(IDYPRT.EQ.0) WRITE(6,33) UNITL,UNITL                  TGMOD5
C       IF(IDYPRT.EQ.1) WRITE(6,733) UNITL,UNITL                 TGMOD5
33 FORMAT(///120X,'CARDS B.3' /)                                  BINPUT
* 3X,'JOINT',15X,'LOCATION(' ,A4,') - SEG(JNT)' ,                BINPUT
*       3X,'LOCATION(' ,A4,') - SEG(J+1)' ,                       BINPUT
*       2X, 'PRIN. AXIS(DEG) - SEG(JNT)' ,                       BINPUT
*       2X, 'PRIN. AXIS(DEG) - SEG(J+1)' /                       BINPUT
* ' J SYM PLOT JNT PIN', 2(6X,'X',8X,'Y',8X,'Z',3X),          BINPUT
*       2(5X,'YAW',5X,'PITCH',5X,'ROLL',1X) /)                   BINPUT
733 FORMAT(///120X,'CARDS B.3' /)                                  TGMOD5
* 3X,'JOINT',15X,'LOCATION(' ,A4,') - SEG(JNT)' ,                TGMOD5
*       3X,'LOCATION(' ,A4,') - SEG(J+1)' ,                       TGMOD5
*       2X, 'PRIN. AXIS(DEG) - SEG(JNT)' ,                       TGMOD5
*       2X, 'PRIN. AXIS(DEG) - SEG(J+1)' /                       TGMOD5
* ' J SYM PLOT JNT PIN', 2(6X,'X',8X,'Y',8X,'Z',3X),          TGMOD5
*       'ID1 YAW ID2 PITCH ID3 ROLL ' ,                          TGMOD5
*       'ID4 YAW ID5 PITCH ID6 ROLL ' ,/)                         TGMOD5
DO 34 J=1,NJNT                                                  BINPUT
IF (IDYPRT.EQ.0)                                               TGMOD5
*WRITE (6,35) J,JOINT(J),JS(J),JNT(J),IPIN(J), (SR(I,2*J-1),I=1,3), TGMOD5
*       (SR(I,2*J),I=1,3), (YPR1(I,J),I=1,3), (YPR2(I,J),I=1,3) BINPUT
IF (IDYPRT.EQ.1)                                               TGMOD5
*WRITE(6,735) J,JOINT(J),JS(J),JNT(J),IPIN(J), (SR(I,2*J-1),I=1,3), TGMOD5
*       (SR(I,2*J),I=1,3), (IDYPR(I,J),YPR1(I,J),I=1,3),       TGMOD5
*       (IDYPR(I+3,J),YPR2(I,J),I=1,3)                          TGMOD5
IF (.NOT.EULER(J)) GO TO 34                                     SLIP
IEULER(J) = 8                                                  BINPUT
IF (IPIN(J).EQ.4) GO TO 34                                     BINPUT
IEULER(J) = 11 + IPIN(J)                                       BINPUT
IPIN(J) = -4                                                   BINPUT
34 CONTINUE                                                    BINPUT
35 FORMAT(I3,1X,A4,2X,A1,2X,2I3,2(1X,3F9.3),2(1X,3F9.2) )      BINPUT
735 FORMAT(I3,1X,A4,2X,A1,2X,2I3,2(1X,3F9.3),2(1X,3(1X,I1,F7.2))) TGMOD5
IF (.NOT.SLIP) GO TO 89                                        SLIP
WRITE (6,83) UNITM,UNITM                                       SLIP
83 FORMAT(// ' UNLOCK CONDITIONS FOR SLIP JOINTS' /           SLIP
*       ' JOINT TENSION COMPRESSION' /)                       SLIP

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      * 14X,'(',A4,')',7X,'(',A4,')'//
      DO 85 J = 1,NJNT
      IF (EULER(J)) GO TO 85
      IF (IABS(IPIN(J)).LT.5) GO TO 85
      WRITE (6,84) J,CONST(1,J),CONST(2,J)
84  FORMAT(1X,I6,4X,F10.3,3X,F10.3)
85  CONTINUE

C
C   SET UP HT MATRIX FROM YPR1 & YPR2 INPUT.
C   HA IS 3RD COLUMN & HB IS 2ND COLUMN OF HT.
C   FOR A SLIP JOINT(IPIN=7),HB IS 3RD COLUMN OF HT.
C
89  IF (NPRT(23).NE.0) WRITE (6,36) NPG
      IF (NPRT(23).NE.0) NPG=NPG+1
36  FORMAT('1 HT ARRAY AS COMPUTED FROM YPR1 & YPR2 INPUT.',77X,
      *      'PAGE',I5)
      DO 38 J=1,NJNT
      SR(4,2*J-1) = 0.0
      SR(4,2*J ) = 0.0
      CALL DRCYPR (TMP1,YPR1(1,J),IDYPR(1,J))
      CALL DRCYPR (TMP2,YPR2(1,J),IDYPR(4,J))
      DO 37 I=1,3
      ANG(I,J) = 0.0
      HA(I,2*J-1) = 0.0
      HA(I,2*J ) = 0.0
      K = 2
      IF (IABS(IPIN(J)).EQ.7) K = 3
      HB(I,2*J-1) = TMP1(K,I)
      HB(I,2*J ) = TMP2(K,I)
      DO 77 K=1,3
      HT(I,K,2*J-1) = TMP1(K,I)
77  HT(I,K,2*J ) = TMP2(K,I)
      IF (.NOT.EULER(J)) GO TO 37
      CONST(I,J) = YPR3(I,J)*RADIAN
      ANG(I,J) = ANG(I,J)*RADIOAN - CONST(I,J)
37  CONTINUE
38  IF (NPRT(23).NE.0) WRITE (6,39) J,JOINT(J),
      *      ((HT(I,K,2*J-1),K=1,3),(HT(I,K,2*J),K=1,3),I=1,3)
39  FORMAT('0',I4,2X,A4,3X,3F12.6,3X,3F12.6/(14X,3F12.6,3X,3F12.6))

C
C   PRINT CARDS B.4.J FOR EACH JOINT.
C
      WRITE (6,41) NPG,UNITL,UNITM,UNITL,UNITM
      NPG=NPG+1
41  FORMAT('1 JOINT TORQUE CHARACTERISTICS',93X,
      *      'PAGE',I5/120X,'CARDS B.4'/
      *23X,'FLEXURAL SPRING CHARACTERISTICS',28X,'TORSIONAL SPRING' ,
      *' CHARACTERISTICS'//
      *15X,'SPRING COEF. (' ,2A4,'/DEG**J)',6X,'ENERGY      JOINT',
      * 7X,'SPRING COEF. (' ,2A4,'/DEG**J)',6X,'ENERGY      JOINT'/

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*OINT ' ,2(8X,'LINEAR    QUADRATIC    CUBIC    DISSIPATION STOP ')BINPUT
*/8X,2(8X,'(J=1)',7X,'(J=2)',7X,'(J=3)',7X,'COEF.    (DEG)')//) BINPUT
DO 42 J=1,NJNT BINPUT
J1 = 3*J-2 BINPUT
J2 = 3*J-1 BINPUT
J3 = 3*J BINPUT
WRITE (6,43) J,JOINT(J),((SPRING(I,JJ),I=1,5),JJ=J1,J2) BINPUT
42 IF (EULER(J)) WRITE (6,44) (SPRING(I,J3),I=1,5) SLIP
43 FORMAT(I3,1X,A4,2(3X,3F12.3,2F10.3)) BINPUT
44 FORMAT(11X,3F12.3,2F10.3) BINPUT
C BINPUT
C PRINT CARDS B.5.J FOR EACH JOINT. BINPUT
C BINPUT
WRITE (6,46) (UNITL,UNITM,UNITT,I=1,2),(UNITL,UNITM,I=1,2),UNITT BINPUT
46 FORMAT(///120X,'CARDS B.5'/ BINPUT
*38X,'JOINT VISCOUS CHARACTERISTICS AND LOCK-UNLOCK CONDITIONS'// BINPUT
*14X,'VISCOUS',9X,'COULOMB',7X,'FULL FRICTION',5X,'MAX TORQUE FOR', BINPUT
*4X,'MIN TORQUE FOR',4X,'MIN. ANG. VELOCITY',6X,'IMPULSE'/ BINPUT
*2X,'JOINT',5X,'COEFFICIENT',4X,'FRICTION COEF. ANGULAR VELOCITY', BINPUT
*4X,'A LOCKED JOINT',4X,'UNLOCKED JOINT',4X,'FOR UNLOCKED JOINT', BINPUT
*4X,'RESTITUTION'/ BINPUT
*8X,'(' ,3A4,'/DEG) (' ,2A4,')',6X,'(DEG/' ,A4,')',10X,'(' ,2A4,')', BINPUT
*8X,'(' ,2A4,')',10X,'(RAD/' ,A4,')',8X,'COEFFICIENT'/ ) BINPUT
DO 47 J=1,NJNT BINPUT
J1 = 3*J-2 BINPUT
J2 = 3*J-1 BINPUT
J3 = 3*J BINPUT
WRITE (6,48) J,JOINT(J),(VISC(I,J1),I=1,7) BINPUT
47 IF (EULER(J)) WRITE (6,49) ((VISC(I,JJ),I=1,7),JJ=J2,J3) SLIP
48 FORMAT(I3,1X,A4,F13.3,2F15.2,F22.2,F18.2,F20.2,F17.3) BINPUT
49 FORMAT( 8X,F13.3,2F15.2,F22.2,F18.2,F20.2,F17.3) BINPUT
C BINPUT
C PRINT CARDS B.6.I FOR EACH SEGMENT. BINPUT
C BINPUT
50 WRITE (6,51) NPG,(UNITT,UNITL,UNITT,I=1,2) PAGE
NPG=NPG+1 PAGE
51 FORMAT('1',122X,'PAGE',I5/20X, PAGE
* 'SEGMENT INTEGRATION CONVERGENCE TEST INPUT',58X,'CARDS B.6'//PAGE
* 17X,'ANGULAR VELOCITIES', 11X,'LINEAR VELOCITIES', BINPUT
* 10X,'ANGULAR ACCELERATIONS',9X,'LINEAR ACCELERATIONS'/ BINPUT
* 21X,'(RAD/' ,A4,')', 18X,'(' ,A4,'/' ,A4,')', BINPUT
* 17X,'(RAD/' ,A4,'**2)', 16X,'(' ,A4,'/' ,A4,'**2)'/ BINPUT
* ' SEGMENT', 4(' MAG. ABS. REL.') / BINPUT
* ' NO. SYM', 4(' TEST ERROR ERROR') /) BINPUT
DO 52 I=1,NSEG BINPUT
52 WRITE (6,53) I,SEG(I),((SGTEST(J,K,I),J=1,3),K=1,4) BINPUT
53 FORMAT(I3,1X,A4,4(F11.3,F9.3,F9.4) ) BINPUT
IF (NFLX.EQ.0) GO TO 62 BINPUT
C BINPUT
C INPUT AND PRINT CARDS B.7 BINPUT

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C      CARD B.7.A  NFX: NO. OF INTERIOR SEGMENTS OF FLEXIBLE ELEMENTS.  BINPUT
C      KNT(J),J=1,NFX: THE SEGMENT NUMBERS.  BINPUT
C      READ (5,54) NFX,(KNT(J),J=1,NFX)  BINPUT
54  FORMAT(18I4)  BINPUT
      IF (NFX.NE.NFLX) WRITE (6,55) NFX,NFLX  BINPUT
55  FORMAT('0INPUT ERROR ON CARD B.7.A, NFX =',I4, ' BUT NFLX =',I4/  BINPUT
      *      ' AS COMPUTED FROM CARDS B.3. PROGRAM TERMINATED.')  BINPUT
      IF (NFX.NE.NFLX) STOP 4  BINPUT
      WRITE (6,56) NPG  PAGE
      NPG=NPG+1  PAGE
56  FORMAT('1',122X,'PAGE',I5/121X,'CARDS B.7')  PAGE
      DO 60 JJ=1,NFX  BINPUT
      DO 57 K=1,NFLX  BINPUT
      IF (KNT(JJ).EQ.NFLEX(2,K)) GO TO 59  BINPUT
57  CONTINUE  BINPUT
      WRITE (6,58) KNT(JJ)  BINPUT
58  FORMAT('0INPUT ERROR ON CARD B.7.J, SEGMENT NO.',I4, ' IS NOT AN INBINPUT
      *TERIOR SEGMENT OF A FLEXIBLE ELEMENT FROM DATA ON CARDS B.3.'/  BINPUT
      *      ' PROGRAM TERMINATED.')  BINPUT
      STOP 5  BINPUT
59  IF(NFLX.GT.MNFLX) STOP 99  TGMOD5
C      CARDS B.7.J  HF ARRAY FOR SEGMENT KNT(JJ)  BINPUT
C      READ (5,29) ((HF(I,J,K),J=1,12),I=1,4)  TGMOD5
      DO 737 LL=1,3  TGMOD5
      L = (LL-1)*4  TGMOD5
      DO 737 I=1,4  TGMOD5
      DO 737 J=1,4  TGMOD5
737 IF(HF(I,J+L,K).NE.HF(J,I+L,K)) STOP 100  TGMOD5
60  WRITE (6,61) KNT(JJ),K,(NFLEX(I,K),I=1,3),  BINPUT
      *      ((HF(I,J,K),J=1,12),I=1,4)  BINPUT
61  FORMAT('0 HF ARRAY FOR INTERIOR SEGMENT NO.',I4,20X,  BINPUT
      *      '(NFLEX(I,',I1,')',I=1,3) =',3I6//  BINPUT
      *      (3X,4F10.4,3X,4F10.4,3X,4F10.4) )  BINPUT
62  IF (NJNT.EQ.0) GO TO 65  BINPUT
C      CHANGE SPRING AND VISC FROM DEG TO RAD  BINPUT
C      DO 64 I=1,NJNT  BINPUT
      J1 = 3*I-2  BINPUT
      J2 = 3*I-1  BINPUT
      IF (EULER(I)) J2= 3*I  BINPUT
      DO 63 J=J1,J2  BINPUT
      SPRING(1,J) = SPRING(1,J)/RADIAN  BINPUT
      SPRING(2,J) = SPRING(2,J)/RADIAN**2  BINPUT
      SPRING(3,J) = SPRING(3,J)/RADIAN**3  BINPUT
      SPRING(5,J) = SPRING(5,J)*RADIAN  BINPUT
63  CONTINUE  BINPUT

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	IF (.NOT.EULER(I)) J2 = J1	SLIP
	DO 64 J=J1,J2	BINPUT
	VISC (1,J) = VISC (1,J)/RADIAN	BINPUT
64	VISC (3,J) = VISC (3,J)*RADIAN	BINPUT
C		BINPUT
C	W ARRAY HAS BEEN SUPPLIED IN LBS. SET UP RECIPROCAL MASS (RW)	BINPUT
C	AND MOMENT OF INERTIA (RPHI) ARRAYS. HOWEVER, IF W OR ANY ELEMENT	BINPUT
C	OF PHI IS ZERO, SEGMENT WILL BE CONSIDERED SINGULAR (ISING=1) AND	BINPUT
C	ALL RECIPROCAL WILL BE ZERO SO AS TO NULLIFY COMPUTATIONS IN THE	BINPUT
C	DAUX ROUTINES. NS IS THE NUMBER OF SINGULAR SEGMENTS.	BINPUT
C		BINPUT
65	NS = 0	BINPUT
	DO 68 I=1,NSEG	BINPUT
	ISING(I) = 0	BINPUT
	RW(I) = 0.0	BINPUT
	IF (W(I).EQ.0.0) ISING(I) = 1	BINPUT
	DO 66 K=1,3	BINPUT
	IF (PHI(K,I).EQ.0.0) ISING(I) = 1	BINPUT
66	RPHI(K,I) = 0.0	BINPUT
	IF (ISING(I).EQ.1) NS = NS+1	BINPUT
	IF (ISING(I).EQ.1) GO TO 68	BINPUT
	RW(I) = G/W(I)	BINPUT
	DO 67 K=1,3	BINPUT
67	RPHI(K,I) = 1.0/PHI(K,I)	BINPUT
68	CONTINUE	BINPUT
C		BINPUT
C	SET UP ELLIPSOID MATRIX AND INVERSE (ASSUME YAW,PITCH,ROLL = 0)	BINPUT
C	FOR 1ST NSEG ELLIPSOIDS IN BD(7-15) AND BD(16-24).	BINPUT
C		BINPUT
	DO 71 J=1,NSEG	BINPUT
	DO 70 I=7,24	BINPUT
70	BD(I,J) = 0.0	BINPUT
	DO 71 I=1,3	BINPUT
	BD(4*I+3,J) = 1.0/BD(I,J)**2	BINPUT
71	BD(4*I+12,J) = BD(I,J)**2	BINPUT
	RETURN	BINPUT
	END	BINPUT



	SUBROUTINE BLKDTA		REV IV	07/23/86	TWOPI	BLKDTA
C						BLKDTA
C	THIS SUBROUTINE REPLACES THE BLOCK DATA SUBPROGRAM OF PREVIOUS					BLKDTA
C	VERSIONS OF CVS-III TO INITIALIZE COMMON/CNSNTS/ IN A MANNER					BLKDTA
C	THAT IS INDEPENDENT OF THE COMPUTER SYSTEM BEING UTILIZED.					BLKDTA
C						BLKDTA
	IMPLICIT REAL*8 (A-H,O-Z)					BLKDTA
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),					BLKDTA
	*                  UNITL,UNITM,UNITT,GRAVTY(3),TWOPI					TWOPI
	COMMON/TEMPVS/ ZERO,ONE,THREE,TEN,ONE80					BLKDTA
	DATA UM/8H LBS      / , UT/8H SEC      / , UL/8H IN      /					BLKDTA
	ZERO = 0.0					BLKDTA
	ONE = 1.0					BLKDTA
	UNITM = UM					BLKDTA
	UNITT = UT					BLKDTA
	UNITL = UL					BLKDTA
	G = 386.088D0					BLKDTA
	GRAVTY(1) = ZERO					BLKDTA
	GRAVTY(2) = ZERO					BLKDTA
	GRAVTY(3) = G					BLKDTA
	THREE = 3.0					BLKDTA
	TEN = 10.0					BLKDTA
	ONE80 = 180.0					BLKDTA
	PI = DATAN2(ZERO,-ONE)					BLKDTA
	TWOPI = 2.0*PI					TWOPI
	RADIAN = PI/ONE80					BLKDTA
	THIRD = ONE/THREE					BLKDTA
	EPS(1) = ONE/TEN					BLKDTA
	DO 10 I=2,24					BLKDTA
10	EPS(I) = EPS(I-1)/TEN					BLKDTA
	RETURN					BLKDTA
	END					BLKDTA

	SUBROUTINE CFACTT(A,B,D)			CFACTT
C		REV 03	05/31/73	CFACTT
C	GIVEN 3X3 MATRIX A			CFACTT
C	COMPUTE B TRANSPOSE OF COFACTORS (SIGNED MINORS)			CFACTT
C	AND D THE VALUE OF THE DETERMINANT OF A.			CFACTT
C	INVERSE OF A IS B(J,K)/D			CFACTT
C				CFACTT
	IMPLICIT REAL*8 (A-H,O-Z)			CFACTT
	DIMENSION A(3,3),B(3,3)			CFACTT
	M = 4			CFACTT
	L = 2			CFACTT
	N = 3			CFACTT
	D = 0.0			CFACTT
	DO 20 J=1,3			CFACTT
	B(J,J) = A(L,L)*A(N,N)-A(L,N)*A(N,L)			CFACTT
	IF (J.EQ.3) GO TO 20			CFACTT
	L = N			CFACTT
	N = J			CFACTT
	KK = J+1			CFACTT
	DO 15 K=KK,3			CFACTT
	M = M-1			CFACTT
	B(K,J) = A(K,M)*A(M,J)-A(K,J)*A(M,M)			CFACTT
15	B(J,K) = A(J,M)*A(M,K)-A(J,K)*A(M,M)			CFACTT
20	D = D+A(1,J)*B(J,1)			CFACTT
	RETURN			CFACTT
	END			CFACTT

	SUBROUTINE CHAIN(ISKIP)	REV IV 07/24/86	JDRIFT
C			SLIP
C	COMPUTES THE LINEAR POSITION AND VELOCITY IN INERTIAL REFERENCE		CHAIN
C	OF BODY SEGMENTS FROM THOSE OF THE REFERENCE SEGMENTS		CHAIN
C	(I.E., SEGMENT NO. 1 AND EACH SEGMENT J FOR WHICH JNT(J)=0).		CHAIN
C			CHAIN
	IMPLICIT REAL*8(A-H,O-Z)		CHAIN
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		CHAIN
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		CHAIN
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		CHAIN
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		CHAIN
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		CHAIN
	COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30),		SLIP
*	FE(3,30),TQE(3,30),CONST(5,30)		SLIP
	COMMON/TEMPVS/ T1(3),T2(3),T3(3),T4(3),T5(3),T6(3),T7(3)		SLIP
	DATA IFIRST/1/		SLIP
	CALL ELTIME (1,11)		ATBIII
	IF (NJNT.EQ.0) GO TO 71		ATBIII
	IF(ISKIP.NE.0) CALL DRIFT		JDRIFT
	DO 70 J=1,NJNT		ATBIII
	K = IABS(JNT(J))		ATBIII
	IF (K.EQ.0) GO TO 70		ATBIII
	IF (ISING(J+1).LT.0) GO TO 70		ATBIII
C			ATBIII
C	COMPUTE SEGMENT POSITIONS BY		ATBIII
C	P(J+1) = P(K) + D(K)'*R(K,J) - D(J+1)'*R(J+1,J)		ATBIII
C			ATBIII
C	COMPUTE SEGMENT VELOCITIES BY		ATBIII
C	V(J+1) = V(K) + D(K)'*W(K) X R(K,J) - D(J+1)'*W(J+1) X R(J+1,J)		ATBIII
C			ATBIII
	CALL CROSS (WMEG(1,K),SR(1,2*J-1),T1)		JDRIFT
	CALL DOT31 (D(1,1,K),T1,T3)		ATBIII
	CALL CROSS (WMEG(1,J+1),SR(1,2*J),T2)		ATBIII
	CALL DOT31 (D(1,1,J+1),T2,T4)		ATBIII
	CALL DOT31 (D(1,1,K),SR(1,2*J-1),T1)		ATBIII
	CALL DOT31 (D(1,1,J+1),SR(1,2*J),T2)		ATBIII
	IF (IABS(IPIN(J)).LT.5) GO TO 50		SLIP
	IF (IEULER(J).EQ.-1)GO TO 50		SLIP
	IF (IFIRST.EQ.1) GO TO 50		SLIP
	DO 40 I = 1,3		SLIP
	T5(I) = SEGLP(I,J+1) + T2(I) - SEGLP(I,K) - T1(I)		SLIP
40	T6(I) = SEGLV(I,J+1) + T4(I) - SEGLV(I,K) - T3(I)		SLIP
	CALL DOT31 (D(1,1,K),HT(1,3,2*J-1),T7)		SLIP
	SR(4,2*J-1) = T5(1)*T7(1) + T5(2)*T7(2) + T5(3)*T7(3)		SLIP
	SR(4,2*J) = T6(1)*T7(1) + T6(2)*T7(2) + T6(3)*T7(3)		SLIP
	CALL CROSS (WMEG(1,K),HT(1,3,2*J-1),T5)		SLIP
	CALL DOT31 (D(1,1,K),T5,T6)		SLIP
	DO 45 I = 1 ,3		SLIP

	T1(I) = T1(I) + SR(4,2*J-1)*T7(I)	SLIP
45	T3(I) = T3(I) + SR(4,2*J )*T7(I) + SR(4,2*J-1)*T6(I)	SLIP
50	DO 60 I=1,3	SLIP
	SEGLP(I,J+1) = SEGLP(I,K) + T1(I) - T2(I)	ATBIII
60	SEGLV(I,J+1) = SEGLV(I,K) + T3(I) - T4(I)	ATBIII
70	CONTINUE	CHAIN
	IFIRST = 0	SLIP
C		CHAIN
C	OPTIONAL OUTPUT	CHAIN
C		CHAIN
	71 IF (NPRT(20).NE.0) WRITE(6,90) TIME	CHAIN
	* ,((SEGLP(I,J),I=1,3),J=1,NSEG)	CHAIN
	* ,((SEGLV(I,J),I=1,3),J=1,NSEG)	CHAIN
90	FORMAT('0 LINEAR POSITIONS AND VELOCITIES OF BODY SEGMENTS FROM CH	CHAIN
	*AIN FOR TIME = ',F12.6/(9F13.5))	CHAIN
	CALL ELTIME(2,11)	CHAIN
	RETURN	CHAIN
	END	CHAIN

```

SUBROUTINE CINPUT                                CINPUT
C                                                    REV III.2 08/08/84REVIII
C INPUT CARDS E.1 - E.4 FOR THE FORCE-DEFLECTION, INERTIAL SPIKE, CINPUT
C R FACTOR, G FACTOR AND FRICTION COEFFICIENT FUNCTION DEFINITIONS CINPUT
C                                                    CINPUT
C IMPLICIT REAL*8(A-H,O-Z)                        CINPUT
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND, PAGE
* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG PAGE
COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500) DIMENB
COMMON/TEMPVS/JTITLE(5,51),NF(5),NT(3),KTITLE(31) CINPUT
REAL JTITLE,KTITLE                                CINPUT
C                                                    CINPUT
IS = 0                                             CINPUT
DO 10 I = 1,50                                    CINPUT
10 NTI(I) = 0                                       CINPUT
J1 = 1                                             CINPUT
C                                                    CINPUT
C INPUT CARD E.1 - FUNCTION NO. AND TITLE, IF NO. > 50 SKIP OUT. CINPUT
C                                                    CINPUT
11 READ(5,12) I,(KTITLE(J ),J = 1,5)             CINPUT
12 FORMAT (I4,4X,5A4)                               CINPUT
IF (I.GT.50) GO TO 30                               CINPUT
DO 13 J = 1,5                                       CINPUT
13 JTITLE(J,I) = KTITLE(J)                         CINPUT
C                                                    CINPUT
C HAS FUNCTION NO. BEEN ALREADY USED?             CINPUT
C                                                    CINPUT
IF (NTI(I).NE.0) WRITE(6,14) I                    CINPUT
14 FORMAT('0 FUNCTION NO.',I4,' HAS ALREADY BEEN INPUTTED AND WILL BE CINPUT
*REPLACED BY NEXT FUNCTION')                       CINPUT
NTI(I) = J1                                         CINPUT
J2 = J1+4                                           CINPUT
C                                                    CINPUT
C INPUT CARD E.2                                  CINPUT
C                                                    CINPUT
READ(5,15) (TAB(J),J = J1,J2)                     CINPUT
15 FORMAT (6F12.0)                                  CINPUT
IS = 1-IS                                           CINPUT
IF (IS.EQ.0) WRITE(6,16)                           CINPUT
IF (IS.EQ.0) GOTO 40                                CINPUT
WRITE(6,41) NPG                                     PAGE
41 FORMAT('1',122X,'PAGE',I5)                       PAGE
NPG=NPG+1                                           PAGE
16 FORMAT(///// )                                  CINPUT
40 WRITE(6,17) I,(JTITLE(J,I),J=1,5),I,NTI(I),(TAB(J),J=J1,J2) PAGE
17 FORMAT(' FUNCTION NO.',I4,4X,5A4,20X,'NTI(',I2,') =',I5,45X, PAGE
* 'CARDS E'//10X,'D0',13X,'D1',13X,'D2',13X,'D3',13X,'D4'/5F15.4//) CINPUT
DO = TAB(J1)                                       CINPUT
D1 = TAB(J1+1)                                     CINPUT
D2 = TAB(J1+2)                                     CINPUT

```

	J1 = J2+1	CINPUT
	IF (D1) 22,18,20	CINPUT
C		CINPUT
C	FUNCTION IS CONSTANT D2 FOR ALL D.	CINPUT
C		CINPUT
	18 WRITE(6,19) D2	CINPUT
	19 FORMAT(7X,'FUNCTION IS CONSTANT',F12.6)	CINPUT
	GO TO 11	CINPUT
C		CINPUT
C	5TH ORDER POLYNOMIAL ... 1ST FUNCTION	CINPUT
C	INPUT CARD E.3	CINPUT
C		CINPUT
	20 J2 = J1+5	CINPUT
	READ(5,15) (TAB(J), J = J1,J2)	CINPUT
	WRITE(6,21) (TAB(J), J = J1,J2)	CINPUT
	21 FORMAT(7X,'FIRST PART OF FUNCTION - 5TH DEGREE POLYNOMIAL'//	CINPUT
	* 8X,'A0',13X,'A1',13X,'A2',13X,'A3',13X,'A4',13X,'A5',13X/	CINPUT
	* 6F15.6//)	CINPUT
	J1 = J2+1	CINPUT
	GO TO 25	CINPUT
C		CINPUT
C	TABLE LOAD ... 1ST FUNCTION	CINPUT
C	INPUT CARDS E.4.A-E.4.N	CINPUT
C		CINPUT
	22 READ(5,23) NPI	CINPUT
	23 FORMAT (12I6)	CINPUT
	TAB(J1) = NPI	CINPUT
	J1 = J1+1	CINPUT
	J2 = J1+2*NPI-1	CINPUT
	READ(5,15) (TAB(J), J = J1,J2)	CINPUT
	WRITE(6,24) NPI, (TAB(J), J = J1, J2)	CINPUT
	24 FORMAT(7X,'FIRST PART OF FUNCTION - ',I4,' TABULAR POINTS'//	CINPUT
	* 8X,'D',16X,'F(D)' / (F15.6,F15.4))	CINPUT
	J1 = J2+1	CINPUT
C		CINPUT
C	CHECK FOR SECOND FUNCTION	CINPUT
C		CINPUT
	25 IF(D2) 28,11,26	CINPUT
C		CINPUT
C	SECOND FUNCTION ... 5TH ORDER POLYNOMIAL	CINPUT
C	INPUT CARD E.3	CINPUT
C		CINPUT
	26 J2 = J1+5	CINPUT
	READ(5,15) (TAB(J), J = J1,J2)	CINPUT
	WRITE(6,27) (TAB(J), J = J1,J2)	CINPUT
	27 FORMAT(7X,'SECOND PART OF FUNCTION - 5TH DEGREE POLYNOMIAL'//	CINPUT
	* 8X,'B0',13X,'B1',13X,'B2',13X,'B3',13X,'B4',13X,'B5',13X/	CINPUT
	* 6F15.6//)	CINPUT
	J1 = J2+1	CINPUT
	GO TO 11	CINPUT

C		CINPUT
C	SECOND FUNCTION ... TABLE LOAD	CINPUT
C	INPUT CARDS E.4.A-E.4.N	CINPUT
C		CINPUT
	28 READ(5,23) NPI	CINPUT
	TAB(J1) = NPI	CINPUT
	J1 = J1+1	CINPUT
	J2 = J1+2*NPI-1	CINPUT
	READ(5,15) (TAB(J), J = J1,J2)	CINPUT
	WRITE(6,29) NPI, (TAB(J), J = J1,J2)	CINPUT
	29 FORMAT(7X,'SECOND PART OF FUNCTION - ',I4,' TABULAR POINTS'//	CINPUT
	* 8X,'D',16X,'F(D)' /(F15.6,F15.4))	CINPUT
	J1 = J2+1	CINPUT
	GO TO 11	CINPUT
	30 MXTB1 = J1-1	CINPUT
	CALL KINPUT	CINPUT
	CALL FINPUT	CINPUT
	CALL HINPUT	CINPUT
	RETURN	CINPUT
	END	CINPUT

C

```
SUBROUTINE CMPUTE (K,M,FT)                                CMPUTE
                                                         REV III.2 08/08/84REVIII
IMPLICIT REAL*8 (A-H,O-Z)                                CMPUTE
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,  CMPUTE
*      NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG  PAGE
COMMON/CDINT/  UU(4),GH(3,4),                            CMPUTE
*      E(3,240), F(5,240),GG(5,240),Y(5,240),U(5,240),  CMPUTE
*      H,HPRINT,HS,TPRINT,TSTART,ICNT,IDBL,IFLAG        CMPUTE
COMMON/COMAIN/ VAR(240),DER(240),DT,HO,HMAX,HMIN,RSTIME,  CMPUTE
*      ISTEP,NSTEPS,NDINT,NEQ,IRSIN,IRSOUT              CMPUTE
TIME = TSTART + FT                                       CMPUTE
CALL DZP (NEQ,VAR,GG,E,FT,M)                              CMPUTE
IF (NPRT(26).EQ.2) CALL OUTPUT(0)                        CMPUTE
CALL PDAUX (VAR,DER,NEQ,K)                               CMPUTE
IF (NPRT(26).EQ.2) CALL OUTPUT(1)                        CMPUTE
RETURN                                                    CMPUTE
END                                                       CMPUTE
```



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SUBROUTINE CONTACT                                CONTACT
C                                                    REV III.2 08/08/84REVIII
C CONTROLS THE CALLING OF SUBROUTINES REQUIRED TO COMPUTE THOSE CONTACT
C EXTERNAL FORCES AND TORQUES ACTING ON THE BODY SEGMENTS. CONTACT
C                                                    CONTACT
C IMPLICIT REAL*8 (A-H,O-Z)                        CONTACT
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND, CONTACT
* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG PAGE
COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6), CONTACT
* MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6), CONTACT
* NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30) CONTACT
COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20), NCFORC
* PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF CONTACT
COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)DIMENB
COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100), CONTACT
* XLONG(20),HTIME(2),IBAR(5,100),NL(2,100), CONTACT
* NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5) CONTACT
COMMON/WINDFR/ WTIME(30),QFU(3,5),QFV(3,5),WF(3,30),IWIND(30), WINDOP
* MWSEG(7,30),NFVSEG(6),NFVNT(5),MOWSEG(30,30) WINDOP
DATA MAXPSF/70/,MAXBSF/20/,MAXSSF/46/ NCFORC
C CHGIII
C MAXSSF SHOULD BE 40 BUT IT IS ALLOWED TO OVERFLOW INTO BAGSF NCFORC
C CHGIII
CALL ELTIME(1,12) CONTACT
NPSF = 0 CONTACT
NBSF = 0 CONTACT
NSSF = 0 CONTACT
IF (NPL.LE.0) GO TO 21 CONTACT
C CONTACT
C CALL PLELP ROUTINE FOR EACH ALLOWED PLANE-SEGMENT CONTACT. CONTACT
C CONTACT
DO 20 J=1,NPL CONTACT
IF(MNPL(J).EQ.0) GO TO 20 CONTACT
KPL = MNPL(J) CONTACT
DO 19 I=1,KPL CONTACT
NPSF = NPSF+1 CONTACT
IF(NPSF.GT.MAXPSF) STOP 57 CHGIII
M1 = MPL(1,I,J) CONTACT
M2 = MPL(2,I,J) CONTACT
M3 = MPL(3,I,J) CONTACT
NT = NTPL(I,J) CONTACT
JT = NTAB(NT) CONTACT
TAB(JT) = 0.0 CONTACT
19 CALL PLELP(M2,M3,M1,J,NT) CONTACT
20 CONTINUE CONTACT
21 IF(NBLT.LE.0) GO TO 41 CONTACT
C CONTACT
C CALL BELTRT ROUTINE FOR EACH ALLOWED BELT-SEGMENT CONTACT. CONTACT
C CONTACT
DO 30 J=1,NBLT CONTACT

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	IF(MNBLT(J).EQ.0) GO TO 30	CONTCT
	KBLT = MNBLT(J)	CONTCT
	DO 29 I=1,KBLT	CONTCT
	NBSF = NBSF+1	CONTCT
	IF(NBSF.GT.MAXBSF) STOP 58	CHGIII
	M1 = MBLT(1,I,J)	CONTCT
	M2 = MBLT(2,I,J)	CONTCT
	M3 = MBLT(3,I,J)	CONTCT
	NT = NTBLT(I,J)	CONTCT
	JT = NTAB(NT)	CONTCT
	TAB(JT) = 0.0	CONTCT
	NF = NTAB(NT+5)	CONTCT
	IF (NF.NE.0) JT = NTAB(NT+6)	CONTCT
	IF (NF.NE.0) TAB(JT) = 0.0	CONTCT
	29 CALL BELTRT(M2,M3,M1,J,NT)	CONTCT
	30 CONTINUE	CONTCT
C		CONTCT
C	CALL SEGSEG ROUTINE FOR EACH ALLOWED SEGMENT-SEGMENT CONTACT.	CONTCT
C		CONTCT
	41 DO 50 J=1,NSEG	CONTCT
	IF(MNSEG(J).EQ.0) GO TO 50	CONTCT
	KSEG = MNSEG(J)	CONTCT
	DO 49 I=1,KSEG	CONTCT
	NSSF = NSSF+1	CONTCT
	IF(NSSF.GT.MAXSSF) STOP 59	CHGIII
	M1 = MSEG(1,I,J)	CONTCT
	M2 = MSEG(2,I,J)	CONTCT
	M3 = MSEG(3,I,J)	CONTCT
	NT = NTSEG(I,J)	CONTCT
	JT = NTAB(NT)	CONTCT
	TAB(JT) = 0.0	CONTCT
	49 CALL SEGSEG(J,M1,M2,M3,NT)	CONTCT
	50 CONTINUE	CONTCT
C		CONTCT
C	CALL AIRBAG ROUTINE FOR ALLOWED BAG-SEGMENT CONTACTS, IF ANY.	CONTCT
C		CONTCT
	IF (NBAG.NE.0) CALL AIRBAG	CONTCT
C		CONTCT
C	CALL WINDY ROUTINE FOR WIND FORCES ON EACH SEGMENT.	CONTCT
C		CONTCT
	DO 60 J=1,NSEG	CONTCT
	IF (MWSEG(1,J).EQ.0) GO TO 60	CONTCT
	M=MWSEG(1,J)	WINDOP
	M1 = MWSEG(2,J)	CONTCT
	M2 = MWSEG(3,J)	CONTCT
	M3 = MWSEG(4,J)	CONTCT
	NT = MWSEG(5,J)	CONTCT
	CALL WINDY (M,M1,M2,M3,NT)	WINDOP
	60 CONTINUE	CONTCT
C		CONTCT

C	CALL WINDY FOR FORCE FUNCE FUNCTION CALCULATIONS.	CONTCT
C		CONTCT
	NFORCE = NFVSEG(6)	CONTCT
	IF (NFORCE.GT.0) CALL WINDY (0,M1,M2,M3,NT)	WINDOP
C		CONTCT
C	CALL HBELT ROUTINE FOR EACH HARNESS-BELT SYSTEM.	CONTCT
C		CONTCT
	IF (NHRNSS.LE.0) GO TO 80	CONTCT
	J1 = 1	CONTCT
	KNLO = 0	CONTCT
	DO 70 I=1,NHRNSS	CONTCT
	IF (NBLTPH(I).LE.0) GO TO 70	CONTCT
	J2 = J1 + NBLTPH(I) - 1	CONTCT
	CALL HBELT (J1,J2,KNLO,0)	CONTCT
	J1 = J2+1	CONTCT
	70 CONTINUE	CONTCT
C		CONTCT
C	CALL SPDAMP FOR SPRING DAMPER FORCES, IF ANY	CONTCT
C		CONTCT
	80 IF (NSD.NE.0) CALL SPDAMP	CONTCT
	CALL ELTIME (2,12)	CONTCT
	RETURN	CONTCT
	END	CONTCT

C	SUBROUTINE CROSS(A,B,C)		CROSS
C		REV 03	05/31/73CROSS
C	COMPUTES VECTOR CROSS PRODUCT $C = A \times B$ .		CROSS
C	ARGUMENTS		CROSS
C	A,B,C: VECTORS OF LENGTH 3 WHERE $C=AXB$ .		CROSS
C			CROSS
	IMPLICIT REAL*8 (A-H,O-Z)		CROSS
	DIMENSION A(3),B(3),C(3)		CROSS
	C(1) = A(2)*B(3) - A(3)*B(2)		CROSS
	C(2) = A(3)*B(1) - A(1)*B(3)		CROSS
	C(3) = A(1)*B(2) - A(2)*B(1)		CROSS
	RETURN		CROSS
	END		CROSS

	SUBROUTINE DAUX(11)		DAUX
		REV IV	07/24/86SLIP
C	COMPUTES DERIVATIVES FOR INTEGRATOR ROUTINE BY		DAUX
C	(1) SET UP INITIAL VALUES FOR ARRAY OF SYSTEM EQUATIONS.		DAUX
C	(2) MODIFY ARRAYS BY CONSTRAINTS.		DAUX
C	(3) SOLVE SYSTEM OF EQUATION FOR F,TQ,QQ AND V4.		DAUX
C	(4) EVALUATE DERIVATIVES SEGLA AND WMEGD.		DAUX
C			DAUX
	IMPLICIT REAL*8(A-H,O-Z)		DAUX
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		DAUX
*	NS,NQ,MSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		DAUX
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		DAUX
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		DAUX
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		DAUX
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),		DAUX
*	F(3,30),TQ(3,30),WJ(30),A11(3,3,30)		SLIP
	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),		DAUX
*	HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),		DAUX
*	RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),		DAUX
*	KQ1(12),KQ2(12),KQTYPE(12)		DAUX
	COMMON/FLXBLE/ HF(4,12,8),B42(3,3,24),V4(3,8),NFLEX(3,8)		DAUX
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		DAUX
*	UNITL,UNITM,UNITT,GRAVITY(3),TWOPI		TWOPI
	COMMON/RSAVE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30),		ATBIII
*	NSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9)		TTHKREF
C			DAUX
C	NOTE: DAUX SHARES /TEMPVS/ WITH DAUX11,12,22,31,32 &33.		DAUX
C			DAUX
	LOGICAL*1 FREE		SLIP
	COMMON/TEMPVS/ C(3,3,600),RHS(3,54),IJK(54,54),IJ,NQ2S,		SLIP
*	IDUM(458),FREE(30)		SLIP
	DIMENSION T1(3),T2(3),T3(3)		TGMOD2
	CALL ELTIME(1,9)		DAUX
C			DAUX
C	IF I1*0, U1 AND U2 HAVE BEEN SET UP BY CALLING ROUTINE.		DAUX
C			DAUX
	IF (I1.NE.0) GO TO 8		DAUX
C			DAUX
C	SET UP INITIAL VALUES OF A & B ARRAYS AND U & V VECTORS.		DAUX
C	MODIFY U1 & U2 ARRAYS BY CONTACT AND JOINT FORCES.		DAUX
C			DAUX
	CALL CHAIN(NPRT(36))		JDRIFT
	CALL SETUP1		DAUX
	CALL VEHPOS		DAUX
	CALL CONTC		DAUX
	CALL VISPR(0,0)		DAUX
	CALL EJOINT(0,0)		DAUX
	CALL SETUP2		DAUX

	IF (NFLX.GT.0) CALL FLXSEG	DAUX
C		DAUX
C	MODIFY U1,U2 AND ADD G TO U1.	DAUX
C		DAUX
	DO 5 J=1,NGRND	DAUX
	IF (ISING(J)) 1,3,5	DAUX
1	DO 2 I=1,3	DAUX
	U1(I,J) = SEGLA(I,J)	DAUX
2	U2(I,J) = WMEGD(I,J)	DAUX
	GO TO 5	DAUX
3	DO 4 I=1,3	DAUX
	U1(I,J) = U1(I,J)*RW(J) + GRAVTY(I)	DAUX
4	U2(I,J) = U2(I,J)*RPHI(I,J)	DAUX
5	CONTINUE	DAUX
C		DAUX
C	SET UP BODY SEGMENT SYMMETRY	DAUX
C	NSYM(J) = 0 3D MOTION	DAUX
C	NSYM(J) = J CENTRAL SEGMENT 2D MOTION, NO LATERAL MOTION	DAUX
C	NSYM(J) = K SEGMENT J SYMMETRIC TO SEGMENT K, ALL MOTION	DAUX
C	IN THE X-Z PLANE, NO LATERAL MOTION	DAUX
C	NSYM(J) = -K SEGMENT J MIRROR SYMMETRIC TO SEGMENT K, EQUAL	DAUX
C	BUT OPPOSITE LATERAL MOTION PERMITTED	DAUX
C		DAUX
	DO 20 J=1,NGRND	DAUX
	IF (NSYM(J).EQ.0) GO TO 20	DAUX
	K = IABS(NSYM(J))	DAUX
	DO 205 L=1,3	TGMOD2
	T1(L) = U2(L,J)	TGMOD2
	T2(L) = U2(L,K)	TGMOD2
	T3(L) = U2(L,J)	TGMOD2
205	CONTINUE	TGMOD2
	IF (LPMI(J).EQ.0.AND.LPMI(K).EQ.0) GO TO 201	TGMOD2
	IF (LPMI(J).NE.0.AND.LPMI(K).EQ.0) GO TO 202	TGMOD2
	IF (LPMI(J).EQ.0.AND.LPMI(K).NE.0) GO TO 203	TGMOD2
	CALL DOT31(DPMI(1,1,J),U2(1,J),T1)	TGMOD2
	CALL DOT31(DPMI(1,1,K),U2(1,K),T2)	TGMOD2
	GO TO 201	TGMOD2
202	CALL DOT31(DPMI(1,1,J),U2(1,J),T1)	TGMOD2
	GO TO 201	TGMOD2
203	CALL DOT31(DPMI(1,1,K),U2(1,K),T2)	TGMOD2
201	CONTINUE	TGMOD2
	IF (NSYM(J).EQ.J) GO TO 19	DAUX
	IF (K.LT.J) GO TO 16	DAUX
	U1(1,J) = 0.5*(U1(1,J) + U1(1,K))	DAUX
	U1(3,J) = 0.5*(U1(3,J) + U1(3,K))	DAUX
	T3(2) = 0.5*(T1(2) + T2(2))	TGMOD2
	GO TO 17	DAUX
16	U1(1,J) = U1(1,K)	DAUX
	U1(3,J) = U1(3,K)	DAUX
	T3(2) = T2(2)	DAUX

17	IF (NSYM(J).GT.0) GO TO 19	DAUX
	IF (K.LT.J) GO TO 18	DAUX
	U1(2,J) = 0.5*(U1(2,J) - U1(2,K))	DAUX
	T3(1) = 0.5*(T1(1) - T2(1))	TGMOD2
	T3(3) = 0.5*(T1(3) - T2(3))	TGMOD2
	GO TO 206	DAUX
18	U1(2,J) = -U1(2,K)	DAUX
	T3(1) = -T2(1)	TGMOD2
	T3(3) = -T2(3)	TGMOD2
	GO TO 206	DAUX
19	U1(2,J) = 0.0	DAUX
	T3(1) = 0.0	TGMOD2
	T3(3) = 0.0	TGMOD2
206	IF(LPMI(J).EQ.0) GO TO 207	TGMOD2
	CALL MAT31(DPMI(1,1,J),T3,U2(1,J))	TGMOD2
	GO TO 20	TGMOD2
207	U2(1,J) = T3(1)	TGMOD2
	U2(2,J) = T3(2)	TGMOD2
	U2(3,J) = T3(3)	TGMOD2
20	CONTINUE	TGMOD2
C		DAUX
C	INITIALIZE IJK ARRAY AND IJ COUNTER TO ZERO.	DAUX
C		DAUX
	8 NQ2S = 2*NS + NFLX + NQ	DAUX
	NJ2 = NQ2S + 2*NJNT	DAUX
	IF (NJ2.GT.54) WRITE (6,11) NS,NFLX,NQ,NJNT,NJ2	DAUX
11	FORMAT('ONS=',I6,',NFLX=',I6,',NQ=',I6,',NJNT=',I6,', AND NJ2=',I6/AFREVS	DAUX
	*' THE VALUE OF NJ2 EXCEEDS THE ARRAY SIZES FOR RHS AND IJK IN SUBRDAUX	DAUX
	*OUTINE DAUX. PROGRAM TERMINATED.')	DAUX
	IF (NJ2.GT.54) STOP 34	DAUX
	MJ2 = NJ2	DAUX
	DO 10 I=1,MJ2	DAUX
	DO 10 J=1,MJ2	DAUX
10	IJK(I,J) = 0	DAUX
	IJ = 0	DAUX
C		DAUX
C	ELMINATE SEGLA AND WMEGD FROM SYSTEM OF EQUATIONS.	DAUX
C		DAUX
	IF (NS.GT.0) CALL DAUX55	DAUX
	IF (NJNT.EQ.0) GO TO 12	DAUX
	IF (NFLX.GT.0) CALL DAUX44	DAUX
	CALL DAUX11	DAUX
	CALL DAUX12	DAUX
	CALL DAUX22	DAUX
12	IF (NQ.LE.0) GO TO 15	DAUX
	IF (NJNT.EQ.0) GO TO 13	DAUX
	CALL DAUX31	DAUX
	CALL DAUX32	DAUX
13	CALL DAUX33	DAUX
	DO 14 I=1,NQ	DAUX

14	IF (KQTYPE(I).GE.4) MJ2 = -NJ2	DAUX
15	IF (NPRT(8).EQ.0) GO TO 28	DAUX
21	WRITE (6,22) NPG, (J,J=1,NJ2)	PAGE
	NPG=NPG+1	PAGE
22	FORMAT('1 DAUX PRINT OF IJK MATRIX',97X,'PAGE',15//6X,4013)	PAGE
	DO 23 I=1,NJ2	DAUX
23	WRITE (6,24) I, (IJK(I,J),J=1,NJ2)	DAUX
24	FORMAT(I3,3X,4013)	DAUX
	WRITE (6,29)	DAUX
29	FORMAT('0 DAUX PRINT OF RHS ARRAY'//)	DAUX
	DO 30 K=1,NJ2	DAUX
30	WRITE (6,27) K, (RHS(I,K),I=1,3)	DAUX
	WRITE (6,25) NPG	PAGE
	NPG=NPG+1	PAGE
25	FORMAT('1 DAUX PRINT OF C ARRAY ELEMENTS',91X,'PAGE',15//)	PAGE
	DO 26 K=1,IJ	DAUX
26	WRITE (6,27) K, ((C(I,J,K),J=1,3),I=1,3)	DAUX
27	FORMAT(I6,9G14.7)	DAUX
28	IF (NPRT(8).EQ.-2) GO TO 31	DAUX
C		DAUX
C	SOLVE SYSTEM OF EQUATIONS FOR F,TQ,QQ & V4.	DAUX
C		DAUX
	CALL FSMSOL (C,RHS,IJK,MJ2,IJ,54,600)	CHGIII
	IF (NPRT(8).EQ. 2) NPRT(8) = -2	DAUX
	IF (NPRT(8).EQ.-2) GO TO 21	DAUX
31	IF (NPRT(8).EQ.-2) NPRT(8) = 0	DAUX
	EPS12 = EPS(12)	JDRIFT
	IF (NJNT.EQ.0) GO TO 49	DAUX
	DO 51 I=1,NJNT	DAUX
	NJ = NQ2S + I	DAUX
	NI = NJ+NJNT	DAUX
	DO 51 K=1,3	DAUX
	IF (DABS(RHS(K,NJ)).LT.EPS12) RHS(K,NJ) = 0.0	DAUX
	IF (DABS(RHS(K,NI)).LT.EPS12) RHS(K,NI) = 0.0	DAUX
	TQ(K,I) = TQ(K,I) - RHS(K,NI)	DAUX
51	F(K,I) = RHS(K,NJ)	DAUX
49	IF (NQ.EQ.0) GO TO 53	DAUX
	DO 52 I=1,NQ	DAUX
	J = 2*NS + NFX + I	DAUX
	DO 52 K=1,3	DAUX
	IF (KQTYPE(I).LT.0) RHS(K,J) = 0.0	DAUX
	IF (DABS(RHS(K,J)).LT.EPS12) RHS(K,J) = 0.0	DAUX
52	QQ(K,I) = RHS(K,J)	DAUX
53	IF (NFX.EQ.0) GO TO 70	DAUX
	DO 54 I=1,NFX	DAUX
	J = 2*NS + I	DAUX
	DO 54 K=1,3	DAUX
	IF (DABS(RHS(K,J)).LT.EPS12) RHS(K,J) = 0.0	DAUX
54	V4(K,I) = RHS(K,J)	DAUX
C		DAUX



C	BACKUP SOLUTION FOR SEGLA AND WMEGD.	DAUX
C		DAUX
	70 DO 71 J=1,NGRND	DAUX
	DO 71 I=1,3	DAUX
	SEGLA(I,J) = U1(I,J)	DAUX
	71 WMEGD(I,J) = U2(I,J)	DAUX
	IF (NS.EQ.0) GO TO 79	DAUX
C		DAUX
C	SET UP SEGLA & WMEGD FOR SINGULAR SEGMENTS.	DAUX
C		DAUX
	IS = 0	DAUX
	DO 78 J=1,NGRND	DAUX
	IF (ISING(J).LE.0) GO TO 78	DAUX
	IS = IS+2	DAUX
	DO 77 I=1,3	DAUX
	IF (DABS(RHS(I,IS-1)).LT.EPS12) RHS(I,IS-1) = 0.0	DAUX
	SEGLA(I,J) = SEGLA(I,J) + RHS(I,IS-1)	DAUX
	IF (DABS(RHS(I,IS )).LT.EPS12) RHS(I,IS ) = 0.0	DAUX
	77 WMEGD(I,J) = WMEGD(I,J) + RHS(I,IS)	DAUX
	78 CONTINUE	DAUX
	79 IF (NJNT.EQ.0) GO TO 80	DAUX
C		DAUX
C	ELIMINATE F	DAUX
C		DAUX
	DO 75 M=1,NJNT	DAUX
	N = IABS(JNT(M))	DAUX
	IF (N.EQ.0) GO TO 73	DAUX
	DO 72 I=1,3	DAUX
	DO 72 J=1,3	DAUX
	SEGLA(I,N ) = SEGLA(I,N ) - A11(I,J,M)*RW(N )*F(J,M)	SLIP
	SEGLA(I,M+1) = SEGLA(I,M+1) + A11(I,J,M)*RW(M+1)*F(J,M)	SLIP
	WMEGD(I,N ) = WMEGD(I,N ) - B12(J,I,2*M-1)*RPHI(I,N )*F(J,M)	DAUX
	72 WMEGD(I,M+1) = WMEGD(I,M+1) - B12(J,I,2*M )*RPHI(I,M+1)*F(J,M)	DAUX
C		DAUX
C	ELIMINATE TQ	DAUX
C		DAUX
	73 IF (FREE(M)) GO TO 75	SLIP
	L = NQ2S + NJNT + M	DAUX
	DO 74 I=1,3	DAUX
	DO 74 J=1,3	DAUX
	WMEGD(I,N ) = WMEGD(I,N ) - A22(I,J,2*M-1)*RPHI(I,N )*RHS(J,L)	DAUX
	74 WMEGD(I,M+1) = WMEGD(I,M+1) + A22(I,J,2*M )*RPHI(I,M+1)*RHS(J,L)	DAUX
	75 CONTINUE	DAUX
	80 IF (NQ.EQ.0) GO TO 83	DAUX
C		DAUX
C	ELIMINATE QQ	DAUX
C		DAUX
	DO 82 K=1,NQ	DAUX
	IF (KQTYPE(K).LT.0) GO TO 82	DAUX
	N = KQ1(K)	DAUX

	M = KQ2(K)	DAUX
	DO 81 I=1,3	DAUX
	DO 81 J=1,3	DAUX
	SEGLA(I,N) = SEGLA(I,N) - A13(I,J,2*K-1)*RW(N) *QQ(J,K)	DAUX
	SEGLA(I,M) = SEGLA(I,M) - A13(I,J,2*K )*RW(M) *QQ(J,K)	DAUX
	WMEGD(I,N) = WMEGD(I,N) - A23(I,J,2*K-1)*RPHI(I,N)*QQ(J,K)	DAUX
81	WMEGD(I,M) = WMEGD(I,M) - A23(I,J,2*K )*RPHI(I,M)*QQ(J,K)	DAUX
82	CONTINUE	DAUX
83	IF (NFLX.EQ.0) GO TO 90	DAUX
C		DAUX
C	ELIMINATE V4 (TORQUES FOR FLEXIBLE SEGMENTS)	DAUX
C		DAUX
	DO 84 N=1,NFLX	DAUX
	N1 = NFLEX(1,N)	DAUX
	N2 = NFLEX(2,N)	DAUX
	N3 = NFLEX(3,N)	DAUX
	DO 84 I=1,3	DAUX
	DO 84 J=1,3	DAUX
	WMEGD(I,N1) = WMEGD(I,N1) - B42(J,I,3*N-2)*RPHI(I,N1)*V4(J,N)	DAUX
	WMEGD(I,N2) = WMEGD(I,N2) - B42(J,I,3*N-1)*RPHI(I,N2)*V4(J,N)	DAUX
84	WMEGD(I,N3) = WMEGD(I,N3) - B42(J,I,3*N )*RPHI(I,N3)*V4(J,N)	DAUX
90	DO 91 J=1,NGRND	DAUX
	DO 91 I=1,3	DAUX
	IF (DABS(WMEGD(I,J)).LE.EPS12) WMEGD(I,J) = 0.0	DAUX
91	IF (DABS(SEGLA(I,J)).LE.EPS12) SEGLA(I,J) = 0.0	DAUX
C		DAUX
C	OPTIONAL OUTPUT OF FUNCTIONS AND DERIVATIVES.	DAUX
C		DAUX
	IF (NPRT(9).NE.0) CALL PRINT(6H DAUX )	DAUX
C		DAUX
	CALL ELTIME(2,9)	DAUX
	RETURN	DAUX
	END	DAUX



	T1 = -V1(I,M)	SLIP
	DO 15 J = 1,3	DAUX11
	T1 = T1 + B12(I,J,2*M-1)*U2(J,N) + B12(I,J,2*M)*U2(J,M+1)	DAUX11
	* + A11(I,J,M)*(U1(J,N) - U1(J,M+1))	SLIP
	IF (J.LT.I) GO TO 15	DAUX11
	T2 = 0.0	DAUX11
	IF (J.EQ.I) T2 = RW(N) + RW(M+1)	DAUX11
	DO 14 K=1,3	DAUX11
14	T2 = T2 + B12(I,K,2*M-1)*RPHI(K,N) *B12(J,K,2*M-1)	DAUX11
	* + B12(I,K,2*M) *RPHI(K,M+1)*B12(J,K,2*M)	DAUX11
	C(I,J,IJ) = T2	DAUX11
	C(J,I,IJ) = T2	DAUX11
15	RHS(I,MQ) = T1	DAUX11
	IF (ISING(N).NE.0) GO TO 30	DAUX11
	L = 0	DAUX11
	IF (N.GT.1) L = IABS(JNT(N-1))	DAUX11
	IF (L.EQ.0) GO TO 18	DAUX11
C		DAUX11
C	IF (N > 1) AND (L = JNT(N-1) > 0)	DAUX11
C		DAUX11
C	SET C11(M,N-1) = -RW(N) + B12(M,N)PHI(N)'A21(N,N-1)	DAUX11
C		DAUX11
C	AND C11(N-1,M) = C(M,N-1)	DAUX11
C		DAUX11
	KJNT = NQ2S + N -1	DAUX11
	IJ = IJ+1	DAUX11
	IJK(MQ,KJNT) = IJ	DAUX11
	IJK(KJNT,MQ) = IJ+1	DAUX11
	DO 17 I=1,3	DAUX11
	DO 17 J=1,3	DAUX11
	C(I,J,IJ) = 0.0	DAUX11
	DO 16 K=1,3	DAUX11
16	C(I,J,IJ) = C(I,J,IJ) + B12(I,K,2*M-1)*RPHI(K,N)*B12(J,K,2*N-2)	DAUX11
	* - A11(I,K,M)*RW(N)*A11(J,K,N-1)	SLIP
17	C(J,I,IJ+1) = C(I,J,IJ)	DAUX11
	IJ = IJ+1	DAUX11
18	IF (M.EQ.NJNT) GO TO 30	DAUX11
	M1 = M+1	DAUX11
	DO 21 L=M1,NJNT	DAUX11
	IF (IABS(JNT(L)).NE.N) GO TO 21	DAUX11
C		DAUX11
C	IF (L > M) AND (JNT(L) = N)	DAUX11
C		DAUX11
C	SET C11(M,L) = RW(N) + B12(M,N)PHI(N)'A21(N,L)	DAUX11
C		DAUX11
C	AND C11(L,M) = C11(M,L)	DAUX11
C		DAUX11
C		DAUX11
	KJNT = NQ2S + L	DAUX11

IJ = IJ+1	DAUX11
IJK(MQ,KJNT) = IJ	DAUX11
IJK(KJNT,MQ) = IJ+1	DAUX11
DO 20 I=1,3	DAUX11
DO 20 J=1,3	DAUX11
C(I,J,IJ) = 0.0	DAUX11
DO 19 K=1,3	DAUX11
19 C(I,J,IJ) = C(I,J,IJ) + B12(I,K,2*M-1)*RPHI(K,N)*B12(J,K,2*L-1)	DAUX11
*	SLIP
+ A11(I,K,M)*RW(N)*A11(J,K,L)	DAUX11
20 C(J,I,IJ+1) = C(I,J,IJ)	DAUX11
IJ = IJ+1	DAUX11
21 CONTINUE	DAUX11
30 CONTINUE	DAUX11
CALL ELTIME(2,14)	DAUX11
RETURN	DAUX11
END	DAUX11

C  
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C

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SUBROUTINE DAUX12                                DAUX12
                                                REV IV 07/24/86SLIP
CALLED BY SUBROUTINE DAUX TO COMPUTE            DAUX12
                                                DAUX12
                                                -1
(C12) = (B12)(PHI) (A22)                        DAUX12
                                                DAUX12
                                                T
(C21) = (C12)                                  DAUX12
                                                DAUX12
IMPLICIT REAL*8(A-H,O-Z)                        DAUX12
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND, DAUX12
* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG     PAGE
COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60), SLIP
* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),      DAUX12
* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)    DAUX12
COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60), DAUX12
* F(3,30),TQ(3,30),WJ(30),A11(3,3,30)                SLIP
LOGICAL*1 FREE                                  SLIP
COMMON/TEMPVS/ C(3,3,600),RHS(3,54),IJK(54,54),IJ,NQ2S CHGIII
* ,DN(3,3),DM(3,3),SN(3,3),SM(3,3),HH(3,3),BN(3)    DAUX12
* ,IDUM(362),FREE(30)                               SLIP
CALL ELTIME(1,15)                               DAUX12
NQSJNT = NQ2S + NJNT                             DAUX12
DO 60 M=1,NJNT                                   DAUX12
N = IABS(JNT(M))                                 DAUX12
IF (N.EQ.0) GO TO 60                             DAUX12
MQ = NQ2S + M                                    DAUX12
IF (FREE(M)) GO TO 37                            SLIP
MJNT = NQSJNT + M                                DAUX12
IJ = IJ+1                                        DAUX12
IJK(MQ,MJNT) = IJ                                DAUX12
IJK(MJNT,MQ) = IJ+1                              DAUX12
DO 36 I=1,3                                       DAUX12
DO 36 J=1,3                                       DAUX12
SN(I,J) = 0.0                                     DAUX12
SM(I,J) = 0.0                                     DAUX12
DO 35 K=1,3                                       DAUX12
SN(I,J) = SN(I,J) + B12(I,K,2*M-1) * RPHI(K,N ) * A22(K,J,2*M-1) DAUX12
35 SM(I,J) = SM(I,J) + B12(I,K,2*M ) * RPHI(K,M+1) * A22(K,J,2*M ) DAUX12
C(I,J,IJ ) = SN(I,J) - SM(I,J)                   DAUX12
36 C(J,I,IJ+1) = C(I,J,IJ)                       DAUX12
IJ = IJ+1                                        DAUX12
37 IF (ISING(N).NE.0) GO TO 50                    DAUX12
IF (N.EQ.1) GO TO 43                              DAUX12
IF (FREE(N-1)) GO TO 43                           SLIP
MJNT = NQSJNT + N-1                               DAUX12
IJ = IJ+1                                        DAUX12
IJK(MQ,MJNT) = IJ                                DAUX12
IJK(MJNT,MQ) = IJ+1                              DAUX12

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DO 42 I=1,3	DAUX12
DO 42 J=1,3	DAUX12
SN(I,J) = 0.0	DAUX12
DO 41 K=1,3	DAUX12
41 SN(I,J) = SN(I,J) + B12(I,K,2*M-1) * RPHI(K,N ) * A22(K,J,2*N-2)	DAUX12
C(I,J,IJ ) = -SN(I,J)	DAUX12
42 C(J,I,IJ+1) = -SN(I,J)	DAUX12
IJ = IJ+1	DAUX12
43 DO 49 L=N,NJNT	DAUX12
IF (L.EQ.M) GO TO 49	DAUX12
IF (IABS(JNT(L)).NE.N ) GO TO 49	DAUX12
IF (FREE(L)) GO TO 49	SLIP
MJNT = NQSJNT + L	DAUX12
IJ = IJ+1	DAUX12
IJK(MQ,MJNT) = IJ	DAUX12
IJK(MJNT,MQ) = IJ+1	DAUX12
DO 48 I=1,3	DAUX12
DO 48 J=1,3	DAUX12
SN(I,J) = 0.0	DAUX12
DO 47 K=1,3	DAUX12
47 SN(I,J) = SN(I,J) + B12(I,K,2*M-1) * RPHI(K,N ) * A22(K,J,2*L-1)	DAUX12
C(I,J,IJ ) = SN(I,J)	DAUX12
48 C(J,I,IJ+1) = SN(I,J)	DAUX12
IJ = IJ +1	DAUX12
49 CONTINUE	DAUX12
50 IF (M.EQ.NJNT) GO TO 60	DAUX12
IF (ISING(M+1).NE.0) GO TO 60	DAUX12
M1 = M+1	DAUX12
DO 59 L=M1,NJNT	DAUX12
IF (IABS(JNT(L)).NE.M1) GO TO 59	DAUX12
IF (FREE(L)) GO TO 59	SLIP
MJNT = NQSJNT + L	DAUX12
IJ = IJ+1	DAUX12
IJK(MQ,MJNT) = IJ	DAUX12
IJK(MJNT,MQ) = IJ+1	DAUX12
DO 58 I=1,3	DAUX12
DO 58 J=1,3	DAUX12
SM(I,J) = 0.0	DAUX12
DO 57 K=1,3	DAUX12
57 SM(I,J) = SM(I,J) + B12(I,K,2*M ) * RPHI(K,M+1) * A22(K,J,2*L-1)	DAUX12
C(I,J,IJ ) = SM(I,J)	DAUX12
58 C(J,I,IJ+1) = SM(I,J)	DAUX12
IJ = IJ +1	DAUX12
59 CONTINUE	DAUX12
60 CONTINUE	DAUX12
CALL ELTIME(2,15)	DAUX12
RETURN	DAUX12
END	DAUX12

	SUBROUTINE DAUX22		DAUX22
C		REV IV	07/24/86SLIP
C	CALLED BY SUBROUTINE DAUX TO COMPUTE		DAUX22
C			DAUX22
C			DAUX22
C		-1	DAUX22
C	(C22) = (B22)(PHI) (A22) - (B24)		DAUX22
C			DAUX22
C		-1	DAUX22
C	(R2) = (B22)(PHI) (U2) - (V2)		DAUX22
C			DAUX22
	IMPLICIT REAL*8(A-H,O-Z)		DAUX22
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		DAUX22
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),MPG		PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		DAUX22
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		DAUX22
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		DAUX22
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		DAUX22
	COMMON/CMATRIX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),		DAUX22
*	F(3,30),TQ(3,30),WJ(30),A11(3,3,30)		SLIP
	COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30),		JDRIFT
*	FE(3,30),TQE(3,30),CONST(5,30)		JDRIFT
	LOGICAL*1 FREE		SLIP
	COMMON/TEMPVS/ C(3,3,600),RHS(3,54),IJK(54,54),IJ,NQ2S		CHGIII
*	,DN(3,3),DM(3,3),SN(3,3),SM(3,3),HH(3,3),BN(3)		DAUX22
*	,IDUM(362),FREE(30)		SLIP
	LOGICAL TEST		DAUX22
	CALL ELTIME(1,16)		DAUX22
	NQSJNT = NQ2S + NJNT		DAUX22
	DO 90 M=1,NJNT		DAUX22
	MJNT = NQSJNT + M		DAUX22
	DO 60 I=1,3		DAUX22
60	RHS(I,MJNT) = V2(I,M)		DAUX22
	N = IABS(JNT(M))		DAUX22
	IF (N.EQ.0) GO TO 90		DAUX22
	IF (FREE(M)) GO TO 90		SLIP
	IJ = IJ+1		DAUX22
	IJK(MJNT,MJNT) = IJ		DAUX22
	DO 61 J=1,3		DAUX22
	DO 61 I=1,3		DAUX22
61	HH(I,J) = 0.0		DAUX22
	LGO = IPIN(M)+8		SLIP
	TEST = .FALSE.		DAUX22
	GO TO (64,64,64,62,64,64,64,64,63,64,64,64,64,63,63),LGO		SLIP
62	IF (IEULER(M).GE.7) GO TO 64		DAUX22
	TEST = IEULER(M).LT.4		DAUX22
63	AN = 0.0		DAUX22
	DO 51 J=1,3		DAUX22
51	AN = AN + HB(J,2*M-1)**2 * RPHI(J,N)		DAUX22



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*          + HB(J,2*M )**2 * RPHI(J,M+1)                                DAUX22
  IF (TEST) GO TO 64                                                    DAUX22
  CALL DOT31 (D(1,1,N),HB(1,2*M-1),BN)                                DAUX22
  DO 53 J=1,3                                                            DAUX22
  DO 53 I=1,3                                                            DAUX22
53 HH(I,J) = AN*BN(I)*BN(J)                                            DAUX22
64 DO 67 I=1,3                                                            DAUX22
  RHS(I,MJNT) = -V2(I,M)                                               DAUX22
  DO 66 J=1,3                                                            DAUX22
  RHS(I,MJNT) = RHS(I,MJNT) + A22(J,I,2*M-1)*U2(J,N )              DAUX22
*          - A22(J,I,2*M )*U2(J,M+1)                                    DAUX22
  SN(I,J) = 0.0                                                         DAUX22
  IF (TEST) GO TO 66                                                    DAUX22
  DO 65 K=1,3                                                            DAUX22
65 SN(I,J) = SN(I,J) + A22(K,I,2*M-1) * RPHI(K,N ) * A22(K,J,2*M-1) DAUX22
*          + A22(K,I,2*M ) * RPHI(K,M+1) * A22(K,J,2*M )            DAUX22
66 C(I,J,IJ) = SN(I,J) + HH(I,J)                                       DAUX22
67 IF (TEST) C(I,I,IJ) = AN                                             DAUX22
  IF (ISING(N).NE.0) GO TO 90                                           DAUX22
  IF (N.EQ.1) GO TO 80                                                   DAUX22
  IF (FREE(N-1)) GO TO 80                                               SLIP
  N1JNT = NQSJNT + N -1                                                DAUX22
  IJ = IJ+1                                                             DAUX22
  IJK(MJNT,N1JNT) = IJ                                                  DAUX22
  IJK(N1JNT,MJNT) = IJ+1                                               DAUX22
  DO 77 I=1,3                                                            DAUX22
  DO 77 J=1,3                                                            DAUX22
  SN(I,J) = 0.0                                                         DAUX22
  DO 76 K=1,3                                                            DAUX22
76 SN(I,J) = SN(I,J) + A22(K,I,2*M-1) * RPHI(K,N ) * A22(K,J,2*N-2) DAUX22
  C(I,J,IJ) = -SN(I,J)                                                 DAUX22
77 C(J,I,IJ+1) = -SN(I,J)                                             DAUX22
  IJ = IJ+1                                                             DAUX22
80 IF (M.EQ.NJNT) GO TO 90                                             DAUX22
  M1 = M+1                                                              DAUX22
  DO 88 L=M1,NJNT                                                       DAUX22
  IF (IABS(JNT(L)).NE.N) GO TO 88                                       DAUX22
  IF (FREE(L)) GO TO 88                                               SLIP
  LJNT = NQSJNT + L                                                    DAUX22
  IJ = IJ+1                                                             DAUX22
  IJK(MJNT,LJNT) = IJ                                                  DAUX22
  IJK(LJNT,MJNT) = IJ+1                                               DAUX22
  DO 87 I=1,3                                                            DAUX22
  DO 87 J=1,3                                                            DAUX22
  SN(I,J) = 0.0                                                         DAUX22
  DO 86 K=1,3                                                            DAUX22
86 SN(I,J) = SN(I,J) + A22(K,I,2*M-1) * RPHI(K,N ) * A22(K,J,2*L-1) DAUX22
  C(I,J,IJ) = SN(I,J)                                                 DAUX22
87 C(J,I,IJ+1) = SN(I,J)                                             DAUX22
  IJ = IJ+1                                                             DAUX22

```

88 CONTINUE  
90 CONTINUE  
CALL ELTIME(2,16)  
RETURN  
END

DAUX22  
DAUX22  
DAUX22  
DAUX22  
DAUX22

	SUBROUTINE DAUX31		DAUX31
C		REV IV	07/24/86SLIP
C	CALL BY SUBROUTINE DAUX TO COMPUTE		DAUX31
C			DAUX31
C			DAUX31
C	(C13) = (B11)(M) (A13) + (B12)(PHI) (A23)		DAUX31
C			DAUX31
C	(C31) = (B31)(M) (A11) + (B32)(PHI) (A21)		DAUX31
C			DAUX31
	IMPLICIT REAL*8 (A-H,O-Z)		DAUX31
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		DAUX31
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		DAUX31
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		DAUX31
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),		DAUX31
*	F(3,30),TQ(3,30),WJ(30),A11(3,3,30)		SLIP
	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),		DAUX31
*	HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),		DAUX31
*	RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),		DAUX31
*	KQ1(12),KQ2(12),KQTYPE(12)		DAUX31
	COMMON/TEMPVS/ C(3,3,600),RHS(3,54),IJK(54,54),IJ,NQ2S		CHGIII
	CALL ELTIME(1,17)		DAUX31
	DO 30 N=1,NQ		DAUX31
	IF (KQTYPE(N).LT.0) GO TO 30		DAUX31
	K1 = KQ1(N)		DAUX31
	K2 = KQ2(N)		DAUX31
	NNS = NQ2S - NQ + N		DAUX31
	IF (K1.LE.1) GO TO 13		DAUX31
	IF (IABS(JNT(K1-1)).EQ.0) GO TO 13		DAUX31
	IF (ISING(K1).NE.0) GO TO 13		DAUX31
C			DAUX31
C			DAUX31
C	C13(K1-1,N) = B11(K1-1,K1)M (K1)A13(K1,N)		DAUX31
C			DAUX31
C	+ B12(K1-1,K1)PHI (K1)A23(K1,N)		DAUX31
C			DAUX31
C			DAUX31
C	C31(N,K1-1) = B31(N,K1)M (K1)A11(K1,K1-1)		DAUX31
C			DAUX31
C	+ B32(N,K1)PHI (K1)A21(K1,K1-1)		DAUX31
C			DAUX31
	MQ = NQ2S + K1 - 1		DAUX31
	IJ = IJ+1		DAUX31
	IJK(MQ,NNS) = IJ		DAUX31
	IJK(NNS,MQ) = IJ+1		DAUX31
	DO 12 I=1,3		DAUX31
	DO 12 J=1,3		DAUX31
	SUM = 0.0		SLIP





C(I,J,IJ ) = 0.0	DAUX31
22 C(I,J,IJ+1) = 0.0	DAUX31
IJ = IJ+1	DAUX31
23 JJ = IJK(MQ,NNS)	DAUX31
DO 25 I=1,3	DAUX31
DO 25 J=1,3	DAUX31
SUM = C(I,J,JJ)	SLIP
TUM = C(I,J,JJ+1)	SLIP
DO 24 K=1,3	DAUX31
SUM = SUM + B12(I,K,2*L-1)*RPHI(K,K2)*A23(K,J,2*N )	DAUX31
*          + A11(I,K,L)*RW(K2)*A13(K,J,2*N)	SLIP
24 TUM = TUM + B32(I,K,2*N )*RPHI(K,K2)*B12(J,K,2*L-1)	DAUX31
*          + B31(I,K,2*N)*RW(K2)*A11(J,K,L)	SLIP
C(I,J,JJ) = SUM	DAUX31
25 C(I,J,JJ+1) = TUM	DAUX31
26 CONTINUE	DAUX31
30 CONTINUE	DAUX31
CALL ELTIME(2,17)	DAUX31
RETURN	DAUX31
END	DAUX31

	SUBROUTINE DAUX32		DAUX32
		REV IV	07/24/86SLIP
C	CALLLED BY SUBROUTINE DAUX TO COMPUTE		DAUX32
C			DAUX32
C			DAUX32
C	(C23) = (B22)(PHI) (A23)		DAUX32
C			DAUX32
C			DAUX32
C	(C32) = (B32)(PHI) (A22)		DAUX32
C			DAUX32
	IMPLICIT REAL*8 (A-H,O-Z)		DAUX32
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		DAUX32
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		DAUX32
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		DAUX32
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),		DAUX32
*	F(3,30),TQ(3,30),WJ(30),A11(3,3,30)		SLIP
	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),		DAUX32
*	HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),		DAUX32
*	RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),		DAUX32
*	KQ1(12),KQ2(12),KQTYPE(12)		DAUX32
	LOGICAL*1 FREE		SLIP
	COMMON/TEMPVS/ C(3,3,600),RHS(3,54),IJK(54,54),IJ,NQ2S		CHGIII
*	,DN(3,3),DM(3,3),BN(3),IDUM(416),FREE(30)		SLIP
	CALL ELTIME(1,18)		DAUX32
	NQSJNT = NQ2S + NJNT		DAUX32
	DO 60 N=1,NQ		DAUX32
	IF (KQTYPE(N).LT.0) GO TO 60		DAUX32
	K1 = KQ1(N)		DAUX32
	K2 = KQ2(N)		DAUX32
	NNS = NQ2S - NQ + N		DAUX32
	IF (K1.LE.1) GO TO 43		DAUX32
	IF (IABS(JNT(K1-1)).EQ.0) GO TO 43		DAUX32
	IF (FREE(K1-1)) GO TO 43		SLIP
	IF (ISING(K1).NE.0) GO TO 43		DAUX32
C			DAUX32
C			DAUX32
C			DAUX32
C	C23(K1-1,N) = B22(K1-1,K1)PHI (K1)A23(K1,N)		DAUX32
C			DAUX32
C			DAUX32
C	C32(N,K1-1) = B32(N,K1)PHI (K1)A22(K1,K1-1)		DAUX32
C			DAUX32
	KJNT = NQSJNT + K1 - 1		DAUX32
	IJ = IJ+1		DAUX32
	IJK(KJNT,NNS) = IJ		DAUX32
	IJK(NNS,KJNT) = IJ+1		DAUX32
	DO 42 I=1,3		DAUX32
	DO 42 J=1,3		DAUX32
	SUM = 0.0		DAUX32







**RETURN  
END**

**DAUX32  
DAUX32**

```

SUBROUTINE DAUX33                                DAUX33
                                                REV IV 07/24/86SLIP
CALLED BY SUBROUTINE DAUX TO COMPUTE           DAUX33
                                                DAUX33
                                                DAUX33
      -1 -1
(C33) = (B31)(M) (A13) + (B32)(PHI) (A23) - (B35) DAUX33
                                                DAUX33
      -1 -1
(B3) = (B31)(M) (U1) + (B32)(PHI) (U2) - (V3) DAUX33
                                                DAUX33
IMPLICIT REAL*8 (A-H,O-Z)                       DAUX33
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND, DAUX33
* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG PAGE
COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30), DAUX33
* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30) DAUX33
COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60), SLIP
* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90), DAUX33
* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30) DAUX33
COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60), DAUX33
* F(3,30),TQ(3,30),WJ(30),A11(3,3,30) SLIP
COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24), DAUX33
* HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12), DAUX33
* RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12), DAUX33
* KQ1(12),KQ2(12),KQTYPE(12) DAUX33
COMMON/TEMPVS/ C(3,3,600),RHS(3,54),IJK(54,54),IJ,NQ2S CHGII
CALL ELTIME(1,19) DAUX33
DO 90 N=1,NQ DAUX33
IF (KQTYPE(N).LT.0) GO TO 90 DAUX33
K1 = KQ1(N) DAUX33
K2 = KQ2(N) DAUX33
NNS = NQ2S - NQ + N DAUX33
C
C
      -1 -1
RHS(N) = B31(N,K1)M (K1)U1(K1) + B32(N,K1)PHI (K1)U2(K1) DAUX33
      -1 -1
      + B31(N,K2)M (K2)U1(K2) + B32(N,K2)PHI (K2)U2(K2) DAUX33
      - V3(N) DAUX33
C
DO 63 I=1,3 DAUX33
SUM = 0.0 DAUX33
DO 62 K=1,3 DAUX33
62 SUM = SUM + B31(I,K,2*N-1)*U1(K,K1) + B32(I,K,2*N-1)*U2(K,K1) DAUX33
* + B31(I,K,2*N)*U1(K,K2) + B32(I,K,2*N)*U2(K,K2) DAUX33
63 RHS(I,NNS) = SUM - V3(I,N) DAUX33
C
C
      -1 -1
C33(N,N) = B31(N,K1)M (K1)A13(K1,N) + B32(N,K1)PHI (K1)A23(K1,N) DAUX33
      -1 -1
      + B31(N,K2)M (K2)A13(K2,N) + B32(N,K2)PHI (K2)A23(K2,N) DAUX33

```

C			DAUX33
C		- B35(N,N)	DAUX33
C			DAUX33
		IJ = IJ+1	DAUX33
		IJK(NNS,NNS) = IJ	DAUX33
		IF (KQTYPE(N).EQ.2) GO TO 51	DAUX33
		IF (KQTYPE(N).EQ.4) GO TO 51	DAUX33
		DO 65 I=1,3	DAUX33
		DO 65 J=1,3	DAUX33
		SUM = -HRT(I,J,N)	DAUX33
		IF (I.EQ.J) SUM = 1.0+SUM	DAUX33
		DO 64 K=1,3	DAUX33
	64	SUM = SUM + B31(I,K,2*N-1)* RW( K1)*A13(K,J,2*N-1)	DAUX33
		* + B31(I,K,2*N )* RW( K2)*A13(K,J,2*N )	DAUX33
		* + B32(I,K,2*N-1)*RPHI(K,K1)*A23(K,J,2*N-1)	DAUX33
		* + B32(I,K,2*N )*RPHI(K,K2)*A23(K,J,2*N )	DAUX33
	65	C(I,J,IJ) = SUM	DAUX33
		GO TO 59	DAUX33
C			DAUX33
C		FOR KQTYPE = 2 OR 4, SET C33(N,N) = B*I	DAUX33
C		WHERE B = SUM OF DIAGONAL ELEMENTS OF	DAUX33
C		-1 -1	DAUX33
C		(B31)(M) (A13) + (B32)(PHI) (A23)	DAUX33
C			DAUX33
	51	SUM = 0.0	DAUX33
		DO 55 I=1,3	DAUX33
		DO 55 K=1,3	DAUX33
	55	SUM = SUM + B31(I,K,2*N-1)* RW( K1)*A13(K,I,2*N-1)	DAUX33
		* + B31(I,K,2*N )* RW( K2)*A13(K,I,2*N )	DAUX33
		* + B32(I,K,2*N-1)*RPHI(K,K1)*A23(K,I,2*N-1)	DAUX33
		* + B32(I,K,2*N )*RPHI(K,K2)*A23(K,I,2*N )	DAUX33
		DO 57 I=1,3	DAUX33
		DO 56 J=1,3	DAUX33
	56	C(I,J,IJ) = 0.0	DAUX33
	57	C(I,I,IJ) = SUM	DAUX33
	59	IF (N.EQ.NQ) GO TO 90	DAUX33
		N1 = N+1	DAUX33
		DO 85 M=N1,NQ	DAUX33
		IF (KQTYPE(M).LT.0) GO TO 85	DAUX33
		MNS = NQ2S - NQ + M	DAUX33
		IF (ISING(K1).NE.0) GO TO 75	DAUX33
		IF (K1.NE.KQ1(M)) GO TO 70	DAUX33
		IF (IJK(MNS,NNS).NE.0) GO TO 67	DAUX33
C			DAUX33
C		FOR ANY M>N SUCH THAT K1(N) = K1(M)	DAUX33
C			DAUX33
C			DAUX33
C		-1	DAUX33
C		C33(N,M) = C(N,M) + B31(N,K1) M (K1)A13(K1,M)	DAUX33
C		-1	DAUX33
C		+ B32(N,K1)PHI (K1)A23(K1,M)	DAUX33

C				DAUX33
C				DAUX33
C			-1	DAUX33
C		C33(M,N) = C(M,N) + B31(M,K1)	M (K1)A13(K1,N)	DAUX33
C			-1	DAUX33
C			+ B32(M,K1)PHI (K1)A23(K1,N)	DAUX33
C				DAUX33
		IJ = IJ+1		DAUX33
		IJK(MNS,NNS) = IJ		DAUX33
		IJK(NNS,MNS) = IJ+1		DAUX33
		DO 66 J=1,3		DAUX33
		DO 66 I=1,3		DAUX33
		C(I,J,IJ) = 0.0		DAUX33
66		C(I,J,IJ+1) = 0.0		DAUX33
		IJ = IJ+1		DAUX33
67		JJ = IJK(MNS,NNS)		DAUX33
		DO 69 I=1,3		DAUX33
		DO 69 J=1,3		DAUX33
		SUM = C(I,J,JJ)		DAUX33
		TUM = C(I,J,JJ+1)		DAUX33
		DO 68 K=1,3		DAUX33
		SUM = SUM + B31(I,K,2*N-1)* RW( K1)*A13(K,J,2*M-1)		DAUX33
		* + B32(I,K,2*N-1)*RPHI(K,K1)*A23(K,J,2*M-1)		DAUX33
68		TUM = TUM + B31(I,K,2*M-1)* RW( K1)*A13(K,J,2*N-1)		DAUX33
		* + B32(I,K,2*M-1)*RPHI(K,K1)*A23(K,J,2*N-1)		DAUX33
		C(I,J,JJ) = SUM		DAUX33
69		C(I,J,JJ+1) = TUM		DAUX33
70		IF (K1.NE.KQ2(M)) GO TO 75		DAUX33
		IF (IJK(MNS,NNS).NE.0) GO TO 72		DAUX33
C				DAUX33
C		FOR ANY M>N SUCH THAT K1(N) = K2(M)		DAUX33
C				DAUX33
C			-1	DAUX33
C		C33(N,M) = C(N,M) + B31(N,K1)	M (K1)A13(K2,M)	DAUX33
C			-1	DAUX33
C			+ B32(N,K1)PHI (K1)A23(K2,M)	DAUX33
C				DAUX33
C			-1	DAUX33
C		C33(M,N) = C(M,N) + B31(M,K2)	M (K1)A13(K1,N)	DAUX33
C			-1	DAUX33
C			+ B32(M,K2)PHI (K1)A23(K1,N)	DAUX33
C				DAUX33
		IJ = IJ+1		DAUX33
		IJK(MNS,NNS) = IJ		DAUX33
		IJK(NNS,MNS) = IJ+1		DAUX33
		DO 71 J=1,3		DAUX33
		DO 71 I=1,3		DAUX33
		C(I,J,IJ) = 0.0		DAUX33
71		C(I,J,IJ+1) = 0.0		DAUX33
		IJ = IJ+1		DAUX33
72		JJ = IJK(MNS,NNS)		DAUX33



C	FOR ANY M>N SUCH THAT K2(N) = K2(M)	DAUX33
C		DAUX33
C		DAUX33
C	C33(N,M) = C(N,M) + B31(N,K2) M <sup>-1</sup> (K2)A13(K2,M)	DAUX33
C		DAUX33
C	+ B32(N,K2)PHI <sup>-1</sup> (K2)A23(K2,M)	DAUX33
C		DAUX33
C	C33(M,N) = C(M,N) + B31(M,K2) M <sup>-1</sup> (K2)A13(K2,N)	DAUX33
C		DAUX33
C	+ B32(M,K2)PHI <sup>-1</sup> (K2)A23(K2,N)	DAUX33
C		DAUX33
	IJ = IJ+1	DAUX33
	IJK(MNS,NNS) = IJ	DAUX33
	IJK(NNS,MNS) = IJ+1	DAUX33
	DO 81 J=1,3	DAUX33
	DO 81 I=1,3	DAUX33
	C(I,J,IJ) = 0.0	DAUX33
81	C(I,J,IJ+1) = 0.0	DAUX33
	IJ = IJ+1	DAUX33
82	JJ = IJK(MNS,NNS)	DAUX33
	DO 84 I=1,3	DAUX33
	DO 84 J=1,3	DAUX33
	SUM = C(I,J,JJ)	DAUX33
	TUM = C(I,J,JJ+1)	DAUX33
	DO 83 K=1,3	DAUX33
	SUM = SUM + B31(I,K,2*N) * RW(K2)*A13(K,J,2*M)	DAUX33
	* + B32(I,K,2*N) *RPHI(K,K2)*A23(K,J,2*M)	DAUX33
83	TUM = TUM + B31(I,K,2*M) * RW(K2)*A13(K,J,2*N)	DAUX33
	* + B32(I,K,2*M) *RPHI(K,K2)*A23(K,J,2*N)	DAUX33
	C(I,J,JJ) = SUM	DAUX33
84	C(I,J,JJ+1) = TUM	DAUX33
85	CONTINUE	DAUX33
90	CONTINUE	DAUX33
	CALL ELTIME(2,19)	DAUX33
	RETURN	DAUX33
	END	DAUX33

	SUBROUTINE DAUX44		DAUX44
C		REV IV 07/24/86	SLIP
	IMPLICIT REAL*8(A-H,O-Z)		DAUX44
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		DAUX44
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		DAUX44
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		DAUX44
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		DAUX44
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		DAUX44
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),		DAUX44
*	F(3,30),TQ(3,30),WJ(30),A11(3,3,30)		SLIP
	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),		DAUX44
*	HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),		DAUX44
*	RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),		DAUX44
*	KQ1(12),KQ2(12),KQTYPE(12)		DAUX44
	COMMON/FLXBLE/ HF(4,12,8),B42(3,3,24),V4(3,8),NFLEX(3,8)		DAUX44
	LOGICAL*1 FREE		SLIP
	COMMON/TEMPVS/ C(3,3,600),RHS(3,54),IJK(54,54),IJ,NQ2S		CHGII
*	,IDUM(458),FREE(30)		SLIP
	IF (NFLX.EQ.0) GO TO 99		DAUX44
	CALL ELTIME(1,33)		DAUX44
	DO 90 L=1,NFLX		DAUX44
	N1 = NFLEX(1,L)		DAUX44
	N2 = NFLEX(2,L)		DAUX44
	N3 = NFLEX(3,L)		DAUX44
	IJ = IJ+1		DAUX44
	DO 10 I=1,3		DAUX44
	DO 10 J=1,3		DAUX44
	C(I,J,IJ) = 0.0		DAUX44
	DO 10 K=1,3		DAUX44
10	C(I,J,IJ) = C(I,J,IJ) + B42(I,K,3*L-2)*RPHI(K,N1)*B42(J,K,3*L-2)		DAUX44
*	+ B42(I,K,3*L-1)*RPHI(K,N2)*B42(J,K,3*L-1)		DAUX44
*	+ B42(I,K,3*L )*RPHI(K,N3)*B42(J,K,3*L )		DAUX44
	NSL = 2*NS+L		DAUX44
	IJK(NSL,NSL) = IJ		DAUX44
	DO 20 I=1,3		DAUX44
	RHS(I,NSL) = -V4(I,L)		DAUX44
	DO 20 J=1,3		DAUX44
20	RHS(I,NSL) = RHS(I,NSL) + B42(I,J,3*L-2)*U2(I,N1)		DAUX44
*	+ B42(I,J,3*L-1)*U2(I,N2)		DAUX44
*	+ B42(I,J,3*L )*U2(I,N3)		DAUX44
	IF (L.EQ.NFLX) GO TO 30		DAUX44
	LP1 = L+1		DAUX44
	DO 29 M=LP1,NFLX		DAUX44
	DO 28 II=1,3,2		DAUX44
	IL = NFLEX(II,L)		DAUX44
	IF (ISING(IL).NE.0) GO TO 28		DAUX44
	DO 27 JJ=1,3,2		DAUX44
	IF (NFLEX(II,L).NE.NFLEX(JJ,M)) GO TO 27		DAUX44



NSM = 2*NS+M	DAUX44
JK = IJK(NSL,NSM)	DAUX44
KJ = IJK(NSM,NSL)	DAUX44
IF (JK.GT.0) GO TO 22	DAUX44
IJK(NSL,NSM) = IJ+1	DAUX44
IJK(NSM,NSL) = IJ+2	DAUX44
JK = IJ+1	DAUX44
KJ = IJ+2	DAUX44
IJ = IJ+2	DAUX44
DO 21 I=1,3	DAUX44
DO 21 J=1,3	DAUX44
21 C(I,J,JK) = 0.0	DAUX44
22 LI = 3*L+II-3	DAUX44
MJ = 3*M+JJ-3	DAUX44
DO 24 I=1,3	DAUX44
DO 24 J=1,3	DAUX44
DO 23 K=1,3	DAUX44
23 C(I,J,JK) = C(I,J,JK) + B42(I,K,LI)*RPHI(K,IL)*B42(J,K,MJ)	DAUX44
24 C(J,I,KJ) = C(I,J,JK)	DAUX44
27 CONTINUE	DAUX44
28 CONTINUE	DAUX44
29 CONTINUE	DAUX44
30 IF (NQ.EQ.0) GO TO 40	DAUX44
DO 39 M=1,NQ	DAUX44
IF (KQTYPE(M).LT.0) GO TO 39	DAUX44
DO 38 II=1,3	DAUX44
LM = 0	DAUX44
IF (NFLEX(II,L).EQ.KQ1(M)) LM = 2*M-1	DAUX44
IF (NFLEX(II,L).EQ.KQ2(M)) LM = 2*M	DAUX44
IF (LM.EQ.0) GO TO 38	DAUX44
IL = NFLEX(II,L)	DAUX44
IF (ISING(IL).NE.0) GO TO 38	DAUX44
NSM = 2*NS+NFLX+M	DAUX44
JK = IJK(NSL,NSM)	DAUX44
KJ = IJK(NSM,NSL)	DAUX44
IF (JK.GT.0) GO TO 32	DAUX44
IJK(NSL,NSM) = IJ+1	DAUX44
IJK(NSM,NSL) = IJ+2	DAUX44
JK = IJ+1	DAUX44
KJ = IJ+2	DAUX44
IJ = IJ+2	DAUX44
DO 31 I=1,3	DAUX44
DO 31 J=1,3	DAUX44
C(I,J,JK) = 0.0	DAUX44
31 C(I,J,KJ) = 0.0	DAUX44
32 LI = 3*L+II-3	DAUX44
DO 33 I=1,3	DAUX44
DO 33 J=1,3	DAUX44
DO 33 K=1,3	DAUX44
C(I,J,JK) = C(I,J,JK) + B42(I,K,LI)*RPHI(K,IL)*A23(K,J,LM)	DAUX44

33	C(I,J,KJ) = C(I,J,KJ) + B32(I,K,LM)*RPHI(K,IL)*B42(J,K,LI)	DAUX44
38	CONTINUE	DAUX44
39	CONTINUE	DAUX44
40	IF (NJNT.EQ.0) GO TO 90	DAUX44
	DO 59 M=1,NJNT	DAUX44
	IF (JNT(M).EQ.0) GO TO 59	DAUX44
	DO 58 II=1,3	DAUX44
	LM = 0	DAUX44
	IF (NFLEX(II,L).EQ.IABS(JNT(M))) LM = 2*M-1	DAUX44
	IF (NFLEX(II,L).EQ.M+1) LM = 2*M	DAUX44
	IF (LM.EQ.0) GO TO 58	DAUX44
	IL = NFLEX(II,L)	DAUX44
	IF (ISING(IL).NE.0) GO TO 58	DAUX44
	NSM = 2*NS+NFLX+NQ+M	DAUX44
	JK = IJK(NSL,NSM)	DAUX44
	KJ = IJK(NSM,NSL)	DAUX44
	IF (JK.GT.0) GO TO 42	DAUX44
	IJK(NSL,NSM) = IJ+1	DAUX44
	IJK(NSM,NSL) = IJ+2	DAUX44
	JK = IJ+1	DAUX44
	KJ = IJ+2	DAUX44
	IJ = IJ+2	DAUX44
	DO 41 I=1,3	DAUX44
	DO 41 J=1,3	DAUX44
41	C(I,J,JK) = 0.0	DAUX44
42	LI = 3*L+II-3	DAUX44
	DO 44 I=1,3	DAUX44
	DO 44 J=1,3	DAUX44
	DO 43 K=1,3	DAUX44
43	C(I,J,JK) = C(I,J,JK) + B42(I,K,LI)*RPHI(K,IL)*B12(J,K,LM)	DAUX44
44	C(J,I,KJ) = C(I,J,JK)	DAUX44
	IF (FREE(M)) GO TO 58	SLIP
	NSM = 2*NS+NFLX+NQ+NJNT+M	DAUX44
	JK = IJK(NSL,NSM)	DAUX44
	KJ = IJK(NSM,NSL)	DAUX44
	IF (JK.GT.0) GO TO 52	DAUX44
	IJK(NSL,NSM) = IJ+1	DAUX44
	IJK(NSM,NSL) = IJ+2	DAUX44
	JK = IJ+1	DAUX44
	KJ = IJ+2	DAUX44
	IJ = IJ+2	DAUX44
	DO 51 I=1,3	DAUX44
	DO 51 J=1,3	DAUX44
51	C(I,J,JK) = 0.0	DAUX44
52	SET = 1.0	DAUX44
	IF (IL.EQ.M+1) SET = -1.0	DAUX44
	DO 54 I=1,3	DAUX44
	DO 54 J=1,3	DAUX44
	DO 53 K=1,3	DAUX44
53	C(I,J,JK) = C(I,J,JK) + SET*B42(I,K,LI)*RPHI(K,IL)*A22(K,J,LM)	DAUX44

54	C(J,I,KJ) = C(I,J,JK)	DAUX44
58	CONTINUE	DAUX44
59	CONTINUE	DAUX44
90	CONTINUE	DAUX44
	CALL ELTIME(2,33)	DAUX44
99	RETURN	DAUX44
	END	DAUX44

## SUBROUTINE DAUX55

REV IV 07/24/86SLIP

```

C
IMPLICIT REAL*8(A-H,O-Z)
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,
* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG
COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),
* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)
COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),
* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),
* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)
COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),
* F(3,30),TQ(3,30),WJ(30),A11(3,3,30)
COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),
* HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),
* RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),
* KQ1(12),KQ2(12),KQTYPE(12)
COMMON/FLXBLE/ HF(4,12,8),B42(3,3,24),V4(3,8),NFLEX(3,8)
COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),
* UNITL,UNITM,UNITT,GRAVTY(3),TWOPI
LOGICAL*1 FREE
COMMON/TEMPVS/ C(3,3,600),RHS(3,54),IJK(54,54),IJ,NQ2S
* ,IDUM(458),FREE(30)
CALL ELTIME(1,30)
IS = 0
DO 99 I=1,NGRND
IF (ISING(I).LE.0) GO TO 99
IS = IS+1
IJ = IJ+1
IJK(IS ,IS ) = IJ
IJK(IS+1,IS+1) = IJ+1
DO 11 J=1,3
RHS(J,IS ) = U1(J,I) + W(I)*GRAVTY(J)/G
RHS(J,IS+1) = U2(J,I)
U1(J,I) = 0.0
U2(J,I) = 0.0
DO 10 K=1,3
C(J,K,IJ ) = 0.0
10 C(J,K,IJ+1) = 0.0
C(J,J,IJ ) = W(I)/G
11 C(J,J,IJ+1) = PHI(J,I)
IJ = IJ+1
IF (NFLX.EQ.0) GO TO 19
DO 15 N=1,NFLX
LN = 0
IF (NFLEX(1,N).EQ.I) LN = 3*N-2
IF (NFLEX(2,N).EQ.I) LN = 3*N-1
IF (NFLEX(3,N).EQ.I) LN = 3*N
IF (LN.EQ.0) GO TO 15
DO 14 J=1,3
DO 14 K=1,3

```

	C(J,K,IJ+1) = B42(K,J,LN)	DAUX55
14	C(J,K,IJ+2) = B42(J,K,LN)	SLIP
	NNS = 2*NS+N	DAUX55
	IJK(IS+1,NNS) = IJ+1	DAUX55
	IJK(NNS,IS+1) = IJ+2	DAUX55
	IJ = IJ+2	DAUX55
15	CONTINUE	DAUX55
19	IF (NQ.EQ.0) GO TO 30	DAUX55
	DO 25 N=1,NQ	DAUX55
	IF (KQTYPE(N).LT.0) GO TO 25	DAUX55
	LN = 0	DAUX55
	IF (I.EQ.KQ1(N)) LN = 2*N-1	DAUX55
	IF (I.EQ.KQ2(N)) LN = 2*N	DAUX55
	IF (LN.EQ.0) GO TO 25	DAUX55
	DO 20 J=1,3	DAUX55
	DO 20 K=1,3	DAUX55
	C(J,K,IJ+1) = A13(J,K,LN)	DAUX55
	C(J,K,IJ+2) = A23(J,K,LN)	DAUX55
	C(J,K,IJ+3) = B31(J,K,LN)	DAUX55
20	C(J,K,IJ+4) = B32(J,K,LN)	SLIP
	NNS = 2*NS+NFLX+N	SLIP
	IJK(IS ,NNS) = IJ+1	DAUX55
	IJK(IS+1,NNS) = IJ+2	DAUX55
	IJK(NNS,IS ) = IJ+3	DAUX55
	IJK(NNS,IS+1) = IJ+4	DAUX55
	IJ = IJ+4	DAUX55
25	CONTINUE	DAUX55
30	IF (NJNT.EQ.0) GO TO 98	DAUX55
	DO 65 N=1,NJNT	DAUX55
	IF (JNT(N).EQ.0) GO TO 65	DAUX55
	LN = 0	DAUX55
	IF (I.EQ.IABS(JNT(N))) LN = 2*N-1	DAUX55
	IF (I.EQ.N+1) LN = 2*N	DAUX55
	IF (LN.EQ.0) GO TO 65	DAUX55
	SET = 1.0	DAUX55
	IF (I.EQ.N+1) SET = -1.0	DAUX55
	DO 40 J=1,3	DAUX55
	DO 40 K=1,3	DAUX55
	C(J,K,IJ+1) = SET*A11(J,K,N)	SLIP
	C(J,K,IJ+3) = SET*A11(K,J,N)	SLIP
	C(J,K,IJ+2) = B12(K,J,LN)	SLIP
40	C(J,J,IJ+4) = B12(J,K,LN)	DAUX55
	NNS = NQ2S + N	SLIP
	IJK(IS ,NNS) = IJ+1	DAUX55
	IJK(IS+1,NNS) = IJ+2	DAUX55
	IJK(NNS,IS ) = IJ+3	DAUX55
	IJK(NNS,IS+1) = IJ+4	DAUX55
	IJ = IJ+4	DAUX55
	IF (FREE(N)) GO TO 65	SLIP
	DO 60 J=1,3	DAUX55

```
DO 60 K=1,3
C(J,K,IJ+1) = SET*A22(J,K,LN)
60 C(J,K,IJ+2) = SET*A22(K,J,LN)
NNS = NQ2S + NJMT + N
IJK(IS+1,NNS) = IJ+1
IJK(NNS,IS+1) = IJ+2
IJ = IJ+2
65 CONTINUE
98 IS = IS+1
99 CONTINUE
CALL ELTIME(2,30)
RETURN
END
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DAUX55
DAUX55
SLIP
DAUX55
DAUX55
DAUX55
DAUX55
DAUX55
DAUX55
DAUX55
DAUX55
DAUX55
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	SUBROUTINE DHPIN(DD,BN,L,M,N)		DHPIN
C		REV IV 07/24/86	SLIP
C	SETS DD = D(L) IF JOINT M IS NOT PINNED		DHPIN
C	OR DD = (I-HH.) (D(L)) IF PINNED		DHPIN
C			DHPIN
	IMPLICIT REAL*8 (A-H,O-Z)		DHPIN
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30)		DHPIN
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		DHPIN
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60)		SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90)		DHPIN
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		DHPIN
	COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30)		JDRIFT
*	FE(3,30),TQE(3,30),CONST(5,30)		JDRIFT
	DIMENSION DD(3,3),BN(3)		DHPIN
	DO 10 J=1,3		DHPIN
	BN(J) = 0.0		DHPIN
	DO 10 I=1,3		DHPIN
10	DD(I,J) = D(I,J,L)		DHPIN
	LGO = IPIN(M)+8		SLIP
	TSIGN = -1.0		DHPIN
	GO TO (90,90,90,20,90,90,90,90,30,90,90,90,90,30,30),LGO		SLIP
20	IF (IEULER(M).GE.7) GO TO 90		DHPIN
	IF (IEULER(M).GE.4) GO TO 30		DHPIN
	TSIGN = 1.0		DHPIN
	DO 21 J=1,3		DHPIN
	DO 21 I=1,3		DHPIN
21	DD(I,J) = 0.0		DHPIN
30	DO 31 J=1,3		DHPIN
	BN(J) = HB(1,N)*D(1,J,L) + HB(2,N)*D(2,J,L) + HB(3,N)*D(3,J,L)		DHPIN
	DO 31 I=1,3		DHPIN
31	DD(I,J) = DD(I,J) + TSIGN*BN(J)*HB(I,N)		DHPIN
90	RETURN		DHPIN
	END		DHPIN

```

SUBROUTINE DINT
C
C          REV IV      07/23/86TWOPI
IMPLICIT REAL*8 (A-H,O-Z)
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,
*          NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG
COMMON/INTEST/ SGTEST(3,4,30),KTEST(360 ),SEGT(120),REGT(120)
C
NOTE: KTEST SINGLY DIMENSIONED HERE.
REAL      SEGT
COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),
*          UNITL,UNITM,UNITT,GRAVTY(3),TWOPI
COMMON/CDINT/ UU(4),GH(3,4),
*          E(3,240),F(5,240),GG(5,240),Y(5,240),U(5,240),
*          H,HPRINT,HS,TPRINT,TSTART,ICNT,IDBL,IFLAG
COMMON/COMAIN/ VAR(240),DER(240),DT,HO,HMAX,HMIN,RSTIME,
*          ISTEP,NSTEPS,NDINT,NEQ,IRTSIN,IRSOUT
LOGICAL LNRT
CALL ELTIME(1,3)
IF (ISTEP.NE.0) GO TO 11
C
C          IN=0: INITIAL CALL TO INTEGRATOR - INITIALIZE AND RESET PARAMETERS
C          NOTE: FOR EARLIER VERSIONS OF CVS, THE VARIABLE 'IN' (ISTEP IN THE
C          CALLING PROGRAM) RAN FROM 1 TO NSTEPS+1, NOW IT RUNS FROM
C          0 TO NSTEPS.
C
TPRINT = TIME
IDBL = 2
K = 0
GO TO 13
C
C          IN=0: ADVANCE TPRINT - TIME TO RETURN TO CALLING PROGRAM.
C
11 TPRINT = TPRINT + DT
H = HPRINT
C
C          ENTRY TO ADVANCE INTEGRATOR
C
12 K = 1
CALL UPDATE(K)
C
C          NEGATIVE K FROM UPDATE IS INDICATOR TO RESET INTEGRATOR.
C
IF (K.EQ.1) GO TO 15
C
C          RESET OR INITIALIZE INTEGRATOR.
C
13 H = HO
HPRINT = HO
HS = 0.0
ICNT = -2
IF (ISTEP.EQ.0 .OR. NPRT(26).EQ.2) CALL OUTPUT(0)

```



	CALL PDAUX (VAR,DER,NEQ,K)	DINT
	IF (ISTEP.NE.0 .AND. NPRT(26).EQ.2) CALL OUTPUT(1)	DINT
	DO 14 I=1,NEQ	DINT
	F(1,I) = VAR(I)	DINT
	F(2,I) = DER(I)	DINT
	DO 14 J=3,5	DINT
	F(J,I) = 0.0	DINT
	U(J,I) = 0.0	DINT
14	Y(J,I) = 0.0	DINT
	IF (ISTEP.EQ.0) GO TO 65	DINT
	K = 1	DINT
C		DINT
C	ADJUST H (CURRENT TIME STEP) IF IT WILL ADVANCE T BEYOND TPRINT.	DINT
C		DINT
15	IF (H+EPS(8).GE.TPRINT-TIME) H = TPRINT-TIME	DINT
C		DINT
C	BACKUP ENTRY POINT IF H HAS BEEN HALVED.	DINT
C		DINT
16	D1 = 0.5*H	DINT
	CALL TRIGFS	DINT
	TSTART = TIME	DINT
	DO 20 I=1,NEQ	DINT
	U(3,I) = Y(5,I)	DINT
	U(4,I) = U(5,I)	DINT
	DO 20 J=1,5	DINT
20	GG(J,I) = F(J,I)	DINT
	CALL CMPUTE (K,1,D1)	DINT
	IF (K.LT.0) GO TO 50	DINT
	CALL ADJUST (1,D1)	DINT
	K = 2	DINT
	CALL CMPUTE (K,0,D1)	DINT
	IF (K.LT.0) GO TO 50	DINT
	CALL ADJUST (2,D1)	DINT
	NQUAT = K	DINT
	K = 3	DINT
	CALL CMPUTE (K,1, H)	DINT
	IF (K.LT.0) GO TO 50	DINT
	CALL ADJUST (3,D1)	DINT
	DO 49 L=1,NDINT	DINT
	M = 1	DINT
	IF (L.EQ.1) M = 0	DINT
	IF (NPRT(26).NE.2) CALL OUTPUT(0)	DINT
	CALL CMPUTE (K,M, H)	DINT
	IF (K.LT.0) GO TO 50	DINT
	FAIL = 1.0	DINT
	JJ = 0	DINT
	DO 47 II=1,NEQ,3	DINT
	JJ = JJ+1	DINT
	IF (XTEST(II).LE.0.0) GO TO 47	DINT
	TT = DER(II)**2 + DER(II+1)**2 + DER(II+2)**2	DINT

```

TX = VAR(II)**2 + VAR(II+1)**2 + VAR(II+2)**2          DINT
TE = 0.0                                                DINT
TY = 0.0                                                DINT
I2 = II+2                                              DINT
DO 45 I=II,I2                                          DINT
Z = GG(5,I)*(VAR(I)-GG(1,I)) + GG(2,I) + H*(GG(3,I)+H*GG(4,I)) DINT
TE = TE + (DER(I)-Z)**2                                DINT
TYD = TT + TX*GG(5,I)**2                              DINT
IF (TYD.EQ.0.0) TYD = 1.0                              DINT
45 TY = TY + (DER(I)-Z)**2/TYD                          DINT
TM = 1000.0*TIME                                       DINT
IF (NPRT(25).NE.0) WRITE (6,46) TM,SEGT(JJ),REGT(JJ),TT,TE,TY, DINT
*                                                       DINT
(XTEST(I),I=II,I2)                                     DINT
46 FORMAT ('0 DINT CONV. TEST',F10.3,2X,A4,2X,A8,6G12.4) DINT
IF (TT.LT.XTEST(II)) GO TO 47                           DINT
IF (XTEST(II+1).GT.0.0 .AND. TE.LT.XTEST(II+1)) GO TO 47 DINT
IF (TY.GT.XTEST(II+2)) GO TO 48                         DINT
47 CONTINUE                                            DINT
FAIL = 0.0                                             DINT
48 CALL ADJUST (4,D1)                                   DINT
IF (FAIL.EQ.0.0) GO TO 60                               DINT
IF (L.EQ.NDINT) GO TO 49                               DINT
CALL CMPUTE (K,1,D1)                                   DINT
IF (K.LT.0) GO TO 50                                   DINT
CALL ADJUST (5,D1)                                     DINT
49 CONTINUE                                            DINT
IF (NPRT(25).EQ.0) WRITE (6,46) TM,SEGT(JJ),REGT(JJ),TT,TE,TY, DINT
*                                                       DINT
(XTEST(I),I=II,I2)                                     DINT
50 WRITE (6,51) TIME,H                                  DINT
51 FORMAT('0 TEST FAILED AT TIME = ',F10.6,' FOR H = ',F10.6) DINT
ICNT = 0                                               DINT
IDBL = IDBL+2                                         DINT
IF (IDBL.GT.6) IDBL = 6                               DINT
IF (K.GE.0) GO TO 58                                   DINT
IF (H.GT.HMIN+EPS(8)) GO TO 59                       DINT
WRITE (6,52)                                           DINT
52 FORMAT('0 PROGRAM TERMINATED. PDAUX NEG SQRT. H < HMIN+EPS8.'/ DINT
* ' RERUN PROGRAM WITH SMALLER HMIN ON INPUT CARD A.4') DINT
STOP 31                                               DINT
58 IF (H.LE.HMIN+EPS(8)) GO TO 61                     DINT
IF (NPRT(26).EQ.2) CALL OUTPUT(1)                    DINT
59 TIME = TSTART                                       DINT
H = 0.5*H                                             DINT
HPRINT = 0.5*HPRINT                                   DINT
K = 2                                                 DINT
GO TO 16                                              DINT
60 IF (H.GT.0.74*HPRINT) ICNT = ICNT+1               DINT
61 K = 4                                               DINT
M = 0                                                 DINT
IF (H.GT.HMIN .AND. IDBL.GT.2) IDBL = IDBL-1        DINT

```

	GG4 = 2.0*H	DINT
	GG5 = DEXP(-1600.0*H)	DINT
	DO 63 I=1,NEQ	DINT
	F(3,I) = GG(3,I) + GG4*GG(4,I)	DINT
	F(4,I) = GG(4,I)	DINT
	F(5,I) = GG(5,I)	DINT
	Y(3,I) = Y(1,I)	DINT
	Y(4,I) = Y(2,I)	DINT
	Y(5,I) = GG5*U(3,I)	DINT
63	U(5,I) = GG5*U(4,I)	DINT
	CALL QSET(F,Y,VAR,DER,NQUAT)	DINT
	CALL PDAUX (VAR,DER,M,K)	DINT
	DO 64 I=1,NEQ	DINT
	F(1,I) = VAR(I)	DINT
64	F(2,I) = DER(I)	DINT
	HS = H	DINT
	IF (ICNT.LT.IDBL) GO TO 65	DINT
	ICNT = 0	DINT
	H = DMIN1(2.0*H,HMAX)	DINT
	HPRINT = DMIN1(2.0*HPRINT,HMAX)	DINT
65	CALL UPDATE(2)	DINT
	XPRINT = TPRINT - TIME	TGMOD1
	IF(XPRINT.GE.EPS(8).AND.NPRT(26).NE.3.AND.NPRT(26).GE.0)	TGMOD1
	* CALL OUTPUT(1)	TGMOD1
	IF(XPRINT.GE.EPS(8)) GO TO 12	TGMOD1
	LNRT = .FALSE.	TGMOD1
	IF(NPRT(26).GE.0) LNRT = .TRUE.	TGMOD1
	IF(NPRT(26).LT.0) INRT = IABS(NPRT(26))	TGMOD1
	IF(NPRT(26).LT.0) LNRT = (MOD(ISTEP,INRT).EQ.0)	TGMOD1
	IF(LNRT) CALL OUTPUT(1)	TGMOD1
	CALL ELTIME(2,3)	DINT
	RETURN	DINT
	END	DINT

	SUBROUTINE DOTT31 (A,B,C)		DOTT31
C		REV 17	12/20/76DOTT31
C	PERFORMS MATRIX MULTIPLICATION C = AB'		DOTT31
C	WHERE C IS A 3X3 MATRIX, AND A AND B ARE VECTORS OF LENGTH 3.		DOTT31
C			DOTT31
	IMPLICIT REAL*8 (A-H,O-Z)		DOTT31
	DIMENSION A(3) , B(3) , C(3,3)		DOTT31
	DO 10 I=1,3		DOTT31
	DO 10 J=1,3		DOTT31
10	C(I,J) = A(I)*B(J)		DOTT31
	RETURN		DOTT31
	END		DOTT31

	SUBROUTINE DOTT33 (A,B,C)		DOTT33
C		REV 17	01/03/77DOTT33
C	PERFORMS MATRIX MULTIPLICATION C = AB'		DOTT33
C	WHERE A, B AND C ARE ALL 3X3 MATRICEES.		DOTT33
C			DOTT33
	IMPLICIT REAL*8 (A-H,O-Z)		DOTT33
	DIMENSION A(3,3) , B(3,3) , C(3,3)		DOTT33
	DO 10 I=1,3		DOTT33
	DO 10 J=1,3		DOTT33
10	C(I,J) = A(I,1)*B(J,1) + A(I,2)*B(J,2) + A(I,3)*B(J,3)		DOTT33
	RETURN		DOTT33
	END		DOTT33

	SUBROUTINE DOT31 (A,B,C)	DOT31
C		REV 17 01/03/77DOT31
C	PERFORMS MATRIX MULTIPLICATION C = A'B	DOT31
C	WHERE A IS A 3X3 MATRIX, AND B AND C ARE VECTORS OF LENGTH 3.	DOT31
C		DOT31
	IMPLICIT REAL*8 (A-H,O-Z)	DOT31
	DIMENSION A(3,3) , B(3) , C(3)	DOT31
	C(1) = A(1,1)*B(1) + A(2,1)*B(2) + A(3,1)*B(3)	DOT31
	C(2) = A(1,2)*B(1) + A(2,2)*B(2) + A(3,2)*B(3)	DOT31
	C(3) = A(1,3)*B(1) + A(2,3)*B(2) + A(3,3)*B(3)	DOT31
	RETURN	DOT31
	END	DOT31

	SUBROUTINE DOT33 (A,B,C)		DOT33
C		REV 17	01/03/77DOT33
C	PERFORMS MATRIX MULTIPLICATION C = A'B		DOT33
C	WHERE A, B AND C ARE ALL 3X3 MATRICEES.		DOT33
C			DOT33
	IMPLICIT REAL*8 (A-H,O-Z)		DOT33
	DIMENSION A(3,3) , B(3,3) , C(3,3)		DOT33
	DO 10 I=1,3		DOT33
	DO 10 J=1,3		DOT33
10	C(I,J) = A(1,I)*B(1,J) + A(2,I)*B(2,J) + A(3,I)*B(3,J)		DOT33
	RETURN		DOT33
	END		DOT33

	SUBROUTINE DRCIJK (D,ANG,ID,HT,J)		DRCIJK
C		REV 18	02/24/78DRCIJK
	IMPLICIT REAL*8 (A-H,O-Z)		DRCIJK
	DIMENSION D(9,22),HT(9,42),ANG(3,22),ID(4,22),T1(9),T2(9)		DRCIJK
	M = ID(4,J)		DRCIJK
	IF (M.NE.0) GO TO 10		DRCIJK
	CALL DRCYPR (D(1,J),ANG(1,J),ID(1,J))		DRCIJK
	GO TO 99		DRCIJK
10	CALL DRCYPR (T1,ANG(1,J),ID(1,J))		DRCIJK
	IF (M.LT.0) GO TO 20		DRCIJK
	CALL MAT33 (T1,D(1,M),D(1,J))		DRCIJK
	GO TO 99		DRCIJK
20	M = -M		DRCIJK
	CALL DOT33 (HT(1,2*J-3),D(1,M),D(1,J))		DRCIJK
	CALL MAT33 (T1,D(1,J),T2)		DRCIJK
	CALL MAT33 (HT(1,2*J-2),T2,D(1,J))		DRCIJK
99	RETURN		DRCIJK
	END		DRCIJK



	SUBROUTINE DRCQUA(DC,Q)	DRCQUA
		REV III.5 07/31/85JTF785
C	COMPUTES DIRECTION COSINE MATRIX FROM QUATERNIONS	DRCQUA
C	IMPLICIT REAL*8(A-H,O-Z)	DRCQUA
	DIMENSION DC(3,3),Q(4)	DRCQUA
	C = Q(1)**2 - Q(2)**2 - Q(3)**2 - Q(4)**2	JTF785
	DO 12 I = 1,3	DRCQUA
	DO 10 J = 1,3	DRCQUA
10	DC(I,J) = 2.0*Q(I+1)*Q(J+1)	DRCQUA
12	DC(I,I) = DC(I,I) + C	DRCQUA
	E = Q(1) + Q(1)	DRCQUA
	DO 14 I = 1,3	DRCQUA
	J = 1 + MOD(I,3)	DRCQUA
	K = 1 + MOD(I+1,3)	DRCQUA
	D = E*Q(I+1)	DRCQUA
	DC(K,J) = DC(K,J) - D	DRCQUA
14	DC(J,K) = DC(J,K) + D	DRCQUA
	DO 18 I = 1,3	DRCQUA
	DO 18 J = 1,3	DRCQUA
18	IF(DABS(DC(I,J)).GT.1.0D0)DC(I,J) = DSIGN(1.0D0,DC(I,J))	DRCQUA
	RETURN	DRCQUA
	END	DRCQUA



	SUBROUTINE DRIFT		DRIFT
		REV IV	07/24/86SLIP
C	CORRECTS FOR DRIFT IN CONSTRAINED JOINTS		DRIFT
C			DRIFT
C			DRIFT
C	IMPLICIT REAL*8(A-H,O-Z)		DRIFT
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		DRIFT
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		DRIFT
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		DRIFT
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		DRIFT
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
	* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		DRIFT
	* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		DRIFT
	COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30),		DRIFT
	* FE(3,30),TQE(3,30),CONST(5,30)		DRIFT
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		DRIFT
	* UNITL,UNITM,UNITT,GRAVTY(3),TWOPI		TWOPI
	COMMON/TEMPVS/ T1(3),T2(3),T3(3),T4(3),TP(3,3),H1(3),H2(3)		DRIFT
	IF (NJNT.EQ.0) GO TO 51		DRIFT
	DO 50 J=1,NJNT		DRIFT
	K = IABS(JNT(J))		DRIFT
	IF (K.EQ.0) GO TO 50		DRIFT
	IF (ISING(J+1).LT.0) GO TO 50		DRIFT
C			DRIFT
	M = 0		DRIFT
	IF (IPIN(J).EQ.1) M = 4		DRIFT
	IF (IPIN(J).EQ.6) M = 4		SLIP
	IF (IPIN(J).EQ.7) M = 4		SLIP
	IF (IABS(IPIN(J)).NE.4) GO TO 15		DRIFT
	IF (IEULER(J).EQ.1) M = 2		DRIFT
	IF (IEULER(J).EQ.2) M = 3		DRIFT
	IF (IEULER(J).EQ.3) M = 1		DRIFT
	IF (IEULER(J).EQ.4) M = 4		DRIFT
	IF (IEULER(J).EQ.5) M = 4		DRIFT
	IF (IEULER(J).EQ.6) M = 4		DRIFT
	15 IF (M.EQ.0) GO TO 50		DRIFT
	IF(M.EQ.4)GO TO 23		DRIFT
	IF(M.NE.3)GO TO 21		DRIFT
	CALL EJOINT(-1,J)		DRIFT
	CALL CROSS(HIR(1,2,2*J+29),HIR(1,1,2*J+29),T1)		DRIFT
	DO 17 I = 1,3		DRIFT
	H1(I) = CONST(4,J)*HIR(I,1,2*J+29) + CONST(5,J)*T1(I)		DRIFT
	17 H2(I) = HIR(I,3,2*J+30)		DRIFT
	GO TO 25		DRIFT
	21 DO 22 I = 1,3		DRIFT
	H1(I) = HIR(I,M,2*J+29)		DRIFT
	22 H2(I) = HIR(I,M+1,2*J+30)		DRIFT
	GO TO 25		DRIFT
	23 DO 24 I = 1,3		DRIFT
	H1(I) = HB(I,2*J-1)		DRIFT



```
47 CALL MAT31(D(1,1,J+1),T1,T2) DRIFT
CALL CROSS(T2,H2,H1) DRIFT
48 CALL DOT31(D(1,1,K),WMEG(1,K),T1) DRIFT
CALL MAT31(D(1,1,J+1),T1,T2) DRIFT
HW = H1(1)*(T2(1) - WMEG(1,J+1)) DRIFT
* + H1(2)*(T2(2) - WMEG(2,J+1)) DRIFT
* + H1(3)*(T2(3) - WMEG(3,J+1)) DRIFT
DO 49 I = 1,3 DRIFT
49 WMEG(I,J+1) = WMEG(I,J+1) + HW*H1(I) DRIFT
50 CONTINUE DRIFT
51 RETURN DRIFT
END DRIFT
```

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SUBROUTINE DSETD(D,TH,T)                                DSETD
C                                                       REV IV   07/23/86TWOPI
C   UPDATES A DIRECTION COSINE MATRIX (D)              DSETD
C   USING AN INCREMENTAL ANGULAR MOTION (TH).         DSETD
C   ARGUMENTS D: 3X3 DIRECTION COSINE MATRIX TO BE   DSETD
C   UPDATED.                                          DSETD
C   TH: 3 COMPONENTS OF INCREMENTAL ANGULAR MOTION   DSETD
C   ABOUT LOCAL X,Y AND Z AXIS RESPECTIVELY.         DSETD
C   T: MAGNITUDE OF VECTOR TH COMPUTED BY ROUTINE.   DSETD
C                                                       DSETD
    IMPLICIT REAL*8(A-H,O-Z)                            DSETD
    DIMENSION D(3,3),TH(3),S(3),TEMP(3,3)            DSETD
    COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),        DSETD
    *          UNITL,UNITM,UNITT,GRAVITY(3),TWOPI     TWOPI
    T=DSQRT(TH(1)**2+TH(2)**2+TH(3)**2)              DSETD
    IF(T.EQ.0.)RETURN                                  DSETD
    ST=DSIN(T)                                         DSETD
    CT=DCOS(T)                                         DSETD
    STT=ST/T                                           DSETD
    CTT=STT**2/(1.+CT)                                 DSETD
    DO 10 J=1,3                                       DSETD
    S(1)=-TH(3)*D(2,J)+TH(2)*D(3,J)                  DSETD
    S(2)= TH(3)*D(1,J)-TH(1)*D(3,J)                  DSETD
    S(3)=-TH(2)*D(1,J)+TH(1)*D(2,J)                  DSETD
    DTT=(TH(1)*D(1,J)+TH(2)*D(2,J)+TH(3)*D(3,J))*CTT DSETD
    DO 5 K=1,3                                        DSETD
5   D(K,J)=D(K,J)*CT-STT*S(K)+TH(K)*DTT             DSETD
10  CONTINUE                                          DSETD
C                                                       DSETD
C   RENORMALIZATION OF DIRECTION COSINE MATRIX        DSETD
C   BY AVERAGING MATRIX AND TRANSPOSE OF ITS INVERSE. DSETD
C                                                       DSETD
    DO 23 ITER=1,10                                    DSETD
    CALL CFACTT(D,TEMP,DET)                            DSETD
    DO 22 I=1,3                                       DSETD
    DO 22 J=1,3                                       DSETD
    D(I,J) = 0.5*(D(I,J)+TEMP(J,I)/DET)              DSETD
22  IF (DABS(D(I,J)).LT.EPS(15)) D(I,J)=0.0         DSETD
    IF (DABS(DET-1.0).LT.EPS(6)) GO TO 24             DSETD
23  CONTINUE                                          DSETD
    WRITE (6,27) DET                                    DSETD
27  FORMAT('0 DSETD RENORMALIZATION DID NOT CONVERGE, DET =',1PD25.15)DSETD
24  RETURN                                           DSETD
    END                                               DSETD

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SUBROUTINE DSETQ(E,TH,ES,EC,D)                                DSETQ
C                                                             REV IV    07/23/86TWOPI
C COMPUTES NEW DIRECTION MATRIX (D), GIVEN ORIGINAL MATRIX (E) DSETQ
C AND INCREMENTAL MOTION EXPRESSED IN QUATERNION FORM.      DSETQ
C                                                             DSETQ
C ARGUMENTS:                                                DSETQ
C                                                             DSETQ
C     E : ORIGINAL DIRECTION COSINE MATRIX.                 DSETQ
C     TH : COMPONENTS OF Q ( UX SIN A/2, UY SIN A/2, UZ SIN A/2) DSETQ
C     ES : SIN**2(A/2)                                       DSETQ
C     EC : COS (A/2)                                         DSETQ
C     D : NEW DIRECTION COSINE MATRIX.                       DSETQ
C                                                             DSETQ
C     IMPLICIT REAL*8(A-H,O-Z)                                DSETQ
C     DIMENSION D(3,3),TH(3),S(3),TEMP(3,3),E(3,3)          DSETQ
C     COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),             DSETQ
C     * UNITL,UNITM,UNITT,GRAVTY(3),TWOPI                   TWOPI
C     CT = 1.0 - 2.0*ES                                       DSETQ
C     DO 10 J=1,3                                             DSETQ
C     S(1) = TH(2)*E(3,J) - TH(3)*E(2,J)                    DSETQ
C     S(2) = TH(3)*E(1,J) - TH(1)*E(3,J)                    DSETQ
C     S(3) = TH(1)*E(2,J) - TH(2)*E(1,J)                    DSETQ
C     DTT = TH(1)*E(1,J) + TH(2)*E(2,J) + TH(3)*E(3,J)    DSETQ
C     DO 5 K=1,3                                             DSETQ
C     5 D(K,J) = E(K,J)*CT + 2.0*(TH(K)*DTT - EC*S(K))      DSETQ
C 10 CONTINUE                                               DSETQ
C                                                             DSETQ
C RENORMALIZATION OF DIRECTION COSINE MATRIX                DSETQ
C BY AVERAGING MATRIX AND TRANSPOSE OF ITS INVERSE.       DSETQ
C                                                             DSETQ
C DO 23 ITER=1,10                                           DSETQ
C CALL CFACTT(D,TEMP,DET)                                     DSETQ
C DO 22 I=1,3                                               DSETQ
C DO 22 J=1,3                                               DSETQ
C D(I,J) = 0.5*(D(I,J)+TEMP(J,I)/DET)                       DSETQ
C 22 IF (DABS(D(I,J)).LT.EPS(15)) D(I,J)=0.0                DSETQ
C     IF (DABS(DET-1.0).LT.EPS(6)) GO TO 24                 DSETQ
C 23 CONTINUE                                               DSETQ
C WRITE (6,27) DET                                          DSETQ
C 27 FORMAT('0 DSETQ RENORMALIZATION DID NOT CONVERGE, DET =',1PD25.15) DSETQ
C 24 RETURN                                                 DSETQ
C END                                                        DSETQ

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	SUBROUTINE DSMSOL (A, KK, LL)		DSMSOL
C		REV 03	07/08/74 DSMSOL
C	SOLVES A SET OF SIMULTANEOUS LINEAR EQUATIONS AX=B.		DSMSOL
C			DSMSOL
C	ARGUMENTS:		DSMSOL
C	A: 2-DIMENSIONAL(KK, KK+1) MATRIX OF COEFFICIENTS.		DSMSOL
C	KK: NUMBER OF EQUATIONS AND UNKNOWNNS.		DSMSOL
C	LL: 1ST DIMENSION OF A IN CALLING PROGRAM.		DSMSOL
C			DSMSOL
C	CALLING PROGRAM SETUP:		DSMSOL
C	A(I, J) FOR I, J=1, KK		DSMSOL
C	A(I, KK+1) = B(I) FOR I=1, KK		DSMSOL
C	THE SOLUTION X IS RETURNED IN COLUMN KK+1 OF A.		DSMSOL
C	MATRIX A IS DESTROYED BY SUBROUTINE.		DSMSOL
C			DSMSOL
	IMPLICIT REAL*8(A-H, O-Z)		DSMSOL
	DIMENSION A(LL, 1)		DSMSOL
	N = KK		DSMSOL
	N1 = N+1		DSMSOL
	DO 50 L=1, N		DSMSOL
	L1 = L+1		DSMSOL
	BIG = 0.0		DSMSOL
	DO 25 I=L, N		DSMSOL
	IF (DABS(A(I, L)).LE.DABS(BIG)) GO TO 25		DSMSOL
	K = I		DSMSOL
	BIG = A(I, L)		DSMSOL
25	CONTINUE		DSMSOL
	IF (BIG.NE.0.0) GO TO 30		DSMSOL
	WRITE (6, 26)		DSMSOL
26	FORMAT('O DSMSOL MATRIX SINGULAR, PROGRAM TERMINATED.')		DSMSOL
	STOP 41		DSMSOL
30	BIG = 1.0/BIG		DSMSOL
	DO 40 J=L, N1		DSMSOL
	B = A(K, J)		DSMSOL
	A(K, J) = A(L, J)		DSMSOL
40	A(L, J) = B*BIG		DSMSOL
	IF (L.EQ.N) GO TO 50		DSMSOL
	DO 48 I=L1, N		DSMSOL
	IF (A(I, L).EQ.0.0) GO TO 48		DSMSOL
	DO 45 J=L1, N1		DSMSOL
45	A(I, J) = A(I, J) - A(I, L)*A(L, J)		DSMSOL
48	CONTINUE		DSMSOL
50	CONTINUE		DSMSOL
	IF (N.EQ.1) GO TO 71		DSMSOL
	N2 = N-1		DSMSOL
	DO 60 L=1, N2		DSMSOL
	I = N-L		DSMSOL
	L1 = I+1		DSMSOL
	DO 60 J=L1, N		DSMSOL
60	A(I, N1) = A(I, N1) - A(I, J)*A(J, N1)		DSMSOL



71 CONTINUE  
RETURN  
END

DSMSOL  
DSMSOL  
DSMSOL



90 CALL ELTIME(2,5)  
RETURN  
END

DZP  
DZP  
DZP







C		*	DXA	EDEPTH
C		C12 =	XA'A---	EDEPTH
C		*	DU	EDEPTH
C				EDEPTH
C		*	DXB	EDEPTH
C		C22 =	(XB-M)'B---	EDEPTH
C		*	DU	EDEPTH
C				EDEPTH
	C12 =	0.0		EDEPTH
	C22 =	0.0		EDEPTH
	DO 26	I=1,3		EDEPTH
	PXBU(I) =	PXAU(I) + XL*(A(I,1)*PXAU(1)		EDEPTH
	*	+ A(I,2)*PXAU(2) + A(I,3)*PXAU(3) )		EDEPTH
	C12 =	C12 + AXA(I)*PXAU(I)		EDEPTH
	26 C22 =	C22 + BXBM(I)*PXBU(I)		EDEPTH
C				EDEPTH
C				EDEPTH
C			SOLVE FOR DL AND DU	EDEPTH
C			C11*DL + C12*DU = C13	EDEPTH
C			C21*DL + C22*DU = C23	EDEPTH
C				EDEPTH
	DET =	C11*C22-C12*C21		EDEPTH
	DL =	(C13*C22-C12*C23)/DET		EDEPTH
	DU =	(C11*C23-C13*C21)/DET		EDEPTH
C				EDEPTH
C				EDEPTH
C			INCREMENT L AND U	EDEPTH
C			TEST FOR CONVERGENCE	EDEPTH
				EDEPTH
	XL =	XL + DL		EDEPTH
	XU =	XU + DU		EDEPTH
	IF (DABS(DL/XL).GT.EPS(12))	GO TO 11		EDEPTH
	IF (DABS(DU/XU).GT.EPS(12))	GO TO 11		EDEPTH
	31 CONTINUE			EDEPTH
	RETURN			EDEPTH
	END			EDEPTH

	DOUBLE PRECISION FUNCTION EFUNCT (TH,THD,SPR,JSTOP)	EFUNCT
	REV 20 04/29/80	EFUNCT
C	COMPUTES NONLINEAR SRRING TORQUE FOR EULER JOINTS.	EFUNCT
C		EFUNCT
C	ARGUMENTS:	EFUNCT
C	TH - THETA IS THE ANGLE OF THE EULER AXIS	EFUNCT
C	THD - THETA DOT	EFUNCT
C	SPR - ARRAY OF 5 VALUES DESCRIBING FUNCTION EVALUATION	EFUNCT
C	JSTOP - INDICATOR TO BE SET TO ONE IF IN STOP	EFUNCT
C		EFUNCT
	IMPLICIT REAL*8(A-H,O-Z)	EFUNCT
	DIMENSION SPR(5)	EFUNCT
	JSTOP = 0	EFUNCT
	EFUNCT = TH*SPR(1)	EFUNCT
	TEN = 10.0	EFUNCT
	Q = DSIGN(TEN*THD,TH*THD)	EFUNCT
	IF (Q.GT.1.0) Q = 1.0	EFUNCT
	IF (Q.LT.-1.0) Q = -1.0	EFUNCT
	X = 0.5*(1.0+SPR(4)+Q*(1.0-SPR(4)))	EFUNCT
	IF (SPR(5).GT.0.0) GO TO 10	EFUNCT
	EFUNCT = X*EFUNCT	EFUNCT
	GO TO 99	EFUNCT
10	IF (DABS(TH).LT.SPR(5)) GO TO 99	EFUNCT
	JSTOP = 1	EFUNCT
	Z = DABS(TH) - SPR(5)	EFUNCT
	EFUNCT = EFUNCT + DSIGN(X*(SPR(2)+Z*SPR(3))*Z**2,TH)	EFUNCT
99	RETURN	EFUNCT
	END	EFUNCT



	SUBROUTINE EJOINT(IJ,NK)		JDRIFT
C		REV IV	07/24/86SLIP
C	COMPUTES THE TORQUES ACTING ON AN EULER JOINT		EJOINT
C	AND ADDS THEM TO THE U2 ARRAY.		EJOINT
C			EJOINT
C	ARGUMENTS:		EJOINT
C	NK = 0 - REGULAR COMPUTATION FOR ALL EULER JOINTS		JDRIFT
C	* 0 - COMPUTE ONLY FOR JOINT NJ IMPULSE		EJOINT
C			EJOINT
C	IJ = 1 IMPULSE ON PRECESSION AXIS ONLY		EJOINT
C	= 2 IMPULSE ON NUTATION AXIS ONLY		EJOINT
C	= 3 IMPULSE ON SPIN AXIS ONLY		EJOINT
C	= 4 IMPULSE ON GLOBALGRAPHIC AXIS		EJOINT
C	NK = 0, IJ * 0, SPECIAL COMPUTATIONS OF HIR AND HB ONLY		JDRIFT
C			EJOINT
C	IMPLICIT REAL*8(A-H,O-Z)		EJOINT
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		EJOINT
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		EJOINT
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		EJOINT
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		EJOINT
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		EJOINT
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),		EJOINT
*	F(3,30),TQ(3,30),WJ(30),A11(3,3,30)		SLIP
	COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30),		JDRIFT
*	FE(3,30),TQE(3,30),CONST(5,30)		JDRIFT
	COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),		NCFORC
*	PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF		EJOINT
	COMMON/TEMPVI/ CREST,TTI(3),R1I(3),R2I(3),JSTOP(4,2,30)		EJOINT
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		EJOINT
*	UNITL,UNITM,UNITT,GRAVTY(3),TWOPI		TWOPI
	COMMON/TEMPVS/ DH1(3,3),DH4(3,3),TH(3,3),HIM(3,3),HIJ(3,3),		EJOINT
*	HDT(3,3),H2(3,3),SH(3),TM(3),TJ(3),WMJ(3),AD(3),		EJOINT
*	CV(3),CS(3),ANGL(3),HD3(3),CC(3),T9(3),LSKIP(3)		EJOINT
	LOGICAL LSKIP		EJOINT
	IF (NJNT.LE.0) GO TO 99		EJOINT
	CALL ELTIME(1,31)		EJOINT
	J1 = 1		EJOINT
	J2 = NJNT		EJOINT
	NJ = NK		JDRIFT
	IF (NJ.EQ.0) GO TO 11		EJOINT
	J1 = NJ		EJOINT
	J2 = NJ		EJOINT
	IF(IJ.LT.0) NJ = 0		JDRIFT
11	DO 98 J=J1,J2		EJOINT
	IF (IABS(IPIN(J)).NE.4) GO TO 98		EJOINT
	M = IABS(JNT(J))		EJOINT
	CALL DOT33(D(1,1,M),HT(1,1,2*J-1),DH1)		EJOINT
	CALL DOT33(D(1,1,J+1),HT(1,1,2*J),DH4)		EJOINT

CALL DOT33(DH4,DH1,TH)	EJOINT
DO 12 I=1,3	EJOINT
12 ANG(I,J) = ANG(I,J) + CONST(I,J)	EJOINT
IC = IEULER(J)	EJOINT
CALL EULRAD (TH,ANG(1,J),IC)	EJOINT
CALL ROT(H2,3,-ANG(1,J))	EJOINT
DO 13 I=1,3	EJOINT
ANG(I,J) = ANG(I,J) - CONST(I,J)	EJOINT
HIR(I,1,J) = DH1(I,3)	EJOINT
HIR(I,3,J) = DH4(I,3)	EJOINT
HIM(I,1) = HT(I,3,2*J-1)	EJOINT
HIJ(I,3) = HT(I,3,2*J)	EJOINT
LSKIP(I) = .FALSE.	EJOINT
FE(I,J) = 0.0	EJOINT
CV(I) = 0.0	EJOINT
CS(I) = 0.0	EJOINT
V2(I,J) = 0.0	EJOINT
TQE(I,J) = 0.0	EJOINT
13 TQ(I,J) = 0.0	EJOINT
WJ(J) = 0.0	EJOINT
TQC = 0.0	EJOINT
IF (IJ.EQ.4) GO TO 55	EJOINT
CALL MAT31 (HT(1,1,2*J-1),H2(1,1),HIM(1,2))	EJOINT
CALL MAT31 (HT(1,1,2*J-1),H2(1,2),HIM(1,3))	EJOINT
CALL DOT31 (D(1,1,M),HIM(1,2),H2(1,2))	EJOINT
CALL DOT31 (D(1,1,M),HIM(1,3),H2(1,3))	EJOINT
CALL CROSS (H2(1,2),HIR(1,3,J),H2(1,1))	EJOINT
CALL DOT31 (D(1,1,M),WMEG(1,M),TM)	EJOINT
CALL DOT31 (D(1,1,J+1),WMEG(1,J+1),TJ)	EJOINT
SWJ = 0.0	EJOINT
DO 14 I=1,3	EJOINT
HIR(I,2,J) = H2(I,2)	EJOINT
WMJ(I) = TJ(I) - TM(I)	EJOINT
14 SWJ = SWJ + WMJ(I)**2	EJOINT
WJ(J) = DSQRT(SWJ)	EJOINT
CALL DOT31 (HIR(1,1,J),WMJ,AD)	EJOINT
CALL CROSS (TM,HIR(1,1,J),HDT(1,1))	EJOINT
CALL CROSS (TM,HIR(1,2,J),HDT(1,2))	EJOINT
CALL CROSS (TJ,HIR(1,3,J),HDT(1,3))	EJOINT
CALL MAT31 (D(1,1,J+1),HIR(1,1,J),HIJ(1,1))	EJOINT
CALL MAT31 (D(1,1,J+1),HIR(1,2,J),HIJ(1,2))	EJOINT
CALL MAT31 (D(1,1,M),HIR(1,3,J),HIM(1,3))	EJOINT
N = IEULER(J)	EJOINT
DO 15 I=1,3	EJOINT
SH(I) = AD(I)	JDRIFT
DO 15 K=1,3	JDRIFT
HIR(I,K,2*J+29) = HIM(I,K)	JDRIFT
15 HIR(I,K,2*J+30) = HIJ(I,K)	JDRIFT
IF (N.EQ.8) GO TO 19	EJOINT
IF (N.GT.3) GO TO 16	EJOINT

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SH(N) = 0.0 EJOINT
GO TO 18 EJOINT
16 DO 17 I=1,3 EJOINT
17 IF (I.NE.N-3) SH(I) = 0.0 EJOINT
18 IF (N.NE.2) GO TO 21 EJOINT
19 HX = H2(1,1)*HIR(1,1,J) + H2(2,1)*HIR(2,1,J) + H2(3,1)*HIR(3,1,J) EJOINT
IF (DABS(HX).GE.EPS(6)) GO TO 20 EJOINT
SH(1) = ANG D(1,J) EJOINT
SH(3) = ANG D(3,J) EJOINT
GO TO 21 EJOINT
20 CALL DOT31 (H2,WMJ,SH) EJOINT
SH(1) = SH(1)/HX EJOINT
IF (N.EQ.2) SH(2) = 0.0 EJOINT
SH(3) = SH(3)/HX EJOINT
21 DO 22 I=1,3 EJOINT
ANG D(I,J) = SH(I) EJOINT
22 HDT(I,2) = HDT(I,2) + SH(1)*H2(I,3) EJOINT
IF (NJ.NE.0) N = IJ+3 EJOINT
IF (N.GT.3) GO TO 30 EJOINT
N4 = 4-N EJOINT
IF (N.EQ.2) AHDT = HDT(1,2)*WMJ(1)+HDT(2,2)*WMJ(2)+HDT(3,2)*WMJ(3) EJOINT
IF (N.NE.2) AHDT = -(SH(2)*HDT(1,2)+SH(N4)*HDT(1,N4))*H2(1,N) EJOINT
* -(SH(2)*HDT(2,2)+SH(N4)*HDT(2,N4))*H2(2,N) EJOINT
* -(SH(2)*HDT(3,2)+SH(N4)*HDT(3,N4))*H2(3,N) EJOINT
CALL MAT31 (D(1,1,M ),H2(1,N),HB(1,2*J-1)) EJOINT
CALL MAT31 (D(1,1,J+1),H2(1,N),HB(1,2*J )) EJOINT
DO 25 I=1,3 EJOINT
V2(I,J) = AHDT*H2(I,N) EJOINT
25 IF (N.EQ.I) LSKIP(I) = .TRUE. EJOINT
GO TO 42 EJOINT
30 IF (N.GT.6) GO TO 40 EJOINT
K3J = 3*J-2 EJOINT
DO 32 I=1,3 EJOINT
IF (NJ.EQ.0) GO TO 31 EJOINT
IF (I.EQ.N-3) CREST = VISC(7,K3J) EJOINT
TQE(I,J) = H2(I,N-3) EJOINT
GO TO 32 EJOINT
31 V2(I,J) = -HDT(I,N-3)*AD(N-3) EJOINT
HB(I,2*J-1) = HIM(I,N-3) EJOINT
HB(I,2*J ) = HIJ(I,N-3) EJOINT
IF (I.NE.N-3) LSKIP(I) = .TRUE. EJOINT
32 K3J = K3J + 1 EJOINT
IF (NJ) 35,42,35 EJOINT
40 IF (N.EQ.7) GO TO 97 EJOINT
42 IF(IJ.NE.0) GOTO 98 EJOINT
DO 41 I=1,3 EJOINT
IF (LSKIP(I)) GO TO 41 EJOINT
K3J = 3*J-3+I EJOINT
CV(I) = ANG D(I,J)*VISCOS(DABS(ANG D(I,J)),VISC(1,K3J),HA(I,2*J)) EJOINT
CS(I) = EFUNCT(ANG(I,J),ANG D(I,J),SPRING(1,K3J),JSTOP(I,1,J)) EJOINT

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	FE(I,J) = CS(I) + CV(I) + HA(I,2*J)*HA(I,2*J-1)	EJOINT
41	CONTINUE	EJOINT
	CALL MAT31(HIR(1,1,J),FE(1,J),TQE(1,J))	EJOINT
	IF(NJ.GT.0) GO TO 34	EJOINT
55	IF (IGLOB(J).EQ.0) GO TO 34	EJOINT
	HD3(1) = TH(3,1)	EJOINT
	HD3(2) = TH(3,2)	EJOINT
	HD3(3) = TH(3,3)	EJOINT
	CALL GLOBAL (J,HD3,DH1,TQC,T9,ANGL)	EJOINT
34	CONTINUE	EJOINT
C		EJOINT
C	ADD TORQUE CONVERTED TO LOCAL REFERENCE TO U2 ARRAY BY	EJOINT
C	U2(M ) = U2(M ) + D(M )*TQ	EJOINT
C	U2(J+1) = U2(J+1) - D(J+1)*TQ	EJOINT
C		EJOINT
35	DO 51 I=1,3	EJOINT
	TQ(I,J) = TQE(I,J)+TQC*T9(I)	EJOINT
	TTI(I) = TQ(I,J)	EJOINT
	DO 51 K=1,3	EJOINT
	U2(K,M ) = U2(K,M ) + D(K,I,M )*TQ(I,J)	EJOINT
51	U2(K,J+1) = U2(K,J+1) - D(K,I,J+1)*TQ(I,J)	EJOINT
C		EJOINT
C	STORE DATA INTO PRJNT ARRAY FOR OUTPUT ROUTINE	EJOINT
C		EJOINT
97	PRJNT(1,J) = IEULER(J)	EJOINT
	PRJNT(2,J) = ANG(1,J)	EJOINT
	PRJNT(3,J) = ANG(2,J)	EJOINT
	PRJNT(4,J) = ANG(3,J)	EJOINT
	PRJNT(5,J)=CS(1)**2+CS(3)**2+2.0*CS(1)*CS(3)*TH(3,3)+CS(2)**2	JTF785
	PRJNT(6,J)=CV(1)**2+CV(3)**2+2.0*CV(1)*CV(3)*TH(3,3)+CV(2)**2	JTF785
	PRJNT(7,J) = TQ(1,J)**2 + TQ(2,J)**2 + TQ(3,J)**2	EJOINT
98	CONTINUE	EJOINT
	CALL ELTIME(2,31)	EJOINT
99	RETURN	EJOINT
	END	EJOINT

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DOUBLE PRECISION FUNCTION ELONG(A,B,C,D,E)                                ELONG
C                                                                                   REV 01    10/05/72ELONG
C COMPUTES ARC LENGTH OF ELLIPSE          AX**2 + 2BXY + CY**2 = 1      ELONG
C FROM THETA=0 (POSITIVE X AXIS) TO THETA=E (RADIANS)                   ELONG
C WHERE D IS NOMINAL INCREMENT OF INTEGRATION.                          ELONG
C                                                                                   ELONG
IMPLICIT REAL*8(A-H,O-Z)                                                ELONG
N=DABS(E/D)                                                                ELONG
N=N+N                                                                      ELONG
IF(N.EQ.0)N=2                                                              ELONG
Z=N                                                                        ELONG
T=E/Z                                                                      ELONG
F = DSQRT ((1.+(B/A)**2)/A)                                               ELONG
CS=1.                                                                      ELONG
SN=0.                                                                      ELONG
DCS=DCOS(T)                                                                ELONG
DSN=DSIN(T)                                                                ELONG
S=F/2.                                                                      ELONG
AC = A+C                                                                    ELONG
BAC = B*B-A*C                                                                ELONG
DO 10 I=1,N,2                                                              ELONG
CSS=CS*DCS-SN*DSN                                                         ELONG
SN=SN*DCS+CS*DSN                                                         ELONG
CS=CSS                                                                      ELONG
G=(A*CS+B*SN)*CS+(B*CS+C*SN)*SN                                          ELONG
G = G**2/(AC + BAC/G)                                                     ELONG
F=(F+1./(F*G))/2.                                                         ELONG
S=S+F+F                                                                    ELONG
CSS=CS*DCS-SN*DSN                                                         ELONG
SN=SN*DCS+CS*DSN                                                         ELONG
CS=CSS                                                                      ELONG
G=(A*CS+B*SN)*CS+(B*CS+C*SN)*SN                                          ELONG
G = G**2/(AC + BAC/G)                                                     ELONG
F=(F+1./(F*G))/2.                                                         ELONG
S=S+F                                                                      ELONG
10 CONTINUE                                                                ELONG
ELONG=(S+S-F)*T/3.                                                         ELONG
RETURN                                                                      ELONG
END                                                                           ELONG

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SUBROUTINE ELTIME(L,N)                                ELTIME
C                                                     REV III.2 08/08/84REVIII
C COUNTS THE NUMBER OF TIMES CERTAIN BASIC SUBROUTINES ARE CALLED ELTIME
C AND ACCOUNTS FOR ALL COMPUTER CPU TIME USED BY THESE ROUTINES. ELTIME
C                                                     ELTIME
C ARGUMENTS L: 1 INDICATES CALL IS AT START OF ROUTINE ELTIME
C              2 INDICATES CALL IS AT END OF ROUTINE. ELTIME
C              >2 PAGE NUMBER FOR CALL AT END OF RUN PAGE
C              N: THE SUBROUTINE IDENTIFICATION NUMBER. ELTIME
C                                                     ELTIME
C ASSUMES FUNCTION LTIME(1) IS GIVING ELAPSED CPU TIME IN INTEGER ELTIME
C UNITS OF 0.01 SECONDS SINCE FUNCTION LTIME(0) WAS CALLED. ELTIME
C                                                     ELTIME
DIMENSION NT(40),MTIN(40),NC(40),IND(40) ELTIME
REAL*8 SUB(40) ELTIME
DATA SUB/ ELTIME
* 8H MAIN3D ,8H INPUT ,8H DINT ,8H PRIPLT ,8H DZP , ELTIME
* 8H PDAUX ,8H UPDATE ,8H OUTPUT ,8H DAUX ,8H SETUP1 , ELTIME
* 8H CHAIN ,8H CONTCT ,8H VISPR ,8H DAUX11 ,8H DAUX12 , ELTIME
* 8H DAUX22 ,8H DAUX31 ,8H DAUX32 ,8H DAUX33 ,8H FSMSOL , ELTIME
* 8H PLELP ,8H BELTRT ,8H SEGSEG ,8H AIRBAG ,8H RSTART , ELTIME
* 8H SETUP2 ,8H IMPULS ,8H IMPLS2 ,8H AIRBG3 ,8H DAUX55 , ELTIME
* 8H EJOINT ,8H SPDAMP ,8H DAUX44 ,8H FLXSEG ,8H EQUILB , ELTIME
* 8H POSTPR ,8H WINDY ,8H HBELT ,8H HPTURB ,8H / ELTIME
IF (N.GT.1) GO TO 20 ELTIME
IF (L.GT.1) GO TO 40 ELTIME
C ELTIME
C INITIAL CALL AT BEGINNING OF MAIN PROGRAM. ELTIME
C ELTIME
MTIN(1) = LTIME(0) ELTIME
DO 11 I=1,40 ELTIME
IND(I) = 0 ELTIME
NC(I) = 0 ELTIME
MTIN(I) = -1 ELTIME
11 NT(I) = 0 ELTIME
NSUB = 1 ELTIME
IND(1) = 1 ELTIME
NC(1) = 1 ELTIME
MTIN(1) = 0 ELTIME
GO TO 99 ELTIME
C ELTIME
C CALL AT BEGINNING OF NTH SUBROUTINE. ELTIME
C ELTIME
20 IF (L.GT.1) GO TO 30 ELTIME
MTIN(N) = LTIME(1) ELTIME
IF (NC(N).NE.0) GO TO 21 ELTIME
NSUB = NSUB+1 ELTIME
IND(NSUB) = N ELTIME
21 NC(N) = NC(N)+1 ELTIME
GO TO 99 ELTIME

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C		ELTIME
C	CALL AT END OF NTH SUBROUTINE.	ELTIME
C		ELTIME
	30 MTOUT = LTIME(1)	ELTIME
	NDIFF = MTOUT-MTIN(N)	ELTIME
	MTIN(N) = -1	ELTIME
	IF (NDIFF.EQ.0) GO TO 32	ELTIME
	NT(N) = NT(N) + NDIFF	ELTIME
	DO 31 I=1,40	ELTIME
	IF (MTIN(I).NE.-1) MTIN(I) = MTIN(I) + NDIFF	ELTIME
	31 CONTINUE	ELTIME
	32 GO TO 99	ELTIME
C		ELTIME
C	SUBSEQUENT CALLS FROM MAIN PROGRAM, PRINT SUMMARY TABLE.	ELTIME
C		ELTIME
	40 NTSUM = LTIME(1)	ELTIME
	NT(1) = NTSUM - MTIN(1)	ELTIME
	TIME = FLOAT(NTSUM)/100.0	ELTIME
	WRITE (6,41) TIME,L	PAGE
	41 FORMAT('1 ELAPSED CPU TIME =',F10.2,' SECONDS',85X,'PAGE',I5//	PAGE
	* ' SUB CALLS TIME % '//)	ELTIME
	PCSUM = 0.0	ELTIME
	NTSUM = 0	ELTIME
	DO 42 I=1,NSUB	ELTIME
	J = IND(I)	ELTIME
	PC = FLOAT(NT(J))/TIME	ELTIME
	PCSUM = PCSUM + PC	ELTIME
	NTSUM = NTSUM + NT(J)	ELTIME
	42 WRITE (6,43) SUB(J),NC(J),NT(J),PC	ELTIME
	43 FORMAT(A10,2I10,F10.2)	ELTIME
	WRITE (6,44) NTSUM,PCSUM	ELTIME
	44 FORMAT('0TOTAL',14X,I10,F10.2)	ELTIME
	99 RETURN	ELTIME
	END	ELTIME

C  
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SUBROUTINE EQUILB (YPR,IYPR)                                EQUILB
                                                                REV IV    02/01/88MISDOT
                                                                EQUILB
ADJUSTS INITIAL INPUT POSITION PARAMETERS SUPPLIED ON CARDS G.2 EQUILB
AND G.3 SUCH THAT INITIAL NORMAL CONTACT FORCES ARE EQUAL TO EQUILB
EITHER SUPPLIED VALUES OR THOSE COMPUTED BY CONSTRAINT FORCES. EQUILB
                                                                EQUILB
IMPLICIT REAL*8(A-H,O-Z)                                    EQUILB
DIMENSION YPR(3,30) , IYPR(4,30)                            EQUILB
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,      EQUILB
* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG          PAGE
COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30), EQUILB
* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)             EQUILB
COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60), SLIP
* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),           EQUILB
* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)          EQUILB
COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60), EQUILB
* F(3,30),TQ(3,30),WJ(30),A11(3,3,30)                       SLIP
COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24), EQUILB
* HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12), EQUILB
* RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),                    EQUILB
* KQ1(12),KQ2(12),KQTYPE(12)                                EQUILB
COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500) DIMENB
COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6), EQUILB
* MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6), EQUILB
* NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30)                      EQUILB
COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)   EDGE
COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),                  EQUILB
* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI                        TWOPI
COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5), EQUILB
* BLTTTL(5,8),PLTTL(5,30),BAGTTL(5,6),SEG(30),             EQUILB
* JOINT(30),CGS(30),JS(30)                                  EQUILB
COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20), EQUILB
* PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF               EQUILB
REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,SEG,JOINT EQUILB
LOGICAL*1 CGS,JS                                           EQUILB
COMMON/TEMPVS/ DMNT(3,3),XMN(3),XMM(3),TM(3),RM(3)         EQUILB
DIMENSION TEMP(3),T(5),FX(10),FX1(10)                      EDGE
DIMENSION X(10),GX(10),DX(10),DXP(10),DPN(5,10)           EQUILB
DIMENSION JPL(10),JSG(10),JX(10),M1(10),M2(10),M3(10),MT(10) EQUILB
DIMENSION NTV(10),NI1(10),NSG(10),NAV(10),KSG(5,10)       EQUILB
DIMENSION ISG(5),IPL(5),LTYPE(5),INDGX(5),NTNQ(5)         EQUILB
DIMENSION SX(10),SGX(10),XDEV(10),WORD(2)                 EQUILB
DATA BLANK/' ' / , WORD/' SEGLP' , ' YPR' /                EQUILB
CALL ELTIME (1,35)                                          EQUILB
                                                                EQUILB
INPUT CARDS G.4, G.5.A-G.5.N, AND G.6.A-G.6.M              EQUILB
                                                                EQUILB
READ (5,60) NVAR,NCON                                       EQUILB
WRITE (6,51) NVAR,NCON,NPG                                   PAGE
```

C  
C  
C



	NPG=NPG+1	PAGE
51	FORMAT('1',5X,'NVAR =',I3,3X,'NCON =',I3,96X,	PAGE
	* 'PAGE',I5/120X,'CARD G.4'//)	PAGE
	ICARD = 4	EQUILB
	JCARD = 0	EQUILB
	IF (NVAR.LT.1 .OR. NVAR.GT.10) GO TO 65	EQUILB
	IF (NCON.LT.0 .OR. NCON.GT.5 ) GO TO 65	EQUILB
	WRITE (6,52)	EQUILB
52	FORMAT('0',4X,'J',4X,'NTV',3X,'N11',3X,'NSG',8X,'GX',12X,'XDEV',	EQUILB
	*7X,'JPL',3X,'JSG',3X,'NAV',3X,'KSG(I,J),I=1,NAV',28X,'CARDS G.5'//)	EQUILB
	ICARD = 5	EQUILB
	DO 58 J=1,NVAR	EQUILB
	JCARD = J	EQUILB
	READ (5,53) NTV(J),N11(J),NSG(J),GX(J),XDEV(J),	EQUILB
	* JPL(J),JSG(J),IAV,(KSG(I,J),I=1,IAV)	EQUILB
53	FORMAT(3I4,2F8.0,8I4)	EQUILB
	NAV(J) = IAV	EQUILB
	WRITE (6,54) J,NTV(J),N11(J),NSG(J),GX(J),XDEV(J),	EQUILB
	* JPL(J),JSG(J),IAV,(KSG(I,J),I=1,IAV)	EQUILB
54	FORMAT(4I6,2F15.6,8I6)	EQUILB
	IF (NTV(J).LT.1 .OR. NTV(J).GT.2 ) GO TO 65	EQUILB
	IF (N11(J).LT.1 .OR. N11(J).GT.3 ) GO TO 65	EQUILB
	IF (NSG(J).LT.1 .OR. NSG(J).GT.NSEG) GO TO 65	EQUILB
	IF (NAV(J).LT.0 .OR. NAV(J).GT.5 ) GO TO 65	EQUILB
	IF (JPL(J).LT.1 .OR. JPL(J).GT.NPL ) GO TO 65	EQUILB
	IF (JSG(J).LT.1 .OR. JSG(J).GT.NSEG) GO TO 65	EQUILB
	K = JPL(J)	EQUILB
	NNPL = MNPL(K)	EQUILB
	IF (NNPL.LT.1 .OR. NNPL.GT.5) GO TO 65	EQUILB
	DO 55 I=1,NNPL	EQUILB
	IF (JSG(J).NE.MPL(2,I,K)) GO TO 55	EQUILB
	JSG(J) = I	EQUILB
	GO TO 56	EQUILB
55	CONTINUE	EQUILB
	GO TO 65	EQUILB
56	IF (NAV(J).LE.0) GO TO 58	EQUILB
	DO 57 I=1,IAV	EQUILB
	IF (KSG(I,J).LT.1 .OR. KSG(I,J).GT.NSEG) GO TO 65	EQUILB
57	CONTINUE	EQUILB
58	CONTINUE	EQUILB
	IF (NCON.LE.0) GO TO 17	EQUILB
	WRITE (6,59)	EQUILB
59	FORMAT('0',4X,'I',4X,'IPL',3X,'ISG',2X,'LTYPE',2X,'INDGX',	EQUILB
	* 87X,'CARDS G.6'//)	EQUILB
	ICARD = 6	EQUILB
	DO 64 I=1,NCON	EQUILB
	JCARD = I	EQUILB
	READ (5,60) IPL(I),ISG(I),LTYPE(I),INDGX(I)	EQUILB
	WRITE (6,61) I,IPL(I),ISG(I),LTYPE(I),INDGX(I)	EQUILB
60	FORMAT(4I4)	EQUILB

61	FORMAT(5I6)	EQUILB
	IF ( IPL(I).LT.1 .OR. IPL(I).GT.NPL ) GO TO 65	EQUILB
	IF ( ISG(I).LT.1 .OR. ISG(I).GT.NSEG) GO TO 65	EQUILB
	IF (LTYPE(I).LT.3 .OR. LTYPE(I).GT.4 ) GO TO 65	EQUILB
	IF (INDGX(I).LT.0 .OR. INDGX(I).GT.NVAR) GO TO 65	EQUILB
	J = IPL(I)	EQUILB
	NNPL = MNPL(J)	EQUILB
	IF (NNPL.LT.1 .OR. NNPL.GT.5) GO TO 65	EQUILB
	DO 62 K=1,NNPL	EQUILB
	IF (ISG(I).NE.MPL(2,K,J)) GO TO 62	EQUILB
	ISG(I) = K	EQUILB
	GO TO 63	EQUILB
62	CONTINUE	EQUILB
	GO TO 65	EQUILB
63	IF (INDGX(I).LE.0) GO TO 64	EQUILB
	K = INDGX(I)	EQUILB
	IF (IPL(I).NE.JPL(K) .OR. ISG(I).NE.JSG(K)) GO TO 65	EQUILB
64	CONTINUE	EQUILB
	GO TO 17	EQUILB
C		EQUILB
C	INPUT ERROR - PRINT MESSAGE AND TERMINATE PROGRAM.	EQUILB
C		EQUILB
65	WRITE (6,66) ICARD,JCARD	EQUILB
66	FORMAT('0 INPUT ERROR ON CARD G.',I2,'.',I2,	EQUILB
	* '. PROGRAM TERMINATED.')	EQUILB
	STOP 26	EQUILB
C		EQUILB
C	DATA INITIALIZATION.	EQUILB
C		EQUILB
17	NQORG = NQ	EQUILB
	DO 19 K=1,NVAR	EQUILB
	J = JPL(K)	EQUILB
	I = JSG(K)	EQUILB
	M1(K) = MPL(1,I,J)	EQUILB
	M2(K) = MPL(2,I,J)	EQUILB
	M3(K) = MPL(3,I,J)	EQUILB
	MT(K) = NTPL (I,J)	EQUILB
	JX(K) = 1	EQUILB
	DXP(K) = 0.0	EQUILB
	I1 = NI1(K)	EQUILB
	I2 = NSG(K)	EQUILB
	IF (NTV(K).EQ.1) X(K) = SEGLP(I1,I2)	EQUILB
	IF (NTV(K).EQ.2) X(K) = YPR(I1,I2)	EQUILB
	SX(K) = X(K)	EQUILB
	SGX(K) = GX(K)	EQUILB
	IF (NAV(K).LE.0) GO TO 19	EQUILB
	IAV = NAV(K)	EQUILB
	DO 18 L=1,IAV	EQUILB
	J2 = KSG(L,K)	EQUILB
	IF (NTV(K).EQ.1) DPN(L,K) = SEGLP(I1,I2) - SEGLP(I1,J2)	EQUILB

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18 IF (NTV(K).EQ.2) DPN(L,K) = YPR(I1,I2) - YPR(I1,J2)      EQUILB
19 CONTINUE                                                    EQUILB
   IF (NPRT(27).EQ.0) GO TO 20                                EQUILB
C   LET'S SEE WHAT USER INPUT LOOKS LIKE.                    EQUILB
C   CALL OUTPUT(0)                                             EQUILB
C   CALL DAUX(0)                                               EQUILB
C   CALL PRINT(6H USER )                                       EQUILB
C   CALL OUTPUT(1)                                             EQUILB
C   START FDF FORCE -> CONSTRAINT FORCE ITERATION              EQUILB
C   20 PENDOT = 0.0                                            EQUILB
C   DO 50 JITTER=1,10                                         EQUILB
C   ITERATE INPUT (X) SUCH THAT F(X) = G(X)                   EQUILB
C   MVAR = 2                                                    EQUILB
C   IF (NVAR.EQ.1) MVAR = 1                                    EQUILB
C   DO 32 M=1,2                                                 EQUILB
C   DO 32 I=MVAR,NVAR                                          EQUILB
C   DO 32 J=1,I                                                 EQUILB
C   NITER = 10                                                 EQUILB
C   IF (DXP(J).EQ.0.0) NITER = 50                             EQUILB
C   DX(J) = 0.25                                               EQUILB
C   N1 = M1(J)                                                  EQUILB
C   N2 = M2(J)                                                  EQUILB
C   N3 = M3(J)                                                  EQUILB
C   NP = JPL(J)                                                 EQUILB
C   NT = MT(J)                                                  EQUILB
C   I1 = NI1(J)                                                 EQUILB
C   I2 = NSG(J)                                                 EQUILB
C   IAV = NAV(J)                                                EQUILB
C   IF (NTV(J).NE.2) GO TO 15                                  EQUILB
C   CALL DRCIJK (D,YPR,IYPR,HT,I2)                             EQUILB
C   IF (NAV(J).LE.0) GO TO 15                                  EQUILB
C   DO 14 K=1,IAV                                              EQUILB
C   J2 = KSG(K,J)                                              EQUILB
14 CALL DRCIJK (D,YPR,IYPR,HT,J2)                             EQUILB
15 DO 29 ITER=1,NITER                                          EQUILB
C   CALL CHAIN(0)                                              JDRIFT
C   PEN1 = PEN                                                 EQUILB
C   NPSF = 1                                                   EDGE
C   CALL PLELP(N2,N3,N1,NP,NT)                                  MISDOT
C   PEN = PSF(1,1)                                             EDGE
C   FX1(J) = FX(J)                                             EQUILB
C   FXJ = 0.0                                                  EQUILB
C   IF (PEN.GT.0.0) FXJ = PSF(2,1)                             EDGE
C   IF (PEN.GT.0.0) CALL FRCDFL (PEN,PENDOT,NT,1,FXJ,ELOSS)  EQUILB

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FX(J) = FXJ
IF (JX(J)-2) 23,21,25
21 IF (FX(J)*FX1(J).GT.0.0) GO TO 22
IF (FX1(J).EQ.0.0) JX(J) = 1
FX(J) = FX1(J)
PEN = PEN1
DX(J) = 0.5*DX(J)
X(J) = X(J) - DX(J)
GO TO 27
22 F2 = FX(J) - GX(J)
F1 = FX1(J) - GX(J)
IF (F1*F2.LE.0.0) GO TO 24
IF (DABS(F2).LT.DABS(F1)) GO TO 23
26 FX(J) = FX1(J)
DX(J) = -DX(J)
PEN = PEN1
X(J) = X(J) + 2.0*DX(J)
GO TO 27
23 JX(J) = 1
IF (PEN.GT.0.0) JX(J) = 2
IF (ITER.GT.1 .AND. PEN.LT.0.0 .AND. PEN.LT.PEN1) GO TO 26
X(J) = X(J) + DX(J)
GO TO 27
24 DXP(J) = DX(J)/(FX(J)-FX1(J))
JX(J) = 3
25 IF (DABS(FX(J)-GX(J)).LT.EPS(6)) GO TO 30
IF (PEN.LT.0.0) CALL FRCDFL (-PEN,PENDOT,NT,1,FXJ,ELOSS)
IF (PEN.LT.0.0) FX(J) = -FXJ
X(J) = X(J) - DXP(J)*(FX(J)-GX(J))
27 IF (XDEV(J).LE.0.0) GO TO 42
IF (DABS(X(J)-SX(J)).LE.XDEV(J)) GO TO 42
WRITE (6,41) J,X(J),SX(J),XDEV(J)
41 FORMAT('0 PROGRAM IS BEING TERMINATED IN SUBROUTINE EQUILB.'//
* ' ITERATION FOR VARIABLE NO.',I3,' IS NOT CONVERGING.'//
* ' VALUE OF X IS OUT OF RANGE. VALUES OF X,SX,XDEV ARE'//
* 3G20.8)
STOP 27
42 IF (NTV(J).EQ.1) SEGLP(I1,I2) = X(J)
IF (NTV(J).EQ.2) YPR(I1,I2) = X(J)
IF (NTV(J).EQ.2) CALL DRCIJK (D,YPR,IYPR,HT,I2)
IF (NAV(J).LE.0) GO TO 29
DO 28 K=1,IAV
J2 = KSG(K,J)
IF (NTV(J).EQ.1) SEGLP(I1,J2) = X(J) - DPN(K,J)
IF (NTV(J).EQ.2) YPR(I1,J2) = X(J) - DPN(K,J)
28 IF (NTV(J).EQ.2) CALL DRCIJK (D,YPR,IYPR,HT,J2)
29 CONTINUE
30 IF (NPRT(27).NE.0) WRITE (6,31) M,I,J,ITER,X(J),FX(J)
31 FORMAT(4I3,4X,2F12.6)
32 CONTINUE

```

	IF (NQ.LE.0) GO TO 40	EQUILB
C		EQUILB
C	COMPUTE VEHICLE COORDINATES FOR FIXED POINT CONSTRAINTS.	EQUILB
C		EQUILB
	DO 35 K=1,NQ	EQUILB
	IF (KQTYPE(K).NE.1) GO TO 35	EQUILB
	IF (KQ2(K).NE.NVEH) GO TO 35	EQUILB
	L = KQ1(K)	EQUILB
	CALL DOT31(D(1,1,L),RK1(1,K),T)	EQUILB
	DO 34 I=1,3	EQUILB
34	T(I) = T(I) + SEGLP(I,L) - SEGLP(I,NVEH)	EQUILB
	CALL MAT31(D(1,1,NVEH),T,RK2(1,K))	EQUILB
35	CONTINUE	EQUILB
40	IF (NPRT(27).EQ.0) GO TO 36	EQUILB
C		EQUILB
C	SOLVE SYSTEM EQUATIONS WITH CONSTRAINTS OFF.	EQUILB
C		EQUILB
	CALL OUTPUT(0)	EQUILB
	CALL DAUX(0)	EQUILB
	CALL PRINT(6HEQUIL2)	EQUILB
	CALL OUTPUT(1)	EQUILB
C		EQUILB
C	SET UP CONSTRAINTS TO PRODUCE ZERO ACCELERATIONS.	EQUILB
C		EQUILB
36	NQ = NQORG	EQUILB
	IF (NCON.LE.0) GO TO 81	EQUILB
	DO 37 I=1,NCON	EQUILB
	NQ = NQ+1	EQUILB
	J = IPL(I)	EQUILB
	K = ISG(I)	EQUILB
	NT = NTPL(K,J)	EQUILB
	NTNQ(I) = NTAB(NT+1)	EQUILB
	NTAB(NT+1) = -NQ	EQUILB
	KQ1(NQ) = MPL(2,K,J)	EQUILB
	KQ2(NQ) = MPL(1,K,J)	EQUILB
37	KQTYPE(NQ) = LTYPE(I)	EQUILB
C		EQUILB
C	SOLVE SYSTEM EQUATIONS WITH CONSTRAINTS ON.	EQUILB
C		EQUILB
	CALL OUTPUT(0)	EQUILB
	CALL DAUX(0)	EQUILB
	IF (NPRT(27).NE.0.AND.JITTER.EQ.1) CALL PRINT(6HEQUIL1)	EQUILB
C		EQUILB
C	FETCH CONSTRAINTS FORCES NORMAL TO PLANE SURFACES.	EQUILB
C	STORE FRICTION FORCE AND TURN OFF CONSTRAINTS.	EQUILB
C		EQUILB
	CONV = 1.0	EQUILB
	DO 39 I=1,NCON	EQUILB
	MQ = NQORG+I	EQUILB
	J = IPL(I)	EQUILB

	K = ISG(I)	EQUILB
	NT = NTPL(K,J)	EQUILB
	NTAB(NT+1) = NTNQ(I)	EQUILB
	M = MPL(2,K,J)	EQUILB
	N = MPL(1,K,J)	EQUILB
	CALL DOT31(D(1,1,N),PL(1,J),TEMP)	EQUILB
	T(I) = TEMP(1)*QQ(1,MQ) + TEMP(2)*QQ(2,MQ) + TEMP(3)*QQ(3,MQ)	EQUILB
	I1 = INDGX(I)	EQUILB
	IF (I1.GT.0 .AND. DABS(GX(I1)+T(I)).GT.EPS(2)) CONV = 0.0	EQUILB
	IF (I1.GT.0) GX(I1) = 0.5*(GX(I1)-T(I))	EQUILB
	DO 38 L=1,3	EQUILB
38	TEMP(L) = QQ(L,MQ) - T(I)*TEMP(L)	EQUILB
	LT = NTAB(NT)	EQUILB
39	CALL MAT31(D(1,1,M),TEMP,TAB(LT+19))	EQUILB
	NQ = NQORG	EQUILB
	IF (CONV.EQ.1.0) GO TO 81	EQUILB
50	CONTINUE	EQUILB
C		EQUILB
C	PRINT INPUT AND CHANGES MADE.	EQUILB
C		EQUILB
81	IF (NJNT.LE.0) GO TO 86	EQUILB
	CALL OUTPUT(0)	EQUILB
	CALL DAUX(0)	EQUILB
	IPRINT = 0	EQUILB
	DO 84 J=1,NJNT	EQUILB
	IF (IPIN(J).GE.0) GO TO 84	EQUILB
	IF (VISC(4,3*J-2).GT.0.0) GO TO 84	EQUILB
	IF (IPIN(J).EQ.-1) T1 = DABS(XDY(HB(1,2*J),D(1,1,J+1),TQ(1,J)))	EQUILB
	IF (IPIN(J).LE.-2) T1 = DSQRT(TQ(1,J)**2+TQ(2,J)**2+TQ(3,J)**2)	EQUILB
	VISC(4,3*J-2) = 1.5*T1	EQUILB
	IF (IPRINT.EQ.0) WRITE (6,82)	EQUILB
82	FORMAT('0 THE FOLLOWING VALUES FOR THE MAX TORQUE FOR A LOCKED JOEQUILB	
	*INT ON CARDS B.5 HAVE BEEN SET UP BY SUBROUTINE EQUILB: '//	EQUILB
	* ' J SYM IPIN T1=VISC(4)' /)	EQUILB
	IPRINT = 1	EQUILB
	WRITE (6,83) J,JOINT(J),IPIN(J),VISC(4,3*J-2)	EQUILB
83	FORMAT(I6,1X,A4,I6,F15.6)	EQUILB
84	CONTINUE	EQUILB
86	IF (NQ.LE.0) GO TO 91	EQUILB
	IPRINT = 0	EQUILB
	DO 89 K=1,NQ	EQUILB
	IF (KQTYPE(K).NE.1) GO TO 89	EQUILB
	IF (KQ2(K).NE.NVEH) GO TO 89	EQUILB
	IF (IPRINT.EQ.0) WRITE (6,87)	EQUILB
87	FORMAT('0 THE FOLLOWING VALUES FOR RK2 ON CARDS D.6 FOR FIXED POIEQUILB	
	*NT CONSTRAINTS HAVE BEEN CHANGED BY SUBROUTINE EQUILB: '//	EQUILB
	* 5X, 'K', 3X, 'KQTYPE', 4X, 'KQ1', 5X, 'KQ2', 8X, 'RK2(X)',	EQUILB
	* 9X, 'RK2(Y)', 9X, 'RK2(Z)' /)	EQUILB
	IPRINT = 1	EQUILB
	WRITE (6,88) K,KQTYPE(K),KQ1(K),KQ2(K), (RK2(I,K), I=1,3)	EQUILB

88	FORMAT(16,3I8,3F15.6)	EQUILB
89	CONTINUE	EQUILB
91	WRITE (6,92)	EQUILB
92	FORMAT('0 THE FOLLOWING VARIABLES ON CARDS G.2 AND G.3 ',	EQUILB
	* 'HAVE BEEN CHANGED BY SUBROUTINE EQUILB:'//)	EQUILB
	DO 95 J=1,NVAR	EQUILB
	IO = NTV(J)	EQUILB
	I1 = NIL(J)	EQUILB
	I2 = NSG(J)	EQUILB
	WRITE (6,93) WORD(IO),I1,I2,SX(J),X(J),BLANK,J,SGX(J),GX(J)	EQUILB
93	FORMAT(4X,A6,'(',I2,',',I2,') FROM',F12.6,' TO',F12.6,	EQUILB
	* A4,'AND GX(',I2,') FROM',F12.6,' TO',F12.6)	EQUILB
	IF (NAV(J).LE.0) GO TO 95	EQUILB
	IAV = NAV(J)	EQUILB
	DO 94 I=1,IAV	EQUILB
	J2 = KSG(I,J)	EQUILB
	ZSX = SX(J) - DPN(I,J)	EQUILB
	ZXX = X(J) - DPN(I,J)	EQUILB
94	WRITE (6,93) WORD(IO),I1,J2,ZSX,ZXX	EQUILB
95	CONTINUE	EQUILB
	CALL ELTIME (2,35)	EQUILB
	RETURN	EQUILB
	END	EQUILB





25	T(4) = T(1)	EULRAD
	T(6) = T(3)	EULRAD
26	TMAX = 0.0	EULRAD
	J = 3	EULRAD
	DO 30 I=1,6	EULRAD
	T(I) = DMOD(T(I),TWOPI)	EULRAD
	IF (DABS(T(I)).GT.PI ) T(I) = T(I) - DSIGN(TWOPI,T(I))	EULRAD
	IF (DABS(T(I)).LT.TMAX) GO TO 30	EULRAD
	TMAX = DABS(T(I))	EULRAD
	IF (I.GT.3) J = 0	EULRAD
30	CONTINUE	EULRAD
	IF (Z.LT.0.0) T(J+3) = -T(J+3)	EULRAD
	DO 40 I=1,3	EULRAD
	IJ = I+J	EULRAD
40	A(I) = A(I) + T(IJ)	EULRAD
	RETURN	EULRAD
	END	EULRAD

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DOUBLE PRECISION FUNCTION EVALFD (D,N,L)                                EVALFD
C                                                                                   REV IV 07/23/86JTF786
C EVALUATE FUNCTION THAT IS DEFINED AT LOCATION N OF TAB ARRAY           EVALFD
C FOR ABSCISSA VALUE D. EVALUATES DERIVATIVE, FUNCTION OR INTEGRAL      EVALFD
C AS L EQUALS 0, 1, OR 2. TAB ARRAY IS DEFINED AS FOLLOWS:             EVALFD
C   TAB(N) - DO (NO RESTRICTIONS ON DO)                                  JTF786
C   TAB(N+1) - D1 (F1 DEFINED FOR DO < D < !D1!)                       JTF786
C   TAB(N+2) - D2 (F2 DEFINED FOR !D1! < D < !D2!)                     JTF786
C   TAB(N+3) - (NOT CURRENTLY USED)                                     EVALFD
C   TAB(N+4) - (NOT CURRENTLY USED)                                     EVALFD
C   TAB(N+5) - START OF DEFINITION OF 1ST PART OF FUNCTION (F1)        EVALFD
C   WHICH IS FOLLOWED BY DEFINITION OF 2ND PART OF FUNCTION (F2),      EVALFD
C   IF ANY.                                                            EVALFD
C   2ND PART OF FUNCTION EXISTS IF D2 IS NON-ZERO.                    EVALFD
C   SIGN OF D1 DETERMINES FORM OF DEFINITION FOR 1ST PART OF          EVALFD
C   THE FUNCTION.                                                       EVALFD
C                                                                                   EVALFD
C   D1 ZERO INDICATES THAT FUNCTION IS CONSTANT D2 FOR ALL D.          EVALFD
C                                                                                   EVALFD
C   D1 POSITIVE INDICATES THAT TAB(N+5)-TAB(N+10) CONTAINS             EVALFD
C   A0,A1,...A5. THE COEFFICIENTS OF A 5TH ORDER POLYNOMIAL.          EVALFD
C                                                                                   EVALFD
C   D1 NEGATIVE INDICATES THAT TAB(N+5) CONTAINS NP (REAL)            EVALFD
C   FOLLOWED BY D(1), F(1), D(2), F(2) ..., D(NP), F(NP)              EVALFD
C                                                                                   EVALFD
C   WARNING- TABULAR FUNCTION MUST BE DEFINED FOR WHOLE RANGE,        EVALFD
C   THAT IS, FROM DO TO D1 INCLUSIVE, OR D1 TO D2 INCLUSIVE.          EVALFD
C                                                                                   EVALFD
C   SIMILARLY, THE SIGN OF D2 (IF NON-ZERO) DETERMINES FORM OF        EVALFD
C   DEFINITION OF 2ND PART OF FUNCTION, IF ANY.                       EVALFD
C                                                                                   EVALFD
C   IF D < DO AND D1# 0, DERIVATIVE = 0 OR FUNCTION = F1(DO)          JTF786
C   IF D > !D1! AND D2=0, DERIVATIVE = 0 OR FUNCTION = F1(!D1!)       JTF786
C   IF D > !D2! AND D2#0, DERIVATIVE = 0 OR FUNCTION = F2(!D2!)       JTF786
C                                                                                   EVALFD
C   NOTE: PREVIOUS VERSIONS ASSUMED THAT DO WAS NON-NEGATIVE AND      JTF786
C   THAT F = 0 FOR D < DO.                                             JTF786
C                                                                                   JTF786
C   IMPLICIT REAL*8(A-H,O-Z)                                           EVALFD
C   COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500) EVALFD
C   F = 0.0                                                             EVALFD
C   IOUFR = 0                                                           EVALFD
C   DO = TAB(N)                                                         EVALFD
C   D1 = TAB(N+1)                                                       EVALFD
C   D2 = TAB(N+2)                                                       EVALFD
C   IF (D1.NE.0.0) GO TO 26                                             EVALFD
C   IF (L-1) 40,24,25                                                  JTF786
24 F = D2                                                              EVALFD

```

	GO TO 40	EVALFD
25	F= (D-D0)*D2	EVALFD
	GO TO 40	EVALFD
C		EVALFD
C	COMPUTE INDEX OF F1 DEFINITION	EVALFD
C		EVALFD
26	NP = N+5	EVALFD
	IF (L.EQ.2) GO TO 41	EVALFD
C		EVALFD
C	DERIVATIVES AND FUNCTIONS HERE, INTEGRALS HAVE OTHER LOGIC	EVALFD
C		EVALFD
	IF (D.GE.D0) GOTO 22	JTF786
C		JTF786
C	D < D0, RETURN F=0 FOR L=0, OR F=F1(D0) FOR L=1.	JTF786
C		JTF786
	IF (L.EQ.0) GOTO 40	JTF786
	X = D0	JTF786
	IF (D1.GT.0.0) GOTO 37	JTF786
	F = TAB(NP+2)	JTF786
	GOTO 40	JTF786
22	IF (D.LT.DABS(D1)) GOTO 31	EVALFD
	IF (D2.NE.0.0) GO TO 32	EVALFD
C		EVALFD
C	D .GE. !D1! , D2 = 0	EVALFD
C		EVALFD
	IF (D1.LE.0.0) GO TO 33	EVALFD
C		EVALFD
C	IOUTR.EQ.1 INDICATES D BEYOND RANGE. DERIVATIVE = 0.	EVALFD
C	IOUTR.EQ.0 INDICATES D.LE. !D1!. COMPUTE POLY DERIVATIVE	EVALFD
C		EVALFD
	IF (D.GT.DABS(D1)) IOUTR = 1	EVALFD
	X = D1	EVALFD
	GO TO 37	EVALFD
C		EVALFD
C	D0 < D < !D1!	EVALFD
C		EVALFD
31	IF (D1.LT.0.0) GO TO 35	EVALFD
	X = D	EVALFD
	GO TO 37	EVALFD
C		EVALFD
C	D .GE. !D1!, D2 NON-ZERO, USE F2	EVALFD
C		EVALFD
32	MP = 6	EVALFD
C		EVALFD
C	COMPUTE INDEX OF F2 DEFINITION	EVALFD
C		EVALFD
	IF (D1.LT.0.0) MP = 2.0 * TAB(NP)+1.0	EVALFD
	NP = NP+MP	EVALFD
	IF (D.LT.DABS(D2)) GO TO 34	EVALFD
	IF (D2.LT.0.0) GO TO 33	EVALFD

C		EVALFD
C	IOUTR.EQ.1 INDICATES D BEYOND RANGE. DERIVATIVE = 0.	EVALFD
C	IOUTR.EQ.0 INDICATES D.LE.!D2!. COMPUTE POLY DERIVATIVE	EVALFD
C		EVALFD
C	IF (D.GT.DABS(D2)) IOUTR = 1	EVALFD
C		EVALFD
C	D .GE. D2 (POSITIVE), EVALUATE F2 FOR D2	EVALFD
C		EVALFD
C	X = D2	EVALFD
C	GO TO 37	EVALFD
C		EVALFD
C	D EXCEEDS TABULAR DEFINITION, SET F = F(NP)	EVALFD
C	IF TABLE DEFINITION EXTENDS BEYOND RANGE, USE TABLE VALUES	EVALFD
C		EVALFD
C	33 MB = TAB(NP)	EVALFD
	NB = NP+MB+MB	EVALFD
	IF (D .LE. TAB(NB-1)) GO TO 35	EVALFD
	IF (L.EQ.1) F=TAB(NB)	EVALFD
	GO TO 40	EVALFD
C		EVALFD
C	!D1! .LE. D < !D2!	EVALFD
C		EVALFD
C	34 IF (D2.LT.0.0) GO TO 35	EVALFD
	X = D	EVALFD
	GO TO 37	EVALFD
C		EVALFD
C	EVALUATE F FROM TABULAR DEFINITION	EVALFD
C		EVALFD
C	35 MB = TAB(NP)	EVALFD
	K1 = NP+3	EVALFD
	K2 = NP+MB+MB	EVALFD
	DO 36 K=K1,K2,2	EVALFD
	IF (D.GT.TAB(K)) GO TO 36	EVALFD
	IF (L-1) 28,27,40	EVALFD
C		EVALFD
C	EVALUATE DERIVATIVE FROM TABLE	EVALFD
C		EVALFD
C	28 F = (TAB(K+1)-TAB(K-1))/(TAB(K)-TAB(K-2))	EVALFD
	GO TO 40	EVALFD
C		EVALFD
C	EVALUATE FUNCTION FROM TABLE	EVALFD
C		EVALFD
C	27 R2 = TAB(K)-TAB(K-2)	EVALFD
	R1 = (D-TAB(K-2))/R2	EVALFD
	R2 = (TAB(K)-D)/R2	EVALFD
	F = R1*TAB(K+1)+R2*TAB(K-1)	EVALFD
	GO TO 40	EVALFD
C	36 CONTINUE	EVALFD
	IF (L.EQ.1) F = TAB(K2)	EVALFD
	GO TO 40	EVALFD

```

37 IF (IOUTR.EQ.1 .AND. L.EQ.0 ) GO TO 40                                EVALFD
    IF (L-1) 38,39,40                                                    EVALFD
C                                                                           EVALFD
C    EVALUATE DERIVATIVE OF 5TH DEGREE POLYNOMIAL                       EVALFD
C                                                                           EVALFD
38 F = TAB(NP+1)+X*(2.0*TAB(NP+2)+X*(3.0*TAB(NP+3)+X*(4.0*TAB(NP+4)+    EVALFD
    *      X*5.0*TAB(NP+5))))                                           EVALFD
    GO TO 40                                                              EVALFD
C                                                                           EVALFD
C    EVALUATE 5TH DEGREE POLYNOMIAL                                     EVALFD
C                                                                           EVALFD
39 F =      TAB(NP) + X*(TAB(NP+1)+X*(TAB(NP+2)                          EVALFD
    *      +X*(TAB(NP+3)+X*(TAB(NP+4)+X*TAB(NP+5))))                   EVALFD
    GO TO 40                                                              EVALFD
C                                                                           EVALFD
C    L=2: COMPUTE INTEGRAL OF FUNCTION FROM D0 TO D.                   EVALFD
C                                                                           EVALFD
41 IF (D.EQ.D0) GO TO 40                                                EVALFD
    X0 = D0                                                                EVALFD
    X1 = D1                                                                EVALFD
    DO 50 I=1,2                                                         EVALFD
    IF (X1) 43,49,42                                                    EVALFD
42 A0 = TAB(NP )                                                       EVALFD
    A1 = TAB(NP+1)/2.0                                                  EVALFD
    A2 = TAB(NP+2)/3.0                                                  EVALFD
    A3 = TAB(NP+3)/4.0                                                  EVALFD
    A4 = TAB(NP+4)/5.0                                                  EVALFD
    A5 = TAB(NP+5)/6.0                                                  EVALFD
    NP = NP+6                                                            EVALFD
    X = X0                                                                EVALFD
    IF (X.NE.0.0) F=F-X*(A0+X*(A1+X*(A2+X*(A3+X*(A4+X*A5))))          EVALFD
    X = DMIN1(D,X1)                                                     EVALFD
    IF (X.NE.0.0) F=F+X*(A0+X*(A1+X*(A2+X*(A3+X*(A4+X*A5))))          EVALFD
    IF(D.LE.X1) GO TO 40                                                EVALFD
    IF(I.EQ.1.AND.D2.NE.0.0) GO TO 49                                    EVALFD
C                                                                           EVALFD
C    NOTE - NP WAS UPDATED NP=NP+6 BEFORE THIS, READY FOR SECOND PASS EVALFD
C                                                                           EVALFD
    F = F + (D-X1)*(TAB(NP-6)+X1*(TAB(NP-5)+X1*(TAB(NP-4)              EVALFD
    *      +X1*(TAB(NP-3)+X1*(TAB(NP-2)+X1*TAB(NP-1))))))              EVALFD
    GO TO 40                                                              EVALFD
43 MB = TAB(NP)                                                         EVALFD
    K1 = NP+3                                                            EVALFD
    K2 = NP+MB+MB                                                       EVALFD
    NP = K2+1                                                            EVALFD
    DL = DMIN1(D,DABS(X1))                                              EVALFD
    DO 44 K=K1,K2,2                                                     EVALFD
    IF (X0.GE.TAB(K)) GO TO 44                                          EVALFD
    Z1 = DMAX1(X0,TAB(K-2))                                             EVALFD
    Z2 = DMIN1(DL,TAB(K))                                               EVALFD

```

FYX = TAB(K-1)*TAB(K) - TAB(K+1)*TAB(K-2)	EVALFD
FY = TAB(K+1) - TAB(K-1)	EVALFD
F = F + (FYX + 0.5*FY*(Z1+Z2)) * (Z2-Z1) / (TAB(K)-TAB(K-2))	EVALFD
IF (Z2.NE.DL) GO TO 44	EVALFD
IF (I.EQ.1.AND.D2.NE.0.0) GO TO 49	EVALFD
IF (Z2. EQ. D) GO TO 40	EVALFD
F = F + (D-Z2)*(FYX+Z2*FY) / (TAB(K)-TAB(K-2))	EVALFD
GO TO 40	EVALFD
44 CONTINUE	EVALFD
49 XO = DABS(D1)	EVALFD
50 X1 = D2	EVALFD
40 EVALFD = F	EVALFD
RETURN	EVALFD
END	EVALFD



```
IF (MXTB2.GT.4500) WRITE (6,62) MXTB2 DIMENB
62 FORMAT ('0 ERROR IN SUBROUTINE FDINIT, SIZE OF TAB ARRAY =',I8// FDINIT
* ' PROGRAM TERMINATED.') FDINIT
IF (MXNTB.GT.1250) WRITE (6,63) MXNTB DIMENB
63 FORMAT ('0 ERROR IN SUBROUTINE FDINIT, SIZE OF NTAB ARRAY =',I8// FDINIT
* ' PROGRAM TERMINATED.') FDINIT
IF (MXTB2.GT.4500.OR.MXNTB.GT.1250) STOP 16 DIMENB
RETURN FDINIT
END FDINIT
```



```

SUBROUTINE FINPUT                                FINPUT
C                                               REV IV    02/01/88MISDOT
C INPUT CARDS F.1-F.5 SPECIFYING THE ALLOWED CONTACTS OF THE CRASH FINPUT
C VICTIM BODY SEGMENTS WITH VEHICLE PANELS, BELTS, AIRBAGS AND OTHERFINPUT
C BODY SEGMENTS ALONG WITH THE ASSOCIATED FUNCTIONS TO BE USED FOR FINPUT
C EACH CONTACT.                                FINPUT
C ALSO SETS UP TABLES TO CONTROL TIME HISTORY INFORMATION FOR FINPUT
C EACH FUNCTION FOR EACH ALLOWED CONTACT.      FINPUT
C                                               FINPUT
C IMPLICIT REAL*8(A-H,O-Z)                      FINPUT
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND, FINPUT
* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG PAGE
COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60), SLIP
* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90), FINPUT
* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30) FINPUT
COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6), FINPUT
* MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6), FINPUT
* NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30) FINPUT
COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)DIMENB
COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5), FINPUT
* BLTTTL(5,8),PLTTL(5,30),BAGTTL(5,6),SEG(30), FINPUT
* JOINT(30),CGS(30),JS(30) FINPUT
REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,SEG,JOINT FINPUT
LOGICAL*1 CGS,JS FINPUT
COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24), FINPUT
* HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12), FINPUT
* RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12), FINPUT
* KQ1(12),KQ2(12),KQTYPE(12) FINPUT
COMMON/WINDFR/ WTIME(30),QFU(3,5),QFV(3,5),WF(3,30),IWIND(30), WINDOP
* MWSEG(7,30),NFVSEG(6),NFVNT(5),MOWSEG(30,30) WINDOP
COMMON/TEMPVS/JTITLE(5,51),NF(5),MS(3),KTITLE(31) FINPUT
C                                               FINPUT
REAL JTITLE,KTITLE,BLANK,SURFCE(2,3) FINPUT
DATA BLANK/4H / FINPUT
DATA SURFCE/4H PL,4HANE ,4H BE,4HLT ,4H SEG,4HMENT/ FINPUT
C                                               FINPUT
MXNTI = 50 FINPUT
MXNTB = 0 FINPUT
MXTB2 = MXTB1 FINPUT
C                                               FINPUT
C INPUT ALLOWED CONTACTS AND FUNCTIONS BY REF. NO. FINPUT
C                                               FINPUT
WRITE (6,31) NPG PAGE
NPG=NPG+1 PAGE
31 FORMAT('1 ALLOWED CONTACTS AND ASSOCIATED FUNCTIONS',80X, PAGE
* 'PAGE',15) PAGE
DO 61 I=1,4 FINPUT
IJK = 0 FINPUT
GO TO (32,34,35,36),I FINPUT
32 IF (NPL.LE.0) GO TO 61 FINPUT

```

C		FINPUT
C	INPUT NO. OF SEGMENTS TO CONTACT EACH PLANE.	FINPUT
C	INPUT CARD F.1.A	FINPUT
C		FINPUT
	READ (5,33) (MNPL(J),J=1,NPL)	FINPUT
33	FORMAT(18I4)	FINPUT
	NJJ = NPL	FINPUT
	GO TO 37	FINPUT
34	IF (NBLT.LE.0) GO TO 61	FINPUT
C		FINPUT
C	INPUT NO. OF SEGMENTS TO CONTACT EACH BELT.	FINPUT
C	INPUT CARD F.2.A	FINPUT
C		FINPUT
	READ (5,33) (MNBLT(J),J=1,NBLT)	FINPUT
	NJJ = NBLT	FINPUT
	GO TO 37	FINPUT
35	IF (NSEG.LE.0) GO TO 61	FINPUT
C		FINPUT
C	INPUT NO. OF SEGMENTS TO CONTACT EACH SEGMENT.	FINPUT
C	INPUT CARD F.3.A	FINPUT
C		FINPUT
	READ (5,33) (MNSEG(J),J=1,NSEG)	FINPUT
	NJJ = NSEG	FINPUT
	NSEG1 = NSEG+1	FINPUT
	DO 26 J=NSEG1,NGRND	FINPUT
26	MNSEG(J) = 0	FINPUT
	GO TO 37	FINPUT
36	IF (NJNT.LE.0) GO TO 61	FINPUT
C		FINPUT
C	INPUT CARD F.4.A	FINPUT
C	SUPPLY IGLOB(J)=1 FOR EACH GLOBALGRAPHIC JOINT J=1,NJNT	FINPUT
C		FINPUT
	READ (5,33) (IGLOB(J),J=1,NJNT)	FINPUT
	NJJ = NJNT	FINPUT
C		FINPUT
C	START OF LOOP TO READ CONTACTS FOR PLANES (I=1), BELTS (I=2),	FINPUT
C	SEGMENTS (I=3) AND FUNCTIONS FOR GLOBALGRAPHIC JOINTS (I=4).	FINPUT
C		FINPUT
37	DO 60 J=1,NJJ	FINPUT
	IF (I.EQ.1) NK = MNPL(J)	FINPUT
	IF (I.EQ.2) NK = MNBLT(J)	FINPUT
	IF (I.EQ.3) NK = MNSEG(J)	FINPUT
	IF (I.EQ.4) NK = IGLOB(J)	FINPUT
	IF (NK.LE.0) GO TO 60	FINPUT
	DO 59 K=1,NK	FINPUT
	IF (IJK.EQ.0) WRITE (6,38) I	FINPUT
38	FORMAT('0',119X,'CARDS F.',I1)	FINPUT
	IF (IJK.EQ.0 .AND. I.NE.4) WRITE (6,39) SURFCE(1,I),SURFCE(2,I)	FINPUT
39	FORMAT('0',3X,2A4,8X,'SEGMENT',2X,'FORCE DEFLECTION',6X,'INERTIAL	FINPUT
	*SPIKE',10X,'R FACTOR',13X,'G FACTOR',10X,'FRICTION COEF. OPT')	EDGE

```

IF (IJK.EQ.0 .AND. I.EQ.4) WRITE (6,40) FINPUT
40 FORMAT('0',5X,'JOINT (GLOBALGRAPHIC)',2X,'TORQUE DEFLECTION',6X,'HFINPUT
*ERRON FORMULA',10X,'R FACTOR',13X,'G FACTOR',10X,'FRICTION COEF.')FINPUT
IJK = 1 FINPUT
C FINPUT
C INPUT CONTACT SURFACE NO., SEGMENT NO., AND FUNCTION NOS. FINPUT
C INPUT CARD F. (I). (K) FINPUT
C FINPUT
READ (5,33) NJ,MS,NF,NX EDGE
WRITE (6,41) NJ,MS,NF,NX EDGE
41 FORMAT('0',I7,'-',I3,I11,'-',I3,I8,4I21,I12) EDGE
IF (NJ.NE.J) WRITE (6,42) FINPUT
42 FORMAT(' CONTACT INPUT ERROR. PROGRAM TERMINATED.') FINPUT
IF (NJ.NE.J) STOP 14 FINPUT
IF (I.NE.2.AND.NF(5).EQ.0) WRITE(6,20) MISDOT
20 FORMAT(' FRICTION FUNCTION NUMBER CAN NOT BE ZERO FOR THIS TYPE OFMISDOT
* CONTACT') MISDOT
IF (I.NE.2.AND.NF(5).EQ.0) STOP 105 MISDOT
NLT = 1 FINPUT
DO 43 JJ = 1,31 FINPUT
43 KTITLE(JJ) = BLANK FINPUT
GO TO (44,46,48,49),I FINPUT
C FINPUT
C PLACE SEGMENT NO. AND INDEX TO NTAB ARRAY INTO M- AND NT- ARRAYS. FINPUT
C FINPUT
44 MPL(1,K,J) = MS(1) FINPUT
MPL(2,K,J) = MS(2) FINPUT
MPL(3,K,J) = MS(3) FINPUT
NTPL(K,J) = MXNTB+1 FINPUT
DO 45 JJ = 1,5 FINPUT
45 KTITLE(JJ) = PLTTL (JJ,J) FINPUT
GO TO 50 FINPUT
46 MBLT(1,K,J) = MS(1) FINPUT
MBLT(2,K,J) = MS(2) FINPUT
MBLT(3,K,J) = MS(3) FINPUT
NTBLT(K,J) = MXNTB+1 FINPUT
DO 47 JJ = 1,5 FINPUT
47 KTITLE(JJ) = BLTTTL (JJ,J) FINPUT
C FINPUT
C SET UP TWO TABLES FOR FULL BELT FRICTION FINPUT
C FINPUT
IF (NF(5).NE.0) NLT = 2 FINPUT
GO TO 50 FINPUT
48 MSEG(1,K,J) = MS(1) FINPUT
MSEG(2,K,J) = MS(2) FINPUT
MSEG(3,K,J) = MS(3) FINPUT
NTSEG(K,J) = MXNTB+1 FINPUT
KTITLE (3) = SEG(J) FINPUT
GO TO 50 FINPUT
C FINPUT

```

C	NOTE: GLOBALGRAPHIC JOINT WILL SAVE NT IN IGLOBAL ARRAY	FINPUT
C		FINPUT
	49 IGLOBAL(J) = MKNTB+1	FINPUT
	KTITLE(2) = JOINT(J)	FINPUT
C		FINPUT
C	SET UP POINTERS TO TAB ARRAY IN NTAB ARRAY.	FINPUT
C		FINPUT
	50 NFJ = MS(2)	FINPUT
	IF (NFJ.GT.0) KTITLE(6) = SEG(NFJ)	FINPUT
	DO 51 JJ=1,NLT	FINPUT
	51 CALL FDINIT	FINPUT
	WRITE (6,53) KTITLE	FINPUT
	53 FORMAT(1X,5A4,1X,A4,5(1X,5A4))	FINPUT
	LT = NTAB(MKNTB-5)	EDGE
	IF (I.EQ.1) TAB(LT+22) = NX	EDGE
	IF (NF(1).NE.0) GO TO 59	EDGE
C		FINPUT
C	IF FORCE DEFLECTION FUNCTION NO. IS ZERO,	FINPUT
C	SET UP FOR ROLLING CONSTRAINT	FINPUT
C		FINPUT
	NQ = NQ+1	FINPUT
	NTAB(MKNTB-4) = -NQ	FINPUT
	KQTYPE(NQ) = -4	FINPUT
	KQ1(NQ) = MS(2)	FINPUT
	KQ2(NQ) = MS(1)	FINPUT
	IF (I.NE.3) GO TO 59	EDGE
	KQ1(NQ) = J	FINPUT
	KQ2(NQ) = MS(2)	FINPUT
	59 CONTINUE	FINPUT
	60 CONTINUE	FINPUT
	61 CONTINUE	FINPUT
C		FINPUT
C	INPUT CARD F.5 - JOINT FUNCTIONS TO BE USED.	FINPUT
C		FINPUT
	IF (NJNT.LE.0) GO TO 81	FINPUT
	IF (NJNTF.NE.0) GO TO 76	FINPUT
	DO 75 J=1,NJNT	FINPUT
	75 JOINTF(J) = 0	FINPUT
	GO TO 81	FINPUT
	76 READ (5,33) (JOINTF(J),J=1,NJNT)	FINPUT
	IJK = 0	FINPUT
	DO 80 J=1,NJNT	FINPUT
	IF (JOINTF(J).EQ.0) GO TO 80	FINPUT
	IF (IJK.EQ.0) WRITE (6,77) NPG	PAGE
	IF (IJK.EQ.0) NPG=NPG+1	PAGE
	77 FORMAT('1',122X,'PAGE',I5/120X,'CARD F.5'/	PAGE
	* ' THE FOLLOWING JOINT RESTORING FORCE FUNCTIONS AS DEFINED	FINPUT
	*ON CARDS E.7 WILL BE USED.'//4X,'JOINT',10X,'FUNCTION'//)	FINPUT
	JF = JOINTF(J)	FINPUT
	IJK = 1	FINPUT

	WRITE (6,78) J,JOINT(J),JF,(JTITLE(I,JF),I=1,5)	FINPUT
	78 FORMAT(I6,'-',A4,I10,'-',5A4)	FINPUT
	IF (NTI(JF).EQ.0) WRITE (6,42)	FINPUT
	IF (NTI(JF).EQ.0) STOP 17	FINPUT
	80 CONTINUE	FINPUT
C		FINPUT
C	INPUT CONTACT SEGMENTS FOR AIRBAG, IF ANY.	FINPUT
C		FINPUT
	81 IF (NBAG.LE.0) GO TO 69	FINPUT
	IJK = 0	FINPUT
	DO 68 J=1,NBAG	FINPUT
C		FINPUT
C	INPUT CARD F.6.(J)	FINPUT
C		FINPUT
	READ (5,63) K,NK,(MBAG(2,I,J),MBAG(3,I,J),I=1,NK)	FINPUT
	63 FORMAT(2I4,20I2)	FINPUT
	MNBAG(J) = NK	FINPUT
	IF (NK.EQ.0) GO TO 68	FINPUT
	IF (IJK.EQ.0) WRITE (6,64)	FINPUT
	64 FORMAT(///5X,'AIRBAG',4X,'VS.',4X,'SEGMENTS',90X,'CARDS F.6')	FINPUT
	IF (K.NE.J) WRITE (6,42)	FINPUT
	IF (K.NE.J) STOP 20	FINPUT
	WRITE (6,65) J,(MBAG(2,I,J),MBAG(3,I,J),I=1,NK)	FINPUT
	65 FORMAT('0 NO.',I2,12X,10(I3,'-',I3))	FINPUT
	DO 66 I=1,NK	FINPUT
	K = MBAG(2,I,J)	FINPUT
	66 KTITLE(I) = SEG(K)	FINPUT
	WRITE (6,67) (BAGTTL(I,J),I=1,5),(KTITLE(I),I=1,NK)	FINPUT
	67 FORMAT(1X,5A4,10(3X,A4))	FINPUT
	68 CONTINUE	FINPUT
C		FINPUT
C	INPUT CARDS F.7.A-F.7.B FOR SUBROUTINE WINDY.	FINPUT
C		FINPUT
	69 DO 85 J=1,NGRND	FINPUT
	85 MWSEG(1,J) = 0	FINPUT
	IF (NWINDF.EQ.0) GO TO 99	FINPUT
	READ (5,33) (MWSEG(1,J),J=1,NSEG)	FINPUT
	IPAGE = 0	FINPUT
	DO 73 J=1,NSEG	FINPUT
	IWIND(J) = 0	FINPUT
	WTIME(J) = 0.0	FINPUT
	IF (MWSEG(1,J).EQ.0) GO TO 73	FINPUT
	IF (IPAGE.EQ.0) WRITE (6,70) NPG	PAGE
	IF (IPAGE.EQ.0) NPG=NPG+1	PAGE
	70 FORMAT('1 SEGMENT WIND FORCES',102X,'PAGE',I5/120X,'CARDS F.7'/	PAGE
	* 75X,'DRAG COEFFICIENT BLOCKING'/	WINDOP
	* ' SEGMENT-ELLIPSOID SEGMENT-PLANE',	WINDOP
	* 16X,'WIND FORCE FUNCTION',10X,'FUNCTION',9X,	WINDOP
	* 'SEGMENTS-ELLIPSOID')	WINDOP
	IPAGE = 1	FINPUT

READ(5,86)(MWSEG(I,J),I=1,7),(MOWSEG(J,K),K=1,2*MWSEG(7,J))	WINDOP
86 FORMAT(7I4,22I2/(I30,7I2))	WINDOP
WRITE(6,71)(MWSEG(I,J),I=1,6)	OUT385
71 FORMAT(1H0,I6,2H -,I3,I13,2H -,I3,I31,I23)	OUT385
IF(IABS(MWSEG(1,J)).NE.J) WRITE(6,42)	WINDOP
IF(IABS(MWSEG(1,J)).NE.J) STOP 21	WINDOP
M3 = MWSEG(3,J)	FINPUT
M4 = MWSEG(4,J)	FINPUT
M5 = MWSEG(5,J)	FINPUT
M6 = MWSEG(6,J)	WINDOP
M7 = MWSEG(7,J)	OUT385
DO 172 II=1,5	FIXWBS
KTITLE(II)=BLANK	FIXWBS
172 IF(M6.NE.0) KTITLE(II)=JTITLE(II,M6)	FIXWBS
WRITE(6,72) SEG(J),SEG(M3),(PLTTL(I,M4),I=1,5)	FINPUT
* , (JTITLE(I,M5),I=1,5), (KTITLE(I),I=1,5)	FIXWBS
* , (MOWSEG(J,K),K=1,2*M7)	OUT385
72 FORMAT(3X,A4,14X,A4,1H-,5A4,3X,5A4,3X,5A4,2X,3(5(I3,1H-,I3)/94X))	OUT385
73 CONTINUE	FINPUT
99 RETURN	FINPUT
END	FINPUT

	SUBROUTINE FLXSEG		FLXSEG
C		REV IV 07/23/86	TWOPI
	IMPLICIT REAL*8(A-H,O-Z)		FLXSEG
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		FLXSEG
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		FLXSEG
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		FLXSEG
	COMMON/FLXBLE/ HF(4,12,8),B42(3,3,24),V4(3,8),NFLEX(3,8)		FLXSEG
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		FLXSEG
	* UNITL,UNITM,UNITT,GRAVTY(3),TWOPI		TWOPI
	COMMON/TEMPVS/ TT(3,3), THN(4), CN1(3,3), CN(3,3), WNM1(3),		FLXSEG
	* THND(4), PTD(3), WCSN(3), RHSN(3), RHS1(3),		FLXSEG
	* RHS2(3), GF(3,4), GC(3,3), CGC(3,3), THA(3),		FLXSEG
	* THAD(3), THADEG(3), DN2N1(3,3), RMG(3)		FLXSEG
	DIMENSION IDYPR(3)		FLXSEG
	DATA IDYPR/3,2,1/		FLXSEG
	IF (NFLX.EQ.0) GO TO 99		FLXSEG
	CALL ELTIME(1,34)		FLXSEG
	IFX = 1		FLXSEG
11	N1 = NFLEX(1,IFX)		FLXSEG
	N3 = NFLEX(3,IFX)		FLXSEG
	CALL DOT33(D(1,1,N3),D(1,1,N1),TT)		FLXSEG
	THN(1) = DATAN2(TT(1,2),TT(1,1))		FLXSEG
	THN(2) = -DASIN(TT(1,3))		FLXSEG
	THN(3) = DATAN2(TT(2,3),TT(3,3))		FLXSEG
	THN(4) = 1.0		FLXSEG
	CT22 = 1.0-TT(1,3)**2		FLXSEG
	CT2 = DSQRT(CT22)		FLXSEG
	ST2 = -TT(1,3)		FLXSEG
	CT1 = TT(1,1)/CT2		FLXSEG
	ST1 = TT(1,2)/CT2		FLXSEG
	CN1(1,1) = -TT(1,1)*TT(1,3)/CT22		FLXSEG
	CN1(1,2) = -TT(1,2)*TT(1,3)/CT22		FLXSEG
	CN1(1,3) = 1.0		FLXSEG
	CN1(2,1) = -ST1		FLXSEG
	CN1(2,2) = CT1		FLXSEG
	CN1(2,3) = 0.0		FLXSEG
	CN1(3,1) = TT(1,1)/CT22		FLXSEG
	CN1(3,2) = TT(1,2)/CT22		FLXSEG
	CN1(3,3) = 0.0		FLXSEG
	CALL DOT31(TT,WMEG(1,N3),WNM1)		FLXSEG
	DO 12 I=1,3		FLXSEG
12	WNM1(I) = WNM1(I) - WMEG(I,N1)		FLXSEG
	CALL MAT31(CN1,WNM1,THND)		FLXSEG
	THND(4) = 0.0		FLXSEG
	CALL CROSS(WMEG(1,N1),WNM1,WCSN)		FLXSEG
	RHSN(1) = ( (-THND(1)*ST1*ST2 + THND(2)*CT1/CT2)*WNM1(1)		FLXSEG
	* + ( THND(1)*CT1*ST2 + THND(2)*ST1/CT2)*WNM1(2) )/CT2		FLXSEG
	RHSN(2) = -THND(1)*(CT1*WNM1(1) + ST1*WNM1(2))		FLXSEG
	RHSN(3) = ( (-THND(1)*ST1 + THND(2)*CT1*ST2/CT2)*WNM1(1)		FLXSEG





25	RHS1(I) = RHS2(I) - RHS1(I)	FLXSEG
	CALL MAT31(GC, WNM1, RHS2)	FLXSEG
	RHS1(1) = RHS1(1) - THAD(1)*(CN(2,2)*RHS2(2)-CN(1,2)*CSC*RHS2(3))	FLXSEG
*	- THAD(2)*CN(2,2)*CSS*RHS2(3)	FLXSEG
	RHS1(2) = RHS1(2) + THAD(1)*(CN(1,2)*RHS2(2)+CN(2,2)*CSC*RHS2(3))	FLXSEG
*	+ THAD(2)*CN(1,2)*CSS*RHS2(3)	FLXSEG
	RHS1(3) = RHS1(3) - THAD(2)*CSC*RHS2(3)	FLXSEG
	CALL MAT31(GF, RHSN, RHS2)	FLXSEG
	M = 1	FLXSEG
	DO 30 I=1,3	FLXSEG
	DO 26 J=1,3	FLXSEG
	PTD(J) = 0.0	FLXSEG
	DO 26 K=1,3	FLXSEG
	KK = K+M-1	FLXSEG
26	PTD(J) = PTD(J) + HF(J, KK, IFX)*THND(K)	FLXSEG
	RHS2(I) = RHS2(I) + XDY(PTD, CN1, WNM1)	FLXSEG
30	M = M+4	FLXSEG
	CALL MAT31(CN, RHS2, PTD)	FLXSEG
	DO 35 I=1,3	FLXSEG
35	RHS1(I) = RHS1(I) + PTD(I)	FLXSEG
	CALL DOT31(D(1,1,N1), RHS1, V4(1, IFX))	FLXSEG
	IF (IFX.EQ.NFLX) GO TO 98	FLXSEG
	IFX = IFX+1	FLXSEG
	IF (NFLEX(1, IFX).EQ.N1 .AND. NFLEX(3, IFX).EQ.N3) GO TO 13	FLXSEG
	GO TO 11	FLXSEG
98	CALL ELTIME(2, 34)	FLXSEG
99	RETURN	FLXSEG
	END	FLXSEG

```

C      DOUBLE PRECISION FUNCTION FENTERP(THETA,PHI,NT)                                FENTERP
C                                                                                   REV IV   04/10/87FNFIX
C      COMPUTES THE RESTORING TORQUE OF A JOINT AS A FUNCTION OF THE FENTERP
C      FLEXURE ANGLE (THETA) AND THE AZIMUTH ANGLE (PHI) AS DEFINED BY FENTERP
C      FUNCTION NO. NT FENTERP
C
C      ASSUMES  0 < THETA < PI FENTERP
C              -PI < PHI < PI FENTERP
C              DATA IN TAB ARRAY CONTAINS NTHETA,NPHI FOLLOWED BY FENTERP
C              TWO DIMENSIONAL ARRAY OF FUNCTIONAL VALUES (NTHETA > 0) FENTERP
C              OR POLYNOMIAL COEFFICIENTS (NTHETA < 0) FOR EQUALLY FENTERP
C              SPACED VALUES OF PHI. FENTERP
C
C              THETA(I) = (I-1)*PI/(NTHETA-1) FOR I=1,NTHETA FENTERP
C              PHI(J) = -PI + (J-1)*2*PI/NPHI FOR J=1,NPHI FENTERP
C              F(THETA,PI) = F(THETA,-PI) FENTERP
C
C      SUBROUTINE EVALUATES G1(THETA) = F(THETA,PHI(J) ) FENTERP
C              G2(THETA) = F(THETA,PHI(J+1)) FENTERP
C              FOR PHI(J) < PHI < PHI(J+1) FENTERP
C      BY LINEAR INTERPOLATION OR POLYNOMIAL EVALUATION AND THEN LINEAR FENTERP
C      INTERPOLATES BETWEEN G1 AND G2 TO OBTAIN F(THETA,PHI). FENTERP
C      IF F < 0, F IS SET TO ZERO, THEREFORE A DEAD BAND IS OBTAINED FENTERP
C      BY NEGATIVE VALUES IN THE TABLE. FENTERP
C
C      IMPLICIT REAL*8 (A-H,O-Z) FENTERP
C      COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24), FENTERP
C      *      UNITL,UNITM,UNITT,GRAVTY(3),TWOPI FENTERP
C      COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)DIMENB FENTERP
C      IERROR = 0 FENTERP
C      IF (PHI.LT.-PI) IERROR = 1 FENTERP
C      IF (PHI.GT. PI) IERROR = 2 FENTERP
C      IF (THETA.LT.0.0) IERROR = 3 FENTERP
C      IF (THETA.GT.PI ) IERROR = 4 FENTERP
C      IF (IERROR.NE.0) WRITE (6,11) IERROR,THETA,PHI,NT FENTERP
11  FORMAT('0 IMPROPER ARGUMENTS TO FUNCTION FENTERP. ERROR CODE = ',I4/FENTERP
C      *      '0 THETA =',G25.15, ' PHI =',G25.15,' NT =',I6) FENTERP
C      IF (IERROR.NE.0) STOP 36 FENTERP
C      NF = NTI(NT) + 5 FENTERP
C      NTHETA = TAB(NF) FENTERP
C      NPHI = TAB(NF+1) FENTERP
C
C      DETERMINE INDEX AND INTERPOLATION PARAMETERS FOR PHI. FENTERP
C
C      IF (PHI.GE.PI-EPS(15)) PHI=0.0-PI FNFIX
C      XNP = (PHI+PI)/TWOPI*TAB(NF+1) TWOPI
C      NP1 = XNP FENTERP
C      NP2 = NP1+1 FENTERP
C      IF (NP2.GE.NPHI) NP2 = 0 FENTERP
C      RP2 = XNP - DFLOAT(NP1) FENTERP

```

	RP1 = 1.0 - RP2	FNTERP
	NTH = IABS(NTHETA)	FNTERP
	IP1 = NF+1+NP1*NTH	FNTERP
	IP2 = NF+1+NP2*NTH	FNTERP
C		FNTERP
C	DETERMINE INDEX AND INTERPOLATION PARAMETERS FOR THETA.	FNTERP
C		FNTERP
	IF (NTHETA.LT.0) GO TO 20	FNTERP
	XNT = THETA/PI*(TAB(NF)-1.0)	FNTERP
	NT1 = XNT	FNTERP
	RT2 = XNT - DFLOAT(NT1)	FNTERP
	RT1 = 1.0 - RT2	FNTERP
	IT1 = IP1 + NT1	FNTERP
	IT2 = IP2 + NT1	FNTERP
	G1 = RT1*TAB(IT1+1) + RT2*TAB(IT1+2)	FNTERP
	G2 = RT1*TAB(IT2+1) + RT2*TAB(IT2+2)	FNTERP
	GO TO 23	FNTERP
C		FNTERP
C	COMPUTE FOR POLYNOMIALS IN THETA FOR FIXED PHI.	FNTERP
C		FNTERP
	20 NPOLY = -NTHETA-1	FNTERP
	IT1 = IP1 + NPOLY + 2	FNTERP
	IT2 = IP2 + NPOLY + 2	FNTERP
	THETA1 = THETA - TAB(IP1+1)	FNTERP
	THETA2 = THETA - TAB(IP2+1)	FNTERP
	G1 = 0.0	FNTERP
	G2 = 0.0	FNTERP
	DO 21 I=1,NPOLY	FNTERP
	IT1 = IT1-1	FNTERP
	IT2 = IT2-1	FNTERP
	G1 = THETA1*(TAB(IT1)+G1)	FNTERP
	21 G2 = THETA2*(TAB(IT2)+G2)	FNTERP
	IF (THETA1.LT.0.0) G1=0.0	FNFIX
	IF (THETA2.LT.0.0) G2=0.0	FNFIX
	23 FNTERP = RP1*G1 + RP2*G2	FNTERP
	IF (FNTERP.LT.0.0) FNTERP = 0.0	FNTERP
	RETURN	FNTERP
	END	FNTERP

```

SUBROUTINE FRCDFL (D,RATE,M,N,FRCDF,ELOSS)                                FRCDFL
C                                                                           REV III.2 08/08/84REVIII
C EVALUATE FORCE DEFLECTION FUNCTION AT POINT D, WHERE DEFINITION        FRCDFL
C OF FUNCTION IS CONTROLLED BY M INDEX OF NTAB ARRAY.                   FRCDFL
C DERIVATIVE, FUNCTION OR INTEGRAL IS EVALUATED AS N = 0,1 OR 2.       FRCDFL
C   NTAB(M)      - INDEX TO TAB ARRAY FOR REAL DATA                   FRCDFL
C   NTAB(M+1)    - INDEX TO TAB ARRAY FOR BASE FUNCTION                 FRCDFL
C   NTAB(M+2)    - INDEX TO TAB ARRAY FOR INERTIAL FUNCTION, IF ANY    FRCDFL
C                                                                           FRCDFL
C ASSUMES  0 < DG < DCUBIC < DREF < DMAX                               FRCDFL
C           BUT ANY < MAY BE LESS THAN OR EQUAL TO                     FRCDFL
C                                                                           FRCDFL
C IMPLICIT REAL*8(A-H,O-Z)                                              FRCDFL
C COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500) DIMENB
C F = 0.0                                                                FRCDFL
C ELOSS = 0.0                                                            FRCDFL
C L = NTAB(M)                                                            FRCDFL
C TAB(L) = D                                                             FRCDFL
C IF (D.LT.0.0) GO TO 99                                                FRCDFL
C DMAX = TAB(L+8)                                                        FRCDFL
C IF (D.LT.DMAX) GO TO 10                                              FRCDFL
C                                                                           FRCDFL
C DMAX < D , USE MAX VALUE                                             FRCDFL
C                                                                           FRCDFL
C IF (N-1) 99,9,99                                                      FRCDFL
C 9  FDMAX = TAB(L+10)                                                  FRCDFL
C F = FDMAX                                                              FRCDFL
C GO TO 40                                                                FRCDFL
C 10 DREF = TAB(L+7)                                                    FRCDFL
C IF (D.GE.DREF) GO TO 30                                               FRCDFL
C DCUBIC = TAB(L+6)                                                     FRCDFL
C IF (DCUBIC.GE.DREF) GO TO 20                                          FRCDFL
C IF (D.LE.DCUBIC) GO TO 20                                             FRCDFL
C                                                                           FRCDFL
C DCUBIC < D < DREF , USE CUBIC                                        FRCDFL
C                                                                           FRCDFL
C LC = L+14                                                              FRCDFL
C DCO = TAB(L+18)                                                        FRCDFL
C X = D-DCO                                                              FRCDFL
C IF (N-1) 12,11,99                                                    FRCDFL
C                                                                           FRCDFL
C USE CUBIC DEFINITION                                                 FRCDFL
C                                                                           FRCDFL
C 11 F = TAB(LC) + X *(TAB(LC+1)+X*(TAB(LC+2)+X*TAB(LC+3)))          FRCDFL
C GO TO 40                                                                FRCDFL
C                                                                           FRCDFL
C USE DERIVATIVE OF CUBIC                                             FRCDFL
C                                                                           FRCDFL
C 12 F = TAB(LC+1)+X*(2.0*TAB(LC+2)+X*3.0*TAB(LC+3))                FRCDFL
C GO TO 99                                                                FRCDFL

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20	DG = TAB(L+5)	FRCDFL
	IF (D.LE.DG) GO TO 40	FRCDFL
C		FRCDFL
C	DG < D < DCUBIC , USE QUADRATIC	FRCDFL
C		FRCDFL
	LQ = L+11	FRCDFL
	X = D-DG	FRCDFL
	IF (N-1) 22,21,99	FRCDFL
C		FRCDFL
C	USE QUADRATIC DEFINITION	FRCDFL
C		FRCDFL
21	F = TAB(LQ)+X*(TAB(LQ+1)+X*TAB(LQ+2))	FRCDFL
	GO TO 40	FRCDFL
C		FRCDFL
C	USE DERIVATIVE OF QUADRATIC.	FRCDFL
C		FRCDFL
22	F = TAB(LQ+1)+X*2.0*TAB(LQ+2)	FRCDFL
	GO TO 99	FRCDFL
C		FRCDFL
C	DREF < D < DMAX, USE BASE FUNCTION	FRCDFL
C		FRCDFL
30	IF (N-1) 31,31,99	FRCDFL
31	NB = NTAB(M+1)	FRCDFL
C		FRCDFL
C	EVALUATE BASE FUNCTION	FRCDFL
C		FRCDFL
	IF (NB.GT.0) F = EVALFD(D,NB,N)	FRCDFL
	NI = NTAB(M+2)	FRCDFL
C		FRCDFL
C	ADD INERTIAL FUNCTION , IF ANY	FRCDFL
C		FRCDFL
	IF (NI.GT.0) F = F+EVALFD(D,NI,N)	FRCDFL
40	IF (N.NE.1) GO TO 99	FRCDFL
C		FRCDFL
C	COMPUTE AND ADD RATE DEPENDENT FUNCTIONS, IF ANY.	FRCDFL
C		FRCDFL
C	CURRENT RESTRICTIONS:	FRCDFL
C		FRCDFL
C	1) COMPUTED FOR N=1 (FUNCTION) ONLY.	FRCDFL
C		FRCDFL
C	2) FUNCTION NOS. M+2,M+3 AND M+4 (USED FOR INERTIAL SPIKE,	FRCDFL
C	R FACTOR AND G FACTOR FUNCTIONS) MUST BE NEGATIVE OR ZERO,	FRCDFL
C	I.E., THESE FUNCTIONS CANNOT BE USED IN CONJUNCTION WITH	FRCDFL
C	THE RATE DEPENDENT FUNCTIONS.	FRCDFL
C		FRCDFL
C	3) ASSUMES THE FUNCTIONAL FORM	FRCDFL
C		FRCDFL
C	$F(D,D') = F1(D) + F2(D)*F3(D') + F4(D')$	FRCDFL
C		FRCDFL
C	WHERE F1(D ) IS DEFINED BY FUNCTION NTAB(M+1)>0,	FRCDFL



```

C          SUBROUTINE FSMSOL (C,R,NN,MX,MAXN,JN,MAXDIM)                FSMSOL
C          REV III.2 08/08/84REVIII                                   FSMSOL
C          SOLVES A SET OF SIMULTANEOUS EQUATIONS OF SIZE 3*MM        FSMSOL
C          WHERE THE MATRIX CONSISTS OF A SET OF 3*3 SUBMATRICES      FSMSOL
C          STORED IN C(3,3,IJ). THE LOCATION OF THE I,J ELEMENT      FSMSOL
C          IS STORED IN NN(I,J). I.E. IJ= NN(I,J)                     FSMSOL
C
C          A NEGATIVE IJ IMPLIES THAT C( , ,!IJ!) IS AN              FSMSOL
C          IDENTITY AND THE RIGHT SIDE IS ZERO. A NEGATIVE           FSMSOL
C          IJ WILL ONLY OCCUR ON A DIAGONAL ENTRY OF NN.             FSMSOL
C
C          THE BASIC EQUATION IS   CX=R                                FSMSOL
C
C          DURING THE SOLUTION THE C MATRIX IS DESTROYED ,IT MAY    FSMSOL
C          BE NECESSARY TO ADD TO THE C ARRAY.                        FSMSOL
C          THE SOLUTION IS STORED IN R.                                FSMSOL
C
C          INPUT                                                       FSMSOL
C
C          C(3,3,K)   GIVEN ARRAY                                       FSMSOL
C          R(3,MM)    GIVEN RIGHT HAND SIDE                             FSMSOL
C          NN(JJ,JJ) GIVEN ARRAY CONTAINING LOCATIONS OF I,J,ELEMENT  FSMSOL
C          MX        SIZE OF SYSTEM OF SUBMATRICES (POSITIVE INDICATES FSMSOL
C                   THAT C MATRIX IS SYMMETRIC, NEGATIVE IT IS NOT.) FSMSOL
C          MAXN      LARGEST VALUE IN NN ARRAY                         FSMSOL
C          JN        DIMENSION OF NN                                   FSMSOL
C          MAXDIM    THIRD DIMENSION OF C IN CALLING ROUTINE         FSMSOL
C
C          IMPLICIT REAL*8 (A-H,O-Z)                                    FSMSOL
C          COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,    FSMSOL
C          *          NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG  FSMSOL
C          DIMENSION C(3,3,1),R(3,1),NN(JN,1)                        FSMSOL
C          CALL ELTIME(1,20)                                          FSMSOL
C          MM = IABS(MX)                                               FSMSOL
C          IF (MM.LE.0) GO TO 99                                       FSMSOL
C          MM1 = MM-1                                                  FSMSOL
C          MP1 = MM+1                                                  FSMSOL
C          DO 50 II=1,MM                                               FSMSOL
C          I = MP1-II                                                  FSMSOL
C
C          START PIVOT AT BOTTOM - FIND PIVOT - INVERT.             FSMSOL
C
C          L = NN(I,I)                                                 FSMSOL
C          IF (L.LE.0) GO TO 50                                         FSMSOL
C          DO 14 M=1,3                                                 FSMSOL
C          B = 1.0/C(M,M,L)                                             FSMSOL
C          C(M,M,L) = 1.0                                              FSMSOL
C          C(M,1,L) = B*C(M,1,L)                                       FSMSOL
C          C(M,2,L) = B*C(M,2,L)                                       FSMSOL
C          C(M,3,L) = B*C(M,3,L)                                       FSMSOL

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IF (KI.EQ.0 .AND. IK.EQ.0) GO TO 40	FSMSOL
DO 30 J=K,IM1	FSMSOL
IJ = NN(I,J)	FSMSOL
JI = NN(J,I)	FSMSOL
IF (KI.EQ.0 .OR. IJ.EQ.0) GO TO 24	FSMSOL
KJ = NN(K,J)	FSMSOL
IF (KJ.NE.0) GO TO 22	FSMSOL
MAXN = MAXN+1	FSMSOL
IF (MAXN.GT.MAXDIM) GO TO 41	FSMSOL
KJ = MAXN	FSMSOL
NN(K,J) = KJ	FSMSOL
DO 21 M=1,3	FSMSOL
DO 21 N=1,3	FSMSOL
21 C(N,M,KJ) = 0.0	FSMSOL
22 DO 23 M=1,3	FSMSOL
DO 23 N=1,3	FSMSOL
23 C(N,M,KJ) = C(N,M,KJ) - C(N,1,KI)*C(1,M,IJ)	FSMSOL
* - C(N,2,KI)*C(2,M,IJ)	FSMSOL
* - C(N,3,KI)*C(3,M,IJ)	FSMSOL
24 IF (J.EQ.K) GO TO 30	FSMSOL
IF (JI.EQ.0 .OR. IK.EQ.0) GO TO 30	FSMSOL
JK = NN(J,K)	FSMSOL
IF (JK.NE.0) GO TO 26	FSMSOL
MAXN = MAXN+1	FSMSOL
IF (MAXN.GT.MAXDIM) GO TO 41	FSMSOL
JK = MAXN	FSMSOL
NN(J,K) = JK	FSMSOL
DO 25 M=1,3	FSMSOL
DO 25 N=1,3	FSMSOL
25 C(N,M,JK) = 0.0	FSMSOL
26 IF (MX.LT.0) GO TO 28	FSMSOL
DO 27 M=1,3	FSMSOL
DO 27 N=1,3	FSMSOL
27 C(N,M,JK) = C(M,N,KJ)	FSMSOL
GO TO 30	FSMSOL
28 DO 29 M=1,3	FSMSOL
DO 29 N=1,3	FSMSOL
29 C(N,M,JK) = C(N,M,JK) - C(N,1,JI)*C(1,M,IK)	FSMSOL
* - C(N,2,JI)*C(2,M,IK)	FSMSOL
* - C(N,3,JI)*C(3,M,IK)	FSMSOL
30 CONTINUE	FSMSOL
IF (KI.EQ.0) GO TO 40	FSMSOL
DO 35 N=1,3	FSMSOL
35 R(N,K) = R(N,K) - C(N,1,KI)*R(1,I)	FSMSOL
* - C(N,2,KI)*R(2,I)	FSMSOL
* - C(N,3,KI)*R(3,I)	FSMSOL
40 CONTINUE	FSMSOL
50 CONTINUE	FSMSOL
GO TO 51	FSMSOL
41 WRITE (6,49) MAXDIM,NPG,(L,L=1,MM)	PAGE

	NPG=NPG+1	PAGE
	DO 42 I=1,MM	FSMSOL
42	WRITE (6,43) I,(NN(I,L),L=1,MM)	FSMSOL
43	FORMAT(13,3X,40I3,3X/6X,40I3)	FSMSOL
	WRITE (6,44) NPG	PAGE
	NPG=NPG+1	PAGE
44	FORMAT('1 FSMSOL PRINT OF RHS ARRAY',96X,'PAGE',I5//)	PAGE
	DO 45 K=1,MM	FSMSOL
45	WRITE (6,46) K,(R(I,K),I=1,3)	FSMSOL
46	FORMAT(16,9G14.7)	FSMSOL
	WRITE (6,47) NPG	PAGE
	NPG=NPG+1	PAGE
47	FORMAT('1 FSMSOL PRINT OF C ARRAY ELEMENTS',89X,'PAGE',I5//)	PAGE
	DO 48 K=1,MAXN	FSMSOL
48	WRITE (6,46) K,((C(I,L,K),L=1,3),I=1,3)	FSMSOL
49	FORMAT('1 MAXIMUM DIMENSION OF',I4,' ON C ARRAY HAS BEEN EXCEEDED FSMSOL	FSMSOL
	*IN SUBROUTINE FSMSOL.',46X,'PAGE',I5//' IF 600, CALL IS FROM SUBROPAGE	FSMSOL
	*UTINE DAUX. IF 200'	PAGE
	*,' CALL IS FROM SUBROUTINE HPTURB.'/'/' PROGRAM IS BEING TERMINATEPAGE	PAGE
	*D. COMPLETE PRINT-OUT OF IJK, RHS AND C ARRAYS FOLLOW.'/'	FSMSOL
	*' FSMSOL PRINT OF IJK MATRIX'//(6X,40I3))	FSMSOL
	STOP 35	FSMSOL
C		FSMSOL
C	BACKDOWN SOLUTION	FSMSOL
C		FSMSOL
51	IF (MM.EQ.1) GO TO 99	FSMSOL
	DO 90 J=1,MM1	FSMSOL
	IP = J+1	FSMSOL
	DO 80 I=IP,MM	FSMSOL
	IF (NN(I,J).EQ.0) GO TO 80	FSMSOL
	IJ = NN(I,J)	FSMSOL
	DO 75 N=1,3	FSMSOL
75	R(N,I) = R(N,I) - C(N,1,IJ)*R(1,J)	FSMSOL
	* - C(N,2,IJ)*R(2,J)	FSMSOL
	* - C(N,3,IJ)*R(3,J)	FSMSOL
80	CONTINUE	FSMSOL
90	CONTINUE	FSMSOL
99	CALL ELTIME(2,20)	FSMSOL
	RETURN	FSMSOL
	END	FSMSOL

	SUBROUTINE GLOBAL (J,HD3,DH1,TQC,T9,ANGL)		GLOBAL
C		REV IV	07/24/86SLIP
	IMPLICIT REAL*8 (A-H,O-Z)		GLOBAL
	DIMENSION HD3(3),DH1(3,3),T9(3),ANGL(3),CC(3)		GLOBAL
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		GLOBAL
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		GLOBAL
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)		DIMENB
	COMMON/TEMPVI/ CREST,TTI(3),R1I(3),R2I(3),JSTOP(4,2,30)		GLOBAL
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		GLOBAL
*	UNITL,UNITM,UNITT,GRAVTY(3),TWOPI		TWOPI
	IF (DABS(HD3(3)).GT.1.0-EPS(6)) GO TO 34		GLOBAL
	ANGL(1) = DACOS(HD3(3))		GLOBAL
	NT = IGLOB(J)		GLOBAL
	NT1 = NTAB(NT+2)		GLOBAL
	CALL HERRON(HD3,NT1,THETO,THETOP)		GLOBAL
	JSTOP(4,1,J) = 0		GLOBAL
	IF (ANGL(1).LE.THETO) GO TO 34		GLOBAL
	JSTOP(4,1,J) = 1		GLOBAL
	MT = NTAB(NT+5)		GLOBAL
	CREST = TAB(MT+3)		GLOBAL
	STH2 = 1.0-HD3(3)**2		GLOBAL
	STH = DSQRT(STH2)		GLOBAL
	CTH = HD3(3)/STH		GLOBAL
	CST = DSQRT(STH2+THETOP**2)		GLOBAL
	DR = (ANGL(1)-THETO)*STH/CST		GLOBAL
	LT = NTAB(NT)		GLOBAL
	TAB(LT) = DR		GLOBAL
	NTAB(NT+2) = 0		GLOBAL
	DRDOT = 0.0		GLOBAL
	CALL FRCDFL (DR,DRDOT,NT,1,TQF,ELOSS)		GLOBAL
	NTAB(NT+2) = NT1		GLOBAL
	TQC = TQF/CST		GLOBAL
	CC(1) = -HD3(2)+HD3(1)*CTH*THETOP		GLOBAL
	CC(2) = HD3(1)+HD3(2)*CTH*THETOP		GLOBAL
	CC(3) = -STH*THETOP		GLOBAL
	DO 28 L=1,3		GLOBAL
28	T9(L) = CC(1)*DH1(L,1) + CC(2)*DH1(L,2) + CC(3)*DH1(L,3)		GLOBAL
34	RETURN		GLOBAL
	END		GLOBAL

	SUBROUTINE HBELT (J1,J2,KNLO,IND)		HBELT
C		REV IV	02/01/88MISDOT
C	ARGUMENTS:		HBELT
C	J1,J2 - FIRST AND LAST INDEX FOR BELTS.		HBELT
C	KNLO - ZERO VALUE FOR KNL INDEX.		HBELT
C	IND - 0: CALL IS FROM SUBROUTINE CONTCT		HBELT
C	1: CALL IS FROM SUBROUTINE UPDATE		HBELT
C			HBELT
	IMPLICIT REAL*8 (A-H,O-Z)		HBELT
	COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)		EDGE
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		MISDOT
*	UNITL,UNITM,UNITT,GRAVTY(3),TWOPI		MISDOT
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		HBELT
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		HBELT
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)		DIMENB
	COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),		NCFORC
*	PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF		HBELT
	COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100),		HBELT
*	XLONG(20),HTIME(2),IBAR(5,100),NL(2,100),		HBELT
*	NPTSPB(20),NPTPLY(20),NTHRMS(20),NBLTPH(5)		HBELT
C	THIS COMMON/TEMPVS/ IS SHARED BY HPTURB, HBPLAY, HBELT AND HSETC.		HBELT
	COMMON/TEMPVS/ B(3,3,3),S(3,3),T(3),R(3),V(3),T1(3),T2(3),		HBELT
*	E(3,3,50),EDOT(3,50),FCE(3,50),FR(3,50),ZR(3,50),		HBELT
*	TR(3,50),U(3,50),PTLOSS(2,50),BL(50),FB(50),FP(50),		HBELT
*	OLDBB(100),RHS(3,54),C(3,3,200),IJK(54,54)		HBELT
	CALL ELTIME (1,38)		HBELT
	NTP = 0		HBELT
	K2 = 0		HBELT
	DO 31 JB=J1,J2		HBELT
	IF (IND.EQ.0) NBSF = NBSF + 1		HBELT
	IF (NPTPLY(JB).LE.0) GO TO 31		HBELT
C			HBELT
C	FIRST LOOP ON K		HBELT
C	COMPUTE Z(K),ZR(K),E3(K),U(K-1),BL(K-1),FB(K-1)		HBELT
C	NEED NL(K),BB(K-1)		HBELT
C	NOTE: AN INDEX K-1 REFERS TO BELT SEGMENT BETWEEN K-1 AND K.		HBELT
C			HBELT
	K1 = K2 + 1		HBELT
	K2 = K2 + NPTPLY(JB)		HBELT
	DO 20 K=K1,K2		HBELT
	KNL = KNLO + K		HBELT
	KI = NL(1,KNL)		HBELT
C			HBELT
C	HERE K IS INDEX OF POINTS IN PLAY ON EACH HARNESS		HBELT
C	KNL IS INDEX OF ALL POINTS IN PLAY		HBELT
C	KI IS INDEX OF ALL POINTS		HBELT
C			HBELT
	KS = IABS(IBAR(1,KI))		HBELT
	IF (KS.GT.100) NTP = 1		HBELT
	IF (KS.GT.100) KS = MOD(KS,100)		HBELT

	KE = IBAR(2,KI)	HBELT
	CALL DOT31 (D(1,1,KS),BAR(4,KI),T1)	HBELT
	CALL DOT31 (D(1,1,KS),BAR(7,KI),T2)	HBELT
	DO 11 J=1,3	HBELT
	R(J) = V(J)	HBELT
	V(J) = BAR(J+3,KI) + BAR(J+6,KI)	HBELT
	TR(J,K) = T1(J)	HBELT
	ZR(J,K) = T1(J) + T2(J)	HBELT
	S (J,2) = S(J,1)	HBELT
11	S (J,1) = SEGLP(J,KS) + ZR(J,K)	HBELT
	CALL CROSS (WMEG(1,KS),V,T)	HBELT
	IF (KE.EQ.0) GO TO 12	HBELT
	CALL MAT31 (BD(7,KE),BAR(4,KI),T2)	HBELT
	CALL DOT31 (D(1,1,KS),T2,T1)	HBELT
12	DO 13 J=1,3	HBELT
	T(J) = T(J) + BAR(J+12,KI)	HBELT
13	E(J,3,K) = T1(J)	HBELT
	CALL DOT31 (D(1,1,KS),T,V)	HBELT
	DO 14 J=1,3	HBELT
14	V(J) = V(J) + SEGLV(J,KS)	HBELT
	FB(K) = 0.0	HBELT
	FP(K) = 0.0	HBELT
	IF (K.EQ.K1) GO TO 20	HBELT
	DO 15 J=1,3	HBELT
15	U(J,K-1) = S(J,1) - S(J,2)	HBELT
	BL(K-1) = DSQRT(U(1,K-1)**2 + U(2,K-1)**2 + U(3,K-1)**2)	HBELT
	DO 16 J=1,3	HBELT
16	U(J,K-1) = U(J,K-1)/BL(K-1)	HBELT
	STRAIN = (BL(K-1)/BB(KNL-1)) - 1.0	HBELT
	IF (STRAIN.LT.EPS(12)) STRAIN = 0.0	MISDOT
	NT = NL(2,KNL)	HBELT
	BLDOT = U(1,K-1)*(V(1)-R(1))	HBELT
	* + U(2,K-1)*(V(2)-R(2))	HBELT
	* + U(3,K-1)*(V(3)-R(3))	HBELT
	STRDOT = (BB(KNL-1)*BLDOT-BL(K-1)*BBDOT(KNL-1))/BB(KNL-1)**2	HBELT
	CALL FRCDFL (STRAIN,STRDOT,NT,0,FPK,ELOSS)	HBELT
	CALL FRCDFL (STRAIN,STRDOT,NT,1,FBK,ELOSS)	HBELT
	PTLOSS(1,K-1) = BB(KNL-1)*ELOSS	HBELT
	FP(K-1) = FPK	HBELT
	FB(K-1) = FBK	HBELT
	IF (IND.NE.0) GO TO 20	ENDPFX
	IF (K.NE.K1+1) GO TO 19	ENDPFX
	BSF(1,NBSF) = STRAIN	ENDPFX
	BSF(2,NBSF) = FBK	ENDPFX
19	IF (K.NE.K2) GO TO 20	ENDPFX
	BSF(3,NBSF) = STRAIN	ENDPFX
	BSF(4,NBSF) = FBK	ENDPFX
20	CONTINUE	HBELT
C		HBELT
C	SECOND LOOP ON K	HBELT

C	COMPUTE FCE(K),E1(K),E2(K),EDOT(K),FR(K),U1(KS),U2(KS))	HBELT
C	NEED FB(K&K-1),U(K&K-1),ZR(K),E3(K)	HBELT
C		HBELT
	DO 30 K=K1,K2	HBELT
	KNL = KNL0 + K	HBELT
	KI = NL(1,KNL)	HBELT
	KS = IABS(IBAR(1,KI))	HBELT
	IF (KS.GT.100) KS = MOD(KS,100)	HBELT
	DO 21 J=1,3	HBELT
	FCE(J,K) = 0.0	BUTLER1
	IF (K.NE.K2) FCE(J,K) = FB(K)*U(J,K)	BUTLER1
21	IF (K.NE.K1) FCE(J,K) = FCE(J,K) - FB(K-1)*U(J,K-1)	HBELT
	NT = IBAR(3,KI)	HBELT
	NF = NTAB(NT+5)	HBELT
	IF (NF.EQ.0 .AND. IND.EQ.0) GO TO 30	HBELT
	IF (IBAR(4,KI).EQ.0) GO TO 22	HBELT
	CALL DOT31 (D(1,1,KS),BAR(10,KI),T1)	HBELT
	GO TO 24	HBELT
22	DO 23 J=1,3	HBELT
	T1(J) = 0.0	HBELT
	IF (K.NE.K2) T1(J) = U(J,K)	HBELT
23	IF (K.NE.K1) T1(J) = T1(J) + U(J,K-1)	HBELT
24	CALL CROSS (T1,E(1,3,K),E(1,1,K))	HBELT
	CALL CROSS (E(1,3,K),E(1,1,K),E(1,2,K))	HBELT
	DO 25 J=1,3	HBELT
	EDOT(J,K) = DSQRT(E(1,J,K)**2 + E(2,J,K)**2 + E(3,J,K)**2)	HBELT
	DO 25 I=1,3	HBELT
25	E(I,J,K) = E(I,J,K)/EDOT(J,K)	HBELT
	CALL DOT31 (E(1,1,K),FCE(1,K),FR(1,K))	HBELT
30	CONTINUE	HBELT
31	CONTINUE	HBELT
	IF (NTP.LE.0) GO TO 41	HBELT
C		HBELT
C	SUM FCE,FR FOR TIE-POINTS	HBELT
C		HBELT
	KNL1 = KNL0 + 2	HBELT
	KNL2 = KNL0 + K2	HBELT
	DO 40 KNL=KNL1,KNL2	HBELT
	KI = NL(1,KNL)	HBELT
	KS = IABS(IBAR(1,KI))	HBELT
	IF (KS.LT.100) GO TO 40	HBELT
	KS1 = KS/100	HBELT
	KH = KNL - KNL0	HBELT
	MH = 0	HBELT
	DO 38 JNL=KNL1,KNL	HBELT
	KI = NL(1,JNL-1)	HBELT
	KS = IABS(IBAR(1,KI))	HBELT
	IF (KS.LT.100) GO TO 38	HBELT
	KS2 = KS/100	HBELT
	IF (KS2.NE.KS1) GO TO 38	HBELT

	JH = JNL-1 - KNLO	HBELT
	IF (MH.EQ.0) MH = JH	HBELT
	DO 37 J=1,3	HBELT
	IF (MH.EQ.JH) FCE(J,MH) = FCE(J,MH) + FCE(J,KH)	HBELT
37	FCE(J,JH) = FCE(J,MH)	HBELT
	CALL DOT31 (E(1,1,JH),FCE(1,JH),FR(1,JH))	HBELT
38	CONTINUE	HBELT
	IF (MH.EQ.0) GO TO 40	HBELT
	KI = NL(1,KNL)	HBELT
	IBAR(1,KI) = -IABS(IBAR(1,KI))	HBELT
	DO 39 J=1,3	HBELT
39	FCE(J,KH) = FCE(J,MH)	HBELT
	CALL DOT31 (E(1,1,KH),FCE(1,KH),FR(1,KH))	HBELT
40	CONTINUE	HBELT
C		HBELT
C	IF CALL IS FROM SUBROUTINE CONTCT,	HBELT
C	ADD FORCES (FCE) MODIFIED BY FRICTION TO U1,U2 ARRAYS.	HBELT
C		HBELT
41	IF (IND.NE.0) GO TO 52	HBELT
	K2 = 0	HBELT
	DO 51 JB=J1,J2	HBELT
	IF (NPTPLY(JB).LE.0) GO TO 51	HBELT
	K1 = K2 + 1	HBELT
	K2 = K2 + NPTPLY(JB)	HBELT
	DO 50 K=K1,K2	HBELT
	KNL = KNLO + K	HBELT
	KI = NL(1,KNL)	HBELT
	IF (IBAR(1,KI).LT.0) GO TO 50	HBELT
	KS = IBAR(1,KI)	HBELT
	IF (KS.GT.100) KS = MOD(KS,100)	HBELT
	NT = IBAR(3,KI)	HBELT
	NF = NTAB(NT+5)	HBELT
	IF (NF.EQ.0) GO TO 43	HBELT
	DO 42 J=1,3	HBELT
42	T1(J) = FR(J,K)	HBELT
	FR1 = TAB(NF+2)*DABS(T1(3))	HBELT
	FR2 = TAB(NF+4)*DABS(T1(3))	HBELT
	IF (DABS(T1(1)).GT.FR1) T1(1) = DSIGN(FR1,T1(1))	HBELT
	IF (DABS(T1(2)).GT.FR2) T1(2) = DSIGN(FR2,T1(2))	HBELT
	CALL MAT31 (E(1,1,K),T1,FCE(1,K))	HBELT
43	CALL CROSS (ZR(1,K),FCE(1,K),T2)	HBELT
	CALL MAT31 (D(1,1,KS),T2,T1)	HBELT
	DO 44 J=1,3	HBELT
	U1(J,KS) = U1(J,KS) + FCE(J,K)	HBELT
44	U2(J,KS) = U2(J,KS) + T1(J)	HBELT
50	CONTINUE	HBELT
51	CONTINUE	HBELT
52	KNLO = KNLO + K2	HBELT
	CALL ELTIME (2,38)	HBELT
	RETURN	HBELT
	END	HBELT

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SUBROUTINE HBPLAY                                HBPLAY
C                                                REV III.5 10/17/85EDGE
IMPLICIT REAL*8 (A-H,O-Z)                        HBPLAY
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND, HBPLAY
*          NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG PAGE
COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40) EDGE
COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30), HBPLAY
*          SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30) HBPLAY
COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100), HBPLAY
*          XLONG(20),HTIME(2),IBAR(5,100),NL(2,100), HBPLAY
*          NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5) HBPLAY
C THIS COMMON/TEMPVS/ IS SHARED BY HPTURB, HBPLAY, HBELT AND HSETC. HBPLAY
COMMON/TEMPVS/ B(3,3,3),S(3,3),T(3),R(3),V(3),T1(3),T2(3), HBPLAY
*          E(3,3,50),EDOT(3,50),FCE(3,50),FR(3,50),ZR(3,50), HBPLAY
*          TR(3,50),U(3,50),PTLOSS(2,50),BL(50),FB(50),FP(50), HBPLAY
*          OLDBB(100),RHS(3,54),C(3,3,200),IJK(54,54) HBPLAY
IF (NHRNSS.LE.0) GO TO 99 HBPLAY
C HBPLAY
C SAVE PREVIOUS NL,BB AND PLOSS ARRAYS. HBPLAY
C USE IJK,OLDBB AND PTLOSS AS TEMP STORAGE. HBPLAY
C HBPLAY
DO 10 I=1,100 HBPLAY
IJK(I,1) = NL(1,I) HBPLAY
PTLOSS(I,1) = PLOSS(1,I) HBPLAY
10 OLDBB(I) = BB(I) HBPLAY
JNL = 1 HBPLAY
J1 = 1 HBPLAY
K1 = 1 HBPLAY
LL = 0 HBPLAY
DO 90 NH=1,NHRNSS HBPLAY
IF (NBLTPH(NH).LE.0) GO TO 90 HBPLAY
J2 = J1 + NBLTPH(NH) - 1 HBPLAY
DO 80 NB=J1,J2 HBPLAY
L1 = LL HBPLAY
IF (NPTSPB(NB).LE.0) GO TO 80 HBPLAY
K2 = K1 + NPTSPB(NB) - 1 HBPLAY
KB = 0 HBPLAY
DO 30 K=K1,K2 HBPLAY
KB = KB + 1 HBPLAY
C HBPLAY
C HERE K IS INDEX OF ALL POINTS HBPLAY
C KB IS INDEX OF POINTS ON A SINGLE BELT HBPLAY
C LL IS INDEX OF ALL POINTS IN PLAY HBPLAY
C JB IS INDEX OF PREVIOUS POINT ON BELT IN PLAY HBPLAY
C HBPLAY
KS = IABS(IBAR(1,K)) HBPLAY
IF (KS.GT.100) KS = MOD(KS,100) HBPLAY
CALL DOT31 (D(1,1,KS),BAR(4,K),T1) HBPLAY
CALL DOT31 (D(1,1,KS),BAR(7,K),T2) HBPLAY
DO 11 J=1,3 HBPLAY

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11	U(J,KB) = SEGLP(J,KS) + T1(J) + T2(J)	HBPLAY
	IF (K.EQ.K1) GO TO 30	HBPLAY
	LL = LL + 1	HBPLAY
12	JJ = NL(1,LL)	HBPLAY
	JB = JJ - K1 + 1	HBPLAY
	DSS = 0.0	HBPLAY
	DO 13 J=1,3	HBPLAY
	ZR(J,KB) = U(J,KB) - U(J,JB)	HBPLAY
13	DSS = DSS + ZR(J,KB)**2	HBPLAY
	BL(LL) = DSQRT(DSS)	HBPLAY
	IF (JJ.EQ.K1 .OR. IABS(IBAR(1,JJ)).GT.100) GO TO 30	HBPLAY
	JS = IBAR(1,JJ)	HBPLAY
	JE = IBAR(2,JJ)	HBPLAY
	IF (JE.LE.0) GO TO 30	HBPLAY
	CALL MAT31 (BD(7,JE),BAR(4,JJ),T2)	HBPLAY
	CALL DOT31 (D(1,1,JS),T2,R)	HBPLAY
	DPR = 0.0	HBPLAY
	DO 17 J=1,3	HBPLAY
17	DPR = DPR + R(J)*(ZR(J,KB)/BL(LL) - ZR(J,JB)/BL(LL-1))	HBPLAY
	IF (DPR.LT.0.0) GO TO 30	HBPLAY
	LL = LL - 1	HBPLAY
	GO TO 12	HBPLAY
30	NL(1,LL+1) = K	HBPLAY
	L2 = L1 + 1	HBPLAY
	LL = LL + 1	HBPLAY
	L3 = LL-1	HBPLAY
	DO 31 J=L2,LL	HBPLAY
31	NL(2,J) = NTHRNS(NB)	HBPLAY
	IF (XLONG(NB).EQ.0.0) GO TO 35	HBPLAY
C		HBPLAY
C	FIRST TIME IN ROUTINE, SET INITIAL BB ARRAY.	HBPLAY
C	INPUT XLONG MUST BE NON-ZERO TO TRIGGER THIS TEST.	HBPLAY
C		HBPLAY
	XLG = 0.0	HBPLAY
	DO 32 J=L2,L3	HBPLAY
32	XLG = XLG + BL(J)	HBPLAY
	XLG = 1.0 + XLONG(NB)/XLG	HBPLAY
	DO 33 J=L2,L3	HBPLAY
33	BB(J) = XLG*BL(J)	HBPLAY
	XLONG(NB) = 0.0	HBPLAY
	GO TO 52	HBPLAY
C		HBPLAY
C	DETERMINE IF NEW NL ARRAY IS DIFFERENT FROM PREVIOUS NL ARRAY.	HBPLAY
C	IF SO, RECOMPUTE BB ELEMENTS FOR POINTS THAT ARE DIFFERENT.	HBPLAY
C		HBPLAY
35	IF (NL(1,L2).EQ.IJK(JNL,1)) GO TO 61	HBPLAY
	WRITE (6,62)	HBPLAY
62	FORMAT ('0 LOGIC ERROR IN SUB HBPLAY. PROGRAM TERMINATED.')	HBPLAY
	STOP 42	HBPLAY
61	LTEST = 0	HBPLAY

	M = L2	HBPLAY
	N = JNL	HBPLAY
36	IF (NL(1,M+1)-IJK(N+1,1)) 39,37,41	HBPLAY
37	BB(M) = OLDBB(N)	HBPLAY
	PLOSS(1,M) = PTLOSS(N,1)	HBPLAY
38	M = M+1	HBPLAY
	N = N+1	HBPLAY
	IF (M-LL) 36,51,51	HBPLAY
C		HBPLAY
C	POINT M+1 IS NEW.	HBPLAY
C		HBPLAY
39	MO = M	HBPLAY
	NO = N	HBPLAY
	LTEST = 1	HBPLAY
40	M = M+1	HBPLAY
C		CHGIII
C	MODIFY NEW POINT TO LIE IN BELT PLANE	CHGIII
C		CHGIII
	IP1 = N - 1	CHGIII
	IF (N.GT.JNL) GO TO 63	CHGIII
	IP1 = N	CHGIII
C	(IS THIRD POINT AVAILABLE FROM OLD POINTS IN PLAY?)	CHGIII
	IF (IJK(N+1,1).EQ.NL(1,LL)) GO TO 43	CHGIII
63	DO 64 I=1,3	CHGIII
	IP = IP1 + I - 1	CHGIII
C	(USE OLD POINTS IP = N-1,N,N+1 IF N > JNL	CHGIII
C	OR IP = N,N+1,N+2 IF N = JNL AND N+2 EXISTS)	CHGIII
	NI = IJK(IP,1)	CHGIII
	NSI= IABS(IBAR(1,NI))	NSFIX
	IF (NSI.GT.100) NSI = MOD(NSI,100)	NSFIX
	CALL DOT31 (D(1,1,NSI),BAR(4,NI),T1)	NSFIX
	CALL DOT31 (D(1,1,NSI),BAR(7,NI),T2)	NSFIX
	DO 64 J=1,3	CHGIII
64	S(J,I) = SEGLP(J,NSI)+ T1(J) + T2(J)	NSFIX
	DO 65 J=1,3	CHGIII
	S(J,3) = S(J,3) - S(J,2)	CHGIII
65	S(J,2) = S(J,2) - S(J,1)	CHGIII
C	(S(*,1) IS POINT P1 IN INERTIAL REFERENCE)	CHGIII
C	(S(*,2) IS VECTOR (P2-P1) IN INERTIAL REFERENCE)	CHGIII
C	(S(*,3) IS VECTOR (P3-P2) IN INERTIAL REFERENCE)	CHGIII
	CALL CROSS (S(1,3),S(1,2),T2)	CHGIII
	ABST = DSQRT(T2(1)**2 + T2(2)**2 + T2(3)**2)	CHGIII
	DO 66 J=1,3	CHGIII
66	T2(J) = T2(J)/ABST	CHGIII
C	(T2 IS T, THE NORMALIZED PLANE VECTOR IN INERTIAL REFERENCE)	CHGIII
	MI = NL(1,M)	CHGIII
	MS = IABS(IBAR(1,MI))	CHGIII
	IF (MS.GT.100) MS = MOD(MS,100)	CHGIII
	ME = IBAR(2,MI)	CHGIII
	CALL MAT31 (D(1,1,MS),T2,T1)	CHGIII

```

C      (T1 IS T IN ELLIPSOID REFERENCE OF NEW POINT M)
D1 = T2(1)*S(1,1) + T2(2)*S(2,1) + T2(3)*S(3,1)
D2 = T1(1)*BAR(7,MI) + T1(2)*BAR(8,MI) + T1(3)*BAR(9,MI)
D3 = T2(1)*SEGLP(1,MS) + T2(2)*SEGLP(2,MS) + T2(3)*SEGLP(3,MS)
DD = D1 - D2 - D3
C      (DD IS D, THE DISTANCE OF ELLIPSOID CENTER TO PLANE)
CALL MAT31 (BD(16,ME),T1,R)
BX = DD/(T1(1)*R(1) + T1(2)*R(2) + T1(3)*R(3))
D4 = T1(1)*BAR(4,MI) + T1(2)*BAR(5,MI) + T1(3)*BAR(6,MI)
DO 67 J=1,3
R(J) = BX*R(J)
C      (R IS S, THE CENTER OF THE ELLIPSE)
67 V(J) = BAR(J+3,MI) + (DD-D4)*T1(J)
C      (BAR(J+3,MI) IS P, THE NEW POINT TO BE ADDED)
C      (V IS Q, THE PROJECTION OF POINT P ONTO THE PLANE)
AX = DSQRT( (BX*DD-1.0) / (BX*DD-XDY(V,BD(7,ME),V)) )
DO 68 J=1,3
68 BAR(J+3,MI) = R(J) + AX*(V(J)-R(J))
C      (BAR(J+3,MI) IS R = S + A(Q - S), Q EXTENDED TO ELLIPSOID)
GO TO 43
C
C      POINT N+1 IS DROPPED.
C
41 MO = M
NO = N
LTEST = 1
42 N = N+1
43 IF (NL(1,M+1)-IJK(N+1,1)) 40,44,42
C
C      POINTS NO TO N+1 ARE BEING REPLACED WITH POINTS MO TO M+1.
C
44 SUMBL = 0.0
DO 45 J=MO,M
45 SUMBL = SUMBL + BL(J)
SUMPL = 0.0
SUMBB = 0.0
DO 46 J=NO,N
SUMPL = SUMPL + PTLOSS(J,1)
46 SUMBB = SUMBB + OLDBB(J)
RATPL = SUMPL/SUMBL
RATIO = SUMBB/SUMBL
DO 47 J=MO,M
PLOSS(1,J) = RATPL*BL(J)
47 BB(J) = RATIO*BL(J)
GO TO 38
51 JNL = N+1
IF (LTEST.EQ.0) GO TO 79
C
C      PRINT NEW POINT ARRAY IF DIFFERENT.
C

```

52	NPTS = LL - L1	HBPLAY
	USEC = 1000.0*TIME	HBPLAY
	WRITE (6,53) USEC,NH,NB,NPTS,NTHRNS(NB)	HBPLAY
53	FORMAT ('0 HBPLAY TIME =',F10.3,' MSEC. NH,NB,NPTS NT=',4I6)	HBPLAY
	WRITE (6,54) (NL(1,J),J=L2,LL)	HBPLAY
54	FORMAT (' NL(1)=' ,15I8/(8X,15I8))	HBPLAY
	WRITE (6,55) (BB(J),J=L2,L3)	HBPLAY
55	FORMAT (' BB =',6X,14F8.3/(6X,15F8.3))	HBPLAY
79	K1 = K2 + 1	HBPLAY
80	NPTPLY(NB) = LL - L1	HBPLAY
	J1 = J2 + 1	HBPLAY
90	CONTINUE	HBPLAY
99	RETURN	HBPLAY
	END	HBPLAY



C	NOTE: MT WILL BE THE PAGE OR OUTPUT UNIT COUNTER	HEDING
C	NT WILL BE THE ACTUAL OUTPUT UNIT NUMBER	HEDING
C	IT WILL BE THE INDEX TO THE DATA ARRAY	HEDING
C	NLINES WILL BE THE NUMBER OF LINES TO BE PRINTED	HEDING
C		HEDING
C		HEDING
C	EVERY LPP LINES PRINT HEADINGS FOR 9 TYPES OF OUTPUT ABOVE.	WINDOP
C		HEDING
	DO 20 K=1,9	WINDOP
	IF (NSG(K).LE.0) GO TO 20	HEDING
	KSG = NSG(K)	HEDING
	IF (K.EQ.9) GO TO 455	WINDOP
	J3 = 3	HEDING
	IF (K.EQ.7) J3 = 2	HEDING
	DO 19 J1=1,KSG,J3	HEDING
	MT = MT + 1	HEDING
	NT = MT	HEDING
	IF (LNEW) NT = 6	HEDING
	IT = MT - 20	HEDING
	PAGE = FLOAT(MT) + XPAGE	HEDING
C	P & E PRINTER CARRIAGE CONTROL	PECONV
	CALL CARCON(NT,1)	PECONV
	IF (NT.EQ.6) WRITE(NT,121) DATE,BLANK,NPG	PAGE
	IF (NT.NE.6) WRITE(NT,121) DATE	PAGE
	IF (NT.EQ.6) NPG=NPG+1	PAGE
	WRITE (NT,21) COMENT,PAGE,VPSTTL,BDYTTL	PAGE
	IF (K.EQ.1) WRITE (NT,22)	TTHKREF
	IF (K.EQ.2) WRITE (NT,23) UNITL,UNITT	TTHKREF
	IF (K.EQ.3) WRITE (NT,24) UNITL	TTHKREF
	IF (K.EQ.4) WRITE (NT,25) UNITT	TTHKREF
	IF (K.EQ.5) WRITE (NT,26) UNITT	TTHKREF
	IF (K.EQ.6) WRITE (NT,27)	HEDING
	IF (K.EQ.7) WRITE (NT,28)	TTHKREF
	IF (K.EQ.8) WRITE(NT,200) UNITM	HEDING
	J2 = MIN0(J1+J3-1,KSG)	HEDING
	DO 14 J=J1,J2	HEDING
	KK = MSG(J,K)	HEDING
	HEAD(J) = SEG(IABS(KK))	ACCEL
	IF ((K.LT.7).OR.(K.EQ.8)) GO TO 214	TTHKREF
	KK = IABS(KK)	HEDING
	HEAD(J) = JOINT(KK)	HEDING
	JJ2 = J-J1+1	HEDING
	K2 = 1	HEDING
	IF (MSG(J,K).LT.0) K2 = 2	HEDING
	DO 35 K1=1,4	HEDING
	35 HEADJJ(K1,JJ2) = HEDJ(K1,K2)	HEDING
	GO TO 14	TTHKREF
214	IF (MSG(J,K).LT.0) GOTO 302	ACCEL
	IF (KREF(J,K).EQ.0) HEADR(J)=SEG(NVEH)	ACCEL
	IF (K.EQ.8) HEADR(J)=SEG(NGRND)	TTHKREF

	IF (K.EQ.1 .OR. K.EQ.4) HEADR(J)=SEG(KK)	TTHKREF
	IF (KREF(J,K).NE.0) HEADR(J)=SEG(KREF(J,K))	TTHKREF
	DO 301 II=1,5	ACCEL
301	AHEAD(II,J)=AHED(II,1)	ACCEL
	AHEAD(2,J)=HEADR(J)	ACCEL
	GOTO 14	ACCEL
302	HEADR(J)=SEG(IABS(KK))	ACCEL
	DO 303 II=1,4	ACCEL
303	AHEAD(II,J)=AHED(II,2)	ACCEL
	AHEAD(5,J)=GHED(KREF(J,K)+1)	ACCEL
14	CONTINUE	HEDING
	IF (K.LE.3) WRITE (NT,29) (BLANK,(XSG(I,J,K),I=1,3),J=J1,J2)	HEDING
	IF (K.LE.6) WRITE (NT,30) (BLANK,MSG(J,K),HEAD(J),J=J1,J2)	HEDING
	IF (K.EQ.8) WRITE (NT,30) (BLANK,MSG(J,K),HEAD(J),J=J1,J2)	WINDOP
	IF (K.LE.6 .OR. K.EQ.8) WRITE (NT,230)	ACCEL
	* (BLANK,(AHEAD(II,J),II=1,5),J=J1,J2)	ACCEL
	IF ((K.LE.5).OR.(K.EQ.8)) WRITE (NT,31) (BLANK,J=J1,J2)	WINDOP
	IF (K.EQ.6) WRITE (NT,32) (BLANK,J=J1,J2)	HEDING
	IF ((K.LT.7).OR.(K.EQ.8)) GOTO 15	WINDOP
	WRITE (NT,33) (BLANK,MSG(J,K),HEAD(J),J=J1,J2)	HEDING
	WRITE (NT,36) (BLANK,UNITL,UNITM,J=J1,J2)	HEDING
	WRITE (NT,37) (BLANK,(HEADJJ(K1,J),K1=1,4),J=1,JJ2)	HEDING
15	WRITE (NT,38)	HEDING
	IF (.NOT.LNEW) GO TO 19	HEDING
	IF (K.EQ.7) GO TO 17	HEDING
	JJ = 4*(J2-J1+1)	HEDING
	DO 16 I=1,NLINES	HEDING
16	WRITE (NT,39) USEC(I),(ZTTH(J,I,IT),J=1,JJ)	HEDING
	GO TO 19	HEDING
17	JJ = 7*(J2-J1+1)	HEDING
	DO 18 I=1,NLINES	HEDING
18	WRITE (NT,40) USEC(I),(ZTTH(J,I,IT),J=1,JJ)	HEDING
19	CONTINUE	HEDING
	GO TO 20	CHGIII
C		CHGIII
C	PRINT HEADING FOR JOINT FORCES & TORQUES	CHGIII
C		CHGIII
455	CONTINUE	CHGIII
	DO 860 II=1,KSG	CHGIII
	IF(KREF(II,K).EQ.0) KRF = NVEH	TTHKREF
	IF(KREF(II,K).NE.0) KRF = KREF(II,K)	TTHKREF
	JRF = MSG(II,9)	WINDOP
	MT = MT + 1	CHGIII
	NT = MT	CHGIII
	IF (LNEW) NT = 6	CHGIII
C	P & E CARRIAGE CONTROL	PECONV
	CALL CARCON(NT,1)	PECONV
	IT = MT - 20	CHGIII
	PAGE = FLOAT (MT) + XPAGE	CHGIII
	IF (NT.EQ.6) WRITE(NT,121) DATE,BLANK,NPG	PAGE

IF (NT.NE.6) WRITE(NT,121) DATE	PAGE
IF (NT.EQ.6) NPG=NPG+1	PAGE
WRITE (NT,21) COMENT,PAGE,VPSTTL,BDYTTL	PAGE
WRITE (NT,850) JOINT(JRF),SEG(JRF+1),SEG(KRF)	OUT385
WRITE (NT,38)	CHGIII
WRITE (NT,851) UNITM,UNITL,UNITM	CHGIII
WRITE (NT,852)	CHGIII
WRITE (NT,38)	CHGIII
IF (.NOT.LNEW) GO TO 857	CHGIII
DO 858 JK=1,NLINES	CHGIII
WRITE (NT,856) USEC(JK),(ZTTH(J,JK,IT),J=1,6)	CHGIII
858 CONTINUE	CHGIII
857 CONTINUE	CHGIII
850 FORMAT(' '/47X,	TTHKREF
* A4,' JOINT FORCES & TORQUES ON ',A4,' IN ',A4,' REFERENCE')	OUT385
851 FORMAT(4X,4HTIME,7X,13HJOINT FORCE (,A4,7H 10**2),10X,	CHGIII
*14HJOINT TORQUE (,A4,1H-,A4,7H 10**2))	CHGIII
852 FORMAT(3X,6H(MSEC),8X,1HX,8X,1HY,8X,1HZ,14X,1HX,11X,1HY,11X,1HZ)	CHGIII
856 FORMAT(F9.3,3X,3F9.3,3X,3(2X,D10.3))	CHGIII
860 CONTINUE	CHGIII
20 CONTINUE	HEDING
121 FORMAT('1',18X,'DATE:',3X,4A4,80X,'PAGE',15)	PAGE
21 FORMAT(8X,'RUN DESCRIPTION:',3X,20A4/27X,20A4,'PAGE:',F6.2/	PAGE
* 3X,'VEHICLE DECELERATION:',3X,20A4/	HEDING
* 11X,'CRASH VICTIM:',3X,5A4 )	HEDING
22 FORMAT(' '47X,	TTHKREF
* 'POINT TOTAL ACCELERATION (G''S)')/)	TTHKREF
23 FORMAT(' '47X,	TTHKREF
* 'POINT REL. VELOCITY (' ,A4,'/' ,A4,')')/)	TTHKREF
24 FORMAT(' '47X,	TTHKREF
* 'POINT REL. LINEAR DISPLACEMENT (' ,A4,')')/)	TTHKREF
25 FORMAT(' '/47X,	TTHKREF
* 'SEGMENT ANGULAR ACCELERATION (REV/' ,A4, '**2)')/)	TTHKREF
26 FORMAT(' '/47X,	TTHKREF
* 'SEGMENT REL. ANGULAR VELOCITY (REV/' ,A4, ')')/)	TTHKREF
27 FORMAT(' '/47X,	TTHKREF
* 'SEGMENT REL. ANGULAR DISPLACEMENT (DEG)')/)	TTHKREF
28 FORMAT(' '/47X,'JOINT PARAMETERS')/)	TTHKREF
200 FORMAT(' '/47X,'SEGMENT WIND FORCE (' ,A4, ')')/)	TTHKREF
29 FORMAT(9X,3(A4,3X,'POINT (' ,F6.2, ',' ,F6.2, ',' ,F6.2, ') ON ') )	HEDING
30 FORMAT(' ' ,3(A4,9X,'SEGMENT NO.',13,' - ' ,A4,5X) )	TTHKREF
230 FORMAT(' TIME ' ,3(A4,9X,5A4,6X))	ACCEL
31 FORMAT(' (MSEC)' ,3(A4,5X,'X',8X,'Y',8X,'Z',7X,'RES',1X) )	HEDING
32 FORMAT(' (MSEC)' ,3(A4,4X,'YAW',5X,'PITCH',5X,'ROLL',5X,'RES ')) )	HEDING
33 FORMAT(9X,2(A1,21X,'JOINT NO.',13,' - ' ,A4,20X) )	HEDING
36 FORMAT(' TIME ' ,2(A1,'STATE',5X,'JOINT ANGLES (DEG)',8X,	HEDING
* 'TOTAL TORQUE (' ,2A4, ')') )	HEDING
37 FORMAT(' (MSEC)' ,2(A1,4A8,4X,'SPRING VISCOUS RES. ')) )	HEDING
38 FORMAT(1X)	HEDING
39 FORMAT(F9.3,3(3X,4F9.3) )	HEDING



	40	FORMAT(F9.3,2(F5.0,3F9.3,2X,3F9.3))	HEDING
C			ATBIII
C		PRINT BODY PROPERTIES CONTROLLED BY H.10 CARDS	WINDOP
C			ATBIII
		IF (MCG.EQ.0) GO TO 131	ATBIII
		DO 130 NCG=1,MCG	ATBIII
		MT = MT +1	ATBIII
		NT = MT	ATBIII
		IF (LNEW) NT = 6	ATBIII
C		P & E CARRIAGE CONTROL	PECONV
		CALL CARCON(NT,1)	PECONV
		IT = MT - 20	ATBIII
		PAGE = FLOAT(MT) + XPAGE	ATBIII
		IF (NT.EQ.6) WRITE(NT,121) DATE,BLANK,NPG	PAGE
		IF (NT.NE.6) WRITE(NT,121) DATE	PAGE
		IF (NT.EQ.6) NPG=NPG+1	PAGE
		WRITE (NT,21) COMENT,PAGE,VPSTTL,BDYTTL	PAGE
		M = MCGIN(1,NCG)	ATBIII
		WRITE (NT,132) M,SEG(M)	ATBIII
		N = MCGIN(2,NCG)	ATBIII
		WRITE (NT,133) (MCGIN(I+2,NCG),I=1,N)	ATBIII
		WRITE (NT,38)	ATBIII
		WRITE (NT,134) UNITL,UNITM,UNITT,UNITL,UNITM,UNITT,UNITM,UNITL	KINETIC
		WRITE (NT,38)	ATBIII
		IF (.NOT.LNEW) GO TO 130	ATBIII
		DO 129 I=1,NLINES	ATBIII
	129	WRITE (NT,135) USEC(I), (ZTTH(J,I,IT), J=1,12)	KINETIC
	130	CONTINUE	ATBIII
	131	CONTINUE	ATBIII
	132	FORMAT(' ',47X,39HBODY PROPERTIES - REFERENCE SEGMENT NO.,	TTHKREF
		* I3,2H(,A4,1H) )	ATBIII
	133	FORMAT(15X,21HINCLUDED SEGMENT NOS:,20I3)	ATBIII
	134	FORMAT(14X,17HCENTER OF GRAVITY,13X,15HLINEAR MOMENTUM,17X,	KINETIC
		* 16HANGULAR MOMENTUM,18X,14HKINETIC ENERGY/	KINETIC
		* 4X,4HTIME,11X,1H(,A4,1H),21X,1H(,A4,1H-,A4,1H),19X,	KINETIC
		* 1H(,A4,1H-,A4,1H-,A4,1H),20X,1H(,A4,1H-,A4,1H)/	MISC
		* 3X,6H(MSEC),5X,1HX,7X,1HY,7X,1HZ,	KINETIC
		* 2(10X,1HX,10X,1HY,10X,1HZ),6X,6HLINEAR,5X,	KINETIC
		* 7HANGULAR,5X,5HTOTAL)	KINETIC
	135	FORMAT(F9.3,3F8.3,9(1X,D10.3))	KINETIC
C			HEDING
C		PLANE FORCES HEADINGS	HEDING
C			HEDING
		MPSF = 0	HEDING
		IF (NPL.EQ.0) GO TO 52	HEDING
		IF (NPRT(18).EQ.1.OR.NPRT(18).EQ.7) GO TO 52	VARTTH
		IF (NPRT(18).EQ.10.OR.NPRT(18).EQ.11) GO TO 52	VARTTH
		IF (NPRT(18).GE.14) GO TO 52	VARTTH
		DO 42 J=1,NPL	HEDING
		IF (MNPL(J).EQ.0) GO TO 42	HEDING

KPL = MNPL(J)	HEDING
DO 41 I=1,KPL	HEDING
MPSF = MPSF+1	HEDING
NOPL(MPSF) = J	HEDING
IF (MPL(3,I,J).LT.0) M1PL(MPSF) = MPL(2,I,J)	CHGIII
IF (MPL(3,I,J).GE.0) M1PL(MPSF) = MPL(1,I,J)	CHGIII
41 MOPL(MPSF) = MPL(2,I,J)	HEDING
42 CONTINUE	HEDING
IF (MPSF.EQ.0) GO TO 52	HEDING
DO 44 J1=1,MPSF,2	HEDING
J2 = MINO(J1+1,MPSF)	HEDING
MT = MT + 1	HEDING
NT = MT	HEDING
IF (LNEW) NT = 6	HEDING
C P & E CARRIAGE CONTROL	PECONV
CALL CARCON(NT,1)	PECONV
IT = MT - 20	HEDING
PAGE = FLOAT(MT) + XPAGE	HEDING
IF (NT.EQ.6) WRITE(NT,121) DATE,BLANK,NPG	PAGE
IF (NT.NE.6) WRITE(NT,121) DATE	PAGE
IF (NT.EQ.6) NPG=NPG+1	PAGE
WRITE (NT,21) COMENT,PAGE,VPSTTL,BDYTTL	PAGE
WRITE (NT,45)	HEDING
N1 = NOPL(J1)	HEDING
N2 = NOPL(J2)	HEDING
M1 = MOPL(J1)	HEDING
M2 = MOPL(J2)	HEDING
MM1 = M1PL(J1)	CHGIII
MM2 = M1PL(J2)	CHGIII
IF (J1.EQ.J2) WRITE (NT,46)	HEDING
* BLANK,N1,( PLTTL(I,N1),I=1,5),M1,SEG(M1)	HEDING
IF (J1.NE.J2) WRITE (NT,46)	HEDING
* BLANK,N1,( PLTTL(I,N1),I=1,5),M1,SEG(M1),	HEDING
* BLANK,N2,( PLTTL(I,N2),I=1,5),M2,SEG(M2)	HEDING
WRITE (NT,47) (BLANK,UNITL,J=J1,J2)	HEDING
IF (J1.EQ.J2) WRITE (NT,48) BLANK,SEG(MM1)	CHGIII
IF (J1.NE.J2) WRITE (NT,448) BLANK,SEG(MM1),BLANK,SEG(MM2)	CHGIII
WRITE (NT,49) (BLANK,UNITL,UNITM,UNITM,UNITM,J=J1,J2)	HEDING
WRITE (NT,38)	HEDING
IF (.NOT.LNEW) GO TO 44	HEDING
JJ = 7*(J2-J1+1)	HEDING
DO 43 I=1,NLINES	HEDING
43 WRITE (NT,50) USEC(I),(ZTTH(J,I,IT),J=1,JJ)	HEDING
44 CONTINUE	HEDING
45 FORMAT(27X,'CONTACT FORCES - SEGMENT PANELS VS. SEGMENTS' )	CHGIII
46 FORMAT(' '/8X,2(A4,' PANEL',I3,' (' ,5A4,') VS. SEGMENT',I3,	HEDING
* (' ,A4,') ' )	HEDING
47 FORMAT(' ',8X,A4,'DEFL- NORMAL FRICTION RESULTANT CONTACT LOCATED	HEDING
*ION (' ,A4,') ',A2,'DEFL- NORMAL FRICTION RESULTANT CONTACT LOCATED	HEDING
*ION (' ,A4,') ')	HEDING

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48 FORMAT(' TIME',A4,'ECTION FORCE FORCE FORCE (' ,A4 CHGIII
*,' REFERENCE)' ) CHGIII
448 FORMAT(' TIME',A4,'ECTION FORCE FORCE FORCE (' ,A4 CHGIII
*,' REFERENCE)',2X,A4,'ECTION FORCE FORCE FORCE (' ,A4 CHGIII
*,' REFERENCE)' ) CHGIII
49 FORMAT(' (MSEC)',2(A3,'(' ,A4,')',2X,'(' ,A4,')',4X,'(' ,A4,')',3X,HEDING
* '(',A4,') X Y Z ') HEDING
50 FORMAT(F9.3,2(F9.3,3F9.2,3F8.3) ) HEDING
51 FORMAT(3X,'(MSEC)',4(A1,9X,'X',8X,'Y',8X,'Z',1X)) HEDING
C HEDING
C BELT FORCES HEADINGS HEDING
C HEDING
52 MBSF = 0 HEDING
IF (NPRT(18).EQ.2.OR.NPRT(18).GE.13) GO TO 83 VARTTH
IF (NPRT(18).GE.7.AND.NPRT(18).LE.9) GO TO 83 VARTTH
IF (NBLT.EQ.0) GO TO 83 HEDING
DO 54 J=1,NBLT HEDING
IF (MNBLT(J).EQ.0) GO TO 54 HEDING
MBSF = MBSF+1 HEDING
NOPL(MBSF) = J HEDING
MOPL(MBSF) = MBLT(2,1,J) HEDING
54 CONTINUE HEDING
IF (MBSF.EQ.0) GO TO 83 HEDING
DO 56 J1=1,MBSF,2 HEDING
J2 = MINO(J1+1,MBSF) HEDING
MT = MT + 1 HEDING
NT = MT HEDING
IF (LNEW) NT = 6 HEDING
C P & E CARRIAGE CONTROL PECONV
CALL CARCON(NT,1) PECONV
IT = MT - 20 HEDING
PAGE = FLOAT(MT) + XPAGE HEDING
IF (NT.EQ.6) WRITE(NT,121) DATE,BLANK,NPG PAGE
IF (NT.NE.6) WRITE(NT,121) DATE PAGE
IF (NT.EQ.6) NPG=NPG+1 PAGE
WRITE (NT,21) COMENT,PAGE,VPSTTL,BDYTTL PAGE
WRITE (NT,57) HEDING
N1 = NOPL(J1) HEDING
N2 = NOPL(J2) HEDING
M1 = MOPL(J1) HEDING
M2 = MOPL(J2) HEDING
IF (J1.EQ.J2) WRITE (NT,58) HEDING
* BLANK,N1,(BLTTTL(I,N1),I=1,5),M1,SEG(M1) HEDING
IF (J1.NE.J2) WRITE (NT,58) HEDING
* BLANK,N1,(BLTTTL(I,N1),I=1,5),M1,SEG(M1), HEDING
* BLANK,N2,(BLTTTL(I,N2),I=1,5),M2,SEG(M2) HEDING
WRITE (NT,59) (BLANK,J=J1,J2) HEDING
WRITE (NT,60) (BLANK,J=J1,J2) HEDING
WRITE (NT,61) (BLANK,UNITL,UNITL,UNITM,UNITL,UNITL,UNITM,J=J1,J2) HEDING
WRITE (NT,38) HEDING

```

	IF (.NOT.LNEW) GO TO 56	HEDING
	JJ = 4*(J2-J1+1)	HEDING
	DO 55 I=1,NLINES	HEDING
	55 WRITE (NT,62) USEC(I),(ZTTH(J,I,IT),J=1,JJ)	HEDING
	56 CONTINUE	HEDING
	57 FORMAT('0',26X,'CONTACT FORCES - BELTS VS. SEGMENTS')	HEDING
	58 FORMAT(' ',7X,2(A4,' BELT',I3,' (' ,5A4,') VS. SEGMENT',I3,	HEDING
	* ' (' ,A4,') ' )	HEDING
	59 FORMAT(' ',2X,2(A4,11X,'ANCHOR POINT A',14X,'ANCHOR POINT B'))	HEDING
	60 FORMAT(4X,'TIME',2(A4,5X,'STRAIN',7X,'FORCE',12X,	HEDING
	* 'STRAIN',7X,'FORCE',3X) )	HEDING
	61 FORMAT(3X,'(MSEC)',2(A4,2X,' (' ,A4,') / ' ,A4,')',4X,' (' ,A4,')',9X,	HEDING
	* ' (' ,A4,') / ' ,A4,')',4X,' (' ,A4,')',3X) )	HEDING
	62 FORMAT(F9.3,4(F15.6,F12.2,3X) )	HEDING
C		HEDING
C	HARNES BELT ENDPOINTS FORCES HEADINGS	HEDING
C		HEDING
	83 IF (NHRNSS.LE.0) GO TO 91	HEDING
	MBSF = 0	HEDING
	IF (NPRT(18).EQ.3.OR.NPRT(18).EQ.11) GO TO 91	VARTTH
	IF (NPRT(18).EQ.9.OR.NPRT(18).EQ.8) GO TO 91	VARTTH
	IF (NPRT(18).EQ.13.OR.NPRT(18).EQ.14) GO TO 91	VARTTH
	IF (NPRT(18).GE.16) GO TO 91	VARTTH
	J1 = 1	HEDING
	K1 = 1	HEDING
	DO 85 I=1,NHRNSS	HEDING
	IF (NBLTPH(I).LE.0) GO TO 85	HEDING
	J2 = J1 + NBLTPH(I) - 1	HEDING
	DO 84 J=J1,J2	HEDING
	MBSF = MBSF + 1	HEDING
	IF (NPTSPB(J).LE.0) GO TO 84	HEDING
	K2 = K1 + NPTSPB(J) - 1	HEDING
	NOPL(2*MBSF-1) = J	HEDING
	NOPL(2*MBSF ) = I	HEDING
	MOPL(2*MBSF-1) = K1	HEDING
	MOPL(2*MBSF ) = K2	HEDING
	K1 = K2 + 1	HEDING
	84 CONTINUE	HEDING
	J1 = J2 + 1	HEDING
	85 CONTINUE	HEDING
	DO 87 J1=1,MBSF,2	HEDING
	J2 = MINO(J1+1,MBSF)	HEDING
	MT = MT + 1	HEDING
	NT = MT	HEDING
	IF (LNEW) NT = 6	HEDING
C	P & E CARRIAGE CONTROL	PECONV
	CALL CARCON(NT,1)	PECONV
	IT = MT - 20	HEDING
	PAGE = FLOAT(MT) + XPAGE	HEDING
	IF (NT.EQ.6) WRITE(NT,121) DATE,BLANK,NPG	PAGE

	IF (NT.NE.6) WRITE(NT,121) DATE	PAGE
	IF (NT.EQ.6) NPG=NPG+1	PAGE
	WRITE (NT,21) COMENT,PAGE,VPSTTL,BDYTTTL	PAGE
	WRITE (NT,88)	HEDING
	WRITE (NT,89) (BLANK,NOPL(2*J-1),NOPL(2*J),J=J1,J2)	HEDING
	WRITE (NT,90) (BLANK,MOPL(2*J-1),MOPL(2*J),J=J1,J2)	HEDING
	WRITE (NT,60) (BLANK,J=J1,J2)	HEDING
	WRITE (NT,61) (BLANK,UNITL,UNITL,UNITM,UNITL,UNITL,UNITM,J=J1,J2)	HEDING
	WRITE (NT,38)	HEDING
	IF (.NOT.LNEW) GO TO 87	HEDING
	JJ = 4*(J2-J1+1)	HEDING
	DO 86 I=1,NLINES	HEDING
	86 WRITE (NT,62) USEC(I),(ZTTH(J,I,IT),J=1,JJ)	HEDING
	87 CONTINUE	HEDING
	88 FORMAT('0',26X,'HARNES SYSTEM BELT ENDPOINT FORCES')	HEDING
	89 FORMAT(9X,2(A4,11X,'BELT NO.',I4,' OF HARNES NO.',I3,15X))	HEDING
	90 FORMAT(9X,2(A4,6X,'POINT NO.',I5,16X,'POINT NO.',I5,6X))	HEDING
C		HEDING
C	SPRING DAMPER FORCES HEADINGS	HEDING
C		HEDING
	91 IF (NSD.LE.0) GO TO 63	HEDING
	IF (NPRT(18).EQ.4.OR.NPRT(18).EQ.9) GO TO 63	VARTTH
	IF (NPRT(18).GE.12) GO TO 63	VARTTH
	DO 94 J1=1,NSD,4	HEDING
	J2 = MIN0(J1+3,NSD)	HEDING
	MT = MT + 1	HEDING
	NT = MT	HEDING
	IF (LNEW) NT = 6	HEDING
C	P & E CARRIAGE CONTROL	PECONV
	CALL CARCON(NT,1)	PECONV
	IT = MT - 20	HEDING
	PAGE = FLOAT(MT) + XPAGE	HEDING
	IF (NT.EQ.6) WRITE(NT,121) DATE,BLANK,NPG	PAGE
	IF (NT.NE.6) WRITE(NT,121) DATE	PAGE
	IF (NT.EQ.6) NPG=NPG+1	PAGE
	WRITE (NT,21) COMENT,PAGE,VPSTTL,BDYTTTL	PAGE
	WRITE (NT,95) (BLANK,J,J=J1,J2)	HEDING
	DO 92 J=J1,J2	HEDING
	M1 = MSDM(J)	HEDING
	N1 = MSDN(J)	HEDING
C	POSSIBLE OVERFLOW INTO NOPL ARRAY IS INTENTIONAL.	HEDING
	HEAD(2*J-1) = SEG(M1)	HEDING
	92 HEAD(2*J ) = SEG(N1)	HEDING
	WRITE (NT,96) (BLANK,MSDM(J),HEAD(2*J-1),MSDN(J),HEAD(2*J),J=J1,J2)	HEDING
	WRITE (NT,97) (BLANK,J=J1,J2)	HEDING
	WRITE (NT,98) (BLANK,UNITL,UNITM,J=J1,J2)	HEDING
	WRITE (NT,38)	HEDING
	IF (.NOT.LNEW) GO TO 94	HEDING
	JJ = 2*(J2-J1+1)	HEDING
	DO 93 I=1,NLINES	HEDING

93	WRITE (NT,99) USEC(I), (ZTTH(J,I,IT), J=1, JJ)	HEDING
94	CONTINUE	HEDING
95	FORMAT('0', 26X, 'SPRING DAMPER FORCES' /	HEDING
*	9X, 4(A3, 3X, 'SPRING DAMPER NO.', I3, 4X))	HEDING
96	FORMAT(9X, 4(A3, 'SEG', I3, '(', A4, ') - SEG', I3, '(', A4, ')'))	HEDING
97	FORMAT(4X, 'TIME', 1X, 4(A3, 5X, 'LENGTH', 7X, 'FORCE', 4X))	HEDING
98	FORMAT(3X, ' (MSEC)', 4(A3, 5X, '(', A4, ')', 6X, '(', A4, ')', 4X))	HEDING
99	FORMAT (F9.3, 4(F14.3, F12.2, 4X))	HEDING
C		HEDING
C	SEGMENT FORCES HEADINGS	HEDING
C		HEDING
63	MSSF = 0	HEDING
	IF (NPRT(18).EQ.5.OR.NPRT(18).EQ.13) GO TO 161	VARTTH
	IF (NPRT(18).EQ.10.OR.NPRT(18).EQ.11) GO TO 161	VARTTH
	IF (NPRT(18).GE.15) GO TO 161	VARTTH
	DO 65 J=1, NSEG	HEDING
	IF (MNSEG(J).EQ.0) GO TO 65	HEDING
	LSEG = MNSEG(J)	HEDING
	DO 64 I=1, LSEG	HEDING
	MSSF = MSSF+1	HEDING
	NOPL(MSSF) = J	HEDING
64	MOPL(MSSF) = MSEG(2, I, J)	HEDING
65	CONTINUE	HEDING
	IF (MSSF.EQ.0) GO TO 70	HEDING
	DO 67 J=1, MSSF	HEDING
	MT = MT + 1	HEDING
	NT = MT	HEDING
	IF (LNEW) NT = 6	HEDING
C	P & E CARRIAGE CONTROL	PECONV
	CALL CARCON(NT, 1)	PECONV
	IT = MT - 20	HEDING
	PAGE = FLOAT(MT) + XPAGE	HEDING
	IF (NT.EQ.6) WRITE(NT, 121) DATE, BLANK, NPG	PAGE
	IF (NT.NE.6) WRITE(NT, 121) DATE	PAGE
	IF (NT.EQ.6) NPG=NPG+1	PAGE
	WRITE (NT, 21) COMENT, PAGE, VPSTTL, BDYTTL	PAGE
	N1 = NOPL(J)	HEDING
	M1 = MOPL(J)	HEDING
	WRITE (NT, 68) N1, SEG(N1), M1, SEG(M1), UNITL, N1, M1	HEDING
*	UNITL, UNITM, UNITM, UNITM	HEDING
	IF (.NOT.LNEW) GO TO 67	HEDING
	DO 66 I=1, N1LINES	HEDING
66	WRITE (NT, 69) USEC(I), (ZTTH(JJ, I, IT), JJ=1, 10)	HEDING
67	CONTINUE	HEDING
68	FORMAT('0', 26X, 'CONTACT FORCES - SEGMENT NO.', I3, '(', A4,	HEDING
*	) VS. SEGMENT NO.', I3, '(', A4, ') '//	HEDING
*	13X, 'DEFL- NORMAL FRICTION RESULTANT',	HEDING
*	14X, 'CONTACT LOCATION (' , A4, ') '/	HEDING
*	4X, 'TIME ECTION', 3(3X, 'FORCE', 1X),	HEDING
*	2(' SEG.', I3, ' LOCAL REFERENCE ')/	HEDING

	*        3X,'(MSEC)',3X,'(',A4,')', 3(3X,'(',A4,')'),	HEDING
	*        2(5X,'X',7X,'Y',7X,'Z',4X)/1X)	HEDING
	69 FORMAT(2F9.3,3F9.2,3F8.3,2X,3F8.3)	HEDING
	161 CONTINUE	VARTTH
C		HEDING
C	AIRBAG FORCES HEADINGS	HEDING
C		HEDING
	70 IF (NBAG.EQ.0) GO TO 82	HEDING
	IF (NPRT(18).EQ.6.OR.NPRT(18).EQ.9) GO TO 82	VARTTH
	IF (NPRT(18).GE.12) GO TO 82	VARTTH
	DO 77 J=1,NBAG	HEDING
	IF (MNBAG(J).EQ.0) GO TO 77	HEDING
	MT = MT + 1	HEDING
	NT = MT	HEDING
	IF (LNEW) NT = 6	HEDING
C	P & E CARRIAGE CONTROL	PECONV
	CALL CARCON(NT,1)	PECONV
	IT = MT - 20	HEDING
	PAGE = FLOAT(MT) + XPAGE	HEDING
	IF (NT.EQ.6) WRITE(NT,121) DATE,BLANK,NPG	PAGE
	IF (NT.NE.6) WRITE(NT,121) DATE	PAGE
	IF (NT.EQ.6) NPG=NPG+1	PAGE
	WRITE (NT,21) COMENT,PAGE,VPSTTL,BDYTTL	PAGE
	WRITE (NT,78) J,(BAGTTL(I,J),I=1,5)	HEDING
	IF (.NOT.LNEW) GO TO 72	HEDING
	DO 71 I=1,NLINES	HEDING
	71 WRITE (NT, 79) USEC(I),(ZTTH(JJ,I,IT),JJ=1,12)	HEDING
	72 KBAG = 0	HEDING
	KP = NPANEL(J)+1	HEDING
	DO 73 K=1,KP	HEDING
	KBAG = KBAG+1	HEDING
	73 HEAD(KBAG) = PHED(K)	HEDING
	KP = MNBAG(J)	HEDING
	DO 74 K=1,KP	HEDING
	KBAG = KBAG+1	HEDING
	M = MBAG(2,K,J)	HEDING
	74 HEAD(KBAG) = SEG(M)	HEDING
	DO 76 J1=1,KBAG,4	HEDING
	J2 = MINO(J1+3,KBAG)	HEDING
	MT = MT + 1	HEDING
	NT = MT	HEDING
	IF (LNEW) NT = 6	HEDING
C	P & E CARRIAGE CONTROL	PECONV
	CALL CARCON(NT,1)	PECONV
	IT = MT - 20	HEDING
	PAGE = FLOAT(MT) + XPAGE	HEDING
	IF (NT.EQ.6) WRITE(NT,121) DATE,BLANK,NPG	PAGE
	IF (NT.NE.6) WRITE(NT,121) DATE	PAGE
	IF (NT.EQ.6) NPG=NPG+1	PAGE
	WRITE (NT,21) COMENT,PAGE,VPSTTL,BDYTTL	PAGE

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WRITE (NT,80)UNITM,J,(BAGTTL(I,J),I=1,5),(BLANK,J,HEAD(K),K=J1,J2)HEDING
WRITE (NT,51) (BLANK,K=J1,J2) HEDING
WRITE (NT,38) HEDING
IF (.NOT.LNEW) GO TO 76 HEDING
JJ = 3*(J2-J1+1) HEDING
DO 75 I=1,NLINES HEDING
75 WRITE (NT, 81) USEC(I),(ZTTH(K,I,IT),K=1,JJ) HEDING
76 CONTINUE HEDING
77 CONTINUE HEDING
78 FORMAT('0',26X,'PARAMETERS FOR AIRBAG NO.',I2,4X,5A4// HEDING
* 16X,'SUPPLY CYLINDER STATIC'/ HEDING
* 4X,'TIME',8X,'PRES.',4X,'TEMP.',4X,'PRES.',12X,'AIRBAG', HEDING
* 3X,'CENTER',14X,'AIRBAG SEMIAXES',12X,'ORIENTATION (DEG.)'/ HEDING
* 3X,'(MSEC)',7X,'(PSIG) (DEG.R) (PSIG)',8X,'X',8X,'Y',8X,'Z', HEDING
* 11X,'A',8X,'B',8X,'C',10X,'YAW',4X,'PITCH',5X,'ROLL'/ ) HEDING
79 FORMAT (F9.3,3X,3F9.2,2(3X,3F9.3),3X,3F9.2) HEDING
80 FORMAT('0',26X,'CONTACT FORCES (' ,A4,') ON AIRBAG NO.',I2,4X,5A4//HEDING
* /4X,'TIME',4(A1,11X,'AIRBAG',I2,' VS. ',A4,1X)) HEDING
81 FORMAT (F9.3,4(3X,3F9.2)) HEDING
82 RETURN HEDING
END HEDING

```





C		HERRON
C	EVALUATE THETO AND THETOP FROM REGULAR FUNCTION DEFINITION WHERE	HERRON
C	THETO (ORDINATE) IS A FUNCTION OF PHI (ABSCISSA) (0 < PHI < 2*PI)	HERRON
C		HERRON
30	PHI = DATAN2(HD3(2),HD3(1))	HERRON
	IF (PHI.LT.0.0) PHI = PHI + TWOPI	TWOPI
	THETO = EVALFD(PHI,NT1,1)	HERRON
	THETOP = EVALFD(PHI,NT1,0)	HERRON
99	RETURN	HERRON
	END	HERRON



```

AREA(1) = 0.0
H1 = SQRT(Z(1,JH)) * Z(1,JH)**2
DO 17 I=2,NPTS
H2 = SQRT(Z(I,JH)) * Z(I,JH)**2
DT = 0.5*(Z(I,1) - Z(I-1,1))
AREA(I) = AREA(I-1) + DT*(Z(I-1,JH)+Z(I,JH))
HSI = HSI + DT*(H1+H2)
IF (HMX.GT.Z(I,JH)) GO TO 17
HMX = Z(I,JH)
HMT = Z(I,1)
17 H1 = H2
HSI = 0.001*HSI

C
C COMPUTE HIC - HEAD INJURY CRITERION - AND TIME DURATION HT1,HT2
C

DO 19 K=2,NPTS
DO 18 L=K,NPTS
DT = Z(L,1) - Z(K-1,1)
DH = AREA(L) - AREA(K-1)
HT = DH/DT
HM = DT*SQRT(HT)*HT**2
IF (HM.LE.HIC) GO TO 18
HIC = HM
HT1 = Z(K-1,1)
HT2 = Z(L,1)
HA2 = Z(L,JH)
HA1 = Z(K-1,JH)
AVE = HT
18 CONTINUE
19 CONTINUE
HIC = 0.001*HIC
WRITE (6,21) HIC,HT1,HT2,HA1,HA2,AVE
21 FORMAT (1H0, ' HEAD INJURY CRITERION'//
* ' HIC = ', F8.2,
* 9X, 'TIME DURATION = ', F9.3, ' TO ', F9.3, ' MSEC'//
* 20X, 'WITH HEAD RESULTANTS = ', F9.3, ' AND ', F9.3, ' G'S'//
*14X, 'AVERAGE HEAD RESULTANT FOR TIME DURATION = ', F9.3, ' G'S')
WRITE (6,22) HSI,HMX,HMT
22 FORMAT (1H0, ' HEAD SEVERITY INDEX'//
* ' HSI = ', F8.2//
* ' MAX HEAD RESULTANT = ', F9.3, ' G'S AT ', F9.3, ' MSEC')
23 IF (JDTPTS(2).EQ.0) GO TO 25
WRITE (6,24) CSI,CMX,CMT
24 FORMAT (1H0, ' CHEST SEVERITY INDEX'//
* ' CSI = ', F8.2//
* ' MAX CHEST RESULTANT = ', F9.3, ' G'S AT ', F9.3, ' MSEC')
25 CONTINUE
IF(NPTS.LT.25) WRITE(6,101) NPTS
101 FORMAT(1X,/,2X, 'HIC, HSI AND CSI NOT COMPUTED BECAUSE THE NUMBER
*OF POINTS TO BE USED IN THE COMPUTATION = ',I2,',',/,2X

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\* 'WHICH IS LESS THAN THE MINIMUM REQUIREMENT OF 25 POINTS.',/)  
RETURN  
END

TGMOD1  
TGMOD1  
HICCSI

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SUBROUTINE HINPUT                                HINPUT
C                                               REV IV    07/23/86TWOPI
C   CONTROLS THE INPUT OF CARDS F.8.A - F.8.D CONTAINING THE SETUP ANDHINPUT
C   CONTROL OF THE HARNESS BELT SYSTEM.          HINPUT
C                                               HINPUT
C                                               HINPUT
C   IMPLICIT REAL*8(A-H,O-Z)                    HINPUT
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND, HINPUT
*   NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG   PAGE
COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24), HINPUT
*   UNITL,UNITM,UNITT,GRAVITY(3),TWOPI              TWOPI
COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100), HINPUT
*   XLONG(20),HTIME(2),IBAR(5,100),NL(2,100), HINPUT
*   NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5) HINPUT
COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)DIMENB
COMMON/CNTRF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40) EDGE
COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5), HINPUT
*   BLTTTL(5,8),PLTTL(5,30),BAGTTL(5,6),SEG(30), HINPUT
*   JOINT(30),CGS(30),JS(30) HINPUT
REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,SEG,JOINT HINPUT
LOGICAL*1 CGS,JS HINPUT
C   THIS COMMON/TEMTVS/ IS SHARED BY CINPUT, FINPUT, HINPUT AND FDINITHINPUT
COMMON/TEMPVS/ JTITLE(5,51),NF(5),MS(3),KTITLE(31) HINPUT
REAL JTITLE,KTITLE HINPUT
IF (NHRNSS.EQ.0) GO TO 99 HINPUT
C                                               HINPUT
C   INPUT CARD F.8.A HINPUT
C   (NOTE: NHRNSS NOW SUPPLIED ON INPUT CARD D.1) HINPUT
C   NBLTPH - NO. OF BELTS PER HARNESS HINPUT
C                                               HINPUT
C   READ (5,11) (NBLTPH(I),I=1,NHRNSS) HINPUT
11 FORMAT(18I4) HINPUT
WRITE (6,12) NPG,NHRNSS,(NBLTPH(I),I=1,NHRNSS) PAGE
NPG=NPG+1 PAGE
12 FORMAT('1 HARNESS-BELT SYSTEM INPUT',96X,'PAGE',I5/120X, PAGE
*   'CARDS F.8'/' NO. OF HARNESSES =',I4// PAGE
*   ' NO. OF BELTS PER HARNESS =',5I6) HINPUT
J1 = 1 HINPUT
K1 = 1 HINPUT
DO 90 I=1,NHRNSS HINPUT
IF (NBLTPH(I).LE.0) GO TO 90 HINPUT
J2 = J1 + NBLTPH(I) -1 HINPUT
C                                               HINPUT
C   INPUT CARD F.8.B - NPTSPB - NO. OF POINTS PER BELT. HINPUT
C                                               HINPUT
C   READ (5,11) (NPTSPB(J),J=J1,J2) HINPUT
WRITE (6,13) I,(NPTSPB(J),J=J1,J2) HINPUT
13 FORMAT('0 FOR HARNESS NO.',I3,' NO. OF POINTS PER BELT =',20I4) HINPUT
DO 80 J=J1,J2 HINPUT
IF (NPTSPB(J).EQ.0) GO TO 80 HINPUT

```

C		HINPUT
C	INPUT CARD F.8.C - 5 FUNCTION NOS AND LENGTH OF EACH BELT.	HINPUT
C		HINPUT
	READ (5,14) NF,XLONG(J)	HINPUT
14	FORMAT(5I4,F12.6)	HINPUT
	WRITE (6,15) I,J,NF,XLONG(J),UNITL	HINPUT
15	FORMAT('0 HARNESS NO.',I3,' BELT NO.',I3,' FUNCTION NOS.',5I6,	HINPUT
*	' REFERENCE SLACK = ',F9.3,1X,A4/)	HINPUT
	IF (XLONG(J).EQ.0.0) XLONG(J) = EPS(24)	HINPUT
	WRITE (6,16)	HINPUT
16	FORMAT ('0 K KS KE NT NPD NDR FUNCTION NOS.',	HINPUT
*	66X,'CARDS F.8.D'/)	CHGIII
C		HINPUT
C	SET UP POINTERS IN NTAB AND INITIAL VALUES OF TAB FOR BELT J	HINPUT
C	AS WAS DONE FOR OTHER CONTACTS IN SUBROUTINE FINPUT.	HINPUT
C		HINPUT
	NTHRNS(J) = MXNTB+1	HINPUT
	CALL FDINIT	HINPUT
	K2 = K1 + NPTSPB(J) - 1	HINPUT
	DO 70 K=K1,K2	HINPUT
C		HINPUT
C	INPUT CARD F.8.D	HINPUT
C		HINPUT
	READ (5,21) KS,KE,NPD,NDR,NF, (BAR(L,K),L=1,3)	HINPUT
21	FORMAT (9I4,3F12.0)	HINPUT
	READ (5,22) (BAR(L,K),L=7,12)	HINPUT
22	FORMAT (6F12.0)	HINPUT
	ICHEC = 0	CHGIII
	IF (K.EQ.K1.OR.K.EQ.K2) ICHEC = 1	CHGIII
	IF (ICHEC.EQ.1.AND.NPD.EQ.0) STOP 60	CHGIII
	IF (ICHEC.EQ.1.AND.NDR.EQ.0) STOP 61	CHGIII
	IF (NDR.EQ.0.AND.NPD.NE.0) STOP 62	CHGIII
	IBAR(1,K) = KS	HINPUT
	IBAR(2,K) = KE	HINPUT
	IBAR(4,K) = NPD	HINPUT
	IBAR(5,K) = NDR	HINPUT
	IBAR(3,K) = MXNTB+1	HINPUT
	CALL FDINIT	HINPUT
	SQRER = 1.0	HINPUT
	IF (KE.NE.0) SQRER = DSQRT(XDY(BAR(1,K),BD(7,KE),BAR(1,K)))	HINPUT
	DO 26 L=1,3	HINPUT
	IF (KE.NE.0) BAR(L+6,K) = BD(L+3,KE)	HINPUT
26	BAR(L+3,K) = BAR(L,K)/SQRER	HINPUT
	WRITE (6,31) K, (IBAR(L,K),L=1,5),NF	HINPUT
31	FORMAT (11I6)	HINPUT
70	CONTINUE	HINPUT
	WRITE (6,71) UNITL,UNITL,UNITL,UNITL	HINPUT
71	FORMAT ('0',12X,'BASE REFERENCE (' , A4,')',	HINPUT
*	7X,'ADJUSTED REFERENCE (' , A4,')',	HINPUT
*	11X,'OFFSET (' , A4,')',	HINPUT

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*          11X,'PREFERRED DIRECTION (' ,A4,')' / HINPUT
*          5X,'K', 4(8X,'X',8X,'Y',8X,'Z',3X) / HINPUT
WRITE (6,72) (K,(BAR(L,K),L=1,12),K=K1,K2) HINPUT
72 FORMAT (I6,3X,3F9.3,3X,3F9.3,3X,3F9.3,3X,3F9.3) HINPUT
K1 = K2+1 HINPUT
80 CONTINUE HINPUT
J1 = J2+1 HINPUT
90 CONTINUE HINPUT
DO 92 K=1,100 HINPUT
  BBDOT(K) = 0.0 HINPUT
  DO 91 J=1,2 HINPUT
91 PLOSS(J,K) = 0.0 HINPUT
  DO 92 J=1,3 HINPUT
92 BAR(J+12,K) = 0.0 HINPUT
99 RETURN HINPUT
END HINPUT
```



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SUBROUTINE HPTURB                                HPTURB
C                                               REV IV    07/23/86TWOPI
IMPLICIT REAL*8 (A-H,O-Z)                        HPTURB
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND, HPTURB
* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG PAGE
COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),        HPTURB
* UNITL,UNITM,UNITT,GRAVTY(3),TWOPI            TWOPI
COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40) EDGE
COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30), HPTURB
* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30) HPTURB
COMMON/RSAVE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30), ATBIII
* NSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9) TTHKREF
COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100), HPTURB
* XLONG(20),HTIME(2),IBAR(5,100),NL(2,100),    HPTURB
* NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5)   HPTURB
C THIS COMMON/TEMPVS/ IS SHARED BY HPTURB, HBPLAY, HBELT AND HSETC. HPTURB
COMMON/TEMPVS/ B(3,3,3),S(3,3),T(3),R(3),V(3),T1(3),T2(3), HPTURB
* E(3,3,50),EDOT(3,50),FCE(3,50),FR(3,50),ZR(3,50), HPTURB
* TR(3,50),U(3,50),PTLOSS(2,50),BL(50),FB(50),FP(50), HPTURB
* OLDBB(100),RHS(3,54),C(3,3,200),IJK(54,54)   HPTURB
DIMENSION BLOSS(2,20),HLOSS(2,5)                HPTURB
EQUIVALENCE (BLOSS(1,1),C(1,1,1)) , (HLOSS(1,1),C(1,1,10)) HPTURB
LOGICAL LAST                                     HPTURB
DATA MAXITR/10/                                  HPTURB
CALL ELTIME (1,39)                               HPTURB
CALL HBPLAY                                       HPTURB
DHT = 0.0                                         HPTURB
IF (TIME.NE.0.0) DHT = TIME - HTIME(1)          HPTURB
HTIME(1) = TIME                                   HPTURB
DO 11 J=1,100                                     HPTURB
PTLOSS(J,1) = 0.0                               HPTURB
OLDBB(J) = BB(J)                                 HPTURB
DO 11 I=1,3                                       HPTURB
11 BAR(I,J) = BAR(I+3,J)                           HPTURB
TSEC = 1000.0*TIME                                HPTURB
IF (NPRT(28).NE.0) WRITE (6,12) TSEC,NPG,UNITL,UNITM,UNITL, HPTURB
* UNITL,UNITM,UNITL,UNITM                        PAGE
IF (NPRT(28).NE.0) NPG=NPG+1                     PAGE
12 FORMAT('1  HARNESS BELT RESULTS FOR TIME =',F9.3,' MSEC.',73X, PAGE
* 'PAGE',I5//                                     PAGE
* 36X,'BELT STRAIN',6X,'(LOCAL OR ELLIPSOID)',18X, CHGIII
* '(INERTIAL)',14X,'PENETRATION'/              CHGIII
* ' POINT POINT SEGMENT LENGTH ENERGY LOSS',5X, HPTURB
* 'REFERENCE POINT (' ,A4,')',13X,'BELT FORCES (' ,A4,')', AFREVS
* 9X,'ENERGY LOSS'/                             HPTURB
* ' NO. INDEX NO. (' ,A4,') (' ,2A4,')',7X,    HPTURB
* 'X',8X,'Y',8X,'Z',13X,'X',10X,'Y',10X,'Z',8X,'(' ,2A4,')'//) HPTURB
J1 = 1                                             HPTURB
KO = 1                                             HPTURB
KNLO = 0                                          HPTURB

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	DO 61 NH=1,NHRNSS	HPTURB
	IF (NBLTPH(NH).LE.0) GO TO 61	HPTURB
	ITER = 1	HPTURB
	KNL1 = KNLO	HPTURB
	KNLN = 0	CHG I I
C		HPTURB
C	START OF DO 59 ITER=1,MAXITR LOOP	HPTURB
C		HPTURB
	13 NJ2 = 54	HPTURB
	DO 14 I=1,NJ2	HPTURB
	DO 14 J=1,NJ2	HPTURB
	14 IJK(I,J) = 0	HPTURB
	KNLO = KNL1	HPTURB
	J2 = J1 + NBLTPH(NH) - 1	HPTURB
	NTP = 0	HPTURB
	IJ = 0	HPTURB
	CALL HBELT (J1,J2,KNLO,1)	HPTURB
	KHO = 0	HPTURB
	KNLO = KNL1	HPTURB
	DO 15 NB=J1,J2	HPTURB
	IF (NPTPLY(NB).LE.0) GO TO 15	HPTURB
	NPTS = NPTPLY(NB)	HPTURB
	CALL HSETC (NPTS,KHO,KNLO,NTP,IJ)	HPTURB
	KHO = KHO + NPTS	HPTURB
	KNLO = KNLO + NPTS	HPTURB
	15 CONTINUE	HPTURB
	KNLN = KNLO	CHG I I
C		HPTURB
C	SET UP C AND IJK ELEMENTS FOR TIE-POINTS.	HPTURB
C		HPTURB
	KNLO = KNL1	HPTURB
	KNLK = KNLO + 1	HPTURB
	K1 = KNLK	HPTURB
	DO 22 NB=J1,J2	HPTURB
	IF (NPTPLY(NB).LE.0) GO TO 22	HPTURB
	K2 = K1 + NPTPLY(NB) - 1	HPTURB
	DO 21 KNL=K1,K2	HPTURB
	KI = NL(1,KNL)	HPTURB
	KS = IABS(IBAR(1,KI))	HPTURB
	IF (KS.LT.100) GO TO 21	HPTURB
	KS1 = KS/100	HPTURB
	DO 16 K=KNLK,KNL	HPTURB
	KK = K	HPTURB
	KI = NL(1,K)	HPTURB
	KS = IABS(IBAR(1,KI))	HPTURB
	IF (KS.LT.100) GO TO 16	HPTURB
	KS2 = KS/100	HPTURB
	IF (KS2.EQ.KS1) GO TO 17	HPTURB
	16 CONTINUE	HPTURB
	17 IF (KK.EQ.KNL) GO TO 21	HPTURB

KK1 = KK - KNLO	HPTURB
KK2 = KNL - KNLO	HPTURB
IQ1 = MAXO(1, KK2-1)	HPTURB
IQ2 = MINO(KK2+1, KH0)	HPTURB
DO 18 IQ=IQ1, IQ2	HPTURB
IF (IJK(KK2, IQ).EQ.0) GO TO 18	HPTURB
IJK(KK1, IQ) = IJK(KK2, IQ)	HPTURB
IJK(KK2, IQ) = 0	HPTURB
18 CONTINUE	HPTURB
IJK(KK2, KK2) = IJ+1	HPTURB
IJK(KK2, KK1) = IJ+2	HPTURB
DO 20 J=1, 3	HPTURB
DO 19 I=1, 3	HPTURB
C(I, J, IJ+1) = 0.0	HPTURB
19 C(I, J, IJ+2) = 0.0	HPTURB
C(J, J, IJ+1) = 1.0	HPTURB
20 C(J, J, IJ+2) = -1.0	HPTURB
IJ = IJ + 2	HPTURB
21 CONTINUE	HPTURB
K1 = K2 + 1	HPTURB
22 CONTINUE	HPTURB
MJ2 = -(KH0+NTP)	HPTURB
IF (NPRT(28).LT.3) GO TO 29	HPTURB
NJ2 = -MJ2	HPTURB
DO 25 J=1, NJ2	HPTURB
25 WRITE (6, 26) J, (RHS(I, J), I=1, 3), (IJK(J, I), I=1, NJ2)	HPTURB
26 FORMAT (I6, 3F12.6, 2O14/(42X, 2O14))	HPTURB
DO 27 KLM=1, IJ	HPTURB
27 WRITE (6, 28) KLM, ((C(J, I, KLM), I=1, 3), J=1, 3)	HPTURB
28 FORMAT (I6, 9F12.6)	HPTURB
29 CALL FSMSOL (C, RHS, IJK, MJ2, IJ, 54, 200)	HPTURB
IF (NPRT(28).LT.3) GO TO 31	HPTURB
DO 30 J=1, NJ2	HPTURB
30 WRITE (6, 26) J, (RHS(I, J), I=1, 3), (IJK(J, I), I=1, NJ2)	HPTURB
31 ONE = 1.0	HPTURB
DELMAX = 0.0	HPTURB
SCALE = 1.0	HPTURB
DO 44 IT=1, 2	HPTURB
K1 = K0	HPTURB
KH = 0	HPTURB
KR = NTP	HPTURB
DO 43 NB=J1, J2	HPTURB
IF (NPTPLY(NB).LE.0) GO TO 43	HPTURB
K2 = K1 + NPTPLY(NB) - 1	HPTURB
DO 42 K=K1, K2	HPTURB
KH = KH + 1	HPTURB
KR = KR + 1	HPTURB
C	HPTURB
C	HPTURB
C	HPTURB
HERE K IS INDEX OF ALL POINTS IN PLAY	HPTURB
KH IS INDEX OF ALL POINTS IN PLAY ON A SINGLE HARNESS	HPTURB

C	KR IS INDEX OF RHS ARRAY ELEMENTS	HPTURB
C	KI = NL(1,K)	HPTURB
	KS = IABS(IBAR(1,KI))	HPTURB
	IF (KS.GT.100) KS = MOD(KS,100)	HPTURB
	IF (IBAR(5,KI).EQ.0) GO TO 32	HPTURB
	CALL MAT31 (D(1,1,KS),RHS(1,KR),R)	HPTURB
	GO TO 37	HPTURB
C	NOTE: ENDPOINTS (K = K1 & K2) MUST BE TYPE 5.	HPTURB
C	32 CALL DOT31 (E(1,1,KH),RHS(1,KR),T1)	HPTURB
	IF (IT.EQ.2) GO TO 33	HPTURB
	DELMAX = DMAX1(DELMAX,DABS(T1(2)/DMIN1(BB(K),BB(K-1))))	HPTURB
	GO TO 34	HPTURB
	33 BB(K ) = BB(K ) + SCALE*T1(2)	HPTURB
	BB(K-1) = BB(K-1) - SCALE*T1(2)	HPTURB
	34 DO 35 J=1,3	HPTURB
	35 T2(J) = T1(1)*E(J,1,KH) + T1(3)*E(J,3,KH)	HPTURB
	CALL MAT31 (D(1,1,KS),T2,R)	HPTURB
	IF (NPRT(28).GE.3) WRITE (6,36) K,T1,T2,R	HPTURB
	36 FORMAT ('0',I6,3(3X,3F12.6))	HPTURB
	37 IF (IT.EQ.2) GO TO 39	HPTURB
	DO 38 J=1,3	HPTURB
	38 DELMAX = DMAX1(DELMAX,DABS(R(J)/DMAX1(EPS(1),DABS(BAR(J+3,KI)))))	HPTURB
	GO TO 42	HPTURB
	39 DO 40 J=1,3	HPTURB
	40 BAR(J+3,KI) = BAR(J+3,KI) + SCALE*R(J)	HPTURB
	KE = IBAR(2,KI)	HPTURB
	IF (KE.EQ.0) GO TO 42	HPTURB
	RER = XDY(BAR(4,KI),BD(7,KE),BAR(4,KI))	HPTURB
	IF (RER.LE.1.0) GO TO 42	HPTURB
	SQRER = 1.0/DSQRT(RER)	HPTURB
	DO 41 J=1,3	HPTURB
	41 BAR(J+3,KI) = SQRER*BAR(J+3,KI)	HPTURB
	42 CONTINUE	HPTURB
	K1 = K2 + 1	HPTURB
	43 CONTINUE	HPTURB
	IF (IT.EQ.2) GO TO 44	HPTURB
	IF (DELMAX.NE.0.0) SCALE = DMIN1(ONE,EPS(1)/DELMAX)	HPTURB
	44 CONTINUE	HPTURB
	IF (NPRT(28).GE.2) WRITE (6,45) ITER,DELMAX,SCALE	HPTURB
	45 FORMAT ('0 ITER =',I6,' DELMAX =',F15.6,' SCALE =',F15.6)	HPTURB
	LAST = DELMAX.LE.EPS(2) .OR. ITER.EQ.MAXITR	HPTURB
	IF (.NOT.LAST) GO TO 52	HPTURB
	KH = 0	HPTURB
	K1 = K0	HPTURB
	HLOSS(1,NH) = 0.0	HPTURB
	HLOSS(2,NH) = 0.0	HPTURB
	DO 51 NB=J1,J2	HPTURB

BLOSS(1,NB) = 0.0	HPTURB
BLOSS(2,NB) = 0.0	HPTURB
IF (NPTPLY(NB).LE.0) GO TO 51	HPTURB
K2 = K1 + NPTPLY(NB) - 1	HPTURB
KK1 = NL(1,K1)	HPTURB
KK2 = NL(1,K2)	HPTURB
DO 46 K=KK1,KK2	HPTURB
DO 46 J=1,3	HPTURB
46 BAR(J+12,K) = 0.0	HPTURB
IF (DHT.EQ.0.0) GO TO 49	HPTURB
DO 48 K=K1,K2	HPTURB
KH = KH + 1	HPTURB
KI = NL(1,K)	HPTURB
PLOSS(2,KI) = PLOSS(2,KI) + DHT*PTLOSS(2,KH)	HPTURB
IF (K.EQ.K1) GO TO 47	HPTURB
BBDOT(K-1) = (BB(K-1)-OLDBB(K-1))/DHT	HPTURB
PLOSS(1,K-1) = PLOSS(1,K-1) + DHT*PTLOSS(1,KH-1)	HPTURB
BLOSS(1,NB) = BLOSS(1,NB) + PLOSS(1,K-1)	HPTURB
47 DO 48 J=1,3	HPTURB
48 BAR(J+12,KI) = (BAR(J+3,KI)-BAR(J,KI))/DHT	HPTURB
BBDOT(K2) = 0.0	HPTURB
PLOSS(1,K2) = 0.0	HPTURB
49 K1 = K2+1	HPTURB
DO 50 K=KK1,KK2	HPTURB
50 BLOSS(2,NB) = BLOSS(2,NB) + PLOSS(2,K)	HPTURB
HLOSS(1,NH) = HLOSS(1,NH) + BLOSS(1,NB)	HPTURB
HLOSS(2,NH) = HLOSS(2,NH) + BLOSS(2,NB)	HPTURB
51 CONTINUE	HPTURB
52 IF (NPRT(28).EQ.0) GO TO 59	HPTURB
IF (.NOT.LAST .AND. IABS(NPRT(28)).EQ.1) GO TO 59	HPTURB
K1 = K0	HPTURB
KH = 0	HPTURB
DO 57 NB=J1,J2	HPTURB
IF (NPTPLY(NB).LE.0) GO TO 57	HPTURB
WRITE (6,53) NB,NH	HPTURB
53 FORMAT ('0 BELT NO.',I4,' OF HARNESS NO.',I4)	HPTURB
K2 = K1 + NPTPLY(NB) - 1	HPTURB
DO 54 K=K1,K2	HPTURB
KH = KH + 1	HPTURB
KI = NL(1,K)	HPTURB
KS = IBAR(1,KI)	HPTURB
BK = 0.0	HPTURB
IF (K.NE.K1) BK = BB(K-1)	HPTURB
PLS = 0.0	HPTURB
IF (K.NE.K1) PLS = PLOSS(1,K-1)	HPTURB
T(1) = BAR(4,KI)	HPTURB
T(2) = BAR(5,KI)	HPTURB
T(3) = BAR(6,KI)	HPTURB
KJ = MOD(IABS(KS),100)	HPTURB
IF (LPMI(KJ).NE.0) CALL DOT31 (DPMI(1,1,KJ),BAR(4,KI),T)	HPTURB

54	WRITE (6,55) K,KI,KS,BK,PLS,(T(J),J=1,3),	HPTURB
*	(FCE(J,KH),J=1,3),PLOSS(2,KI)	HPTURB
55	FORMAT (3I8,F10.3,F12.3,2X,3F9.3,3X,3F11.3,3X,F12.3)	HPTURB
	IF (LAST) WRITE (6,56) BLOSS(1,NB),BLOSS(2,NB)	HPTURB
56	FORMAT ('0 TOTAL BELT ENERGY LOSS',7X,F12.3,68X,F12.3)	HPTURB
	K1 = K2 + 1	HPTURB
57	CONTINUE	HPTURB
	IF (LAST) WRITE (6,58) HLOSS(1,NH),HLOSS(2,NH)	HPTURB
58	FORMAT ('0 TOTAL HARNESS ENERGY LOSS',7X,F12.3,68X,F12.3)	HPTURB
59	ITER = ITER + 1	HPTURB
C		HPTURB
C	END OF DO 59 ITER=1,MAXITR LOOP	HPTURB
C		HPTURB
	IF (.NOT.LAST) GO TO 13	HPTURB
	IF (ITER.GT.MAXITR) WRITE (6,60) MAXITR,TSEC,DELMAX,SCALE	HPTURB
60	FORMAT ('0 HPTURB ITER =',I4,' AT TIME =',F8.3,	HPTURB
*	' MSEC. DELMAX =',F10.6,' SCALE =',F10.6)	HPTURB
	J1 = J2 + 1	HPTURB
	K0 = K1	HPTURB
	KNL0 = KNLN	CHGII I
61	CONTINUE	HPTURB
	IF (NPRT(28).LT.0) NPRT(28) = 0	HPTURB
	CALL ELTIME (2,39)	HPTURB
	RETURN	HPTURB
	END	HPTURB

	SUBROUTINE HSETC (NPTS,KHO,KNL0,NTP,IJ)	HSETC
C		REV III.2 08/08/84REVIII
	IMPLICIT REAL*8 (A-H,O-Z)	HSETC
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),	HSETC
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)	HSETC
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)	DIMENB
	COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100),	HSETC
*	XLONG(20),HTIME(2),IBAR(5,100),NL(2,100),	HSETC
*	NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5)	HSETC
C	THIS COMMON/TEMPVS/ IS SHARED BY HPTURB, HBPLAY, HBELT AND HSETC.	HSETC
	COMMON/TEMPVS/ B(3,3,3),S(3,3),T(3),R(3),V(3),T1(3),T2(3),	HSETC
*	E(3,3,50),EDOT(3,50),FCE(3,50),FR(3,50),ZR(3,50),	HSETC
*	TR(3,50),U(3,50),PTLOSS(2,50),BL(50),FB(50),FP(50),	HSETC
*	OLDBB(100),RHS(3,54),C(3,3,200),IJK(54,54)	HSETC
	DIMENSION KM(3),MK(2)	HSETC
	ONE = 1.0	HSETC
	KNL = KNL0	HSETC
	KH = KHO	HSETC
	K1 = KHO + NTP + 1	HSETC
	K2 = KHO + NTP + NPTS	HSETC
	DO 60 K=K1,K2	HSETC
C		HSETC
C	HERE K IS INDEX OF IJK AND RHS ARRAYS	HSETC
C	KH IS INDEX OF POINTS IN PLAY ON EACH HARNESS	HSETC
C	KNL IS INDEX OF ALL POINTS IN PLAY	HSETC
C	KI IS INDEX OF ALL POINTS	HSETC
C		HSETC
	KH = KH + 1	HSETC
	KNL = KNL + 1	HSETC
C		HSETC
C	ZERO C(K,K) , C(K,K-1) , C(K,K+1) & RHS(K); SET IJK(K,K) = IJ	HSETC
C		HSETC
	KM(1) = K+1	HSETC
	KM(2) = K-1	HSETC
	KM(3) = K	HSETC
	IF (K.EQ.K2) KM(1) = 0	HSETC
	IF (K.EQ.K1) KM(2) = 0	HSETC
	KK = IJ	HSETC
	DO 12 L=1,3	HSETC
	RHS(L,K) = 0.0	HSETC
	IF (KM(L).EQ.0) GO TO 12	HSETC
	KK = KK+1	HSETC
	DO 11 I=1,3	HSETC
	DO 11 J=1,3	HSETC
11	C(I,J,KK) = 0.0	HSETC
12	CONTINUE	HSETC
	IJ = IJ+1	HSETC
	IJK(K,K) = IJ	HSETC
C		HSETC
C	COMPUTE CNORM; IF ZERO, SET C(K,K) = I	HSETC

C	CNORM = 0.0	HSETC
	IF (K.NE.K2) CNORM = FB(KH)/BL(KH)	HSETC
	IF (K.NE.K1) CNORM = CNORM + FB(KH-1)/BL(KH-1)	HSETC
	KI = NL(1,KNL)	HSETC
	IF (IABS(IBAR(1,KI)).GT.100) GO TO 14	HSETC
C	IF (CNORM.NE.0.0) GO TO 14	BUTLER1
	KK = IJK(K,K)	HSETC
	DO 13 I=1,3	HSETC
13	C(I,I,KK) = ONE	HSETC
	IF (CNORM.EQ.0.0) GO TO 60	BUTLER1
14	KK = IBAR(3,KI)	HSETC
	NFD = NTAB(KK+1)	HSETC
	NFR = NTAB(KK+5)	HSETC
C		HSETC
C	SET UP B(3,3,3) AND S(3,3)	HSETC
C		HSETC
	MK(1) = KH	HSETC
	MK(2) = KH-1	HSETC
	IF (K.EQ.K2) MK(1) = 0	HSETC
	IF (K.EQ.K1) MK(2) = 0	HSETC
	DO 18 M=1,2	HSETC
	KK = MK(M)	HSETC
	IF (KK.NE.0 .AND. CNORM.NE.0.0) GO TO 16	HSETC
	DO 15 I=1,3	HSETC
	S(I,M) = 0.0	HSETC
	DO 15 J=1,3	HSETC
15	B(I,J,M) = 0.0	HSETC
	GO TO 18	HSETC
16	CALL DOT31 (E(1,1,KH),U(1,KK),T)	HSETC
	KIM = KNL + 1 - M	HSETC
	FB1 = FB(KK)/BL(KK)	HSETC
	FB2 = FP(KK)/BB(KIM) - FB1	HSETC
	FB3 = FP(KK)*BL(KK)/BB(KIM)**2	HSETC
	DO 17 I=1,3	HSETC
	SGN = ONE	HSETC
	IF (FR(I,KH).LT.0.0) SGN = -ONE	HSETC
	S(I,M) = SGN*(FB3*T(I))	HSETC
	DO 17 J=1,3	HSETC
17	B(I,J,M) = SGN*(FB1*E(J,I,KH) + FB2*T(I)*U(J,KK))	HSETC
18	CONTINUE	HSETC
	DO 19 I=1,3	HSETC
	S(I,3) = -(S(I,1) + S(I,2))	HSETC
	DO 19 J=1,3	HSETC
19	B(I,J,3) = -(B(I,J,1) + B(I,J,2))	HSETC
	IF (NFR.EQ.0) GO TO 20	HSETC
	R(1) = TAB(NFR+2)	HSETC
	R(2) = TAB(NFR+4)	HSETC
20	R(3) = 0.0	HSETC
	DO 50 M=1,3	HSETC



	RH = 0.0	HSETC
	IF (M.EQ.3) GO TO 31	HSETC
	IF (NFR.EQ.0) GO TO 48	HSETC
C		HSETC
C	CONSTRAINTS 1 AND 2	HSETC
C		HSETC
	SGN = -ONE	HSETC
	FR3 = DABS(FR(M,KH)) - R(M)*DABS(FR(3,KH))	HSETC
	IF (IBAR(1,KI).GT.0) RH = FR3	HSETC
	IF (FR3.LE.0.0) GO TO 48	HSETC
	GO TO 40	HSETC
C		HSETC
C	CONSTRAINT NO. 3	HSETC
C		HSETC
31	IF (NFD.EQ.0) GO TO 48	HSETC
	IF (IBAR(1,KI).LT.0) GO TO 40	HSETC
	SGN = ONE	HSETC
	RMAG2 = TR(1,KH)**2 + TR(2,KH)**2 + TR(3,KH)**2	HSETC
	RMAG = DSQRT(RMAG2)	HSETC
	RER2 = TR(1,KH)*E(1,3,KH) + TR(2,KH)*E(2,3,KH) + TR(3,KH)*E(3,3,KH)	HSETC
	RER2 = EDOT(3,KH)*RER2	HSETC
	RER = DSQRT(RER2)	HSETC
	PEN = RMAG/RER - RMAG	HSETC
	RRDOT = BAR(4,KI)*BAR(13,KI)	HSETC
	* + BAR(5,KI)*BAR(14,KI)	HSETC
	* + BAR(6,KI)*BAR(15,KI)	HSETC
	KS = IABS(IBAR(1,KI))	HSETC
	IF (KS.GT.100) KS = MOD(KS,100)	HSETC
	CALL DOT31 (D(1,1,KS),BAR(13,KI),T)	HSETC
	ERDOT = E(1,3,KH)*T(1) + E(2,3,KH)*T(2) + E(3,3,KH)*T(3)	HSETC
	C1 = PEN/RMAG2	HSETC
	C2 = RMAG*EDOT(3,KH)/(RER*RER2)	HSETC
	PDOT = C1*RRDOT - C2*ERDOT	HSETC
	NFDZ = IBAR(3,KI)	CHGII
	CALL FRCDFL (PEN,PDOT,NFDZ,0,FDP,ELOSS)	CHGII
	CALL FRCDFL (PEN,PDOT,NFDZ,1,FD,ELOSS)	CHGII
	RH = FD + FR(3,KH)	HSETC
	PTLOSS(2,KH) = ELOSS	HSETC
	C1 = FDP*C1	HSETC
	C2 = FDP*C2	HSETC
	SGNB3 = -DSIGN(ONE,FR(3,KH))	HSETC
	DO 32 J=1,3	HSETC
32	B(3,J,3) = SGNB3*B(3,J,3) - C1*TR(J,KH) + C2*E(J,3,KH)	HSETC
40	DO 47 LL=1,3	HSETC
	L = 4 - LL	HSETC
	IF (KM(L).EQ.0) GO TO 47	HSETC
	DO 42 J=1,3	HSETC
42	V(J) = R(M)*B(3,J,L) + SGN*B(M,J,L)	HSETC
	KL = KM(L)	HSETC
	KML = KNL + KL - K	HSETC

KIL = NL(1,KML)	HSETC
IF (IBAR(5,KIL).NE.0) GO TO 43	HSETC
KHL = KH + KL - K	HSETC
CALL DOT31 (E(1,1,KHL),V,T)	HSETC
T(2) = R(M)*S(3,L) + SGN*S(M,L)	HSETC
CALL MAT31 (E(1,1,KHL),T,V)	HSETC
43 IF (LL.NE.1) GO TO 44	HSETC
VE = V(1)*E(1,M,KH) + V(2)*E(2,M,KH) + V(3)*E(3,M,KH)	HSETC
EV = 1.0	HSETC
IF (IABS(IBAR(1,KI)).LT.100)	HSETC
* EV = DSIGN(ONE,VE)/DSQRT(V(1)**2+V(2)**2+V(3)**2)	HSETC
RH = EV*RH	HSETC
44 IF (IJK(K,KL).NE.0) GO TO 45	HSETC
IJ = IJ+1	HSETC
IJK(K,KL) = IJ	HSETC
45 KK = IJK(K,KL)	HSETC
DO 46 J=1,3	HSETC
VEV = EV*V(J)	HSETC
DO 46 I=1,3	HSETC
46 C(I,J,KK) = C(I,J,KK) + E(I,M,KH)*VEV	HSETC
47 CONTINUE	HSETC
DO 41 I=1,3	HSETC
41 RHS(I,K) = RHS(I,K) + RH*E(I,M,KH)	HSETC
GO TO 50	HSETC
48 IF (IBAR(1,KI).LE.0) GO TO 50	HSETC
KK = IJK(K,K)	HSETC
DO 49 I=1,3	HSETC
DO 49 J=1,3	HSETC
49 C(I,J,KK) = C(I,J,KK) + E(I,M,KH)*E(J,M,KH)	HSETC
50 CONTINUE	HSETC
60 CONTINUE	HSETC
RETURN	HSETC
END	HSETC

	SUBROUTINE HYABF(B,Z,A,F)		HYABF
C		REV IV	02/07/87HYABF
	IMPLICIT REAL*8(A-H,O-Z)		HYABF
C			HYABF
C	CALCULATES A, AZ, Z.AZ: OLD FORM MUST BE DIAGONAL		HYABF
C			HYABF
	DIMENSION B(24),Z(1),A(3,3)		HYABF
	P2 = 0.0		HYABF
	IF(B(1).LT.0.0)P2 = -B(1) - 2.0		HYABF
	F = 0.0		HYABF
	DO 30 I = 1,3		HYABF
	J = I		HYABF
	IF(B(1).LT.0.0)GO TO 10		HYABF
	A(I,1) = 1.0/B(I)**2		HYABF
	GO TO 15		HYABF
10	A(I,1) = B(I+16)		HYABF
	J = J + 1		HYABF
	A(I,1) = HYFCN(A(I,1),Z(I),B(J),P2)		HYABF
C	IF(P2.GT.0.0)A(I,1) = A(I,1)*DABS(Z(I)/B(J))**P2		HYABF
15	DO 20 J = 2,3		HYABF
20	A(I,J) = A(I,J-1)*Z(I)		HYABF
30	F = F + A(I,3)		HYABF
	RETURN		HYABF
	END		HYABF

	SUBROUTINE HYBND(M,Z,IV,U,C,X)		HYBND
C		REV IV	02/07/87HYBND
	IMPLICIT REAL*8(A-H,O-Z)		HYBND
C			HYBND
C	SEARCHES FOR POINT NEAREST CORNER - DIRECTION C*U		HYBND
C			HYBND
	DIMENSION Z(3,12),IV(12),U(3),X(3)		HYBND
	DO 20 I = 1,M,2		HYBND
	J = IV(I)		HYBND
	ATST = C*(U(1)*Z(1,J) + U(2)*Z(2,J) + U(3)*Z(3,J))		HYBND
	IF(I.EQ.1)GO TO 10		HYBND
	TEST = AMAX - ATST		HYBND
	COMP = DMAX1(DABS(AMAX),DABS(ATST))		HYBND
C	PRECISION TEST - TRY >1000??		HYBND
	IF(1000.*DABS(TEST).LT.COMP)TEST = 0.0		HYBND
	IF(TEST)10,15,20		HYBND
C	IF(AMAX-ATST)10,15,20		HYBND
10	AMAX = ATST		HYBND
	J1 = J		HYBND
15	J2 = J		HYBND
20	CONTINUE		HYBND
	DO 25 I = 1,3		HYBND
25	X(I) = 0.5*(Z(I,J1) + Z(I,J2))		HYBND
	RETURN		HYBND
	END		HYBND



IF(M.EQ.N+4)GO TO 35	HYBOX
C DELETE 0 LENGTH SIDE	HYBOX
IF((Z(I,M-1).EQ.Z(I,M)).AND.(Z(J,M-1).EQ.Z(J,M)))GO TO 35	HYBOX
N = M	HYBOX
35 P1 = P1 - T2(K)	HYBOX
40 CK = -CK	HYBOX
J = K -	HYBOX
45 K = I	HYBOX
C	HYBOX
IF(N.LT.6)GO TO 65	HYBOX
IV(1) = 1	HYBOX
IV(2) = 2	HYBOX
M = 2	HYBOX
DO 60 J = 3,N,2	HYBOX
D = DABS(Z(1,M)) + DABS(Z(2,M)) + DABS(Z(3,M))	HYBOX
DO 55 L = 3,N	HYBOX
DO 50 LL = 2,J	HYBOX
IF(IV(LL-1).EQ.L) GO TO 55	HYBOX
50 CONTINUE	HYBOX
F = DABS(Z(1,M)-Z(1,L))+DABS(Z(2,M)-Z(2,L))+DABS(Z(3,M)-Z(3,L))	HYBOX
IF(F.GT.D)GO TO 55	HYBOX
D = F	HYBOX
K = L	HYBOX
55 CONTINUE	HYBOX
M = K + 1	HYBOX
IF(MOD(K,2).EQ.0)M = K - 1	HYBOX
IV(J) = K	HYBOX
IV(J+1) = M	HYBOX
60 CONTINUE	HYBOX
65 RETURN	HYBOX
END	HYBOX

	SUBROUTINE HYDAD(D,A,DAD)		HYDAD
C		REV IV	02/07/87HYDAD
	IMPLICIT REAL*8(A-H,O-Z)		HYDAD
	COMPUTES D'A(*,1)D		HYDAD
	DIMENSION D(3,3),A(3),DAD(3,3)		HYDAD
	DO 10 I = 1,3		HYDAD
	DO 10 J = 1,3		HYDAD
	DAD(I,J) = 0.0		HYDAD
	DO 10 K = 1,3		HYDAD
	10 DAD(I,J) = DAD(I,J) + D(K,I)*A(K)*D(K,J)		HYDAD
	RETURN		HYDAD
	END		HYDAD

SUBROUTINE HYEST(BM,BN,TAB)		HYEST
C	REV IV	07/23/87HYEST
C LINEAR PROGRAM		HYEST
IMPLICIT REAL*8(A-H,O-Z)		HYEST
DIMENSION BM(24),BN(24),TAB(8)		HYEST
COMMON/TEMPVS/D12(3,3),A(3,3),B(3,3),XMN(3),RLN(3),XMM(3),		HYEST
* T(3),R(3),C(3,3),V(7)		HYEST
C R GOES FROM M TO N D12 = DM*DN'		HYEST
C R = 0 CANNOT BE SOLVED WITH THIS METHOD		HYEST
BE = 1.0		HYEST
RR = R(1)**2 + R(2)**2 + R(3)**2		HYEST
IF(RR.EQ.0.0)GO TO 30		HYEST
C R.R = 0 INVALID		HYEST
M = 1		HYEST
N = 1		HYEST
IF(BM(1).LT.0.0)M = 2		HYEST
IF(BN(1).LT.0.0)N = 2		HYEST
PM = 2.		HYEST
PN = 2.		HYEST
IF(M.EQ.2)PM = -BM(1)		HYEST
IF(N.EQ.2)PN = -BN(1)		HYEST
DO 10 I = 1,3		HYEST
T(I) = R(I)		HYEST
DO 10 J = 1,3		HYEST
10 B(I,J) = D12(I,J)		HYEST
IF(N.EQ.2)CALL DOTT33(D12,BN(8),B)		HYEST
DO 15 I = 1,3		HYEST
DO 15 J = 1,3		HYEST
15 C(I,J) = B(I,J)		HYEST
IF(M.EQ.2)CALL MAT33(BM(8),B,C)		HYEST
C C WILL TRANSFORM FROM NN TO MM		HYEST
IF(M.EQ.2)CALL MAT31(BM(8),R,T)		HYEST
CALL HYLPX(BM(M),BN(N))		HYEST
BE = V(7)		HYEST
IF(V(7).LE.1.0)GO TO 30		HYEST
CALL HYABF(BM(1),V(1),A,F1)		HYEST
CALL HYABF(BN(1),V(4),B,F2)		HYEST
C ESTIMATE ALPHA		HYEST
AA = A(1,2)**2 + A(2,2)**2 + A(3,2)**2		HYEST
BB = B(1,2)**2 + B(2,2)**2 + B(3,2)**2		HYEST
ALP = DSQRT(AA/BB)		HYEST
RA = F1**(1.0/PM)		HYEST
RB = F2**(1.0/PN)		HYEST
ALP = ALP*RA*F2/(RB*F1)		HYEST
C SCALE POINTS TO ELLIPSOIDS		HYEST
DO 20 I = 1,3		HYEST
V(I) = V(I)/RA		HYEST
20 V(I+3) = V(I+3)/RB		HYEST
C ESTIMATE BETA		HYEST
CALL MAT31(C,V(4),T)		HYEST



```
BE = (V(1)-T(1))**2 + (V(2)-T(2))**2 + (V(3) - T(3))**2 HVEST
BE = DSQRT(BE/RR) HVEST
C STORE VALUES IN TAB ARRAY FOR CONTACT HVEST
TAB(1) = ALP HVEST
DO 25 I = 1,6 HVEST
25 TAB(I+2) = V(I) HVEST
30 TAB(2) = BE HVEST
RETURN HVEST
END HVEST
```

	DOUBLE PRECISION FUNCTION HYFCN(C,Z,A,P)		HYFCN
C		REV IV	02/07/87HYFCN
	IMPLICIT REAL*8(A-H,O-Z)		HYFCN
	HYFCN = C		HYFCN
	IF(P.EQ.0.0)GO TO 10		HYFCN
	HYFCN = 0.0		HYFCN
	IF(Z.EQ.0.0)GO TO 10		HYFCN
	Q = P*(DLOG(DABS(Z)) - DLOG(A))		HYFCN
	IF(Q.GT.-88.5) HYFCN = C*DEXP(Q)		HYFCN
	10 RETURN		HYFCN
	END		HYFCN

	SUBROUTINE HYLIM(A,U,B,V,C,W,Z,BD)	HYLIM
C	IMPLICIT REAL*8(A-H,O-Z)	HYLIM
	REV IV 12/11/87HYFIX	
C	GIVEN Z, FIND A,B,Z: ZEZ = 1, ZEV = 0, TZ = TP	HYLIM
	DIMENSION BD(24)	HYLIM
	DIMENSION U(3),V(3),W(3),EI(3),EJ(3),T(3),TV(3)	HYLIM
	DIMENSION Z(3),E(3),EV(3),Q(3),S(3),EZ(3)	HYLIM
	DIMENSION SM(3,3)	HYLIM
	LOGICAL PASS,USEV	HYLIM
	PASS = .FALSE.	HYLIM
	ITER = 100	HYLIM
	PP = -1./BD(1)	HYLIM
	POW = -BD(1) - 2.0	HYLIM
	P1 = -BD(1) - 1.0	HYLIM
	P01 = 1.0/P1	HYLIM
	P2 = -BD(1)/P1	HYLIM
	DO 10 I = 1,3	HYLIM
	TV(I) = 0.0	HYLIM
10	IF(V(I).NE.0.0)TV(I) = HYFCN(1.0/V(I),V(I),BD(I+1),P2)	HYFIX
C	GET RECIPROCAL SET	HYLIM
	CALL CROSS(V,W,EI)	HYLIM
	CALL CROSS(W,U,EJ)	HYLIM
	CALL CROSS(U,V,T)	HYLIM
	EIU = EI(1)*U(1) + EI(2)*U(2) + EI(3)*U(3)	HYLIM
	G = C*EIU	HYLIM
C		HYLIM
	DO 55 IT = 1,ITER	HYLIM
	EVM = 0.0	HYLIM
	EVZ = 0.0	HYLIM
	ZEZ = 0.0	HYLIM
	USEV = .FALSE.	HYLIM
	DO 15 I = 1,3	HYLIM
	E(I) = HYFCN(BD(I+16),Z(I),BD(I+1),POW)	HYLIM
	EV(I) = E(I)*V(I)	HYLIM
	IF(EV(I).EQ.0.0)USEV = .TRUE.	HYLIM
	IF(DABS(EV(I)).GT.EVM)EVM = DABS(EV(I))	HYLIM
	EZ(I) = E(I)*Z(I)	HYLIM
	IF(DABS(EZ(I)).GT.EVZ)EVZ = DABS(EZ(I))	HYLIM
15	ZEZ = ZEZ + Z(I)*EZ(I)	HYLIM
	RHO = ZEZ**PP	HYLIM
	DO 20 I = 1,3	HYLIM
20	Z(I) = Z(I)/RHO	HYLIM
	IF(PASS)GO TO 60	HYLIM
	RHOZ = ZEZ/RHO	HYLIM
	RHOV = EVM*RHOZ/RHO	HYLIM
	RHOZ = EVZ*RHOZ	HYLIM
	IF(.NOT.USEV)GO TO 30	HYLIM
	RHOV = 1.0	HYLIM
	DO 25 I = 1,3	HYLIM
25	EV(I) = TV(I)	HYLIM

C WHAT IF NO TV IS 0 AND EV ARE ALL 0 ?	HYLIM
30 DO 35 I = 1,3	HYLIM
EV(I) = EV(I)/RHOV	HYLIM
35 EZ(I) = EZ(I)/RHOZ	HYLIM
C SET UP MATRIX	HYLIM
CALL CROSS(EV, T, SM(1,1))	HYLIM
CALL CROSS(T, EZ, SM(1,2))	HYLIM
CALL CROSS(EZ, EV, SM(1,3))	HYLIM
TZV = T(1)*SM(1,3) + T(2)*SM(2,3) + T(3)*SM(3,3)	HYLIM
TZ = T(1)*Z(1) + T(2)*Z(2) + T(3)*Z(3)	HYLIM
ZEV = Z(1)*EV(1) + Z(2)*EV(2) + Z(3)*EV(3)	HYLIM
IF(TZV.EQ.0.0)STOP 39	HYLIM
ZEV = ZEV/TZV	HYLIM
Q(1) = 0.0	HYLIM
Q(2) = -ZEV	HYLIM
IF(.NOT.USEV)Q(2) = Q(2)/P1	HYLIM
Q(3) = (G - TZ)/TZV	HYLIM
CALL MAT31(SM,Q,S)	HYLIM
SS = 0.0	HYLIM
ZZ = 0.0	HYLIM
DO 50 I = 1,3	HYLIM
SS = SS + DABS(S(I))	HYLIM
IF(DABS(Z(I)).LT.0.1*BD(I+1))GO TO 45	HYLIM
IF(DABS(S(I)).GT.DABS(Z(I)))S(I) = DSIGN(0.5*Z(I),S(I))	HYLIM
45 Z(I) = Z(I) + S(I)	HYLIM
IF(DABS(Z(I)).GT.BD(I+1))Z(I) = DSIGN(BD(I+1),Z(I))	HYLIM
50 ZZ = ZZ + DABS(Z(I))	HYLIM
IF(SS.LT.1.0E-10*ZZ)PASS = .TRUE.	HYLIM
55 CONTINUE	HYLIM
C	HYLIM
60 A = (EI(1)*Z(1) + EI(2)*Z(2) + EI(3)*Z(3))/EIU	HYLIM
B = (EJ(1)*Z(1) + EJ(2)*Z(2) + EJ(3)*Z(3))/EIU	HYLIM
RETURN	HYLIM
END	HYLIM

	SUBROUTINE HYLPR(J1,J2,ID,C,S,E,T)		HYLPR
C	IMPLICIT REAL*8(A-H,O-Z)	REV IV	02/07/87HYLPR
	DIMENSION ID(16),C(16),S(9,8),E(9),T(7)		HYLPR
	C LINEAR PROGRAM ROUTINE USING SIMPLEX METHOD		HYLPR
	C J1 = J2 FORCED PIVOT ON COLUMN J1		HYLPR
	CALCULATE COSTS		HYLPR
	J = J1		HYLPR
	IF(J.EQ.J2)GO TO 30		HYLPR
10	DO 20 L = 1,7		HYLPR
	T(L) = -C(L)		HYLPR
	IF(C(L).EQ.10.)GO TO 20		HYLPR
	DO 15 I = 1,9		HYLPR
15	T(L) = T(L) + S(I,L)*C(I+7)		HYLPR
20	CONTINUE		HYLPR
	IF(J1.EQ.J2)GO TO 65		HYLPR
C	FIND PIVOT COLUMN		HYLPR
	DO 25 L = 1,7		HYLPR
	J = L		HYLPR
	IF(T(L).GT.0.0)GO TO 30		HYLPR
25	CONTINUE		HYLPR
	GO TO 65		HYLPR
C	FIND PIVOT ROW		HYLPR
30	K = 0		HYLPR
	DO 40 I = 1,9		HYLPR
C	SAVE PIVOT COLUMN		HYLPR
	E(I) = S(I,J)		HYLPR
	IF(S(I,J).LE.0.0)GO TO 40		HYLPR
	IF(K.EQ.0)GO TO 35		HYLPR
	IF(S(I,8).GE.Z*S(I,J))GO TO 40		HYLPR
35	K = I		HYLPR
	Z = S(I,8)/S(I,J)		HYLPR
40	CONTINUE		HYLPR
C	REPLACE COLUMNS		HYLPR
	IF(K.EQ.0)GO TO 65		HYLPR
	M = ID(J)		HYLPR
	ID(J) = ID(K+7)		HYLPR
	ID(K+7) = M		HYLPR
	Q = C(J)		HYLPR
	C(J) = C(K+7)		HYLPR
	C(K+7) = Q		HYLPR
	P = S(K,J)		HYLPR
	DO 45 I = 1,9		HYLPR
45	S(I,J) = 0.0		HYLPR
	S(K,J) = 1.0		HYLPR
	DO 50 L = 1,8		HYLPR
50	S(K,L) = S(K,L)/P		HYLPR
	E(K) = 1.0		HYLPR
	DO 60 I = 1,9		HYLPR
	IF(I.EQ.K)GO TO 60		HYLPR

```
IF(E(I).EQ.0.0)GO TO 60
DO 55 M = 1,8
55 S(I,M) = S(I,M) - E(I)*S(K,M)
60 CONTINUE
GO TO 10
65 RETURN
END
```

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HYLPR
HYLPR
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SUBROUTINE HYLPX(BM,BN)
C
C LINEAR PROGRAM EXEC
  IMPLICIT REAL*8(A-H,O-Z)
  DIMENSION BM(23),BN(23)
  COMMON/TEMPVS/D12(3,3),P(3,3),Q(3,3),XMN(3),RLN(3),XMM(3),
  *             R(3),H(3),D(3,3),V(7),S(9,8),C(16),A(7),B(3),
  *             E(9),T(7),ID(16),IP(2)
  CALL MAT31(D,BN,B)
  DO 10 I = 1,3
  B(I) = BM(I) - B(I) + R(I)
  A(I) = BM(I)
10 A(I+3) = BN(I)
  A(7) = -1.0
  DO 15 I = 1,16
  C(I) = 0.0
15 ID(I) = I
  C(7) = -1.0
  DO 20 I = 1,9
  DO 20 J = 1,8
20 S(I,J) = 0.0
C
COSTS 0 0 -1
C      I -D -R A - DB + R (>0) INF COST
C      I 0 0 2A
C      0 I 0 2B
C
  DO 25 I = 1,6
25 S(I+3,I) = 1.0
  DO 30 I = 1,3
  C(I+7) = 10.
  S(I,7) = -R(I)
  S(I,I) = 1.0
  S(I,8) = B(I)
  S(I+3,8) = 2.0*A(I)
  S(I+6,8) = 2.0*A(I+3)
  DO 30 J = 1,3
30 S(I,J+3) = -D(I,J)
CHECK SIGN OF RHS
  DO 40 I = 1,3
  IF(B(I).GE.0.0)GO TO 40
  DO 35 J = 1,8
35 S(I,J) = -S(I,J)
40 CONTINUE
  J1 = 1
  J2 = 7
C
  CALL HYLPR(J1,J2,ID,C,S,E,T)
  NK = 0
  NZ = 0

```

COUNT ZEROES IN SOLUTION	
DO 45 I = 1,7	HYLPX
C TEST SHOULD PROBABLY BE AN EPSILON TEST, DABS(T(I)).GT.EPS	HYLPX
IF((T(I).NE.0.0).OR.(C(I).EQ.10.))GO TO 45	HYLPX
NZ = NZ + 1	HYLPX
IP(NZ) = I	HYLPX
45 CONTINUE	HYLPX
C SET PASS COUNT	HYLPX
NP = 1	HYLPX
IF(NZ.GT.0)NP = 2**NZ	HYLPX
C	HYLPX
DO 55 M = 1,NP	HYLPX
NM = NK	HYLPX
NK = NK + 1	HYLPX
DO 50 I = 1,16	HYLPX
K = ID(I)	HYLPX
IF(K.GT.7)GO TO 50	HYLPX
W = 0.0	HYLPX
IF(I.GT.7)W = S(I-7,8)	HYLPX
V(K) = (W - A(K) + NM*V(K))/NK	HYLPX
50 CONTINUE	HYLPX
C LOOK FOR ALL SOLUTIONS	HYLPX
IF(M.EQ.NP)GO TO 55	HYLPX
J1 = IP(1)	HYLPX
IP(1) = IP(2)	HYLPX
IP(2) = J1	HYLPX
IF(T(J1).NE.0.0)GO TO 55	HYLPX
J2 = J1	HYLPX
CALL HYLPR(J1,J2,ID,C,S,E,T)	HYLPX
55 CONTINUE	HYLPX
RETURN	HYLPX
END	HYLPX







```
TAB(I+2) = ZM(I)
55 TAB(I+5) = VN(I)
RETURN
END
```

```
HYNTR
HYNTR
HYNTR
HYNTR
```

	DOUBLE PRECISION FUNCTION HYPEN(BD,E,V)		HYPEN
C		REV IV	02/07/87HYPEN
C	POINT OF MAXIMUM PENETRATION		HYPEN
C	SOLVES FOR VALUE OF ALP USED BY PLELP		HYPEN
C	POWERS OF HYPERELLIPSOID MAY BE DIFFERENT		HYPEN
	IMPLICIT REAL*8(A-H,O-Z)		HYPEN
	DIMENSION BD(24),E(3),V(3)		HYPEN
	FX(A) = A**E(1)*V(1)+A**E(2)*V(2)+A**E(3)*V(3)-1.0		HYPEN
	L = 1		HYPEN
	VM = V(1)		HYPEN
	DO 10 I = 2,3		HYPEN
	IF (V(I).LE.VM) GO TO 10		HYPEN
	L = I		HYPEN
	VM = V(I)		HYPEN
10	CONTINUE		HYPEN
	A = V(1) + V(2) + V(3)		HYPEN
	A = 1.0/A**(1.0/E(L))		HYPEN
	DEL = A/2.0		HYPEN
	AP = 0.0		HYPEN
12	F = FX(A)		HYPEN
	IF (DABS(F).LT.1.D-08) GO TO 40		HYPEN
	IF (F) 16,40,14		HYPEN
14	IF (A-DEL.LE.0.0) DEL = A/2.0		HYPEN
	AP = A		HYPEN
	FP = F		HYPEN
	A = A - DEL		HYPEN
	GO TO 12		HYPEN
16	IF (AP.NE.0.0) GO TO 18		HYPEN
	A = A + DEL		HYPEN
	GO TO 12		HYPEN
18	AM = A		HYPEN
	FM = F		HYPEN
20	IF (FP.EQ.FM) GO TO 40		HYPEN
	DEL = -FM*(AP - AM)/(FP - FM)		HYPEN
	AN = AM + DEL		HYPEN
	IF (AN.EQ.A) GO TO 40		HYPEN
	A = AN		HYPEN
	F = FX(A)		HYPEN
	IF (DABS(F).LT.1.D-08) GO TO 40		HYPEN
	IF (F) 18,40,22		HYPEN
22	FP = F		HYPEN
	AP = A		HYPEN
	GO TO 20		HYPEN
40	HYPEN = A		HYPEN
	RETURN		HYPEN
	END		HYPEN

	SUBROUTINE HYREA (L,H,AREA,AB,BB)		HYFIX
C		REV IV	12/11/87HYFIX
	IMPLICIT REAL*8(A-H,O-Z)		HYREA
	DIMENSION H(2,2,5)		HYFIX
	AREA = 0.0		HYREA
	AB = 0.0		HYREA
	BB = 0.0		HYREA
	IF (L.LT.2) GO TO 20		HYFIX
	DO 15 I = 1,L		HYFIX
	AR = H(1,1,I)*H(2,2,I) - H(1,2,I)*H(2,1,I)		HYFIX
	IF (AR.EQ.0.0) GO TO 5		HYFIX
	AB = AB + AR*(H(1,1,I) + H(1,2,I))		HYFIX
	BB = BB + AR*(H(2,1,I) + H(2,2,I))		HYFIX
	AREA = AREA + AR		HYREA
	5 AR = H(1,2,I)*H(2,1,I+1) - H(1,1,I+1)*H(2,2,I)		HYFIX
	IF (AR.EQ.0.0) GO TO 15		HYFIX
	AB = AB + AR*(H(1,1,I+1) + H(1,2,I))		HYFIX
	BB = BB + AR*(H(2,1,I+1) + H(2,2,I))		HYFIX
	AREA = AREA + AR		HYREA
	15 CONTINUE		HYFIX
	IF (AREA.LE.0.0) GO TO 20		HYFIX
	AREA = 3.0*AREA		HYREA
	AB = AB/AREA		HYREA
	BB = BB/AREA		HYREA
C	AREA = AREA/6.0		HYREA
	20 RETURN		HYREA
	END		HYREA

	SUBROUTINE HYSOL(A,N,ND)		HYSOL
C	IMPLICIT REAL*8(A-H,O-Z)	REV IV	02/01/88MISDOT
	DIMENSION A(ND,6)		HYSOL
C	ASSUMES PIVOT ON DIAGONAL , BYPASS 0'S		MISDOT
	N1 = N + 1		HYSOL
	DO 20 L = 1,N		HYSOL
	IF(A(L,L).EQ.0.0)GO TO 20		HYSOL
	L1 = L + 1		HYSOL
	DO 10 J = L1,N1		HYSOL
10	A(L,J) = A(L,J)/A(L,L)		HYSOL
	IF(L.EQ.N)GO TO 20		HYSOL
	DO 21 I = L1,N		HYSOL
	IF(A(I,L).EQ.0.0)GO TO 21		HYSOL
	DO 15 J = L1,N1		HYSOL
15	A(I,J) = A(I,J) - A(I,L)*A(L,J)		HYSOL
21	CONTINUE		HYSOL
20	CONTINUE		HYSOL
	IF(N.EQ.1)GO TO 30		HYSOL
C	BACKUP		HYSOL
	DO 25 L = 2,N		HYSOL
	I = N1 - L		HYSOL
	L1 = I + 1		HYSOL
	DO 25 J = L1,N		HYSOL
25	A(I,N1) = A(I,N1) - A(I,J)*A(J,N1)		HYSOL
30	RETURN		HYSOL
	END		HYSOL

	SUBROUTINE HYVAL(A,U,R,BD,L)		HYVAL
C	IMPLICIT REAL*8(A-H,O-Z)	REV IV	12/11/87HYFIX
C	GIVEN A,U,R: COMPUTE A	Z = A*U + R	HYVAL
	DIMENSION BD(24),U(3),R(3),RM(2)		HYFIX
	ONE = 1.0		HYFIX
	POW = -BD(1) - 2.0		HYVAL
C	ARE THESE THE CORRECT TESTS??		HYFIX
	TEST = -BD(1)*0.000001		HYFIX
	TESD = 0.000001		HYFIX
	CALL HYVBX(U,R,BD(2),M,RM)		HYVAL
	A = 0.0		HYFIX
	IF (M.LT.L) GO TO 50		HYFIX
C	THIS SHOULD NEVER HAPPEN - IMPLIES R IS OUTSIDE BOX		HYFIX
	A = RM(L)		HYVAL
	IF (DABS(A).LT.TESD) GO TO 50		HYFIX
	DEL = A/5.0		HYFIX
	NSTEP = 0		HYFIX
C	ITERATION LOOP		HYFIX
10	DEL = DEL/4.0		HYFIX
	NSTEP = NSTEP + 1		HYFIX
	IF (NSTEP.LT.100) GO TO 12		HYFIX
	WRITE(6,11) M,A,DEL,F1,F2,L,RM(1),RM(2),U,R,BD		HYFIX
11	FORMAT(' HYV ',I4,4F11.6,I3,2F11.6/4X,3F11.6/4X,3F11.6/ * 4(2X,7F10.4/))		HYFIX
	STOP 102		HYFIX
12	F2 = HYVFN(A,U,R,BD,POW)		HYFIX
	IF (DABS(F2).LT.TEST) GO TO 50		HYFIX
	IF (F2) 20,50,30		HYFIX
15	F2 = HYVFN(A,U,R,BD,POW)		HYFIX
	NSTEP = NSTEP + 1		HYFIX
	IF (NSTEP.LT.100) GO TO 17		HYFIX
	WRITE(6,11) M,A,DEL,F1,F2,L,RM(1),RM(2),U,R,BD		HYFIX
	STOP 103		HYFIX
17	IF (DABS(F2).LT.TEST) GO TO 50		HYFIX
	IF (F2) 20,50,35		HYFIX
20	IF (DSIGN(ONE,A).EQ.DSIGN(ONE,A+DEL)) GO TO 22		HYFIX
	A = A/2.0		HYFIX
	DL = -A		HYFIX
	GO TO 23		HYFIX
22	DL = DEL		HYFIX
	A = A + DEL		HYFIX
23	F1 = F2		HYFIX
	GO TO 15		HYFIX
25	F2 = HYVFN(A,U,R,BD,POW)		HYFIX
	NSTEP = NSTEP + 1		HYFIX
	IF (NSTEP.LT.100) GO TO 27		HYFIX
	WRITE(6,11) M,A,DEL,F1,F2,L,RM(1),RM(2),U,R,BD		HYFIX
	STOP 104		HYFIX
27	IF (DABS(F2).LT.TEST) GO TO 50		HYFIX

IF (F2) 35,50,30	HYFIX
30 IF (DSIGN(ONE,A).EQ.DSIGN(ONE,A-DEL)) GO TO 32	HYFIX
A = A/2.0	HYFIX
DL = -A	HYFIX
GO TO 33	HYFIX
32 DL = -DEL	HYFIX
A = A - DEL	HYFIX
33 F1 = F2	HYFIX
GO TO 25	HYFIX
35 IF (F1.EQ.F2) GO TO 50	HYFIX
A = A + F2*DL/(F1 - F2)	HYFIX
IF (DABS(DEL).GT.TESD) GO TO 10	HYFIX
C	HYVAL
50 RETURN	HYVAL
END	HYVAL



	SUBROUTINE HYVBX(Q,S,B,M,RM)		HYVBX
C		REV IV 02/07/87	HYVBX
	IMPLICIT REAL*8(A-H,O-Z)		HYVBX
	DIMENSION Q(3),S(3),B(3),RM(2)		HYVBX
C	FINDS LIMITS OF BOX IN DIRECTION Q, Z = R*Q + S		HYVBX
	LOGICAL VAL		HYVBX
	M = 0		HYVBX
	C = -1.0		HYVBX
	DO 30 I = 1,3		HYVBX
	IF(Q(I).EQ.0.0)GO TO 30		HYVBX
	DO 25 K = 1,2		HYVBX
	VAL = .TRUE.		HYVBX
	D = C*B(I) - S(I)		HYVBX
	DO 10 J = 1,3		HYVBX
	IF(J.EQ.I)GO TO 10		HYVBX
	IF(DABS(D*Q(J) + S(J)*Q(I)).GT.DABS(B(J)*Q(I)))VAL = .FALSE.		HYVBX
C	IF(DABS(R*Q(J) + S(J)).GT.B(J))VAL = .FALSE.		HYVBX
10	CONTINUE		HYVBX
	IF(.NOT.VAL)GO TO 25		HYVBX
	R = D/Q(I)		HYVBX
	IF(M.EQ.0)GO TO 20		HYVBX
	DO 15 L = 1,M		HYVBX
	IF(R.EQ.RM(L)) GO TO 25		HYVBX
15	CONTINUE		HYVBX
20	M = M + 1		HYVBX
	RM(M) = R		HYVBX
25	C = -C		HYVBX
30	CONTINUE		HYVBX
	IF(M.EQ.0)GO TO 35		HYVBX
	IF(RM(1).LT.RM(2))GO TO 35		HYVBX
	R = RM(1)		HYVBX
	RM(1) = RM(2)		HYVBX
	RM(2) = R		HYVBX
35	RETURN		HYVBX
	END		HYVBX

	DOUBLE PRECISION FUNCTION HYVFN(A,U,R,B,P)		HYVFN
C		REV IV	12/11/87HYVFN
	IMPLICIT REAL*8(A-H,O-Z)		HYVFN
	DIMENSION U(3),R(3),B(24)		HYVFN
	F = -1.0		HYVFN
	DO 10 I = 1,3		HYVFN
	Z = A*U(I) + R(I)		HYVFN
	C = B(I+16)		HYVFN
	IF (P.GT.0.0) C = HYFCN(C,Z,B(I+1),P)		HYVFN
10	F = F + C*Z**2		HYVFN
	HYVFN = F		HYVFN
	RETURN		HYVFN
	END		HYVFN



DO 19 I=1,3	IMPLS2
19 V4(I,K) = 0.0	IMPLS2
18 DO 16 I=1,3	IMPLS2
U2(I,M) = RPHI(I,M)*D(I,L,M)	IMPLS2
16 U2(I,N) = -RPHI(I,N)*D(I,L,N)	IMPLS2
CALL DAUX(L)	IMPLS2
DO 17 K=1,NGRND	IMPLS2
DO 17 I=1,3	IMPLS2
TLA(I,L,K) = SEGLA(I,K)	IMPLS2
17 TWA(I,L,K) = WMEGD(I,K)	IMPLS2
20 CONTINUE	IMPLS2
CALL DOT33(D(1,1,M),TWA(1,1,M),TM)	IMPLS2
CALL DOT33(D(1,1,N),TWA(1,1,N),TN)	IMPLS2
CALL DOT31(D(1,1,M),WMEG(1,M),SM)	IMPLS2
CALL DOT31(D(1,1,N),WMEG(1,N),SN)	IMPLS2
DO 22 I=1,3	IMPLS2
DO 21 K=1,3	IMPLS2
T(I,K) = TM(I,K) - TN(I,K)	IMPLS2
21 TT(I,K) = T(I,K)	IMPLS2
T(I,4) = SN(I) - SM(I)	IMPLS2
22 TT(I,4) = H(I)	IMPLS2
IF (MODE.GE.0) CALL DSMSOL(T,3,3)	IMPLS2
IF (MODE.GT.0) CALL DSMSOL(TT,3,3)	IMPLS2
IF (MODE) 24,29,25	IMPLS2
24 ST = 0.0	IMPLS2
STT = XDY(H,T,H)	IMPLS2
GO TO 26	IMPLS2
25 ST = 1.0	IMPLS2
STT = -(H(1)*TT(1,4) + H(2)*TT(2,4) + H(3)*TT(3,4))	IMPLS2
26 STT = (H(1)*T(1,4) + H(2)*T(2,4) + H(3)*T(3,4))/STT	IMPLS2
DO 27 I=1,3	IMPLS2
27 T(I,4) = ST*T(I,4) + STT*TT(I,4)	IMPLS2
29 DO 30 K=1,NGRND	IMPLS2
DO 30 I=1,3	IMPLS2
DO 30 L=1,3	IMPLS2
SEGLV(I,K) = SEGLV(I,K) + T(L,4)*TLA(I,L,K)	IMPLS2
30 WMEG(I,K) = WMEG(I,K) + T(L,4)*TWA(I,L,K)	IMPLS2
IF (NPRT(3).NE.0) CALL PRINT(6HIMPLS2)	IMPLS2
CALL ELTIME(2,28)	IMPLS2
RETURN	IMPLS2
END	IMPLS2



30	V3(I,J) = 0.0	IMPULS
31	DO 32 J=1,NGRND	IMPULS
	DO 32 I=1,3	IMPULS
	U1(I,J) = 0.0	IMPULS
32	U2(I,J) = 0.0	IMPULS
	IF (NJNT.LE.0) GO TO 21	IMPULS
	DO 33 J=1,NJNT	IMPULS
	DO 33 I=1,3	IMPULS
	V1(I,J) = 0.0	IMPULS
33	V2(I,J) = 0.0	IMPULS
21	IF (NFLX.EQ.0) GO TO 23	IMPULS
	DO 22 J=1,NFLX	IMPULS
	DO 22 I=1,3	IMPULS
22	V4(I,J) = 0.0	IMPULS
C		IMPULS
C	REPLACE CALLS TO CONTACT AND VISPR WITH SINGLE CALL	IMPULS
C	AT FIRST CONTACT IF NOT CONSTRAINT.	IMPULS
C		IMPULS
23	IF (I1.NE.1) GO TO 34	IMPULS
	NT = NTPL(I2,I3)	IMPULS
	M1 = MPL(1,I2,I3)	IMPULS
	M2 = MPL(2,I2,I3)	IMPULS
	M3 = MPL(3,I2,I3)	IMPULS
	CALL PLELP(M2,M3,M1,I3,NT)	IMPULS
	IF (NTAB(NT+1).LT.0) GO TO 37	IMPULS
	K1 = M2	IMPULS
	K2 = M1	IMPULS
	GO TO 39	IMPULS
34	IF (I1.NE.3) GO TO 35	IMPULS
	NT = NTSEG(I2,I3)	IMPULS
	M1 = MSEG(1,I2,I3)	IMPULS
	M2 = MSEG(2,I2,I3)	IMPULS
	M3 = MSEG(3,I2,I3)	IMPULS
	CALL SEGSEG(I3,M1,M2,M3,NT)	IMPULS
	IF (NTAB(NT+1).LT.0) GO TO 37	IMPULS
	K1 = I3	IMPULS
	K2 = M2	IMPULS
	GO TO 39	IMPULS
35	IF (I1.NE.4) WRITE (6,36) I1,I2,I3	IMPULS
36	FORMAT('0 IMPROPER ARGUMENTS TO SUBROUTINE IMPULS'/	IMPULS
	* ' ARGUMENTS = ', 3I6 /	IMPULS
	* ' PROGRAM TERMINATED' )	IMPULS
	IF (I1.NE.4) STOP 33	IMPULS
C		IMPULS
C	RECALL VISPR FOR JOINT STOP.	IMPULS
C		IMPULS
	IF (IABS(IPIN(I3)).NE.4) GO TO 25	IMPULS
	CALL EJOINT(I2,I3)	IMPULS
	GO TO 26	IMPULS
25	CALL VISPR(I2,I3)	IMPULS

26	K1 = IABS(JNT(I3))	IMPULS
	K2 = I3+1	IMPULS
	GO TO 39	IMPULS
C		IMPULS
C	SET UP SPECIAL U1,U2 FOR FIRST CONTACT OF CONSTRAINT.	IMPULS
C		IMPULS
37	KQ = -NTAB(NT+1)	IMPULS
	KQTEST = 1	IMPULS
	KQTYPE(KQ) = -IABS(KQTYPE(KQ))	IMPULS
	K1 = KQ1(KQ)	IMPULS
	K2 = KQ2(KQ)	IMPULS
	IF (K1.GT.NSEG) GO TO 38	IMPULS
	CALL MAT31(A13(1,1,2*KQ-1),QQ(1,KQ),U1(1,K1))	IMPULS
	CALL MAT31(A23(1,1,2*KQ-1),QQ(1,KQ),U2(1,K1))	IMPULS
38	IF (K2.GT.NSEG) GO TO 39	IMPULS
	CALL MAT31(A13(1,1,2*KQ),QQ(1,KQ),U1(1,K2))	IMPULS
	CALL MAT31(A23(1,1,2*KQ),QQ(1,KQ),U2(1,K2))	IMPULS
C		IMPULS
C	FINAL SETUP OF U1 AND U2	IMPULS
C		IMPULS
39	DO 40 J=1,NGRND	IMPULS
	DO 40 I=1,3	IMPULS
	U1(I,J) = U1(I,J)*RW(J)	IMPULS
40	U2(I,J) = U2(I,J)*RPHI(I,J)	IMPULS
	CALL DAUX(I1)	IMPULS
	IF (KQTEST.EQ.1) KQTYPE(KQ) = IABS(KQTYPE(KQ))	IMPULS
	IF (NPRT(10).NE.0) CALL PRINT(6HPREIMP)	IMPULS
	IF (I1.GT.3) GO TO 51	IMPULS
	IF (NPRT(10).NE.0) WRITE (6,42) R1I,R2I	IMPULS
42	FORMAT ('0'/(6G20.8))	IMPULS
	CALL CROSS(WMEG (1,K1),R1I(1),TEMP)	IMPULS
	CALL DOT31(D(1,1,K1),TEMP,DWR1(1))	IMPULS
	CALL CROSS(WMEG (1,K2),R2I(1),TEMP)	IMPULS
	CALL DOT31(D(1,1,K2),TEMP,DWR2(1))	IMPULS
	CALL CROSS(WMEGD(1,K1),R1I(1),TEMP)	IMPULS
	CALL DOT31(D(1,1,K1),TEMP,DWR3(1))	IMPULS
	CALL CROSS(WMEGD(1,K2),R2I(1),TEMP)	IMPULS
	CALL DOT31(D(1,1,K2),TEMP,DWR4(1))	IMPULS
	TVREL = 0.0	IMPULS
	TDV = 0.0	IMPULS
	DO 50 I=1,3	IMPULS
	VREL(I) = SEGLV(I,K1)+DWR1(I) - SEGLV(I,K2)-DWR2(I)	IMPULS
	DV (I) = SEGLA(I,K1)+DWR3(I) - SEGLA(I,K2)-DWR4(I)	IMPULS
	TVREL = TVREL + TTI(I)*VREL(I)	IMPULS
50	TDV = TDV + TTI(I)*DV (I)	IMPULS
	GO TO 53	IMPULS
51	CALL DOT31(D(1,1,K1),WMEG (1,K1),DWR1(1))	IMPULS
	CALL DOT31(D(1,1,K2),WMEG (1,K2),DWR2(1))	IMPULS
	CALL DOT31(D(1,1,K1),WMEGD(1,K1),DWR3(1))	IMPULS
	CALL DOT31(D(1,1,K2),WMEGD(1,K2),DWR4(1))	IMPULS

	TVREL = 0.0	IMPULS
	TDV = 0.0	IMPULS
	DO 52 I=1,3	IMPULS
	VREL(I) = DWR1(I) - DWR2(I)	IMPULS
	DV (I) = DWR3(I) - DWR4(I)	IMPULS
	TVREL = TVREL + TTI(I)*VREL(I)	IMPULS
52	TDV = TDV + TTI(I)*DV (I)	IMPULS
53	ALPHA = 0.0	IMPULS
C		IMPULS
C	NOTE: CREST IS SUPPLIED AS (1+E)/2 WHERE E IS THE CLASSICAL	IMPULS
C	COEFFICIENT OF RESTITUTION BUT WITH A RANGE OF -1 TO +1.	IMPULS
C	CREST HAS A RANGE OF 0 TO +1 WHERE 0 (E=-1) REPRESENTS NO IMPULSE.	IMPULS
C		IMPULS
	IF (TDV.NE.0.0) ALPHA = -2.0*CREST*TVREL/TDV	IMPULS
	IF (NPRT(10).NE.0) WRITE (6,42) DWR1,DWR2,DWR3,DWR4,	IMPULS
	* TTI,VREL,DV,	IMPULS
	* TVREL,TDV,CREST,ALPHA	IMPULS
	DO 60 J=1,NGRND	IMPULS
	DO 60 I=1,3	IMPULS
	SEGLV(I,J) = SEGLV(I,J) + ALPHA*SEGLA(I,J)	IMPULS
60	WMEG (I,J) = WMEG (I,J) + ALPHA*WMEGD(I,J)	IMPULS
	IF (NPRT(10).NE.0) CALL OUTPUT(1)	IMPULS
	IF (NPRT( 3).NE.0) CALL PRINT(6HIMPULS)	IMPULS
	CALL ELTIME(2,27)	IMPULS
99	RETURN	IMPULS
	END	IMPULS





C	INITIAL LINEAR POSITION (IN) AND (IF I3=1) VELOCITY (IN/SEC)	INITIAL
C	OF EACH BASE BODY SEGMENT. IF I3=0, VELOCITY WILL BE SET TO	INITIAL
C	INITIAL VELOCITY OF VEHICLE. INPUTS IN INERTIAL REFERENCE.	INITIAL
C		INITIAL
	DO 37 J=1,NSEG	INITIAL
	IF (J.GT.1.AND.IABS(JNT(J-1)).GT.0) GO TO 37	INITIAL
	READ(5,24) (SEGLP(I,J),I=1,3),(SEGLV(I,J),I=1,3)	INITIAL
24	FORMAT (6F10.0 , 4I3)	INITIAL
	IF (I3.GT.0) GO TO 37	INITIAL
	DO 36 I=1,3	INITIAL
36	SEGLV(I,J) = SEGLV(I,NVEH)	INITIAL
37	CONTINUE	INITIAL
C		INITIAL
C	INPUT CARDS G.3.A - G.3.N	INITIAL
C		INITIAL
C	FOR EACH BODY SEGMENT SUPPLY YAW, PITCH AND ROLL (DEGREES)	INITIAL
C	AND (IF I3=1) THE ANGULAR VELOCITY IN LOCAL REFERENCE (DEG/SEC).	INITIAL
C	IF I3=0, THE ANGULAR VELOCITY (BLANK ON INPUT CARDS) WILL BE SET	INITIAL
C	EQUAL TO THE INITIAL ANGULAR VELOCITY OF THE VEHICLE.	INITIAL
C		INITIAL
	FIRST = 0.0	INITIAL
	DO 40 J=1,NSEG	INITIAL
	READ (5,24) (YPR(I,J),I=1,3),(WMGDEG(I,J),I=1,3),(IYPR(I,J),I=1,4)	INITIAL
	ID1 = IYPR(1,J)	INITIAL
	DO 38 I=1,3	INITIAL
	IF (ID1.EQ.0) IYPR(I,J) = I	INITIAL
38	WMEG(I,J) = WMGDEG(I,J)*RADIAN	INITIAL
	IF (ID1.GE.0) GO TO 60	INITIAL
C		INITIAL
C	READ CARD G.3.J2 FOR SEGMENT NO. J WHEN IYPR(1,J) IS NEGATIVE.	INITIAL
C		INITIAL
	READ (5,24) A,II,IK,JJ,JK	INITIAL
	IJ = II	INITIAL
	LK = IK	INITIAL
	DO 54 K=1,2	INITIAL
	IF (IJ.GT.0) GO TO 52	INITIAL
	DO 51 I=1,3	INITIAL
51	Z(I,LK) = A(I,K)	INITIAL
	GO TO 53	INITIAL
52	DA1 = A(1,K)*RADIAN	INITIAL
	DA2 = A(2,K)*RADIAN	INITIAL
	SA1 = DSIN(DA1)	INITIAL
	SA2 = DSIN(DA2)	INITIAL
	CA1 = DCOS(DA1)	INITIAL
	CA2 = DCOS(DA2)	INITIAL
	IJ1 = IJ+1	INITIAL
	IJ2 = IJ+2	INITIAL
	IF (IJ1.GT.3) IJ1= IJ1-3	INITIAL
	IF (IJ2.GT.3) IJ2= IJ2-3	INITIAL
	SGN = 1.0	INITIAL

```

IF (SA1.LT.0.0 .AND. CA2.LT.0.0) SGN = -1.0          INITAL
Z(IJ ,LK) = SGN*SA1*CA2                               INITAL
Z(IJ1,LK) = SGN*SA1*SA2                              INITAL
Z(IJ2,LK) = SGN*CA1*CA2                              INITAL
53 IJ = JJ                                            INITAL
54 LK = JK                                            INITAL
ZDOTIJ = Z(1,IK)*Z(1,JK) + Z(2,IK)*Z(2,JK) + Z(3,IK)*Z(3,JK) INITAL
ZDOTII = Z(1,IK)*Z(1,IK) + Z(2,IK)*Z(2,IK) + Z(3,IK)*Z(3,IK) INITAL
RATIO = ZDOTIJ/ZDOTII                                INITAL
DO 55 I=1,3                                          INITAL
55 Z(I,JK) = Z(I,JK) - RATIO*Z(I,IK)                 INITAL
LK = 6-IK-JK                                         INITAL
IT = MOD(JK-IK+3,3)                                  INITAL
IF (IT.EQ.1) CALL CROSS(Z(1,IK),Z(1,JK),Z(1,LK))    INITAL
IF (IT.EQ.2) CALL CROSS(Z(1,JK),Z(1,IK),Z(1,LK))    INITAL
DO 57 K=1,3                                          INITAL
IYPR(K,J) = 4-K                                       INITAL
SUM = 0.0                                             INITAL
DO 56 I=1,3                                          INITAL
56 SUM = SUM + Z(I,K)**2                               INITAL
SQUM = DSQRT(SUM)                                     INITAL
DO 57 I=1,3                                          INITAL
57 D(K,I,J) = Z(I,K)/SQUM                             INITAL
CALL YPRDEG (D(1,1,J),YPR(1,J))                       INITAL
IF (FIRST.EQ.0.0) WRITE (6,58)                       INITAL
58 FORMAT('0 INITIAL ANGULAR ROTATIONS COMPUTED FROM CARDS G.3.J2'// INITAL
* ' SEGMENT',10X,'SEGMENT PRIMARY AXIS',             INITAL
* ' 12X,'SEGMENT SECONDARY AXIS',30X,'ANGULAR ROTATIONS (DEG)'/ INITAL
* ' NO. SEG',9X,'A1',8X,'A2',8X,'A3',11X,'B1',8X,'B2',8X, INITAL
* 'B3',7X,'II IK JJ JK',9X,'YAW',6X,'PITCH',5X,'ROLL'// INITAL
FIRST = 1.0                                           INITAL
WRITE (6,59) J,SEG(J),A,II,IK,JJ,JK,(YPR(I,J),I=1,3) INITAL
59 FORMAT (I4,1X,A4,3X,3F10.3,3X,3F10.3,3X,4I4,3X,3F10.3) INITAL
60 M = IYPR(4,J)                                       INITAL
IF (M.EQ.0) M=NGRND                                   INITAL
IF (M.GE.J .AND. M.LE.NSEG) STOP 24                  INITAL
IF (J.EQ.1) GO TO 80                                  VAXCHG
IF (M.LT.0 .AND. -M.NE.IABS(JNT(J-1))) STOP 25      INITAL
80 CALL DRCIJK (D,YPR,IYPR,HT,J)                     VAXCHG
IF (I3.GT.0) GO TO 40                                 INITAL
CALL DOT31(D(1,1,NVEH),WMEG(1,NVEH),T)               INITAL
CALL MAT31(D(1,1,J),T,WMEG(1,J))                    INITAL
DO 39 I=1,3                                          INITAL
39 WMGDEG(I,J) = WMEG(I,J)/RADIAN                   INITAL
40 CONTINUE                                           INITAL
CALL VEHPOS                                           INITAL
IF(NJNT.EQ.0) GOTO 41                                 JDRIFT
CALL CHAIN(0)                                         JDRIFT
CALL EJOINT(1,0)                                      JDRIFT
DO 62 J=1,NJNT                                       JDRIFT

```

	IF (IABS(IPIN(J)).NE.4) GOTO 62	JDRIFT
	IF (IEULER(J).NE.2) GOTO 62	JDRIFT
	DA1 = ANG(2,J) + CONST(2,J)	JDRIFT
	CONST(4,J) = DCOS(DA1)	JDRIFT
	CONST(5,J) = DSIN(DA1)	JDRIFT
62	CONTINUE	JDRIFT
C		INITAL
C	OUTPUT INITIAL BODY SEGMENT POSITIONS.	INITAL
C		INITAL
41	WRITE (6,42) UNITL,UNITL,UNITT	JDRIFT
42	FORMAT('0 INITIAL POSITIONS (INERTIAL REFERENCE)',70X,'CARDS G.2'/	INITAL
*	/' SEGMENT',11X,'LINEAR POSITION (' ,A4,')',	INITAL
*	14X,'LINEAR VELOCITY (' ,A4,',' ,A4,')'/	AFREVS
*	' NO. SEG',2(9X,'X',11X,'Y',11X,'Z',5X) )	INITAL
	WRITE (6,43) (J,SEG(J),(SEGLP(I,J),I=1,3),(SEGLV(I,J),I=1,3)	INITAL
*	,J=1,NSEG)	INITAL
43	FORMAT(I4,1X,A4,3X,3F12.5,3X,3F12.5)	INITAL
	WRITE (6,44) UNITT	INITAL
44	FORMAT('0 INITIAL ANGULAR ROTATION AND VELOCITY',71X,'CARDS G.3'//	INITAL
*	' SEGMENT',11X,'ANGULAR ROTATION (DEG)',	AFREVS
*	14X,'ANGULAR VELOCITY (DEG/',' ,A4,')'/	INITAL
*	' NO. SEG',8X,'YAW',8X,'PITCH',7X,'ROLL',	INITAL
*	13X,'X',11X,'Y',11X,'Z',15X,'IYPR' )	INITAL
	WRITE (6,46) (J,SEG(J),(YPR(I,J),I=1,3),(WVGDEG(I,J),I=1,3),	INITAL
*	(IYPR(I,J),I=1,4),J=1,NSEG)	INITAL
46	FORMAT(I4,1X,A4,3X,3F12.5,3X,3F12.5,3X,4I4)	INITAL
	IF (I3.EQ.0) WRITE (6,45)	INITAL
45	FORMAT('0 LINEAR AND ANGULAR VELOCITIES HAVE BEEN SET EQUAL TO THE	INITAL
*	INITIAL VEHICLE VELOCITIES.')	INITAL
	IF (NHRNSS.NE.0) CALL HBPLAY	INITAL
	IF (I1.EQ.15) CALL EQUILB (YPR,IYPR)	INITAL
	CALL UNIT1(0)	JDRIFT
	CALL ROTATE	INITAL
	CALL ELTIME(2,2)	INITAL
	RETURN	INITAL
	END	INITAL



C	CALL DSMSOL(C,3,3)		INTERS
C		EVALUATE AX	INTERS
C		FA(V) = X'AX	INTERS
		FB(V) = -V(X'-M')AX	INTERS
	FA = 0.0		INTERS
	FB = 0.0		INTERS
	CALL MAT31(A,Z,AX)		INTERS
	DO 30 I=1,3		INTERS
	X(I) = Z(I)		INTERS
	FA = FA+X(I)*AX(I)		INTERS
30	FB = FB+(X(I)-XM(I))*AX(I)		INTERS
	FB = -V*FB		INTERS
	IF (T.LT.0.0) FA = 1.0/FA		INTERS
	IF (IDONE.EQ.1) GO TO 60		INTERS
C		TEST FOR INTERSECTION	INTERS
	IF (FA-FB) 32,60,31		INTERS
C		IF FA>FB>1, NO INTERSECTION	INTERS
31	IF (T.GT.0.0.AND.FB.LT.1.0) GO TO 40		INTERS
	IF (T.LT.0.0.AND.FA.GT.1.0) GO TO 40		INTERS
	IF (N.EQ.0) GO TO 60		INTERS
	GO TO 62		INTERS
C		IF FA<FB<1, INTERSECTION	INTERS
32	IF (T.GT.0.0.AND.FB.LE.1.0) N=1		INTERS
	IF (T.LT.0.0.AND.FA.GE.1.0) N=1		INTERS
C		SOLVE (VA+B)Z = AX FOR Z	INTERS
40	DO 42 I=1,3		INTERS
	DO 41 J=1,3		INTERS
41	C(I,J) = V*A(I,J) + B(I,J)		INTERS
42	Z(I) = AX(I)		INTERS
	CALL DSMSOL(C,3,3)		INTERS
C		F'A(V) = -2X'AZ	INTERS
	CALL MAT31(A,Z,AX)		INTERS
	FPA = X(1)*AX(1)		INTERS
	* + X(2)*AX(2)		INTERS
	* + X(3)*AX(3)		INTERS
	FPA = -(FPA+FPA)		INTERS
C		DV = -G(V)/G'(V)	INTERS
	DV = 1.0 + V		INTERS
	IF (T.LT.0.0) DV = V-FA**2		INTERS
	DV = (FB-FA)/(DV*FPA)		INTERS
	IF (ITER.GE.50) GO TO 62		INTERS
C		TEST FOR CONVERGENCE	INTERS
	IF (T*(V+DV).LE.0.0) DV = -0.5*V		INTERS
	V = V+DV		INTERS
	DV = DABS(DV/V)		INTERS
	IF (DV.LE.EPS(12)) IDONE=1		INTERS
	GO TO 20		INTERS
C		FA(V) = FB(B), RETURN	INTERS
60	IF (T.LT.0.0) FA = 1.0/FB		INTERS
	T = DSQRT(FA)		INTERS

```
IF (FA.GT.1.0) GO TO 61
N = 1
GO TO 71
61 IF (N.EQ.0) GO TO 71
62 WRITE (6,63)
63 FORMAT(' INTERS ITERATION DID NOT CONVERGE')
71 CONTINUE
RETURN
END
```

```
INTERS
INTERS
INTERS
INTERS
INTERS
INTERS
INTERS
INTERS
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60	FORMAT(3F12.0,2I12)	WINDOP
	TAB(J2-1) = DFLOAT(NSV)	WINDOP
	TAB(J2) = DFLOAT(NSR)	WINDOP
	IF (TAB(J1).EQ.0.0) GOTO 22	WINDOP
	WRITE(6,23) (TAB(J),J=J1,J2-2),NSV,SEG(NSV),NSR,SEG(NSR)	WINDOP
23	FORMAT(' SPEC. HEAT RATIO    SONIC VEL.    ABS. PRESS.',7X,	WINDOP
	*        'SEGMENT        REF. SEGMENT',/3F15.4,2(I11,A4)//)	WINDOP
	J1=J2+1	WINDOP
	GOTO 30	MISC
22	WRITE (6,18) (TAB(J),J=J1,J2)	KINPUT
17	FORMAT(6F12.0)	KINPUT
18	FORMAT(10X,'D0',13X,'D1',13X,'D2',13X,'D3',8X,'REF. SEGMENT',	WINDOP
	*        /5F15.4//)	WINDOP
	J1 = J2+1	KINPUT
C		KINPUT
C	INPUT CARD E.6.C - NTMPTS	KINPUT
C		KINPUT
	READ (5,11) NTMPTS	KINPUT
	WRITE (6,19) NTMPTS	KINPUT
19	FORMAT('0 WIND FORCE TABLES FOR ',I6,' TIME POINTS.'//	KINPUT
	*        11X,'T',14X,'FX(T)',15X,'FY(T)',15X,'FZ(T)' /)	KINPUT
	TAB(J1) = NTMPTS	KINPUT
	J1 = J1+1	KINPUT
	J2 = J1+4*NTMPTS-1	KINPUT
C		KINPUT
C	INPUT CARDS E.6.D-E.6.N - NTMPTS CARDS OF T,FX(T),FY(T),FZ(T)	KINPUT
C		KINPUT
	READ (5,20) (TAB(J),J=J1,J2)	KINPUT
	WRITE (6,21) (TAB(J),J=J1,J2)	KINPUT
20	FORMAT(4F12.0)	KINPUT
21	FORMAT(3X,F12.6,3G20.6)	KINPUT
	J1 = J2+1	KINPUT
30	CONTINUE	KINPUT
31	IF (NJNTE.LE.0) GO TO 51	KINPUT
	DO 50 K=1,NJNTE	KINPUT
C		KINPUT
C	INPUT CARD E.7.A - FUNCTION NO. AND TITLE	KINPUT
C		KINPUT
	READ (5,12) I,(KTITLE(J),J=1,5)	KINPUT
	WRITE (6,32) I,(KTITLE(J),J=1,5),I,J1,NPG	PAGE
	NPG=NPG+1	PAGE
32	FORMAT('1 JOINT FORCE FUNCTION NO.',I4,4X,5A4,10X,'NTI(',I2,') =',	KINPUT
	*        15,45X,'PAGE',I5/120X,'CARDS E.7'//)	PAGE
	IF (I.LE.0.OR.I.GT.50) WRITE (6,14)	KINPUT
	IF (I.LE.0.OR.I.GT.50) STOP 12	KINPUT
	IF (NTI(I).NE.0) WRITE (6,15) I	KINPUT
	NTI(I) = J1	KINPUT
	DO 33 J=1,5	KINPUT
33	JTITLE(J,I) = KTITLE(J)	KINPUT
C		KINPUT

```

C      INPUT CARD E.7.B - D0,D1,D2,D3,D4 (FOR NOW A BLANK CARD).      KINPUT
C
      J2 = J1+4                                                         KINPUT
      READ (5,17) (TAB(J),J=J1,J2)                                     KINPUT
      WRITE (6,18) (TAB(J),J=J1,J2)                                    KINPUT
      J1 = J2+1                                                         KINPUT
C
C      INPUT CARD E.7.C - NTHETA,NPHI                                    KINPUT
C
      READ (5,11) NTHETA,NPHI                                          KINPUT
      TAB(J1) = NTHETA                                                  KINPUT
      TAB(J1+1) = NPHI                                                  KINPUT
      J1 = J1+2                                                         KINPUT
      IF (NTHETA.LT.0) GO TO 38                                         KINPUT
      DO 35 J=1,NTHETA                                                  KINPUT
35 TH(J) = DFLOAT(J-1)*180.0/DFLOAT(NTHETA-1)                          KINPUT
      WRITE (6,36) NTHETA,NPHI,(TH(J),J=2,NTHETA)                     KINPUT
36 FORMAT('0 FUNCTION IS TABULAR FOR' ,I3,' X',I3,' VALUES OF THETA AKINPUT
      *ND PHI'//30X,'THETA'/5X,'PHI',5X,'THETA0',F16.3,4F20.3/        KINPUT
      * (15X,5F20.3)                                                   KINPUT
37 FORMAT(F9.2,F10.3,5G20.7/(19X,5G20.7))                               KINPUT
      GO TO 40                                                           KINPUT
38 NPOLY = -NTHETA -1                                                  KINPUT
      WRITE (6,39) NPOLY,NPHI,(BLANK,J,J=1,NPOLY)                       KINPUT
39 FORMAT('0 FUNCTION IS COEFFICIENTS OF' ,I3,' ORDER POLYNOMIALS IN KINPUT
      *(THETA-THETA0) FOR',I3,' VALUES OF PHI.'//                     KINPUT
      * 27X,'COEFFICIENTS OF (THETA-THETA0)**N'/                       KINPUT
      * 5X,'PHI',5X,'THETA0',7X,5(A4,'N =' ,I2,11X)/(26X,A4,'N =' ,I2,11X, KINPUT
      * A4,'N =' ,I2,11X,A4,'N =' ,I2,11X,A4,'N =' ,I2,11X,A4,'N =' ,I2) ) KINPUT
40 WRITE (6,21)                                                         KINPUT
      DO 49 I=1,NPHI                                                    KINPUT
      PHIDEG = DFLOAT(I-1)*360.0/DFLOAT(NPHI) - 180.0                 KINPUT
C
C      INPUT CARDS E.7.D - E.7.N NPHI SETS WITH NTHETA ITEMS PER SET. KINPUT
C      EACH SET I IS FOR PHI(I) = -180 +(I-1)*360/NPHI DEGREES AND    KINPUT
C      ASSUMES DATA FOR PHI(NPHI+1) = 180 IS SAME AS PHI(1) = -180. KINPUT
C
      J2 = J1 + IABS(NTHETA) -1                                         KINPUT
      READ (5,17) (TAB(J),J=J1,J2)                                     KINPUT
      WRITE (6,37) PHIDEG,(TAB(J),J=J1,J2)                             KINPUT
      IF (NTHETA.LT.0) TAB(J1) = TAB(J1)*RADIAN                         KINPUT
      IF (NTHETA.LT.0) GO TO 49                                         KINPUT
C
C      FOR TABULAR DATA, FILL IN ZERO VALUES WITH INTERPOLATED NEGATIVE KINPUT
C      VALUES. OVERWRITE VALUE IN FIRST COLUMN (SUPPLIED AS THETA0) WITH KINPUT
C      VALUE FOR THETA = 0 AND ALL OTHER ZERO VALUES.                 KINPUT
C
      THETA0 = TAB(J1)                                                  KINPUT
      IF (THETA0.EQ.0.0) GO TO 49                                       KINPUT
      JJ = THETA0*DFLOAT(NTHETA-1)/180.0 + 1.0 + EPS(6)                KINPUT

```

JJ1 = J1+JJ	KINPUT
IERROR = 0	KINPUT
IF (JJ1.GT.J2) IERROR = 1	KINPUT
IF (TAB(JJ1).LE.0.0) IERROR = 2	KINPUT
IF (IERROR.NE.0) GO TO 46	KINPUT
DO 45 J=1, JJ	KINPUT
J1J = J1+J-1	KINPUT
IF (J.NE.1.AND.TAB(J1J).GT.0.0) IERROR = 3	KINPUT
45 TAB(J1J) = TAB(JJ1)*(TH(J)-THETA0)/(TH(JJ+1)-THETA0)	KINPUT
46 IF (IERROR.NE.0) WRITE (6,47) IERROR	KINPUT
47 FORMAT('0 INPUT ERROR. INCONSISTENT VALUE OF THETA0. IERROR =', I2,	KINPUT
* ' PROGRAM TERMINATED.')	KINPUT
IF (IERROR.NE.0) STOP 13	KINPUT
49 J1 = J2+1	KINPUT
50 CONTINUE	KINPUT
51 MXTB1 = J1-1	KINPUT
RETURN	KINPUT
END	KINPUT

C	SUBROUTINE LINAXS(XO,YO,THETA,NINTVS,TOTLGT)	LINAXS
C		REV 18 02/28/78LINAXS
C	PURPOSE : PREPARE A LINEAR AXIS ON A PLOT.	LINAXS
C		LINAXS
C	DESCRIPTION OF PARAMETERS:	LINAXS
C	XO,YO - STARTING POINT (IN INCHES, REL TO PLOTTER ORIGIN).	LINAXS
C		LINAXS
C	THETA - ANGLE OF AXIS, IN DEGREES.	LINAXS
C		LINAXS
C	NINTVS- MAGNITUDE = NO. OF INTERVALS DELINEATED BY TIC MARKS.	LINAXS
C	- SIGN DETERMINES WHETHER TIC MARKS ARE PLACED ON	LINAXS
C	POSITIVE OR NEGATIVE SIDE OF AXIS, RESPECTIVELY	LINAXS
C	(POSITIVE SIDE IS TO LEFT OF DIRECTION OF TRAVEL).	LINAXS
C		LINAXS
C	TOTLGT- TOTAL LENGTH OF AXIS, IN INCHES.	LINAXS
C		LINAXS
C	SUBROUTINES REQUIRED : SIN, COS, PLOT (NOTE: SINGLE PRECISION).	LINAXS
C		LINAXS
C	AUTHOR: W. D. FRYER, CALSPAN (MARCH 1967).	LINAXS
C		LINAXS
C	PLAGIARIZED FROM CALSPAN SUBROUTINE LIBRARY (NO. CU 0035).	LINAXS
C		LINAXS
C	THR = 1.7453293E-2 * THETA	LINAXS
C	SINT = SIN(THR)	LINAXS
C	COST = COS(THR)	LINAXS
C		LINAXS
C	DL = ABS(TOTLGT/ FLOAT(NINTVS))	LINAXS
C	DX = DL*COST	LINAXS
C	DY = DL*SINT	LINAXS
C		LINAXS
C	TICK = -0.12* SINT	LINAXS
C	TICY = 0.12* COST	LINAXS
C	IF(NINTVS.GT.0) GO TO 30	LINAXS
C	TICK = -TICK	LINAXS
C	TICY = -TICY	LINAXS
C		LINAXS
C	30 X = XO	LINAXS
C	Y = YO	LINAXS
C		LINAXS
C	CALL PLOT (X +TICK,Y+TICY,3)	LINAXS
C	CALL PLOT (X,Y,2)	LINAXS
C	NINT = IABS(NINTVS)	LINAXS
C	DO 40 I=1,NINT	LINAXS
C	X = X+DX	LINAXS
C	Y = Y+DY	LINAXS
C	CALL PLOT(X,Y,2)	LINAXS
C	CALL PLOT(X+TICK,Y+TICY,2)	LINAXS
C	40 CALL PLOT(X,Y,2)	LINAXS
C		LINAXS
C	RETURN	LINAXS
C	END	LINAXS

```

SUBROUTINE LOGAXS(X0,Y0,THETA,NDEC,EXTENT)
C                                     REV 19   09/18/79LOGAXS
C                                     LOGAXS
C PURPOSE : PREPARE LOGARITHMIC AXIS ON A PLOT.
C                                     LOGAXS
C DESCRIPTION OF PARAMETERS:
C                                     LOGAXS
C                                     LOGAXS
C     X0,Y0 - STARTING POINT (IN INCHES, REL TO PLOTTER ORIGIN).
C                                     LOGAXS
C     THETA - ANGLE OF AXIS (DEGREES).
C                                     LOGAXS
C     NDECS - MAGNITUDE OF NDECS SPECIFIES NO. OF DECADES.
C                                     LOGAXS
C             - SIGN DETERMINES WHETHER TIC MARKS ARE TO BE PLACED
C             ON POS. OR NEG. SIDE OF AXIS, RESP. (POS. SIDE IS
C             TO LEFT OF PREDOMINANT DIRECTION OF TRAVEL).
C                                     LOGAXS
C     EXTENT- MAGNITUDE OF EXTENT SETS OVER-ALL LENGTH OF AXIS
C             IN INCHES. IF EXTENT IS POSITIVE, TIC MARKS ARE
C             SPACED NORMALLY (LARGE INTERVALS FIRST). IF EXTENT
C             IS NEGATIVE, TIC MARKS ARE SPACED IN REVERSE ORDER
C             (SMALL INTERVALS FIRST).
C                                     LOGAXS
C SUBROUTINES REQUIRED : SIN, COS, PLOT (NOTE: SINGLE PRECISION).
C                                     LOGAXS
C AUTHOR: W. D. FRYER, CALSPAN (MARCH 1967).
C                                     LOGAXS
C PLAGIARIZED FROM CALSPAN SUBROUTINE LIBRARY (NO. CU 0036).
C                                     LOGAXS
C LOGICAL REVERS
C REAL XL(18),XL0(19)
C EQUIVALENCE (XL0(2),XL(1))
C DATA XL0/ 0.0      , 0.17609, 0.30103, 0.39794, 0.47712, 0.54407,
C * 0.60206, 0.65321, 0.69897, 0.74036, 0.77815, 0.81291, 0.84510,
C * 0.87506, 0.90309, 0.92942, 0.95424, 0.97772, 1.0      /
C DATA RPD /1.7453293E-2/
C                                     LOGAXS
C REVERS = .FALSE.
C IF(EXTENT.LT.0.0) REVERS = .TRUE.
C
C NODEC = IABS(NDEC)
C SPDEC = ABS(EXTENT) / FLOAT(NODEC)
C THR = THETA*RPD
C COST = COS(THR)
C SINT = SIN(THR)
C
C TICX1 = -0.05*SINT
C TICY1 = 0.05*COST
C TICXA = -0.12*SINT
C TICXB = -0.20*SINT
C                                     LOGAXS

```

	TICYA = 0.12*COST	LOGAXS
	TICYB = 0.20*COST	LOGAXS
	IF(NDEC.GT.0) GO TO 50	LOGAXS
C		LOGAXS
	TICK1 = -TICK1	LOGAXS
	TICY1 = - TICY1	LOGAXS
	TICK2 = -TICK2	LOGAXS
	TICXA = - TICXA	LOGAXS
	TICYA = -TICYA	LOGAXS
	TICKB = -TICKB	LOGAXS
	TICYB = - TICYB	LOGAXS
C		LOGAXS
50	COST = COST*SPDEC	LOGAXS
	SINT = SINT* SPDEC	LOGAXS
	TICK2 = TICKA	LOGAXS
	TICY2 = TICYA	LOGAXS
C		LOGAXS
	XD = X0	LOGAXS
	YD = Y0	LOGAXS
	ND = 1	LOGAXS
	N = 0	LOGAXS
C		LOGAXS
C	*****GO TO START POS.*****	LOGAXS
	CALL PLOT(X0+TICKB,Y0+TICYB,3)	LOGAXS
	CALL PLOT(X0,Y0,2)	LOGAXS
C		LOGAXS
60	N = N+1	LOGAXS
	Q = XL(N)	LOGAXS
	IF(.NOT. REVERS) GO TO 65	LOGAXS
	M = 18-N	LOGAXS
	Q = 1.0-XL(M)	LOGAXS
65	X = XD + Q*COST	LOGAXS
	Y = YD + Q*SINT	LOGAXS
	CALL PLOT(X,Y,2)	LOGAXS
	CALL PLOT(X+TICK1,Y+TICY1,2)	LOGAXS
	CALL PLOT (X,Y,2 )	LOGAXS
C		LOGAXS
	N = N+1	LOGAXS
	Q = XL(N)	LOGAXS
	IF(.NOT. REVERS) GO TO 75	LOGAXS
	M = 18-N	LOGAXS
	Q = 1.0 - XL(M)	LOGAXS
75	X = XD + Q*COST	LOGAXS
	Y = YD + Q*SINT	LOGAXS
	CALL PLOT(X,Y,2)	LOGAXS
	CALL PLOT (X+TICK2,Y+TICY2,2)	LOGAXS
	CALL PLOT(X,Y,2)	LOGAXS
C		LOGAXS
	IF(N-16) 60,80,100	LOGAXS
C		LOGAXS

	80	TICK2 = TICXB	LOGAXS
		TICY2 = TICYB	LOGAXS
		GO TO 60	LOGAXS
C			LOGAXS
	100	IF(ND .EQ. NODEC) GO TO 200	LOGAXS
		TICK2 = TICKA	LOGAXS
		TICY2 = TICYA	LOGAXS
		N = 0	LOGAXS
		XD = X	LOGAXS
		YD = Y	LOGAXS
		ND = ND+1	LOGAXS
		GO TO 60	LOGAXS
C			LOGAXS
	200	RETURN	LOGAXS
		END	LOGAXS

	FUNCTION LTIME(N)		LTIME
C		REV III.2 08/08/84REVIII	
C	TEMPORARY FORTRAN VERSION OF S/370 ASSEMBLER LANGUAGE ROUTINE FROM	LTIME	
C	CALSPAN LIBRARY THAT MEASURES ELAPSED CPU TIME IN UNITS OF 0.01	LTIME	
C	SECONDS. IT SHOULD BE REPLACED WITH AN EQUIVALENT ROUTINE BY THE	LTIME	
C	USER TO ENABLE SUBROUTINE ELTIME TO PERFORM ON HIS COMPUTER.	LTIME	
C		LTIME	
C	ORIGINAL CALSPAN ROUTINE PERFORMS AS FOLLOWS:	LTIME	
C	IT = LTIME(0) GIVES ELAPSED CPU TIME (INTEGER NUMBER OF 0.01	LTIME	
C	SECOND UNITS) SINCE SUBROUTINE REFERENCE WAS	LTIME	
C	RESET, AND RESETS THIS REFERENCE.	LTIME	
C	IT = LTIME(1) SAME, EXCEPT THAT THE REFERENCE IS NOT RESET.	LTIME	
C		LTIME	
C		PECONV	
C	THIS SUBROUTINE DOESN'T WORK WITH THE P-E COMPUTER	PECONV	
C	BUT THE CODE IS LEFT HERE AS A DUMMY SUBROUTINE.	PECONV	
C	HOWEVER, THERE IS A VERSION OF THIS SUBROUTINE THAT	PECONV	
C	CAN BE USED, BUT IT CAN ONLY BE COMPILED WITH THE	PECONV	
C	P-E FORTRAN 0 COMPILER. THE OBJECT DECK FOR THIS	PECONV	
C	SUBROUTINE IS KEPT SEPARATELY AND INCLUDED IN THE	PECONV	
C	TASK FILE WHEN THE PROGRAM IS LINKED	PECONV	
C		PECONV	
	DATA KTIME/0/	LTIME	
	KTIME = KTIME+1	LTIME	
	LTIME = KTIME	LTIME	
	IF (N.EQ.0) KTIME = 0	LTIME	
	RETURN	LTIME	
	END	LTIME	



	SUBROUTINE MAT31 (A,B,C)		MAT31
		REV 17	01/03/77MAT31
C	PERFORMS MATRIX MULTIPLICATION C = AB		MAT31
C	WHERE A IS A 3X3 MATRIX, AND B AND C ARE VECTORS OF LENGTH 3.		MAT31
C			MAT31
C	IMPLICIT REAL*8 (A-H,O-Z)		MAT31
	DIMENSION A(3,3) , B(3) , C(3)		MAT31
	C(1) = A(1,1)*B(1) + A(1,2)*B(2) + A(1,3)*B(3)		MAT31
	C(2) = A(2,1)*B(1) + A(2,2)*B(2) + A(2,3)*B(3)		MAT31
	C(3) = A(3,1)*B(1) + A(3,2)*B(2) + A(3,3)*B(3)		MAT31
	RETURN		MAT31
	END		MAT31

	SUBROUTINE MAT33 (A,B,C)			MAT33
C		REV 17	01/03/77	MAT33
C	PERFORMS MATRIX MULTIPLICATION C = AB			MAT33
C	WHERE A, B AND C ARE ALL 3X3 MATRICEES.			MAT33
C				MAT33
	IMPLICIT REAL*8 (A-H,O-Z)			MAT33
	DIMENSION A(3,3) , B(3,3) , C(3,3)			MAT33
	DO 10 I=1,3			MAT33
	DO 10 J=1,3			MAT33
10	C(I,J) = A(I,1)*B(1,J) + A(I,2)*B(2,J) + A(I,3)*B(3,J)			MAT33
	RETURN			MAT33
	END			MAT33

	SUBROUTINE ORTHO(P,X,L)		ORTHO
		REV 03 05/31/73	ORTHO
C	GENERATES A SET OF RIGHT HANDED ORTHONORMAL VECTORS (P),		ORTHO
C	GIVEN ONE OF THE VECTORS (X), WHERE		ORTHO
C	P - LX3 MATRIX OF 3 ORTHONORMAL VECTORS TO BE GENERATED.		ORTHO
C	X - GIVEN VECTOR.		ORTHO
C	L - 1ST SUBSCRIPT OF P IN CALLING PROGRAM.		ORTHO
C			ORTHO
	IMPLICIT REAL*8(A-H,O-Z)		ORTHO
	DIMENSION P(L,3),X(3)		ORTHO
	M=2		ORTHO
	N=3		ORTHO
	TEST=0.		ORTHO
	DO 5 I=1,3		ORTHO
	P(I,3)=X(I)		ORTHO
	D=1.-X(I)**2		ORTHO
	IF(D.LE.TEST)GO TO 4		ORTHO
	TEST=D		ORTHO
	D=DSQRT(D)		ORTHO
	P(I,1)=D		ORTHO
	P(I,2)=0.		ORTHO
	P(M,2)=X(N)/D		ORTHO
	P(N,2)=-X(M)/D		ORTHO
	P(M,1)=X(I)*P(N,2)		ORTHO
	P(N,1)=-X(I)*P(M,2)		ORTHO
4	M=N		ORTHO
	N=I		ORTHO
5	CONTINUE		ORTHO
	RETURN		ORTHO
	END		ORTHO

	SUBROUTINE OUTPUT(IJK)		REV IV 02/01/88	MISDOT	OUTPUT
C					OUTPUT
C	CONTROLS TABULATED OUTPUT ON FORTRAN UNITS (STARTING WITH NO. 21)				OUTPUT
C	OF SELECTED OPTIONAL SEGMENT LINEAR AND ANGULAR ACCELERATIONS,				OUTPUT
C	VELOCITIES AND DISPLACEMENTS, JOINT PARAMETERS AND SELECTED DATA				OUTPUT
C	FROM ALL ALLOWED CONTACT FORCE COMPUTATIONS BETWEEN BODY SEGMENTS				OUTPUT
C	AND VEHICLE COMPONENTS.				OUTPUT
C					OUTPUT
	IMPLICIT REAL*8 (A-H,O-Z)				OUTPUT
	COMMON/CONTRL/ TIME, NSEG, NJNT, NPL, NBLT, NBAG, NVEH, NGRND,				OUTPUT
*	NS, NQ, NSD, NFLX, NHRNSS, NWINDF, NJNPF, NPRT(36), NPG				PAGE
	COMMON/CMATRX/ V1(3,30), V2(3,30), V3(3,12), B12(3,3,60), A22(3,3,60),				OUTPUT
*	F(3,30), TQ(3,30), WJ(30), A11(3,3,30)				SLIP
	COMMON/SGMNTS/ D(3,3,30), WMEG(3,30), WMEGD(3,30), U1(3,30), U2(3,30),				OUTPUT
*	SEGLP(3,30), SEGLV(3,30), SEGLA(3,30), NSYM(30)				OUTPUT
	COMMON/DESCRP/ PHI(3,30), W(30), RW(30), SR(4,60), HA(3,60), HB(3,60),				SLIP
*	RPHI(3,30), HT(3,3,60), SPRING(5,90), VISC(7,90),				OUTPUT
*	JNT(30), IPIN(30), ISING(30), IGLOB(30), JOINTF(30)				OUTPUT
	COMMON/JBARTZ/ MNPL( 30), MNBLT( 8), MNSEG( 30), MNBAG( 6),				OUTPUT
*	MPL(3,5,30), MBLT(3,5,8), MSEG(3,5,30), MBAG(3,10,6),				OUTPUT
*	NTPL( 5,30), NTBLT( 5,8), NTSEG( 5,30)				OUTPUT
	COMMON/TITLES/ DATE(3), COMENT(40), VPSTTL(20), BDYTTL(5),				OUTPUT
*	BLTTTL(5,8), PLTTL(5,30), BAGTTL(5,6), SEG(30),				OUTPUT
*	JOINT(30), CGS(30), JS(30)				OUTPUT
	REAL DATE, COMENT, VPSTTL, BDYTTL, BLTTTL, PLTTL, BAGTTL, SEG, JOINT				OUTPUT
	LOGICAL*1 CGS, JS				OUTPUT
	COMMON/FORCES/PSF(7,70), BSF(4,20), SSF(10,40), BAGSF(3,20),				NCFORC
*	PRJNT(7,30), NPANEL(5), NPSF, NBST, NSSF, NBGSF				OUTPUT
	COMMON/CNSNTS/ PI, RADIANG, THIRD, EPS(24),				OUTPUT
*	UNITL, UNITM, UNITT, GRAVITY(3), TWOPI				TWOPI
	COMMON/RSAVE/ XSG(3,20,3), DPMI(3,3,30), LPMI(30),				ATBIII
*	NSG(9), MSG(20,9), MCG, MCGIN(24,5), KREF(20,9)				TTHKREF
	COMMON/COMAIN/VAR(240), DER(240), DT, HO, HMAX, HMIN, RSTIME,				OUTPUT
*	ISTEP, NSTEPS, NDINT, NEQ, IRSIN, IRSOUT				OUTPUT
	COMMON/DAMPER/ APSDM(3,20), APSDN(3,20), ASD(5,20), MSDM(20), MSDN(20)				OUTPUT
	COMMON/HRNESS/ BAR(15,100), BB(100), BBDOT(100), PLOSS(2,100),				OUTPUT
*	XLONG(20), HTIME(2), IBAR(5,100), NL(2,100),				OUTPUT
*	NPTSPB(20), NPPLY(20), NTHRNS(20), NBLTPH(5)				OUTPUT
	COMMON/WINDFR/ WTIME(30), QFU(3,5), QFV(3,5), WF(3,30), IWIND(30),				WINDOP
*	MWSEG(7,30), NRVSEG(6), NRVNT(5), MOWSEG(30,30)				WINDOP
	COMMON/TEMPVS/ TDATA(14,65), ACC(7,20), T1(3), T2(3), T3(3), T4(9)				CHGIII
*	, T5(3,3), T6(3,3), T7(3)				CHGIII
	LOGICAL LTAPES , LTHIST				OUTPUT
	DATA LINES/-1/, LPP/45/, NTMAX/65/				CHGIII
	DATA KMAX/20/, NMAX/22/, MCGMAX/5/				CHGIII
C					OUTPUT
	IF (IJK.NE.0) GO TO 13				OUTPUT
C					OUTPUT
C	SET ALL FORCE ARRAYS TO ZERO.				OUTPUT
C					OUTPUT

	DO 2 I=1,7	MISDOT
	DO 2 J=1,70	MISDOT
2	PSF(I,J) = 0.0	MISDOT
	DO 3 I=1,4	MISDOT
	DO 3 J=1,20	MISDOT
3	BSF(I,J) = 0.0	MISDOT
	DO 4 I=1,10	MISDOT
	DO 4 J=1,40	MISDOT
4	SSF(I,J) = 0.0	MISDOT
	DO 5 I=1,3	MISDOT
	DO 5 J=1,20	MISDOT
5	BAGSF(I,J) =0.0	MISDOT
	DO 6 I=1,7	MISDOT
	DO 6 J=1,30	MISDOT
6	PRJNT(I,J) = 0.0	MISDOT
	GO TO 66	OUTPUT
C		OUTPUT
C	LTHIST = TRUE MEANS PRINT LINE OF TIME HISTORY DATA FOR THIS	OUTPUT
C	TIME POINT ON EACH OUTPUT UNIT (NT).	OUTPUT
C		OUTPUT
C	LTAPES = TRUE MEANS WRITE TIME HISTORY DATA ON TAPE 8.	OUTPUT
C		OUTPUT
13	NPRT4 = NPRT(4) + 4	OUTPUT
	IF (NPRT4.LE.0 .OR. NPRT4.GT.8) STOP 37	OUTPUT
	IF(NPRT(26).EQ.6) GO TO 66	TGMOD1
	GO TO (66,66,66,15,16,17,17,16) , NPRT4	OUTPUT
15	LTAPES = .FALSE.	OUTSTP
	LTHIST = .TRUE.	TGMOD1
	GO TO 116	TGMOD1
16	LTHIST = .TRUE.	TGMOD1
	LTAPES = .TRUE.	TGMOD1
	GO TO 116	TGMOD1
17	LTHIST = .FALSE.	TGMOD1
	LTAPES = .TRUE.	TGMOD1
	GO TO 217	TGMOD1
116	TEST = DMOD(TIME,DT)	OUTSTP
	TEST = DMIN1(TEST,DABS(DT-TEST))	OUTSTP
	IF ((NPRT(26).EQ.0.OR.NPRT(26).EQ.3).AND.TEST.GE.EPS(8))	TGMOD1
	* LTHIST=.FALSE.	TGMOD1
	IF(.NOT.LTAPES.AND..NOT.LTHIST) GO TO 66	FIXTTH
217	CONTINUE	TGMOD1
	IF(NPRT(26).EQ.4) LTHIST=.FALSE.	TGMOD1
	IF(NPRT(26).EQ.5) LTAPES=.FALSE.	TGMOD1
	IF(.NOT.LTAPES.AND..NOT.LTHIST) GO TO 66	TGMOD1
	CALL ELTIME (1,8)	OUTPUT
	IF (LINES.GE.0) GO TO 21	FIXTTH
	PREVT = -999.0	OUTPUT
	LINES = 0	FIXTTH
	IF (IRSIN.NE.0) GO TO 10	OUTPUT
C		OUTPUT

C	1ST TIME IN ROUTINE, READ CARD INPUT FOR OUTPUT CONTROL.	OUTPUT
C		OUTPUT
C	1. NO. OF POINT TOTAL ACCELERATIONS ,POINT NOS. AND LOCATION	CHGIII
C	2. NO. OF POINT REL. VELOCITIES ,POINT NOS. AND LOCATION	CHGIII
C	3. NO. OF POINT REL. LINEAR DISPLACEMENTS ,POINT NOS. AND LOCATI	CHGIII
C	4. NO. OF SEGMENT ANGULAR ACCELERATIONS AND SEGMENT NOS.	CHGIII
C	5. NO. OF SEGMENT REL. ANGULAR VELOCITIES AND SEGMENT NOS.	CHGIII
C	6. NO. OF SEGMENT REL. ANGULAR DISPLACEMENTS AND SEGMENT NOS.	CHGIII
C	7. NO. OF JOINT PARAMETERS AND JOINT NOS.	OUTPUT
C	8. NO. OF SEGMENT WIND FORCES AND SEGMENT NOS.	WINDOP
C	9. NO. OF JOINT FORCES AND TORQUE NOS.	WINDOP
C	10. NO. OF CENTER OF GRAVITY AND RELATED INFORMATION	WINDOP
C		OUTPUT
	WRITE(6,478)	CHGIII
	478 FORMAT(1X,/,2X,'TABULAR TIME HISTORY CONTROL PARAMETERS')	CHGIII
	WRITE(6,479)	CHGIII
	479 FORMAT(3X,'TYPE KSG SELECTED SEGMENTS OR JOINTS')	TTHKREF
	DO 20 K=1,9	WINDOP
C		OUTPUT
C	INPUT CARDS H.(K).(J) FOR K=1,3	OUTPUT
C		OUTPUT
	IF (K.LE.3) READ (5,18) KSG,KREF(1,K),MSG(1,K),(XSG(I,1,K),I=1,3)	TTHKREF
	18 FORMAT (I6,2I3,3F12.6)	TTHKREF
	IF (KSG.GT.KMAX) STOP 84	CHGIII
	IF (K.GT.3) GO TO 201	ATBIII
	IF (KSG.LE.1) READ(5,213) IDUMMY	ATBIII
	213 FORMAT(I2)	ATBIII
	IF (KSG.LE.1) GO TO 201	ATBIII
	DO 205 J=2,KSG	ATBIII
	READ (5,210) KREF(J,K),MSG(J,K),(XSG(I,J,K),I=1,3)	TTHKREF
	210 FORMAT (I9,I3,3F12.6)	TTHKREF
	205 CONTINUE	ATBIII
	201 CONTINUE	ATBIII
C		OUTPUT
C	INPUT CARDS H.(K) FOR K=4,9	WINDOP
C		OUTPUT
	IF (K.GT.3) READ (5,19) KSG,(KREF(J,K),MSG(J,K),J=1,KSG)	TTHKREF
	19 FORMAT(I6,22I3/(I9,21I3))	TTHKREF
	IF (KSG.GT.KMAX) STOP 85	CHGIII
	WRITE (6,78) K,KSG,(MSG(J,K),J=1,KSG)	TTHKREF
	WRITE (6,81) (KREF(J,K),J=1,KSG)	TTHKREF
	78 FORMAT(' H.',I1,1X,I3,3X,20I3)	TTHKREF
	81 FORMAT(' REF ',20I3)	TTHKREF
	DO 80 J=1,KSG	TTHKREF
	IF(KREF(J,K).GT.NGRND.OR.KREF(J,K).LT.0) STOP 55	TTHKREF
	80 CONTINUE	TTHKREF
	IF (K.NE.7 .OR. KSG.EQ.0) GO TO 20	OUTPUT
	DO 12 J=1,KSG	OUTPUT
	L = MSG(J,K)	OUTPUT
	IF (IABS(IPIN(L)).EQ.4) MSG(J,K) = -L	OUTPUT

	12 CONTINUE	OUTPUT
	20 NSG(K) = KSG	OUTPUT
C		ATBIII
C	READ INPUT CARDS H.10	WINDOP
C		ATBIII
	READ (5,111) MCG	ATBIII
111	FORMAT(I6)	ATBIII
	IF (MCG.GT.MCGMAX) STOP 86	CHGIII
	IF (MCG.EQ.0) GO TO 114	ATBIII
	DO 113 K=1,MCG	ATBIII
	READ (5,112) M,N,(MCGIN(I+2,K),I=1,N)	ATBIII
112	FORMAT (24I3)	ATBIII
	IF (N.GT.NMAX) STOP 87	CHGIII
	WRITE (6,117) N,(MCGIN(I+2,K),I=1,N)	TTHKREF
117	FORMAT(' H.10',I3,3X,22I3)	TTHKREF
	WRITE (6,81) M	TTHKREF
	MCGIN(1,K) = M	ATBIII
113	MCGIN(2,K) = N	ATBIII
114	CONTINUE	ATBIII
	10 IF (.NOT.LTAPE8) GO TO 21	OUTPUT
	WRITE (8) NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,NPANEL,	OUTPUT
	* MNPL,MNBLT,MNSEG,MNBAG,MPL,MBLT,MSEG,MBAG	OUTPUT
	WRITE (8) DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,	OUTPUT
	* SEG,JOINT,UNITL,UNITM,UNITT,NSG,MSG,XSG,MCG,	ATBIII
	* MCGIN,KREF,NHRNSS,NBLTPH,NPTSPB,NSD,MSDM,MSDN	CHGIII
21	IF(LTHIST) LINES= LINES + 1	FIXTTH
	IF (MOD(LINES,LPP).EQ.1 .AND. LTHIST) CALL HEDING (LINES,LPP)	OUTPUT
	NT = 20	OUTPUT
	USEC = 1000.0*TIME	OUTPUT
C		OUTPUT
C	COMPUTE AND PRINT DATA FOR 9 TYPES OF OUTPUT ABOVE	WINDOP
C		OUTPUT
	DO 44 K=1,9	WINDOP
	IF (NSG(K).LE.0) GO TO 44	OUTPUT
	KSG = NSG(K)	OUTPUT
	IF (K.GT.8) GO TO 440	WINDOP
	J3 = 3	OUTPUT
	IF (K.EQ.7) J3 = 2	OUTPUT
	DO 43 J1=1,KSG,J3	OUTPUT
	J2 = MINO(J1+J3-1,KSG)	OUTPUT
	NT =NT + 1	OUTPUT
C	SETUP LOGICAL UNIT CONTROL (FOR PRINTER) FOR PERKIN & ELMER	PECONV
	CALL CARCON(NT,1)	PECONV
	DO 38 J=J1,J2	OUTPUT
	L = IABS(MSG(J,K))	OUTPUT
	GO TO (22,24,26,29,31,34,35,601),K	WINDOP
C		OUTPUT
C	1. POINT TOTAL ACCELERATION IN KREF(1) REFERENCE	CHGIII
C		OUTPUT
	22 IF(LPMI(L).EQ.0) GO TO 521	CHGIII

	CALL MAT31(DPMI(1,1,L),XSG(1,J,K),T7)	CHGIII
	GO TO 523	CHGIII
521	DO 522 JL=1,3	CHGIII
522	T7(JL) = XSG(JL,J,K)	CHGIII
523	CALL CROSS (WMEG(1,L),T7,T1)	CHGIII
	CALL CROSS (WMEG(1,L),T1,T2)	OUTPUT
	CALL CROSS (WMEGD(1,L),T7,T3)	CHGIII
	CALL MAT31(D(1,1,L),GRAVTY,T7)	ACCEL
	CALL MAT31(D(1,1,L),SEGLA(1,L),T4)	OUTPUT
	DO 23 I=1,3	OUTPUT
	IF(MSG(J,K).LT.0) T4(I)=T4(I)+T7(I)	ACCEL
	ACC(I,J) = (T4(I)+T3(I)+T2(I))/G	OUTPUT
23	T1(I) = ACC(I,J)	OUTPUT
	IF(MSG(J,K).GE.0) GO TO 405	ACCEL
	KRF=L	ACCEL
	IF(LPMI(KRF).NE.0) CALL DOT31(DPMI(1,1,KRF),T1,ACC(1,J))	ACCEL
	IF(KREF(J,K).EQ.1) GOTO 33	ACCEL
	DO 600 II=1,3	ACCEL
600	ACC(II,J)=ACC(II,J)-GRAVTY(II)/G	ACCEL
	GOTO 33	ACCEL
C		OUTPUT
C	2. POINT REL. VELOCITY IN KREF(2) REFERENCE	CHGIII
C		OUTPUT
24	IF(KREF(J,2).EQ.0) KRF = NVEH	TTHKREF
	IF(KREF(J,2).NE.0) KRF = KREF(J,2)	TTHKREF
	IF(LPMI(L).EQ.0) GO TO 524	CHGIII
	CALL MAT31(DPMI(1,1,L),XSG(1,J,K),T7)	CHGIII
	GO TO 525	CHGIII
524	DO 526 JL=1,3	CHGIII
526	T7(JL) = XSG(JL,J,K)	CHGIII
525	CALL CROSS (WMEG(1,L),T7,T1)	CHGIII
	CALL DOT31(D(1,1,L),T1,T2)	OUTPUT
	DO 25 I=1,3	OUTPUT
25	T3(I) = T2(I) + SEGLV(I,L) - SEGLV(I,KRF)	CHGIII
	GO TO 28	OUTPUT
C		OUTPUT
C	3. POINT REL. LINEAR DISPLACEMENT IN KREF(3) REFERENCE	CHGIII
C		OUTPUT
26	IF(KREF(J,3).EQ.0) KRF = NVEH	TTHKREF
	IF(KREF(J,3).NE.0) KRF = KREF(J,3)	TTHKREF
	IF (LPMI(L).EQ.0) GO TO 76	CHGIII
	CALL DOT33 (DPMI(1,1,L),D(1,1,L),T4)	OUTPUT
	CALL DOT31 (T4,XSG(1,J,K),T1)	OUTPUT
	GO TO 77	OUTPUT
76	CALL DOT31 (D(1,1,L),XSG(1,J,K),T1)	OUTPUT
77	DO 27 I=1,3	OUTPUT
27	T3(I) = T1(I) + SEGLP(I,L) - SEGLP(I,KRF)	CHGIII
28	IF (LPMI(KRF).EQ.0) GO TO 403	CHGIII
	CALL DOT33(DPMI(1,1,KRF),D(1,1,KRF),T5)	CHGIII
	CALL MAT31(T5,T3,ACC(1,J))	CHGIII



	GO TO 33	OUTPUT
	403 CALL MAT31(D(1,1,KRF),T3,ACC(1,J))	CHGIII
	33 ACC(4,J) = DSQRT(ACC(1,J)**2+ACC(2,J)**2+ACC(3,J)**2)	CHGIII
	GO TO 38	CHGIII
C		OUTPUT
C	4. SEGMENT ANGULAR ACCELERATION IN KREF(4) REFERENCE	CHGIII
C		OUTPUT
	29 DO 30 I=1,3	OUTPUT
	ACC(I,J) = WMEGD(I,L)/(2.0*PI)	OUTPUT
	30 T1(I) = ACC(I,J)	OUTPUT
	405 CONTINUE	CHGIII
	IF(KREF(J,K).EQ.0) GO TO 401	TTHKREF
	KRF = KREF(J,K)	TTHKREF
	IF(LPMI(KRF).EQ.0) GO TO 402	CHGIII
	CALL DOT33(DPMI(1,1,KRF),D(1,1,KRF),T5)	CHGIII
	CALL DOTT33(T5,D(1,1,L),T6)	CHGIII
	CALL MAT31(T6,T1,ACC(1,J))	CHGIII
	GO TO 33	CHGIII
	402 CALL DOTT33(D(1,1,KRF),D(1,1,L),T6)	CHGIII
	CALL MAT31(T6,T1,ACC(1,J))	CHGIII
	GO TO 33	CHGIII
	401 KRF = L	CHGIII
	IF(LPMI(KRF).NE.0) CALL DOT31(DPMI(1,1,KRF),T1,ACC(1,J))	CHGIII
	GO TO 33	OUTPUT
C		OUTPUT
C	5. SEGMENT REL. ANGULAR VELOCITY IN KREF(5) REFERENCE	CHGIII
C		OUTPUT
	31 IF(KREF(J,5).EQ.0) KRF = NVEH	TTHKREF
	IF(KREF(J,5).NE.0) KRF = KREF(J,5)	TTHKREF
	CALL DOT31(D(1,1,L),WMEG(1,L),T1)	CHGIII
	CALL MAT31(D(1,1,KRF),T1,T2)	CHGIII
	DO 32 I=1,3	OUTPUT
	IF(KRF.NE.L) T2(I)=T2(I)-WMEG(I,KRF)	PLTINC
	32 T3(I) = T2(I)/(2.0*PI)	PLTINC
	IF(LPMI(KRF).EQ.0) GO TO 449	CHGIII
	CALL DOT31(DPMI(1,1,KRF),T3,ACC(1,J))	CHGIII
	GO TO 483	CHGIII
	449 CONTINUE	CHGIII
	DO 457 KJL=1,3	CHGIII
	457 ACC(KJL,J) = T3(KJL)	CHGIII
	483 ACC(4,J) = DSQRT(ACC(1,J)**2+ACC(2,J)**2+ACC(3,J)**2)	CHGIII
	GO TO 38	OUTPUT
C		OUTPUT
C	6. SEGMENT REL. ANGULAR DISPLACEMENT IN KREF(6) REFERENCE	CHGIII
C		OUTPUT
	34 IF(KREF(J,6).EQ.0) KRF = NVEH	TTHKREF
	IF(KREF(J,6).NE.0) KRF = KREF(J,6)	TTHKREF
	IF(LPMI(KRF).EQ.0.AND.LPMI(L).EQ.0) GO TO 36	CHGIII
	IF(LPMI(L).EQ.0) GO TO 435	CHGIII
	CALL DOT33(DPMI(1,1,L),D(1,1,L),T4)	CHGIII

435	IF (LPMI(KRF).EQ.0) GO TO 436	CHGIII
	CALL DOT33(DPMI(1,1,KRF),D(1,1,KRF),T5)	CHGIII
436	IF (LPMI(L).NE.0) GO TO 438	CHGIII
	CALL DOT33(D(1,1,L),T5,T1)	CHGIII
	GO TO 37	CHGIII
438	IF (LPMI(KRF).NE.0) GO TO 439	CHGIII
	CALL DOT33(T4,D(1,1,KRF),T1)	CHGIII
	GO TO 37	CHGIII
439	CALL DOT33(T4,T5,T1)	CHGIII
	GO TO 37	CHGIII
36	CALL DOT33(D(1,1,L),D(1,1,KRF),T1)	CHGIII
37	CALL YPRDEG(T1,ACC(1,J))	OUTPUT
	TRACE = 0.5*(T1(1)+T2(2)+T3(3)-1.0)	OUTPUT
	IF (TRACE.GT. 1.0) TRACE = 1.0	OUTPUT
	IF (TRACE.LT.-1.0) TRACE = -1.0	OUTPUT
	ACC(4,J) = DACOS(TRACE)/RADIAN	OUTPUT
	GO TO 38	OUTPUT
C		OUTPUT
C	7. JOINT PARAMETERS	OUTPUT
C		OUTPUT
35	ACC(1,J) = PRJNT(1,L)	OUTPUT
	ACC(2,J) = PRJNT(2,L)/RADIAN	OUTPUT
	ACC(3,J) = PRJNT(3,L)/RADIAN	OUTPUT
	ACC(4,J) = PRJNT(4,L)/RADIAN	OUTPUT
	ACC(5,J) = DSQRT(PRJNT(5,L))	OUTPUT
	ACC(6,J) = DSQRT(PRJNT(6,L))	OUTPUT
	ACC(7,J) = DSQRT(PRJNT(7,L))	OUTPUT
	GOTO 38	WINDOP
C		WINDOP
C	8. SEGMENT WIND FORCE IN KREF(8) REFERENCE	WINDOP
C		WINDOP
601	IF(KREF(J,8).EQ.0) KRF = NGRND	TTHKREF
	IF(KREF(J,8).NE.0) KRF = KREF(J,8)	TTHKREF
	CALL MAT31(D(1,1,KRF),WF(1,L),T2)	WINDOP
	IF(LPMI(KRF).EQ.0) GO TO 602	WINDOP
	CALL DOT31(DPMI(1,1,KRF),T2,ACC(1,J))	WINDOP
	GO TO 604	WINDOP
602	CONTINUE	WINDOP
	DO 603 KJL=1,3	WINDOP
603	ACC(KJL,J) = T2(KJL)	WINDOP
604	ACC(4,J) = DSQRT(ACC(1,J)**2+ACC(2,J)**2+ACC(3,J)**2)	WINDOP
38	CONTINUE	OUTPUT
	IF (.NOT.LTAPE8) GO TO 40	OUTPUT
	KK = 0	OUTPUT
	I2 = 4	OUTPUT
	IF (K.EQ.7) I2 = 7	OUTPUT
	DO 39 J=J1,J2	OUTPUT
	DO 39 I=1,I2	OUTPUT
	KK = KK+1	OUTPUT
39	TDATA(KK,NT-20) = ACC(I,J)	OUTPUT

	40 IF (.NOT.LTHIST) GO TO 43	OUTPUT
	IF (K.LE.6) WRITE (NT,41) USEC,((ACC(I,J),I=1,4),J=J1,J2)	OUTPUT
	IF (K.EQ.8) WRITE (NT,41) USEC,((ACC(I,J),I=1,4),J=J1,J2)	WINDOP
	41 FORMAT(F9.3,3(3X,4F9.3) )	OUTPUT
	IF (K.EQ.7) WRITE (NT,42) USEC,((ACC(I,J),I=1,7),J=J1,J2)	OUTPUT
	42 FORMAT(F9.3,2(F5.0,3F9.3,2X,3F9.3))	OUTPUT
	43 CONTINUE	OUTPUT
	GO TO 44	CHGIII
C		ATBIII
C	9. JOINT FORCES & TORQUES IN KREF(9) GEOMETRIC COORDINATE SYSTEM	WINDOP
C		CHGIII
	440 DO 860 L=1,KSG	PLTINC
	KRF = NVEH	PLTINC
	IF(KREF(L,9).NE.0) KRF = KREF(L,9)	PLTINC
	LL=MSG(L,K)	CHGIII
	IF (LPMI(KRF).EQ.0) GO TO 851	CHGIII
	CALL DOT33 (DPMI(1,1,KRF),D(1,1,KRF),T5)	CHGIII
	CALL MAT31 (T5,F(1,LL),T1)	CHGIII
	CALL MAT31 (T5,TQ(1,LL),T2)	CHGIII
	DO 852 JJ=1,3	CHGIII
	T1(JJ) = T1(JJ)/100.0	CHGIII
	852 T2(JJ) = -T2(JJ)/100.0	OUT385
	GO TO 859	CHGIII
	851 CONTINUE	CHGIII
	CALL MAT31 (D(1,1,KRF),F(1,LL),T1)	CHGIII
	CALL MAT31 (D(1,1,KRF),TQ(1,LL),T2)	CHGIII
	DO 853 JJ=1,3	CHGIII
	T1(JJ) = T1(JJ)/100.0	CHGIII
	853 T2(JJ) = -T2(JJ)/100.0	OUT385
	859 NT = NT + 1	CHGIII
C	P & E CARRIAGE CONTROL	PECONV
	CALL CARCON(NT,1)	PECONV
	IF (.NOT.LTAPE8) GO TO 855	CHGIII
	DO 854 JL=1,3	CHGIII
	TDATA (JL ,NT-20) = T1(JL)	CHGIII
	854 TDATA (JL+3,NT-20) = T2(JL)	CHGIII
	855 CONTINUE	CHGIII
	IF (LTHIST) WRITE (NT,857) USEC,T1,T2	CHGIII
	857 FORMAT(F9.3,3X,3F9.3,3X,3(2X,D10.3))	CHGIII
	860 CONTINUE	CHGIII
	44 CONTINUE	CHGIII
C		ATBIII
C	10. PRINT BODY PROPERTIES	WINDOP
C		ATBIII
	IF (MCG.EQ.0) GO TO 131	ATBIII
	DO 130 NCG=1,MCG	ATBIII
	M = MCGIN(1,NCG)	ATBIII
	N = MCGIN(2,NCG)	ATBIII
	DO 120 J=1,9	ATBIII
	120 T4(J) = 0.0	ATBIII

SUMW = 0.0	ATBIII
T7(1)=0.0	KINETIC
T7(2)=0.0	KINETIC
DO 123 I=1,N	ATBIII
K = MCGIN(I+2, NCG)	ATBIII
WG = W(K)/G	ATBIII
V=(SEGLV(1,K)-SEGLV(1,M))**2	KINETIC
* +(SEGLV(2,K)-SEGLV(2,M))**2	KINETIC
* +(SEGLV(3,K)-SEGLV(3,M))**2	KINETIC
T7(1)=T7(1)+0.5*WG*V	KINETIC
SUMW = SUMW + WG	ATBIII
DO 121 J=1,3	ATBIII
T7(2)=T7(2)+0.5*PHI(J,K)*(WMEG(J,K)-WMEG(J,M))**2	KINETIC
121 T1(J) = PHI(J,K)*WMEG(J,K)	ATBIII
CALL DOT31 (D(1,1,K),T1,T2)	ATBIII
CALL CROSS (SEGLP(1,K),SEGLV(1,K),T1)	ATBIII
DO 122 J=1,3	ATBIII
T4(J ) = T4(J ) + WG*SEGLP(J,K)	ATBIII
T4(J+3) = T4(J+3) + WG*SEGLV(J,K)	ATBIII
122 T4(J+6) = T4(J+6) + WG*T1(J) + T2(J)	ATBIII
123 CONTINUE	ATBIII
T7(3)=T7(1)+T7(2)	KINETIC
DO 124 J=1,3	ATBIII
124 T4(J) = T4(J)/SUMW - SEGLP(J,M)	ATBIII
C	ATBIII
C TRANSFORM FROM PRINCIPAL AXES TO LOCAL AXES	TGMOD1
C	ATBIII
IF (LPMI(M).EQ.0) GO TO 330	ATBIII
CALL DOT33(DPMI(1,1,M),D(1,1,M),T5)	ATBIII
CALL MAT31(T5,T4(1),T1)	ATBIII
CALL MAT31(T5,T4(4),T2)	ATBIII
CALL MAT31(T5,T4(7),T3)	ATBIII
GO TO 333	ATBIII
330 CONTINUE	ATBIII
CALL MAT31 (D(1,1,M),T4(1),T1)	ATBIII
CALL MAT31 (D(1,1,M),T4(4),T2)	ATBIII
CALL MAT31 (D(1,1,M),T4(7),T3)	ATBIII
333 CONTINUE	ATBIII
NT = NT + 1	ATBIII
IF (.NOT.LTAPE8) GO TO 126	ATBIII
DO 125 J=1,3	ATBIII
TDATA (J ,NT-20) = T1(J)	ATBIII
TDATA (J+3,NT-20) = T2(J)	ATBIII
TDATA(J+9,NT-20) = T7(J)	KINETIC
125 TDATA(J+6,NT-20) = T3(J)	ATBIII
126 IF (LTHIST) WRITE (NT,127) USEC,T1,T2,T3,T7	KINETIC
127 FORMAT (F9.3,3F8.3,9(1X,D10.3))	KINETIC
130 CONTINUE	ATBIII
131 CONTINUE	ATBIII
C	OUTPUT

C	PRINT PLANE FORCES	OUTPUT
C	MPSF = 0	OUTPUT
	IF (NPL.EQ.0) GO TO 49	OUTPUT
	IF (NPRT(18).EQ.1.OR.NPRT(18).EQ.7) GO TO 49	VARTTH
	IF (NPRT(18).EQ.10.OR.NPRT(18).EQ.11) GO TO 49	VARTTH
	IF (NPRT(18).GE.14) GO TO 49	VARTTH
	DO 45 J=1,NPL	OUTPUT
45	MPSF = MPSF + MNPL(J)	OUTPUT
	IF (MPSF.EQ.0) GO TO 49	OUTPUT
	DO 47 J1=1,MPSF,2	OUTPUT
	J2 = MINO(J1+1,MPSF)	OUTPUT
	NT = NT+1	OUTPUT
C	SETUP LOGICAL UNIT CONTROL (PRINTER CONTROL) FOR P & E	PECONV
	CALL CARCON(NT,1)	PECONV
	IF (.NOT.LTAPES) GO TO 47	OUTPUT
	KK = 0	OUTPUT
	DO 46 J=J1,J2	OUTPUT
	DO 46 I=1,7	OUTPUT
	KK = KK+1	OUTPUT
46	TDATA(KK,NT-20) = PSF(I,J)	OUTPUT
47	IF (LTHIST) WRITE (NT,48) USEC,((PSF(I,J),I=1,7),J=J1,J2)	OUTPUT
48	FORMAT(F9.3,2(F9.3,3F9.2,3F8.3) )	OUTPUT
C		OUTPUT
C	PRINT BELT FORCES	OUTPUT
C		OUTPUT
49	MBSF = 0	OUTPUT
	IF (NBLT.EQ.0) GO TO 67	OUTPUT
	IF (NPRT(18).EQ.2.OR.NPRT(18).GE.13) GO TO 67	VARTTH
	IF (NPRT(18).GE.7.AND.NPRT(18).LE.9) GO TO 67	VARTTH
	DO 50 J=1,NBLT	OUTPUT
50	MBSF = MBSF + MNBLT(J)	OUTPUT
	IF (MBSF.EQ.0) GO TO 67	OUTPUT
	DO 52 J1=1,MBSF,2	OUTPUT
	J2 = MINO(J1+1,MBSF)	OUTPUT
	NT = NT+1	OUTPUT
C	LOGICAL UNIT (PRINTER CONTROL) FOR P & E	PECONV
	CALL CARCON(NT,1)	PECONV
	IF (.NOT.LTAPES) GO TO 52	OUTPUT
	KK = 0	OUTPUT
	DO 51 J=J1,J2	OUTPUT
	DO 51 I=1,4	OUTPUT
	KK = KK+1	OUTPUT
51	TDATA(KK,NT-20) = BSF(I,J)	OUTPUT
52	IF (LTHIST) WRITE (NT,53) USEC,((BSF(I,J),I=1,4),J=J1,J2)	OUTPUT
53	FORMAT(F9.3,4(F15.6,F12.2,3X) )	OUTPUT
C		OUTPUT
C	PRINT HARNESS-BELT ENDPOINT FORCES (STORED IN BSF ARRAY).	OUTPUT
C		OUTPUT
67	IF (NHRNSS.LE.0) GO TO 71	OUTPUT

IF (NPRT(18).EQ.3.OR.NPRT(18).EQ.11) GO TO 71	VARTTH
IF (NPRT(18).EQ.9.OR.NPRT(18).EQ.8) GO TO 71	VARTTH
IF (NPRT(18).EQ.13.OR.NPRT(18).EQ.14) GO TO 71	VARTTH
IF (NPRT(18).GE.16) GO TO 71	VARTTH
MBSF1 = MBSF + 1	OUTPUT
DO 68 I=1,NHRNSS	OUTPUT
68 MBSF = MBSF + NBLTPH(I)	OUTPUT
DO 70 J1=MBSF1,MBSF,2	OUTPUT
J2 = MINO(J1+1,MBSF)	OUTPUT
NT = NT+1	OUTPUT
C LOGICAL UNIT (PRINTER CONTROL) FOR P & E	PECONV
CALL CARCON(NT,1)	PECONV
IF (.NOT.LTAPE8) GO TO 70	OUTPUT
KK = 0	OUTPUT
DO 69 J=J1,J2	OUTPUT
DO 69 I=1,4	OUTPUT
KK = KK+1	OUTPUT
69 TDATA(KK,NT-20) = BSF(I,J)	OUTPUT
70 IF (LTHIST) WRITE (NT,53) USEC,((BSF(I,J),I=1,4),J=J1,J2)	OUTPUT
C PRINT SPRING DAMPER FORCES (STORED IN BSF ARRAY).	OUTPUT
C	OUTPUT
71 IF (NSD.LE.0) GO TO 54	OUTPUT
IF (NPRT(18).EQ.4.OR.NPRT(18).EQ.9) GO TO 54	VARTTH
IF (NPRT(18).GE.12) GO TO 54	VARTTH
MBSF1 = MBSF + 1	OUTPUT
MBSF = MBSF + (NSD+1)/2	OUTPUT
DO 73 J1=MBSF1,MBSF,2	OUTPUT
J2 = MINO(J1+1,MBSF)	OUTPUT
NT = NT+1	OUTPUT
C LOGICAL UNIT (PRINTER CONTROL) FOR P & E	PECONV
CALL CARCON(NT,1)	PECONV
IF (.NOT.LTAPE8) GO TO 73	OUTPUT
KK = 0	OUTPUT
DO 72 J=J1,J2	OUTPUT
DO 72 I=1,4	OUTPUT
KK = KK+1	OUTPUT
72 TDATA(KK,NT-20) = BSF(I,J)	OUTPUT
73 IF (LTHIST) WRITE (NT,74) USEC,((BSF(I,J),I=1,4),J=J1,J2)	OUTPUT
74 FORMAT (F9.3,4(F14.3,F12.2,4X))	OUTPUT
C PRINT SEGMENT CONTACT FORCES	OUTPUT
C	OUTPUT
54 MSSF = 0	OUTPUT
IF (NPRT(18).EQ.5.OR.NPRT(18).EQ.13) GO TO 161	VARTTH
IF (NPRT(18).EQ.10.OR.NPRT(18).EQ.11) GO TO 161	VARTTH
IF (NPRT(18).GE.15) GO TO 161	VARTTH
DO 55 J=1,NSEG	OUTPUT
55 MSSF = MSSF + MNSEG(J)	OUTPUT
IF (MSSF.EQ.0) GO TO 59	OUTPUT

	DO 57 J=1,MSSF	OUTPUT
	NT = NT+1	OUTPUT
C	LOGICAL UNIT (PRINTER CONTROL) FOR P & E	PECONV
	CALL CARCON(NT,1)	PECONV
	IF (.NOT.LTAPE8) GO TO 57	OUTPUT
	DO 56 I=1,10	OUTPUT
	56 TDATA(I,NT-20) = SSF(I,J)	OUTPUT
	57 IF (LTHIST) WRITE (NT,58) USEC, (SSF(I,J),I=1,10)	OUTPUT
	58 FORMAT(2F9.3,3F9.2,3F8.3,2X,3F8.3)	OUTPUT
	161 CONTINUE	VARTTH
C		OUTPUT
C	PRINT AIRBAG FORCES	OUTPUT
C		OUTPUT
	59 IF (NBAG.EQ.0) GO TO 65	OUTPUT
	IF (NPRT(18).EQ.6.OR.NPRT(18).EQ.9) GO TO 65	VARTTH
	IF (NPRT(18).GE.12) GO TO 65	VARTTH
	K1 = 1	OUTPUT
	DO 64 J=1,NBAG	OUTPUT
	IF (MNBAG(J).EQ.0) GO TO 64	OUTPUT
	KBAG = MNBAG(J)+NPANEL(J)+5	OUTPUT
	DO 63 J1=1,KBAG,4	OUTPUT
	J2 = MINO(J1+3,KBAG)	OUTPUT
	K2 = K1+J2-J1	OUTPUT
	NT = NT+1	OUTPUT
C	LOGICAL UNIT (PRINTER CONTROL) FOR P & E	PECONV
	CALL CARCON(NT,1)	PECONV
	IF (.NOT.LTAPE8) GO TO 61	OUTPUT
	KK = 0	OUTPUT
	DO 60 K=K1,K2	OUTPUT
	DO 60 I=1,3	OUTPUT
	KK = KK+1	OUTPUT
	60 TDATA(KK,NT-20) = BAGSF(I,K)	OUTPUT
	61 IF (.NOT.LTHIST) GO TO 63	OUTPUT
	IF (J1.EQ.1) WRITE (NT,75) USEC, ((BAGSF(I,K),I=1,3),K=K1,K2)	OUTPUT
	IF (J1.NE.1) WRITE (NT,62) USEC, ((BAGSF(I,K),I=1,3),K=K1,K2)	OUTPUT
	75 FORMAT (F9.3,3X,3F9.2,2(3X,3F9.3),3X,3F9.2)	OUTPUT
	62 FORMAT(F9.3,4(3X,3F9.2))	OUTPUT
	63 K1 = K2+1	OUTPUT
	64 CONTINUE	OUTPUT
	65 NT = NT-20	OUTPUT
	IF(NT.GT.NTMAX) STOP 56	CHGIII
	IF (LTAPE8) WRITE (8) NT,USEC, ((TDATA(I,J),I=1,14),J=1,NT)	OUTPUT
	PREVT = TIME	OUTPUT
	CALL ELTIME(2,8)	OUTPUT
	66 RETURN	OUTPUT
	END	OUTPUT

C	SUBROUTINE PANEL (DRR,ZR,JB)	PANEL
C		REV III.2 08/08/84REVIII
C	COMPUTES AIRBAG PARAMETERS DURING INFLATION OF BAG.	PANEL
C		PANEL
C	GIVEN: DRR - DC MATRIX RELATIVE TO VEHICLE	PANEL
C	ZR - CG LOCATION IN VEHICLE REFERENCE	PANEL
C		PANEL
C	COMPUTE: SEGLP,SEGLV,SEGLA,D,WMEG & WMEGD FOR SEGMENT JB.	PANEL
C		PANEL
	IMPLICIT REAL*8 (A-H,O-Z)	PANEL
	DIMENSION DRR(3,3),ZR(3),T1(3),T2(3)	PANEL
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	PANEL
	* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),	PANEL
	* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)	PANEL
	CALL MAT33 (DRR,D(1,1,NVEH),D(1,1,JB))	PANEL
	CALL MAT31 (DRR,WMEG(1,NVEH),WMEG(1,JB))	PANEL
	CALL DOT31 (D(1,1,NVEH),ZR,SEGLP(1,JB))	PANEL
	CALL CROSS (WMEG(1,NVEH),ZR,T1)	PANEL
	CALL DOT31 (D(1,1,NVEH),T1,SEGLV(1,JB))	PANEL
	CALL CROSS (WMEG(1,NVEH),T1,T2)	PANEL
	CALL DOT31 (D(1,1,NVEH),T2,SEGLA(1,JB))	PANEL
	DO 10 I=1,3	PANEL
	SEGLP(I,JB) = SEGLP(I,JB) + SEGLP(I,NVEH)	PANEL
	SEGLV(I,JB) = SEGLV(I,JB) + SEGLV(I,NVEH)	PANEL
	SEGLA(I,JB) = SEGLA(I,JB) + SEGLA(I,NVEH)	PANEL
10	WMEGD(I,JB) = WMEGD(I,NVEH)	PANEL
	RETURN	PANEL
	END	PANEL





10	IF (KDINT.EQ.4) GO TO 48	PDAUX
	IF (KDINT.GT.0) GO TO 20	PDAUX
C		PDAUX
C	KDINT=0 IMPLIES INITIAL CALL FROM DINT. PDAUX TO SUPPLY INITIAL	PDAUX
C	VALUES TO STATE VARIABLES AND COMPUTE VALUE OF NEQ.	PDAUX
C		PDAUX
C		PDAUX
C	(A) SET Q TO IDENTITY QUATERNION	PDAUX
C		PDAUX
	N = 0	PDAUX
	DO 12 M=1,MBAG	PDAUX
	IF (NTST(M).LT.0) GO TO 12	PDAUX
	N = N+1	PDAUX
	REGT(N) = RGTTL(1)	PDAUX
	SEGT(N) = SEG(M)	PDAUX
	E1(N) = 1.0	PDAUX
	DO 11 I=1,3	PDAUX
	XTEST(I,N) = SGTEST(I,1,M)**2	PDAUX
11	VAR(I,N) = 0.0	PDAUX
12	CONTINUE	PDAUX
C		PDAUX
C	(B) SEGLP OF REFERENCE SEGMENTS	PDAUX
C		PDAUX
	DO 14 M=1,MBAG	PDAUX
	IF (LSEG(M)) GO TO 14	PDAUX
	N = N+1	PDAUX
	REGT(N) = RGTTL(2)	PDAUX
	SEGT(N) = SEG(M)	PDAUX
	DO 13 I=1,3	PDAUX
	XTEST(I,N) = SGTEST(I,2,M)**2	PDAUX
13	VAR(I,N) = SEGLP(I,M)	PDAUX
14	CONTINUE	PDAUX
C		PDAUX
C	(C) WMEG	PDAUX
C		PDAUX
	DO 16 M=1,MBAG	PDAUX
	IF (NTST(M).LT.0) GO TO 16	PDAUX
	N = N+1	PDAUX
	REGT(N) = RGTTL(3)	PDAUX
	SEGT(N) = SEG(M)	PDAUX
	DO 15 I=1,3	PDAUX
	XTEST(I,N) = SGTEST(I,3,M)**2	PDAUX
15	VAR(I,N) = WMEG(I,M)	PDAUX
16	CONTINUE	PDAUX
C		PDAUX
C	(D) SEGLV OF REFERENCE SEGMENTS	PDAUX
C		PDAUX
	DO 18 M=1,MBAG	PDAUX
	IF (LSEG(M)) GO TO 18	PDAUX
	N = N+1	PDAUX

	REGT(N) = RGTTL(4)	PDAUX
	SEGT(N) = SEG(M)	PDAUX
	DO 17 I=1,3	PDAUX
	XTEST(I,N) = SGTEST(I,4,M)**2	PDAUX
	17 VAR(I,N) = SEGLV(I,M)	PDAUX
	18 CONTINUE	PDAUX
	NEQ = 3*N	PDAUX
	GO TO 40	PDAUX
	20 IF (KDINT.NE.1) GO TO 30	PDAUX
C		PDAUX
C	KDINT = 1, 1ST STEP IN ADVANCING INTEGRATING INTERVAL,	PDAUX
C	SAVE DC MATRICES IF TIME HAS ADVANCED.	PDAUX
C		PDAUX
	N = 0	PDAUX
	DO 22 M=1,MBAG	PDAUX
	IF (NTST(M).LT.0) GO TO 22	PDAUX
	N = N+1	PDAUX
	DO 21 J=1,3	PDAUX
	DO 21 I=1,3	PDAUX
	21 SD(I,J,N) = D(I,J,M)	PDAUX
	22 CONTINUE	PDAUX
C		PDAUX
C	KDINT > 0,1 - FETCH SAVED DC MATRICES AND UPDATE BY CURRENT THETA.	PDAUX
C		PDAUX
C	(A) UPDATE D BY Q	PDAUX
C		PDAUX
	30 N = 0	PDAUX
	DO 32 M=1,MBAG	PDAUX
	IF (NTST(M).LT.0) GO TO 32	PDAUX
	N = N+1	PDAUX
	EDOTE = VAR(1,N)**2 + VAR(2,N)**2 + VAR(3,N)**2	PDAUX
	IF (EDOTE.GE.1.0) KDINT = -KDINT	PDAUX
	IF (KDINT.LE.0) GO TO 99	PDAUX
	E1(N) = DSQRT(1.0-EDOTE)	PDAUX
	CALL DSETQ(SD(1,1,N),VAR(1,N),EDOTE,E1(N),D(1,1,M))	PDAUX
	32 CONTINUE	PDAUX
C		PDAUX
C	KDINT > 0 - STORE STATE VARIABLES INTO PROGRAM ARRAYS.	PDAUX
C		PDAUX
C	(B) SEGLP OF REFERENCE SEGMENTS	PDAUX
C		PDAUX
	DO 35 M=1,MBAG	PDAUX
	IF (LSEG(M)) GO TO 35	PDAUX
	N = N+1	PDAUX
	DO 34 I=1,3	PDAUX
	34 SEGLP(I,M) = VAR(I,N)	PDAUX
	35 CONTINUE	PDAUX
C		PDAUX
C	(C) WMEG	PDAUX
C		PDAUX

	DO 31 M=1,MBAG	PDAUX
	IF (NTST(M).LT.0) GO TO 31	PDAUX
	N = N+1	PDAUX
	DO 36 I=1,3	PDAUX
	36 WMEG(I,M) = VAR(I,N)	PDAUX
	31 CONTINUE	PDAUX
C		PDAUX
C	(D) SEGLV OF REFERENCE SEGMENTS	PDAUX
C		PDAUX
	DO 38 M=1,MBAG	PDAUX
	IF (LSEG(M)) GO TO 38	PDAUX
	N = N+1	PDAUX
	DO 37 I=1,3	PDAUX
	37 SEGLV(I,M) = VAR(I,N)	PDAUX
	38 CONTINUE	PDAUX
C		PDAUX
C	CALL DAUX ROUTINE TO COMPUTE DERIVATIVES	PDAUX
C		PDAUX
	40 CALL DAUX(0)	PDAUX
C		PDAUX
C	STORE DERIVATIVES FOR INTEGRATING SUBROUTINE.	PDAUX
C		PDAUX
C	(A) DERIVATIVE OF Q	PDAUX
C		PDAUX
	N = 0	PDAUX
	DO 39 M=1,MBAG	PDAUX
	IF (NTST(M).LT.0) GO TO 39	PDAUX
	N = N+1	PDAUX
	CALL CROSS(VAR(I,N),WMEG(I,M),VXT)	PDAUX
	DO 41 I=1,3	PDAUX
	41 DER(I,N) = 0.5*(E1(N)*WMEG(I,M) + VXT(I) )	PDAUX
	39 CONTINUE	PDAUX
	NQUAT = N	PDAUX
C		PDAUX
C	(B) SEGLV OF REFERENCE SEGMENTS	PDAUX
C		PDAUX
	DO 43 M=1,MBAG	PDAUX
	IF (LSEG(M)) GO TO 43	PDAUX
	N = N+1	PDAUX
	DO 42 I=1,3	PDAUX
	42 DER(I,N) = SEGLV(I,M)	PDAUX
	43 CONTINUE	PDAUX
C		PDAUX
C	(C) WMEGD	PDAUX
C		PDAUX
	DO 47 M=1,MBAG	PDAUX
	IF (NTST(M).LT.0) GO TO 47	PDAUX
	N = N+1	PDAUX
	DO 44 I=1,3	PDAUX
	44 DER(I,N) = WMEGD(I,M)	PDAUX

C	47 CONTINUE	PDAUX
C		PDAUX
C	(D) SEGLA OF REFERENCE SEGMENTS	PDAUX
	DO 46 M=1,MBAG	PDAUX
	IF (LSEG(M)) GO TO 46	PDAUX
	N = N+1	PDAUX
	DO 45 I=1,3	PDAUX
	45 DER(I,N) = SEGLA(I,M)	PDAUX
	46 CONTINUE	PDAUX
	IF (KDINT.NE.4) GO TO 99	PDAUX
	48 N = 0	PDAUX
	DO 51 M=1,MBAG	PDAUX
	IF (NTST(M).LT.0) GO TO 51	PDAUX
	N = N+1	PDAUX
	E1(N) = 1.0	PDAUX
	DO 50 I=1,3	PDAUX
	DER(I,N) = 0.5*WMEG(I,M)	PDAUX
	50 VAR(I,N) = 0.0	PDAUX
	51 CONTINUE	PDAUX
	99 IF (KDINT.EQ.2) KDINT = NQUAT	PDAUX
	CALL ELTIME(2,6)	PDAUX
	RETURN	PDAUX
	END	PDAUX

	SUBROUTINE PLEDG(AREAL,BD,PL)		PLEDGD
C		REV IV 12/11/87	HYFIX
	IMPLICIT REAL*8(A-H,O-Z)		PLEDGD
	LOGICAL AREAL		PLEDGD
	DIMENSION BD(24),PL(24)		HYFIX
	DIMENSION HAREA(2,2,5),ZC(3,14),X(3),UV(3,2),IV(14)		HYFIX
C	SHARED WITH PLELP-PLSEGF		HYFIX
	COMMON/TEMPVS/DMNT(3,3),DHNT(3,3),DUM1(18),TM(3),R(3),RM(3),		HYFIX
X	DUM2(9),UP(3),VP(3),U(3),V(3),EU(3),EV(3),ET(3),		HYFIX
X	A(2),B(2),CC(2),DUM4(12),TH(3),XH(3),RMD(3),RND(3),		HYFIX
X	APT(2,2,2),AC(2,2),BC(2,2),AFP,E(2,2),DELT,AREA,		HYFIX
X	AB,BB,BT(2),XNC(3),UH(3),P,AMR,FM,T4(3),ALIM(2,2)		HYFIX
	EQUIVALENCE (UV(1,1),U(1))		HYFIX
	EQUIVALENCE (ALIM(1,1),BMIN), (ALIM(1,2),AMIN)		HYFIX
	EQUIVALENCE (ALIM(2,1),BMAX), (ALIM(2,2),AMAX)		HYFIX
	EQUIVALENCE (AC(1,1),BB1), (AC(1,2),AA1)		HYFIX
	EQUIVALENCE (AC(2,1),BB2), (AC(2,2),AA2)		HYFIX
	EQUIVALENCE (BC(1,1),AB1), (BC(1,2),BA1)		HYFIX
	EQUIVALENCE (BC(2,1),AB2), (BC(2,2),BA2)		HYFIX
C			HYFIX
	AREA = 0.0		PLEDGD
	AREAL = .FALSE.		PLEDGD
	CALCULATE CENTER OF ELLIPSE IN PLANE		PLEDGD
C	T4 IS VECTOR FROM CENTER OF ELLIPSOID TO CENTER OF ELLIPSE		PLEDGD
	DO 10 I = 1,3		PLEDGD
	T4(I) = FM*XH(I)		HYFIX
	10 XNC(I) = XNC(I) + T4(I)		PLEDGD
C	XNC P1 TO CENTER OF ELLIPSE		PLEDGD
C	PUT PLANE VECTORS IN ELLIPSE SYSTEM TH IS PLANE VECTOR		PLEDGD
	IF (BD(1).LT.0.0) CALL MAT33(BD(8),DMNT,DHNT)		HYPER
	IF (BD(1).LT.0.0) GO TO 20		HYPER
	DO 15 I = 1,3		HYPER
	DO 15 J = 1,3		HYPER
	15 DHNT(I,J) = DMNT(I,J)		HYPER
	20 CALL MAT31(DHNT,PL( 8),UP)		HYPER
	CALL MAT31(DHNT,PL(13),VP)		HYPER
	CALL MAT31(DHNT,PL(18), U)		HYPER
	CALL MAT31(DHNT,PL(21), V)		HYPER
C	U IS P2 - P1, V IS P3 - P1, PLANE VECTOR IS TM		PLEDGD
	CALCULATE CENTER FROM P1 IN U, V COORDINATES		PLEDGD
	B(1) = (UP(1)*XNC(1) + UP(2)*XNC(2) + UP(3)*XNC(3))/PL(12)		PLEDGD
	B(2) = (VP(1)*XNC(1) + VP(2)*XNC(2) + VP(3)*XNC(3))/PL(17)		PLEDGD
	AMIN = -B(1)		HYFIX
	AMAX = 1.0 - B(1)		HYFIX
	BMIN = -B(2)		HYFIX
	BMAX = 1.0 - B(2)		HYFIX
C	GET ELLIPSE EQUATION		PLEDGD
	DO 25 I = 1,2		HYPER
	DO 25 J = 1,2		HYPER
	25 E(I,J) = 0.0		HYPER



```

COMPUTE ALPHA'S AT BMIN AND BMAX; BETA'S AT AMIN AND AMAX IF NOT ON
C ELLIPSOID
  IF (BD(1).LT.-2.0) GO TO 80
  DO 76 L = 1,2
  K = 3 - L
  DO 75 J = 1,2
  DIS = 0.0
  AFP = BC(J,L)
  IF (ALIM(J,L).EQ.AC(J,L)) GO TO 74
  AFP = ALIM(J,L)/E(L,L)
  DISC = AMR/E(L,L) - DELT*AFP**2
  DIS = 0.0
  IF (DISC.GT.0.0) DIS = DSQRT(DISC)
  AFP = -AFP*E(1,2)
74  APT(1,J,L) = DMAX1 (AFP-DIS,ALIM(1,K))
  APT(2,J,L) = DMIN1 (AFP+DIS,ALIM(2,K))
75  CONTINUE
76  CONTINUE
  GO TO 95
80  DO 90 L = 1,2
  K = 3 - L
  DO 89 J = 1,2
  DIS = 0.0
  BT(1) = BC(J,L)
  BT(2) = BC(J,L)
  IF (ALIM(J,L).EQ.AC(J,L)) GO TO 88
  M = 2
  IF (ALIM(J,L).LT.0.0) M = 1
  CM = BC(M,L)/AC(M,L)
  CL = ALIM(J,L)*CM
  DO 82 I = 1,3
82  RM(I) = T4(I) + ALIM(J,L)*(UV(I,K) + CM*UV(I,L))
  DO 85 I = 1,2
  CALL HYVAL(BT(I),UV(1,L),RM,BD,I)
85  BT(I) = BT(I) + CL
88  APT(1,J,L) = DMAX1 (BT(1),ALIM(1,K))
  APT(2,J,L) = DMIN1 (BT(2),ALIM(2,K))
89  CONTINUE
90  CONTINUE
C  SET UP LEGAL BOUNDARIES
C  APT          L = 1                      L = 2
C      A-(BMIN)  A-(BMAX)      B-(AMIN)  B-(AMAX)
C      A+(BMIN)  A+(BMAX)      B+(AMIN)  B+(AMAX)
C  SET UP HAREA (LINE SEGMENTS) CLOCKWISE STARTING WITH AMIN
95  L = 0
  HAREA(1,1,L+1) = AMIN
  HAREA(2,1,L+1) = APT(2,1,2)
  HAREA(1,2,L+1) = AMIN
  HAREA(2,2,L+1) = APT(1,1,2)
  IF (APT(2,1,2).GE.APT(1,1,2)) L = L + 1

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HAREA(1,1,L+1) = APT(1,1,1)	HYFIX
HAREA(2,1,L+1) = BMIN	HYFIX
HAREA(1,2,L+1) = APT(2,1,1)	HYFIX
HAREA(2,2,L+1) = BMIN	HYFIX
IF (APT(2,1,1).GE.APT(1,1,1)) L = L + 1	HYFIX
HAREA(1,1,L+1) = AMAX	HYFIX
HAREA(2,1,L+1) = APT(1,2,2)	HYFIX
HAREA(1,2,L+1) = AMAX	HYFIX
HAREA(2,2,L+1) = APT(2,2,2)	HYFIX
IF (APT(2,2,2).GE.APT(1,2,2)) L = L + 1	HYFIX
HAREA(1,1,L+1) = APT(2,2,1)	HYFIX
HAREA(2,1,L+1) = BMAX	HYFIX
HAREA(1,2,L+1) = APT(1,2,1)	HYFIX
HAREA(2,2,L+1) = BMAX	HYFIX
IF (APT(2,2,1).GE.APT(1,2,1)) L = L + 1	HYFIX
IF (L.LE.1) GO TO 140	HYFIX
HAREA(1,1,L+1) = HAREA(1,1,1)	HYFIX
HAREA(2,1,L+1) = HAREA(2,1,1)	HYFIX
IF (BD(1).GE.-2) CALL PLREA(L,HAREA,AREA,AB,BB,E,DELT,AMR)	HYFIX
IF (BD(1).LT.-2) CALL HYREA(L,HAREA,AREA,AB,BB)	HYFIX
AREAL = AREA.GT.0.0	HYFIX
IF (.NOT.AREAL) GO TO 140	HYPER
C	HYPER
DO 120 I = 1,3	HYPER
RM(I) = AB*U(I) + BB*V(I) + T4(I)	HYPER
120 RMD(I) = RM(I)	HYPER
COMPUTE POINT ON ELLIPSOID BELOW CENTROID (CONTACT POINT?)	PLEDGE
CONVERT PLANE VECTOR, ET = E*TM	PLEDGE
C TRY TO USE OTHER LOGIC	HYFIX
IF(BD(1).LT.0.0)GO TO 130	HYPER
CALL MAT31(BD(7),TM,ET)	PLEDGE
A2 = TM(1)*ET(1) + TM(2)*ET(2) + TM(3)*ET(3)	PLEDGE
A1 = AB*(TM(1)*EU(1)+TM(2)*EU(2)+TM(3)*EU(3))	HYFIX
1+FM+ BB*(TM(1)*EV(1)+TM(2)*EV(2)+TM(3)*EV(3))	HYFIX
A1 = A1/A2	HYFIX
A0 = (AB**2*E(1,1) + 2.*AB*BB*E(1,2) + BB**2*E(2,2) - AMR)/A2	HYFIX
DISC = A1**2 - A0	PLEDGE
IF(DISC.LT.0.0)DISC = 0.0	PLEDGE
P = A1 + DSQRT(DISC)	PLEDGE
GO TO 140	HYPER
COMPUTE FOR HYPER	HYPER
130 CALL HYVAL(CA,TH,RM,BD,1)	HYFIX
P = -CA	HYFIX
CALL DOT31(BD(8),RMD,RM)	HYPER
140 RETURN	HYPER
END	PLEDGE

	SUBROUTINE PLELP(M,MM,N,NN,NT)		PLELP
		REV IV	02/07/87HYPER
C	IMPLICIT REAL*8(A-H,O-Z)		PLELP
	LOGICAL AREAL		EDGE
	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)		PLELP
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		PLELP
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		PLELP
	COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),		NCFORC
*	PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF		PLELP
	COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)		EDGE
	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),		PLELP
*	HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),		PLELP
*	RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),		PLELP
*	KQ1(12),KQ2(12),KQTYPE(12)		PLELP
	COMMON/RSAVE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30),		TGMOD7
*	NSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9)		TGMOD7
	COMMON/TEMPVS/DMNT(3,3),TEMP(3,3),B(3,3),XMN(3),RLN(3),XMM(3),		PLELP
*	TM(3),R(3),RM(3),DMNWN(3),RLM(3),RN(3),VMN(3),VR(3),		PLELP
*	WNM(3),WCM(3),WCN(3),VREL(3),FFM(3),FR(3),TQM(3),		PLELP
*	TQN(3),TQNT(3),T(3),H(3),TH(3),XH(3),RMD(3),RND(3),		EDGE
*	TD(3),TT4(3,4),TT5(3,4),XNC(3),UH(3),P,AMR,FM,CF,		EDGE
*	VRM,VRT,VRTS,VRTEST,TF,ELOSS,MCF,NCF		TGMOD7
	CALL ELTIME(1,21)		PLELP
	CALL DOT33(D(1,1,M),D(1,1,N),DMNT)		PLELP
	DO 10 I = 1,3		PLELP
10	XMN(I) = SEGLP(I,M) - SEGLP(I,N)		PLELP
	CALL MAT31(D(1,1,M),XMN,XMM)		PLELP
	CALL MAT31(DMNT,PL(1,NN),TM)		PLELP
	CALL MAT31(DMNT,PL(5,NN),TD)		EDGE
	BET = 0.0		EDGE
	J = 3		HYPER
	IF(BD(1,MM).LT.0.0) J = 4		HYPER
	DO 15 I=1,3		EDGE
	J = J + 1		HYPER
	XNC(I) = XMM(I) + BD(J,MM) - TD(I)		HYPER
15	BET = BET - TM(I)*XNC(I)		EDGE
C			EDGE
C	BET IS FROM CENTER OF FIGURE TO PLANE		EDGE
	IF(BD(1,MM).GT.0.0)GO TO 30		HYPER
C PUT	PLANE VECTOR INTO HYPER		HYPER
	CALL MAT31(BD(8,MM),TM,TH)		HYPER
	CALL MAT31(BD(8,MM),XNC,UH)		HYPER
	DO 20 I = 1,3		HYPER
	XNC(I) = UH(I)		HYPER
	UH(I) = DABS(TH(I))*BD(I+1,MM)/BD(I+19,MM)		HYPER
	R(I) = BD(I+19,MM)/(BD(I+19,MM) - 1.0)		HYPER
20	RND(I) = UH(I)**R(I)		HYPER
	ALP = HYPEN(BD(1,MM),R,RND)		HYPER
	DO 25 I = 1,3		HYPER
	POW = 1.0/(BD(I+19,MM) - 1.0)		HYPER

	XH(I) = -DSIGN(BD(I+1,MM)*(UH(I)*ALP)**POW,TH(I))	HYPER
25	RND(I) = XH(I)	HYPER
	BTE = TH(1)*XH(1) + TH(2)*XH(2) + TH(3)*XH(3)	HYPER
	FM = BET/BTE	HYPER
	AMR = 1.0 - DABS(FM)**(-BD(1,MM))	HYPER
	GO TO 35	HYPER
C	CODE FOR ELLIPSE	EDGE
	XH = E'T	EDGE
C		EDGE
30	CALL MAT31(BD(16,MM),TM,XH)	HYPER
	BTS = TM(1)*XH(1) + TM(2)*XH(2) + TM(3)*XH(3)	EDGE
	BTE = - DSQRT(BTS)	PLELP
	FM = BET/BTS	EDGE
	AMR = 1.0 -BET*FM	EDGE
C		EDGE
35	P = BET - BTE	HYPER
	PSF(1,NPSF) = P	PLELP
	MCF = NTAB(NT+1)	PLELP
	NCF = -MCF	PLELP
	IF(NCF.GT.0)CFQQ(NCF) = -999.	PLELP
	IF(P.LE.0.0) GO TO 85	HYPER
C		EDGE
C	CALL EDGE ROUTINE TO FIND IF ELLIPSOID INTERSECTS FINITE PLANE	EDGE
C	IF IT DOES; AREAL WILL BE TRUE, P WILL BE PENETRATION AT CENTROID	EDGE
C	AND RM WILL BE LOCATION OF CENTROID	EDGE
C	RM IS REFERENCED TO CENTER OF ELLIPSOID	EDGE
C	USE OLD FORMULA FOR ROLL-SLIDE?, I.E. ROLL-SLIDE SHOULDN'T	EDGE
C	CALL PLEDG	EDGE
C		EDGE
	LT = NTAB(NT)	EDGE
	IF(TAB(LT+22).LE.0.0)GO TO 40	HYPER
C		EDGE
	IF (AMR.LE.0.0) GO TO 85	HYPER
	IF (BD(1,MM).LT.0.0.AND.BD(23,MM).NE.0.0) STOP 22	HYPER
	CALL PLEDG(AREAL,BD(1,MM),PL(1,NN))	EDGE
	IF(.NOT.AREAL)GO TO 85	HYPER
	PSF(1,NPSF) = P	EDGE
C		EDGE
40	IF (TAB(LT+22).GT.-2.0.AND.AMR.LE.0.0) GO TO 85	HYPER
	RHO = 0.0	HYPER
	IF(MCF.GT.0)RHO = TAB(MCF+4)	PLELP
	BETE = 1.0 + RHO*P/BTE	HYPER
	IF(BD(1,MM).GT.0.0)BETE = BETE/BTE	HYPER
	IF(BD(1,MM).LT.0.0)CALL DOT31(BD(8,MM),RND,XH)	HYPER
	TRT = P*(1.0 - RHO)	EDGE
	J = 3	HYPER
	IF(BD(1,MM).LT.0.0)J = 4	HYPER
	DO 45 I = 1,3	HYPER
	J = J + 1	HYPER
	IF(TAB(LT+22).LE.0.0)RM(I) = BETE*XH(I)	EDGE
	IF(TAB(LT+22).GT.0.0)RM(I) = RM(I) - TRT*TM(I)	EDGE

	RLM(I) = RM(I) + BD(J,MM)		HYPER
45	RN(I) = RLM(I) + XMM(I)		HYPER
	CALL DOT31(DMNT,RN,RLN)		PLELP
	IF (TAB(LT+22).GT.0.0) GO TO 55		HYPER
	IF (TAB(LT+22).GT.-3.0.AND.TAB(LT+22).LT.0.0) GO TO 55		HYPER
C			EDGE
C	CHECK BOUNDARY USING OLD METHOD		EDGE
	DO 50 I = 8,13,5		HYPER
	IF(PL(I+4,NN).LE.0.0)GO TO 50		HYPER
	DIST = RLN(1)*PL(I,NN)		PLELP
	* + RLN(2)*PL(I+1,NN)		PLELP
	* + RLN(3)*PL(I+2,NN) - PL(I+3,NN)		PLELP
	IF((DIST.LE.0.0).OR.(DIST.GT.PL(I+4,NN))) GO TO 85		HYPER
50	CONTINUE		HYPER
C			EDGE
55	CALL PLSEGF(M,N,NT)		HYPER
C	DMNWN,VMN,VR,WNM,WCM,WCN,VREL,FFM,FR,TQM,TQN,TQNT,T		EDGE
C	FM,CF,VRM,VRT,VRTS,VRTEST,TF,ELOSS		EDGE
C			EDGE
C	STORE RESULTS		EDGE
	DO 60 I = 1,3		HYPER
60	PSF(I+4,NPSF) = RLN(I)		HYPER
	IF(LPMI(N).NE.0) CALL DOT31(DPMI(1,1,N),RLN,PSF(5,NPSF))		EDGE
	IF(MCF.LT.0)GO TO 65		HYPER
	PSF(2,NPSF) = FM		PLELP
	PSF(3,NPSF) = 0.0		PLELP
	TRT = TF**2 - FM**2		PLELP
	IF(TRT.GT.0.0) PSF(3,NPSF) = DSQRT(TRT)		PLELP
	PSF(4,NPSF) = TF		PLELP
	GO TO 85		HYPER
C			PLELP
C	ROLL-SLIDE	REVISED	8/18/85
65	DO 70 I = 1,3		PLELP
70	PSF(I+1,NPSF) = T(I)		HYPER
	IF(BD(1,MM).LT.0.0) STOP 28		HYPER
	CALL CROSS(TM,WNM,TH)		EDGE
	CALL MAT31(BD(16,MM),TH,UH)		EDGE
	TRT = (TM(1)*UH(1) + TM(2)*UH(2) + TM(3)*UH(3))/BTS		EDGE
	DO 75 I = 1,3		HYPER
75	RMD(I) = DABS(BETE)*(UH(I) - TRT*XH(I))		HYPER
	CALL CROSS(DMNWN,TM,TH)		EDGE
	CALL CROSS(WNM,RMD,XNC)		EDGE
	SQQ(NCF) = 0.0		PLELP
	DO 80 I = 1,3		HYPER
80	SQQ(NCF) = SQQ(NCF) + TM(I)*XNC(I) - 2.0*TH(I)*VR(I)		HYPER
	CALL DOT31(D(1,1,M),XNC,RQQ(1,NCF))		EDGE
85	CALL ELTIME(2,21)		HYPER
	RETURN		PLELP
	END		PLELP

	SUBROUTINE PLREA(L,H,AREA,AB,BB,E,D,R)	
C		HYFIX
	IMPLICIT REAL*8(A-H,O-Z)	REV IV 12/11/87HYFIX
	COMPUTES AREA AND CENTROID (TRUE AREA = AREA*!UxV!/6)	PLREA
C	!UxV! IS NEVER COMPUTED !UxV! = UxV.T = AREA OF PARALLELOGRAM	HYFIX
C	THIS ROUTINE WILL ONLY BE CALLED IF THERE IS AN INTERSECTION	PLREA
	DIMENSION H(2,2,5),E(2,2)	HYFIX
	AREA = 0.0	PLREA
	AB = 0.0	PLREA
	BB = 0.0	PLREA
	IF (L.LE.1) GO TO 15	HYFIX
	C = R/DSQRT(D)	HYFIX
	C12 = 2.0*R/D	HYFIX
	C11 = C12*E(1,1)	HYFIX
	C22 = C12*E(2,2)	HYFIX
	C12 = C12*E(1,2)	HYFIX
	DO 10 I = 1,L	HYFIX
	COMPUTE FOR STRAIGHT LINE SEGMENTS	HYFIX
	AR = H(1,1,I)*H(2,2,I) - H(1,2,I)*H(2,1,I)	HYFIX
	IF (AR.EQ.0.0) GO TO 5	HYFIX
	AB = AB + AR*(H(1,1,I) + H(1,2,I))	HYFIX
	BB = BB + AR*(H(2,1,I) + H(2,2,I))	HYFIX
	AREA = AREA + AR	HYFIX
	COMPUTE FOR ELLIPSE	HYFIX
	5 AR = H(1,2,I)*H(2,1,I+1) - H(1,1,I+1)*H(2,2,I)	HYFIX
	IF (AR.EQ.0.0) GO TO 10	HYFIX
	ARC = AR/C	HYFIX
	IF (DABS(ARC).GT.1.0) ARC = DSIGN(1.0D0,ARC)	HYFIX
	AR = C*DASIN(ARC)	HYFIX
	X21 = H(1,1,I+1) - H(1,2,I)	HYFIX
	Y21 = H(2,1,I+1) - H(2,2,I)	HYFIX
	AB = AB + C12*X21 + C22*Y21	HYFIX
	BB = BB - C11*X21 - C12*Y21	HYFIX
	AREA = AREA + AR	HYFIX
	10 CONTINUE	HYFIX
	IF (AREA.LE.0.0) GO TO 15	HYFIX
	AREA = 3.0*AREA	HYFIX
	AB = AB/AREA	PLREA
	BB = BB/AREA	PLREA
C	AREA = AREA/6.0	HYFIX
	15 RETURN	PLREA
	END	PLREA

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SUBROUTINE PLSEGF(M,N,NT)                                PLSEGF
C                                                         REV III.5 09/03/85TGMOD7
IMPLICIT REAL*8 (A-H,O-Z)                                PLSEGF
COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30), PLSEGF
*             SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30) PLSEGF
COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24), PLSEGF
*             HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12), PLSEGF
*             RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12), PLSEGF
*             KQ1(12),KQ2(12),KQTYPE(12) PLSEGF
COMMON/TEMPVI/ CREST,TTI(3),R1I(3),R2I(3),JSTOP(4,2,30) PLSEGF
COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)DIMENB
C THIS COMMON/TEMPVS/ IS SHARED BY PLELP, PLSEGF AND SEGSEG. PLSEGF
COMMON/TEMPVS/DMNT(3,3),TEMP(3,3),B(3,3),XMN(3),RLN(3),XMM(3), PLSEGF
*           TM(3),R(3),RM(3),DMNWN(3),RLM(3),RN(3),VMN(3),VR(3), PLSEGF
*           WMN(3),WCM(3),WCN(3),VREL(3),FFM(3),FR(3),TQM(3), PLSEGF
*           TQN(3),TQNT(3),T(3),H(3),T1(3),T2(3),RMD(3),RND(3), PLSEGF
*           TD(3),TT4(3,4),TT5(3,4),T3(3),T4(3),P,AMR,FM,CF, PLSEGF
*           VRM,VRT,VRTS,VRTEST,TF,ELOSS,MCF,NCF,T5(3),T6(3) TGMOD7
VRTEST = 2.0 PLSEGF
CALL MAT31(DMNT,WMEG(1,N),DMNWN) PLSEGF
DO 15 I=1,3 PLSEGF
  VMN(I) = SEGLV(I,M) - SEGLV(I,N) PLSEGF
15 WMN(I) = DMNWN(I) - WMEG(I,M) PLSEGF
CALL DOT31(D(1,1,M),TM,T) PLSEGF
CALL MAT31(D(1,1,M),VMN,VR) PLSEGF
CALL CROSS(WMEG(1,M),RLM,WCM) PLSEGF
CALL CROSS(DMNWN,RN,WCN) PLSEGF
VRM = 0.0 PLSEGF
DO 16 I=1,3 PLSEGF
  VR(I) = VR(I) + WCM(I) - WCN(I) PLSEGF
16 VRM = VRM + VR(I)*TM(I) PLSEGF
VRT = 0.0 PLSEGF
DO 17 I=1,3 PLSEGF
  VREL(I) = VR(I) - VRM*TM(I) PLSEGF
17 VRT = VRT + VREL(I)**2 PLSEGF
VRT = DSQRT(VRT) PLSEGF
CF = EVALFD (P,NTAB(NT+5),1) PLSEGF
LT = NTAB(NT) PLSEGF
TAB(LT) = P PLSEGF
FM = 1.0 PLSEGF
PDOT = -VRM PLSEGF
ELOSS = 0.0 PLSEGF
IF (MCF.GT.0) CALL FRCDFL(P,PDOT,NT,1,FM,ELOSS) PLSEGF
VRTS = VRT PLSEGF
IF (VRT.LT.VRTEST) VRT = VRTEST/(2.0-VRT/VRTEST) PLSEGF
FF = -DABS(FM)*CF/VRT PLSEGF
IF (NCF.GT.0.AND.KQTYPE(NCF).EQ.6) FF=0.0 PLSEGF
FS = (VRTS-VRT)/VRT PLSEGF
IF (NCF.GT.0.AND.KQTYPE(NCF).EQ.6) FS=0.0 PLSEGF
TF = 0.0 PLSEGF

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L = LT+18	PLSEGF
DO 18 I=1,3	PLSEGF
L = L+1	PLSEGF
FFM(I) = FM*TM(I) + FF*VREL(I) + FS*TAB(L)	PLSEGF
TF = TF + FFM(I)**2	PLSEGF
TTI(I) = T(I)	PLSEGF
R1I(I) = RLM(I)	PLSEGF
18 R2I(I) = RLN(I)	PLSEGF
TF = DSQRT(TF)	PLSEGF
MT = NTAB(NT+5)	PLSEGF
CREST = TAB(MT+3)	PLSEGF
CALL DOT31 (D(1,1,M),FFM,FR)	PLSEGF
IF (MCF.LE.0) GO TO 21	PLSEGF
CALL CROSS (RLM,FFM,TQM)	PLSEGF
CALL CROSS (RN,FFM,TQNT)	PLSEGF
CALL DOT31 (DMNT,TQNT,TQN)	PLSEGF
DO 19 I=1,3	PLSEGF
U1(I,M) = U1(I,M) + FR(I)	PLSEGF
U1(I,N) = U1(I,N) - FR(I)	PLSEGF
U2(I,M) = U2(I,M) + TQM(I)	PLSEGF
19 U2(I,N) = U2(I,N) - TQN(I)	PLSEGF
IF (NCF.LE.0) GO TO 23	PLSEGF
21 DO 22 I=1,3	PLSEGF
HQQ(I,NCF) = FR(I)/TF	PLSEGF
TQQ(I,NCF) = T(I)	PLSEGF
RK1(I,NCF) = RLM(I)	PLSEGF
22 RK2(I,NCF) = RLN(I)	PLSEGF
CFQQ(NCF) = CF	PLSEGF
MT = NTAB(NT+5)	PLSEGF
IF (KQTYPE(NCF).EQ.3) CFQQ(NCF) = TAB(MT+4)	PLSEGF
23 RETURN	PLSEGF
END	PLSEGF

	PLTTYZ
C           SUBROUTINE PLTTYZ(P,C)	REV III.5 05/30/85VEHICL
C           STORES PLOT CHARACTER (C) INTO PLOTYZ, PLOTXZ AND PLOTXY ARRAYS	PLTTYZ
C           IN VEHICLE REFERENCE FOR POINT (P) GIVEN IN INERTIAL REFERENCE.	PLTTYZ
C	PLTTYZ
IMPLICIT REAL*8 (A-H,O-Z)	PLTTYZ
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,	PLTTYZ
*          NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG	PAGE
COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),	PLTTYZ
*          SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)	PLTTYZ
COMMON/VPOSTN/ ZPLT(3),SPLT(3),AXV(3,6),VATAB(6,501,6),	VEHICL
*          VTO(6),VDT(6),TIMEV(6),OMEGV(6),NVTAB(6),INDXV(6)	PLTTYZ
COMMON/TEMPVS/ DUM(101),PLOTYZ(96,55),PLOTXZ(96,55),PLOTXY(96,55)	PLTTYZ
LOGICAL*1   C,PLOTYZ,PLOTXZ,PLOTXY	PLTTYZ
DIMENSION P(3),TMP(3),XYZ(3)	PLTTYZ
DATA NPLTZ/96/ , NPLTX/55/	PLTTYZ
C	PLTTYZ
C           CONVERT P FROM INERTIAL TO VEHICLE REFERENCE BY	PLTTYZ
C           XYZ = DVEH(P-XCOMP)	PLTTYZ
C	PLTTYZ
DO 10 I=1,3	PLTTYZ
10 TMP(I) = P(I) - SEGLP(I,NVEH)	PLTTYZ
CALL MAT31(D(1,1,NVEH),TMP,XYZ)	PLTTYZ
C	PLTTYZ
C           CONVERT XYZ INTO PLOT CORDINATES IX,IY,IZ AND	PLTTYZ
C           IF WITHIN PLOT LIMITS, STORE C IN PLOTYZ, PLOTXZ AND PLOTXY.	PLTTYZ
C	PLTTYZ
IX = SPLT(1)*XYZ(1) + ZPLT(1) + 0.5	PLTTYZ
IZ = SPLT(3)*XYZ(3) + ZPLT(3) + 0.5	PLTTYZ
IF (IZ.LT.1 .OR. IZ.GT.NPLTZ) GO TO 11	PLTTYZ
IY = SPLT(2)*XYZ(2) + ZPLT(2) + 0.5	PLTTYZ
IF (IY.GE.1 .AND. IY.LE.NPLTX) PLOTYZ(IZ,IY) = C	PLTTYZ
IF (IX.GE.1 .AND. IX.LE.NPLTX) PLOTXZ(IZ,IX) = C	PLTTYZ
11 IY = -SPLT(3)*XYZ(2) + ZPLT(2) + 0.5	PLTTYZ
IF (IY.LT.1 .OR. IY.GT.NPLTZ) GO TO 99	PLTTYZ
IF (IX.GE.1 .AND. IX.LE.NPLTX) PLOTXY(IY,IX) = C	PLTTYZ
99 RETURN	PLTTYZ
END	PLTTYZ





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C      AS THE VALUE ASSIGNED TO NW60 WHICH IS THE NUMBER OF WORDS THAT      POSTPR
C      IS NECESSARY TO CONTAIN 60 CONSECUTIVE CHARACTERS DEPENDING ON THEPOSTPR
C      COMPUTER SYSTEM THIS PROGRAM IS OPERATING ON. THE VALUE OF NW60      POSTPR
C      SHOULD BE 15 ON IBM 360 AND 370, 10 ON UNIVAC 1108, 6 ON CDC 6600.POSTPR
C      THE LAST TERM IN FORMAT 13 BELOW SHOULD BE 15A4(IBM), 10A6(UNIVAC)POSTPR
C      OR 6A10(CDC). ALSO, THE FIRST DIMENSION OF PLDATA IN SUBROUTINE      POSTPR
C      HEDING SHOULD BE 97(IBM), 77(UNIVAC) OR 61(CDC).                      REDIM2
C                                                                              POSTPR
C      COMMON/TEMPVS/ TDATA(14,65),HEDATA(470),                             POSTPR
*          XO(20),XN(20),XL(20),XS(20),XLAB(15,20),PLB1(15,20),POSTPR
*          YO(20),YN(20),YL(20),YS(20),YLAB(15,20),PLB2(15,20),POSTPR
*          NYP(20),MK(2,20),MY(2,10,20),NX(20),NY(20),                     POSTPR
*          NXLAB(20),NYLAB(20),NPLB1(20),NPLB2(20),                         POSTPR
*          USEC(45),Z(1000,25),ZTTH(14,45,65)                             MISDOT
      LOGICAL LTABH,LPLOT                                                  POSTPR
      DATA LPP/45/, NZD1/1000/, NZD2/25/                                PLTINC
      DATA NW60/15/                                                    POSTPR
      LTABH = .FALSE.                                                  POSTPR
      LPLOT = .FALSE.                                                  POSTPR
      NPRT4 = IABS(NPRT(4))                                             POSTPR
      LPLOT = NPRT4.EQ.1 .OR. NPRT4.EQ.3                                POSTPR
      LTABH = NPRT4.EQ.2 .OR. NPRT4.EQ.3                                POSTPR
      IF(NPRT(26).EQ.4) LTABH = .FALSE.                                TGMOD1
      IF(NPRT(26).GE.5) GO TO 99                                        TGMOD1
C                                                                              POSTPR
C      READ INPUT CARD H.11 TO CONTROL COMPUTATION OF HIC, HSI & CSI.      WINDOP
C                                                                              POSTPR
      READ (5,11) JDTPTS                                               POSTPR
      WRITE(6,700) NPG                                                 PAGE
      NPG=NPG+1                                                         PAGE
700 FORMAT(1H1,122X,'PAGE',I5/,2X,                                     PAGE
*          'POSTPROCESSOR CONTROL PARAMETERS',/)                       PAGE
      WRITE(6,701)                                                     CHGIII
701 FORMAT(13X,'HIC & HSI POINT',7X,'CSI POINT')                     CHGIII
      WRITE(6,702) JDTPTS(1),JDTPTS(2)                                CHGIII
702 FORMAT(5X,'H.11',10X,I2,17X,I2,/)                                WINDOP
      NDPT = 0                                                         POSTPR
      IHIC = 0                                                         TGMOD1
      I26 = 0                                                         TGMOD1
      ITST1 = 0                                                        TGMOD1
      ITST2 = 0                                                        TGMOD1
      IF(NPRT(26).LT.0) I26 = IABS(NPRT(26))                          TGMOD1
      IF(JDTPTS(1).GT.0.OR.JDTPTS(2).GT.0) IHIC = 1                  TGMOD1
      IF(NPRT(30).EQ.0.AND.NPRT(26).EQ.3) ITST1 = 1                 TGMOD1
      IF(NPRT(30).LT.I26) ITST2 = 1                                   TGMOD1
      IF(IHIC.EQ.1.AND.ITST1.EQ.1) WRITE(6,751)                       TGMOD1
      IF(IHIC.EQ.1.AND.ITST2.EQ.1) WRITE(6,752) NPRT(30),I26        TGMOD1
751 FORMAT(3X,'WARNING! LOGIC OF INPUT INDICATES USER ANTICIPATES HICTGMOD1
* , HSI AND CSI TO BE COMPUTED BASED ON DATA FOR EVERY SUCCESSFUL', TGMOD1
*/ ,10X,'INTEGRATION STEP, YET DATA WAS STORED (WRITTEN TO TAPE8) EVTGMOD1

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*ERY DT.')
752 FORMAT(3X,'WARNING! LOGIC OF INPUT INDICATES USER ANTICIPATES HICTGMOD1
*, HSI AND CSI TO BE COMPUTED BASED ON DATA FOR EVERY ',I2,/,10X,' TGMOD1
*INTEGER MULTIPLE OF DT, YET DATA WAS STORED (WRITTEN TO TAPES) EVETGMOD1
*RY ',I2,' INTEGER MULTIPLE OF DT.') TGMOD1
IF(JDTPTS(1).GT.0.AND.NPRT(26).EQ.2.AND.NPRT(30).LT.1) STOP 91 TGMOD1
IF(JDTPTS(2).GT.0.AND.NPRT(26).EQ.2.AND.NPRT(30).LT.1) STOP 92 TGMOD1
IF (JDTPTS(1).NE.0) NDPT = NDPT + 1 POSTPR
IF (JDTPTS(2).NE.0) NDPT = NDPT + 1 POSTPR
IF (.NOT.LPLOT .AND. .NOT.LTABH .AND. NDPT.EQ.0) GO TO 99 POSTPR
CALL ELTIME (1,36) POSTPR
IF (.NOT.LPLOT) GO TO 20 POSTPR
C POSTPR
C READ INDICES OF VARIABLES TO BE PLOTTED AND POSTPR
C ARGUMENTS TO SUBROUTINE SLPLOT ON CARDS I. POSTPR
C INPUT CARD I.1 POSTPR
C POSTPR
READ (5,11) NPLT , (NYP(K),K=1,NPLT) POSTPR
11 FORMAT (18I4) POSTPR
IF (NPLT.GT.0.AND.ITST1.EQ.1) WRITE(6,753) TGMOD1
IF(NPLT.GT.0.AND.ITST2.EQ.1) WRITE(6,754) NPRT(30),I26 TGMOD1
753 FORMAT(3X,'WARNING! LOGIC OF INPUT INDICATES USER ANTICIPATES PLOTGMOD1
*TS TO BE COMPUTED BASED ON DATA FOR EVERY SUCCESSFUL INTEGRATION STGMOD1
*TEP',/,10X,'YET DATA WAS STORED (WRITTEN TO TAPES) EVERY DT.') TGMOD1
754 FORMAT(3X,'WARNING! LOGIC OF INPUT INDICATES USER ANTICIPATES PLOTGMOD1
*TS TO BE COMPUTED BASED ON DATA FOR EVERY ',I2,/,10X,'INTEGER MULTITGMOD1
*PLE OF DT, YET DATA WAS STORED (WRITTEN TO TAPES) EVERY ',I2, TGMOD1
* ' INTEGER MULTIPLE OF DT.') TGMOD1
IF (NPLT.LE.0) LPLOT = .FALSE. POSTPR
IF (.NOT.LPLOT) GO TO 20 POSTPR
DO 15 K=1,NPLT POSTPR
NYPLT = NYP(K) POSTPR
C POSTPR
C INPUT CARD I.2.K POSTPR
C POSTPR
READ (5,11) MX(1,K), MX(2,K), (MY(1,J,K), MY(2,J,K), J=1,NYPLT) POSTPR
C POSTPR
C INPUT CARD I.3.K POSTPR
C POSTPR
READ (5,12) NX(K), XO(K), XN(K), XL(K), XS(K) POSTPR
12 FORMAT (I4 , 4X , 4F8.0 ) POSTPR
C POSTPR
C INPUT CARD I.4.K POSTPR
C POSTPR
READ (5,12) NY(K), YO(K), YN(K), YL(K), YS(K) POSTPR
C POSTPR
C INPUT CARD I.5.K POSTPR
C POSTPR
READ (5,13) NXLAB(K), (XLAB(I,K),I=1,NW60) POSTPR

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13  FORMAT (I4 , 4X , 15A4)                                POSTPR
C                                                                    POSTPR
C  NOTE - ABOVE FORMAT ASSUMES 4 ALPHANUMERIC CHARACTERS FOR SINGLE POSTPR
C  PRECISION WORDS ON IBM 360 AND 370 COMPUTERS. THE 15A4 TERM IN THEPOSTPR
C  FORMAT WILL HAVE TO BE CHANGED ON NON-IBM COMPUTERS TO PRODUCE A POSTPR
C  CONTINUOUS STRING OF 60 CHARACTERS IN CORE MEMORY.        POSTPR
C                                                                    POSTPR
C  INPUT CARD I.6.K                                          POSTPR
C                                                                    POSTPR
C  READ (5,13) NYLAB(K) , (YLAB(I,K) ,I=1,NW60)            POSTPR
C                                                                    POSTPR
C  INPUT CARD I.7.K                                          POSTPR
C                                                                    POSTPR
C  READ (5,13) NPLB1(K) , (PLB1(I,K) ,I=1,NW60)            POSTPR
C                                                                    POSTPR
C  INPUT CARD I.8.K                                          POSTPR
C                                                                    POSTPR
15  READ (5,13) NPLB2(K) , (PLB2(I,K) ,I=1,NW60)            POSTPR
C                                                                    CHGIII
C  WRITE OUT PLOTTING CONTROL DATA                          CHGIII
C                                                                    CHGIII
C  WRITE(6,703)                                              CHGIII
703  FORMAT(4X,'PLOTTING CONTROLS',/)                        CHGIII
C  WRITE(6,704)                                              CHGIII
704  FORMAT(12X,'NO. PLOTS',11X,'NO. OF Y VARIABLES PER PLOT') CHGIII
C  WRITE(6,705) NPLT, (NYP(JK) ,JK=1,NPLT)                  CHGIII
705  FORMAT(5X,'I.1',7X,I2,7X,20(I2,2X))                    CHGIII
C  WRITE(6,706)                                              CHGIII
706  FORMAT(12X,'MX1 MX2 MY1A MY2A MY1B MY2B MY1C MY2C MY1D MY2D MY1E MCHGIII
      *Y2E MY1F MY2F MY1G MY2G MY1H MY2H MY1I MY2I MY1J MY2J') CHGIII
C  DO 730 IJ=1,NPLT                                          CHGIII
C  WRITE(6,707) IJ,MX(1,IJ) ,MX(2,IJ) ,                    CHGIII
      * (MY(1,L,IJ) ,MY(2,L,IJ) ,L=1,NYP(IJ))                CHGIII
707  FORMAT(5X,'I.2.',I2,2X,I2,2X,I2,2X,20(I2,3X))          CHGIII
730  CONTINUE                                                CHGIII
C  WRITE(6,708)                                              CHGIII
708  FORMAT(14X,'NX',8X,'XO',9X,'XN',8X,'XL',9X,'XS')      CHGIII
C  DO 731 IJ=1,NPLT                                          CHGIII
C  WRITE(6,709) IJ,NX(IJ) ,XO(IJ) ,XN(IJ) ,XL(IJ) ,XS(IJ)  CHGIII
709  FORMAT(5X,'I.3.',I2,2X,I3,4X,4(F8.3,2X))                CHGIII
731  CONTINUE                                                CHGIII
C  WRITE(6,710)                                              CHGIII
710  FORMAT(14X,'NY',8X,'YO',9X,'YN',8X,'YL',9X,'YS')      CHGIII
C  DO 732 IJ=1,NPLT                                          CHGIII
C  WRITE(6,711) IJ,NY(IJ) ,YO(IJ) ,YN(IJ) ,YL(IJ) ,YS(IJ)  CHGIII
711  FORMAT(5X,'I.4.',I2,2X,I3,4X,4(F8.3,2X))                CHGIII
732  CONTINUE                                                CHGIII
C  WRITE(6,712)                                              CHGIII
712  FORMAT(12X,'NXLAB',15X,'XLAB')                          CHGIII
C  DO 733 IJ=1,NPLT                                          CHGIII

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	WRITE(6,713) IJ,NYLAB(IJ),(XLAB(L,IJ),L=1,NW60)	CHGIII
713	FORMAT(5X,'I.5.',I2,2X,I3,5X,15A4)	CHGIII
733	CONTINUE	CHGIII
	WRITE(6,714)	CHGIII
714	FORMAT(12X,'NYLAB',15X,'YLAB')	CHGIII
	DO 734 IJ=1,NPLT	CHGIII
	WRITE(6,715) IJ,NYLAB(IJ),(YLAB(L,IJ),L=1,NW60)	CHGIII
715	FORMAT(5X,'I.6.',I2,2X,I3,5X,15A4)	CHGIII
734	CONTINUE	CHGIII
	WRITE(6,716)	CHGIII
716	FORMAT(12X,'NPLB1',15X,'PLB1')	CHGIII
	DO 735 IJ=1,NPLT	CHGIII
	WRITE(6,717) IJ,NPLB1(IJ),(PLB1(L,IJ),L=1,NW60)	CHGIII
717	FORMAT(5X,'I.7.',I2,2X,I3,5X,15A4)	CHGIII
735	CONTINUE	CHGIII
	WRITE(6,718)	CHGIII
718	FORMAT(12X,'NPLB2',15X,'PLB2')	CHGIII
	DO 736 IJ=1,NPLT	CHGIII
	WRITE(6,719) IJ,NPLB2(IJ),(PLB2(L,IJ),L=1,NW60)	CHGIII
719	FORMAT(5X,'I.8.',I2,2X,I3,5X,15A4)	CHGIII
736	CONTINUE	CHGIII
C		POSTPR
C	READ TIME HISTORY DATA FROM TAPE 8.	POSTPR
C		POSTPR
20	NPTS = 0	POSTPR
	LINES = 0	POSTPR
	IF (NPRT(4).GT.0) REWIND 8	POSTPR
	READ (8,END=29) NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,NPANEL,	POSTPR
*	MNPL,MNBLT,MNSEG,MNBAG,MPL,MBLT,MSEG,MBAG	POSTPR
	READ (8,END=29) DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,	POSTPR
*	SEG,JOINT,UNITL,UNITM,UNITT,NSG,MSG,XSG,MCG,	ATBIII
*	MCGIN,KREF,NHRNSS,NBLTPH,NPTSPB,NSD,MSDM,MSDN	CHGIII
21	READ (8,END=29) NT, UMSEC, ((TDATA(I,J),I=1,14),J=1,NT)	POSTPR
	R30 = 1.0D0	TGMOD1
	IF(NPRT(30).GT.0) R30 = NPRT(30)	TGMOD1
	VDT1 = R30*PRDT	TGMOD1
	TEST1 = DMOD(UMSEC,VDT1)	TGMOD1
	TEST1 = DMIN1(TEST1,DABS(VDT1 -TEST1))	TGMOD1
	IF(NPRT(30).GT.0.AND.TEST1.GT.EPS(4)) GO TO 25	TGMOD1
	NPTS = NPTS + 1	POSTPR
	IF (NPTS.GT.NZD1 .AND. (NDPT.NE.0 .OR. LPLOT) ) STOP 52	ATBIII
	ZZ(NPTS,1) = UMSEC	PLTINC
	Z(NPTS,1) = UMSEC	PLTINC
	IF (NDPT.EQ.0) GO TO 22	POSTPR
C		POSTPR
C	STORE DATA FOR HIC, HSI AND CSI.	POSTPR
C		POSTPR
	JJ = 1	POSTPR
	DO 61 I=1,2	POSTPR
	IF (JDTPPTS(I).EQ.0) GO TO 61	POSTPR

	JJ = JJ + 1	POSTPR
	JD = JDTPTS(I) - 1	POSTPR
	JE = 4*MOD(JD,3) + 4	POSTPR
	JP = JD/3 + 1	POSTPR
	ZZ(NPTS, JJ) = TDATA(JE, JP)	PLTINC
61	CONTINUE	POSTPR
22	IF (.NOT.LPLOT) GO TO 25	POSTPR
C		POSTPR
C	STORE DATA FOR PLOTTING	POSTPR
C		POSTPR
	JY = 1	PLTINC
	DO 24 K=1, NPLT	POSTPR
	JE = IABS(MX(2, K))	POSTPR
	IF (JE.EQ.0) GO TO 23	POSTPR
	JY = JY + 1	POSTPR
	IF (JY.GT.NZD2) STOP 53	ATBIII
	JP = MX(1, K) - 20	POSTPR
	Z(NPTS, JY) = TDATA(JE, JP)	POSTPR
23	NYPLT = NYP(K)	POSTPR
	DO 24 J=1, NYPLT	POSTPR
	JY = JY + 1	POSTPR
	JP = MY(1, J, K) - 20	POSTPR
	IF (JY.GT.NZD2) STOP 54	ATBIII
	JE = IABS(MY(2, J, K))	POSTPR
	Z(NPTS, JY) = UMSEC	POSTPR
24	IF (JE.NE.0) Z(NPTS, JY) = TDATA(JE, JP)	POSTPR
25	IF (.NOT.LTABH) GO TO 21	POSTPR
C		POSTPR
C	STORE DATA TO PRINT TABULAR TIME HISTORIES	POSTPR
C		POSTPR
	R26 = 1.0D0	TGMOD1
	IF(NPRT(26).LT.0) IFLG = 1	TGMOD1
	IF(IFLG.EQ.1) N26 = IABS(NPRT(26))	TGMOD1
	IF(IFLG.EQ.1) R26 = N26	TGMOD1
	VDT2 = R26*PRDT	TGMOD1
	TEST2 = DMOD(UMSEC, VDT2)	TGMOD1
	TEST2 = DMIN1(TEST2, DABS(VDT2 - TEST2))	TGMOD1
	IF (NPRT(26).LE.0 .AND. TEST2.GT.EPS(4)) GO TO 21	TGMOD1
	LINES = LINES + 1	POSTPR
	NTTH = MOD(LINES-1, LPP) + 1	POSTPR
	USEC(NTTH) = UMSEC	POSTPR
	DO 26 J=1, NT	POSTPR
	DO 26 I=1, 14	POSTPR
26	ZTTH(I, NTTH, J) = TDATA(I, J)	POSTPR
	IF (NTTH.EQ.LPP) CALL HEDING (LINES, LPP)	POSTPR
	GO TO 21	POSTPR
29	IF (.NOT.LTABH .OR. LINES.EQ.0) GO TO 30	POSTPR
	IF (NTTH.NE.LPP) CALL HEDING (LINES, LPP)	POSTPR
30	IF (NDPT.NE.0) CALL HICCSI(NPTS)	POSTPR
	IF (.NOT.LPLOT) GO TO 98	POSTPR

C		POSTPR
C	PLOT DATA VIA SUBROUTINE SLPLOT.	POSTPR
C		POSTPR
C	INCLUDE ANY PROGRAM STATEMENTS HERE REQUIRED BY YOUR COMPUTER AND	POSTPR
C	PLOTTING SYSTEMS FOR PLOT INITIALIZATION (E.G., CALL PLOTS).	POSTPR
C		POSTPR
	CALL PLOTS (0.0,0.0,10)	FIXSPT
	JZ = 1	PLTINC
	DO 50 K=1,NPLT	POSTPR
	JX = 1	POSTPR
	IF (MX(2,K).EQ.0) GO TO 42	POSTPR
	JZ = JZ + 1	POSTPR
	JX = JZ	POSTPR
	IF (Z(1,JX).EQ.0.0 .OR. MX(2,K).GE.0) GO TO 42	POSTPR
	DO 41 I=2,NPTS	POSTPR
41	Z(I,JX) = Z(I,JX) - Z(1,JX)	POSTPR
	Z(1,JX) = 0.0	POSTPR
42	NYPLT = NYP(K)	POSTPR
	DO 44 J=1,NYPLT	POSTPR
	JY = JZ + J	POSTPR
	IF (Z(1,JY).EQ.0.0 .OR. MY(2,J,K).GE.0) GO TO 44	POSTPR
	DO 43 I=2,NPTS	POSTPR
43	Z(I,JY) = Z(I,JY) - Z(1,JY)	POSTPR
	Z(1,JY) = 0.0	POSTPR
44	CONTINUE	POSTPR
	NXK = NX(K)	POSTPR
	NYK = NY(K)	POSTPR
	XOK = XO(K)	POSTPR
	YOK = YO(K)	POSTPR
	XNK = XN(K)	POSTPR
	YNK = YN(K)	POSTPR
	XLK = XL(K)	POSTPR
	YLK = YL(K)	POSTPR
	XSK = XS(K)	POSTPR
	YSK = YS(K)	POSTPR
	NXLABK = NXLAB(K)	POSTPR
	NYLABK = NYLAB(K)	POSTPR
	NPLB1K = NPLB1(K)	POSTPR
	NPLB2K = NPLB2(K)	POSTPR
	CALL SLPLOT(Z(1,JX ), NXK, XOK, XNK, XLK, XSK, XLAB(1,K), NXLABK,	POSTPR
*	Z(1,JZ+1), NYK, YOK, YNK, YLK, YSK, YLAB(1,K), NYLABK,	POSTPR
*	NPTS, NYPLT, NZD1, PLB1(1,K), NPLB1K, PLB2(1,K), NPLB2K)	POSTPR
C		POSTPR
C	INSERT ANY CODE REQUIRED BY YOUR SYSTEM TO ADVANCE PLOT PAGES HERE	POSTPR
C		POSTPR
	IF(NPRT(31).EQ.1) GO TO 444	CHGIII
	X00 = -0.5*(XSK-(XLK-0.5)) + XLK + 3.0	FXPLOT
	Y00 = -0.5*(YSK-(YLK-1.0))	FXPLOT
	CALL PLOT (X00,Y00,-3)	FXPLOT
50	JZ = JZ + NYPLT	POSTPR

444	CONTINUE	CHGIII
C		POSTPR
C	INSERT ANY PLOT TERMINATION CODE REQUIRED BY YOUR SYSTEM HERE.	POSTPR
C		POSTPR
	CALL PLOT(12.0,0.0,999)	PECONV
98	CALL ELTIME (2,36)	POSTPR
99	RETURN	POSTPR
	END	POSTPR



	SUBROUTINE PRINT(SUB)		PRINT
C		REV IV 07/24/86	SLIP
C	SUBROUTINE TO PRINT SEGMENT LINEAR AND ANGULAR		PRINT
C	POSITIONS, VELOCITIES AND ACCELERATIONS FOR A GIVEN TIME.		PRINT
C	ARGUMENTS		PRINT
C	SUB: CALLING SUBROUTINE NAME		PRINT
C	IMPLICIT REAL*8(A-H,O-Z)		PRINT
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		PRINT
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		PRINT
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		PRINT
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		PRINT
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		PRINT
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),		PRINT
*	F(3,30),TQ(3,30),WJ(30),A11(3,3,30)		SLIP
	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),		PRINT
*	HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),		PRINT
*	RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),		PRINT
*	KQ1(12),KQ2(12),KQTYPE(12)		PRINT
	COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5),		PRINT
*	BLTTTL(5,8),PLTTL(5,30),BAGTTL(5,6),SEG(30),		PRINT
*	JOINT(30),CGS(30),JS(30)		PRINT
	REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,SEG,JOINT		PRINT
	LOGICAL*1 CGS,JS		PRINT
	COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30),		JDRIFT
*	FE(3,30),TQE(3,30),CONST(5,30)		JDRIFT
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		PRINT
*	UNITL,UNITM,UNITT,GRAVTY(3),TWOPI		TWOPI
	COMMON/RSAVE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30),		ATBIII
*	NSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9)		TTHKREF
	COMMON/TEMPVS/ YPR(3),T1(3),T2(3),HH(3),T3(3,3),SKE(3),TKE(3),V		KINETIC
C			PRINT
	IPC = 1		PRINT
	TMSEC = 1000.0*TIME		PRINT
	WRITE (6,11) IPC,SUB,TMSEC,NPG		PAGE
	NPG=NPG+1		PAGE
	11 FORMAT (I1,6X,A6,' FUNCTIONS FOR TIME=',		CHGIII
*	F10.3,' MSEC',75X,'PAGE',I5/)		PAGE
	WRITE (6,760)		CHGIII
760	FORMAT(1X,23X,' (INERTIAL)',29X,' (LOCAL)',35X,' (LOCAL)')		CHGIII
	WRITE (6,12) UNITT,UNITT		PRINT
	12 FORMAT(19X,' ANGULAR ROTATION (DEG)',		PRINT
*	12X,' ANGULAR VELOCITY (RAD/','A4,')',		PRINT
*	12X,' ANGULAR ACCELERATION (RAD/','A4,'**2)'/		PRINT
*	' SEGMENT',9X,' YAW',7X,' PITCH',7X,' ROLL',		PRINT
*	11X,' X',11X,' Y',11X,' Z',15X,' X',13X,' Y',13X,' Z'/)		PRINT
	MBAG = NVEH + NBAG		PRINT

DO 20 I=1,MBAG	PRINT
IF (LPMI(I).EQ.0) GO TO 19	PRINT
CALL DOT33 (DPMI(1,1,I),D(1,1,I),T3)	PRINT
CALL DOT31(DPMI(1,1,I),WMEG(1,I),T1)	FIXPRT
CALL DOT31(DPMI(1,1,I),WMEGD(1,I),T2)	FIXPRT
CALL YPRDEG (T3,YPR)	PRINT
WRITE (6,31) I,SEG(I),YPR,(T1(K),K=1,3),(T2(K),K=1,3)	FIXPRT
GO TO 20	PRINT
19 CALL YPRDEG (D(1,1,I),YPR)	PRINT
WRITE (6,31) I,SEG(I),YPR,(WMEG(K,I),K=1,3),(WMEGD(K,I),K=1,3)	FIXPRT
20 CONTINUE	FIXPRT
WRITE (6,770)	CHGIII
770 FORMAT (//,1X,23X,'(INERTIAL)',27X,'(INERTIAL)',32X,'(INERTIAL)')	CHGIII
WRITE (6,22) UNITL,UNITL,UNITT	PRINT
22 FORMAT(18X,'LINEAR POSITION ('A4,')',	CHGIII
* 13X,'LINEAR VELOCITY ('A4,','A4,')',	PRINT
* 16X,'LINEAR ACCELERATIONS (G''S)'/	PRINT
* ' SEGMENT',10X,'X',10X,'Y',10X,'Z',	PRINT
* 13X,'X',11X,'Y',11X,'Z',15X,'X',13X,'Y',13X,'Z'//)	PRINT
DO 30 I=1,MBAG	PRINT
DO 29 K=1,3	PRINT
29 T1(K) = SEGLA(K,I)/G	PRINT
30 WRITE (6,31) I,SEG(I),(SEGLP(K,I),K=1,3),(SEGLV(K,I),K=1,3),T1	PRINT
31 FORMAT(13,1X,A4,3X,3F11.4,3X,3F12.5,3X,3F14.6)	PRINT
IF (NSEG.GT.6) WRITE (6,32) NPG	PAGE
IF (NSEG.GT.6) NPG=NPG+1	PAGE
32 FORMAT('1',122X,'PAGE',15)	PAGE
WRITE(6,775)	CHGIII
775 FORMAT (//,1X,23X,'(INERTIAL)',29X,'(LOCAL)')	CHGIII
WRITE (6,33) UNITL,UNITT,UNITT,UNITM,UNITL	KINETIC
33 FORMAT(18X,'U1 ARRAY ('A4,','A4,**2)',	KINETIC
* 14X,'U2 ARRAY (RAD/'A4,**2)',	KINETIC
* 25X,'KINETIC ENERGY'/	KINETIC
* 15X,'EXTERNAL LINEAR ACCELERATIONS',	KINETIC
* 8X,'EXTERNAL ANGULAR ACCELERATIONS',	KINETIC
* 22X,'('A4,'-',A4,')'/	KINETIC
* ' SEGMENT',10X,'X',10X,'Y',10X,'Z',13X,'X',11X,'Y',11X,'Z',	KINETIC
* 14X,'LINEAR',7X,'ANGULAR',7X,'TOTAL'//)	KINETIC
DO 80 J=1,3	KINETIC
80 TKE(J)=0.0	KINETIC
DO 34 I=1,NSEG	PRINT
V=SEGLV(1,I)**2+SEGLV(2,I)**2+SEGLV(3,I)**2	KINETIC
SKE(1)=0.5*W(I)*V/G	KINETIC
SKE(2)=0.0	KINETIC
DO 81 J=1,3	KINETIC
81 SKE(2)=SKE(2)+0.5*PHI(J,I)*WMEG(J,I)**2	KINETIC
SKE(3)=SKE(1)+SKE(2)	KINETIC
DO 82 J=1,3	KINETIC
82 TKE(J)=TKE(J)+SKE(J)	KINETIC
IF (LPMI(I).EQ.0) GO TO 73	FIXPRT

CALL DOT31 (DPMI(1,1,I),U2(1,I),T1)	FIXPRT
WRITE (6,61) I,SEG(I),(U1(K,I),K=1,3),	KINETIC
* (T1(K),K=1,3),(SKE(K),K=1,3)	KINETIC
GO TO 34	PRINT
73 CONTINUE	PRINT
WRITE (6,61) I,SEG(I),(U1(K,I),K=1,3),	KINETIC
* (U2(K,I),K=1,3),(SKE(K),K=1,3)	KINETIC
61 FORMAT(I3,1X,A4,3X,3(D11.4,1X),3X,3(D12.5,1X),3X,3(D12.5,1X))	KINETIC
34 CONTINUE	FIXPRT
WRITE(6,83) (TKE(K),K=1,3)	KINETIC
83 FORMAT(1X,98X,'TOTAL BODY KINETIC ENERGY'/	KINETIC
* 1X,90X,3(1X,D12.5))	KINETIC
IF (NJNT.LE.0) GO TO 39	PRINT
WRITE(6,776)	CHGIII
776 FORMAT(//,1X,27X,'(INERTIAL)',27X,'(INERTIAL)')	CHGIII
WRITE (6,35) UNITM,UNITL,UNITM,UNITT	PRINT
35 FORMAT(24X,'JOINT FORCES (' ,A4,')',	CHGIII
* 15X,'JOINT TORQUES (' ,2A4,')',	PRINT
* 9X,'RELATIVE ANGULAR'/	PRINT
* ' JOINT IPIN',9X,'X',10X,'Y',10X,'Z',13X,'X',11X,'Y',11X,'Z',	PRINT
* 7X,'VELOCITY (RAD/' ,A4,')'//)	PRINT
DO 36 J=1,NJNT	PRINT
IPINJ = IPIN(J)	PRINT
IF (IABS(IPIN(J)).EQ.4) IPINJ = IEULER(J)	PRINT
DO 137 II=1,3	MISC
137 T1(II)=-TQ(II,J)	MISC
WRITE (6,37) J,JOINT(J),IPINJ,(F(K,J),K=1,3),(T1(K),K=1,3),WJ(J)	MISC
37 FORMAT(I3,1X,A4,I4,7X,3(D10.3,1X),3X,3(D11.4,1X),3X,F13.3)	FIXPRT
36 CONTINUE	FIXPRT
39 IF (NQ.LE.0) GO TO 99	PRINT
WRITE (6,41)	CHGIII
WRITE (6,47)	CHGIII
47 FORMAT(1X,45X,'(INERTIAL)')	CHGIII
WRITE (6,49) UNITM,UNITL	CHGIII
41 FORMAT(///' OTHER CONSTRAINT FORCES',/)	CHGIII
49 FORMAT(1X,' NO. TYPE SEG1 SEG2',	CHGIII
* 15X,'CONSTRAINT FORCE (' ,A4,')',	PRINT
* 16X,'DISTANCE (' ,A4,')'//)	PRINT
ICH = 0	FIXPRT
DO 50 J=1,NQ	PRINT
IF (KQTYPE(J).NE.5) ICH = 0	FIXPRT
IF (KQTYPE(J).LT.0) GO TO 50	PRINT
IF (KQTYPE(J).EQ.5) ICH = ICH + 1	FIXPRT
IF (ICH.EQ.2) GO TO 50	FIXPRT
M = KQ1(J)	PRINT
N = KQ2(J)	PRINT
CALL DOT31(D(1,1,M),RK1(1,J),T1)	PRINT
CALL DOT31(D(1,1,N),RK2(1,J),T2)	PRINT
S1 = 0.0	PRINT
DO 42 I=1,3	PRINT

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      HH(I) = SEGLP(I,M)+T1(I) - SEGLP(I,N)-T2(I)          PRINT
42  S1 = S1 + HH(I)**2                                     PRINT
      SQS1 = DSQRT(S1)                                     PRINT
      WRITE (6,43) J,KQTYPE(J),SEG(M),SEG(N),(QQ(I,J),I=1,3),SQS1 PRINT
43  FORMAT(I4,I6,4X,A4,2X,A4,3X,3G15.7,6X,G15.7)          PRINT
50  CONTINUE                                             PRINT
99  IF (NPRT(28).LE.0) NPRT(28) = -1                     PRINT
      RETURN                                             PRINT
      END                                               PRINT
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SUBROUTINE PRIPLT                                PRIPLT
C                                               REV IV    07/24/86SLIP
C PRODUCES PRINTER PLOT OF Y-Z PLANE VIEW AND X-Z PLANE VIEW OF  PRIPLT
C BODY SEGMENT CGS, JOINTS AND SELECTED POINTS OF VEHICLE COMPONENTSPRIPLT
C                                               PRIPLT
C IMPLICIT REAL*8 (A-H,O-Z)                     PRIPLT
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,  PRIPLT
* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG      PAGE
COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),PRIPLT
* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)        PRIPLT
COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),SLIP
* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),      PRIPLT
* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)     PRIPLT
COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6),PRIPLT
* MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6),  PRIPLT
* NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30)                PRIPLT
COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)EDGE
COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5),PRIPLT
* BLTTTL(5,8),PLTTL(5,30),BAGTTL(5,6),SEG(30),        PRIPLT
* JOINT(30),CGS(30),JS(30)                             PRIPLT
COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100),PRIPLT
* XLONG(20),HTIME(2),IBAR(5,100),NL(2,100),           PRIPLT
* NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5)         PRIPLT
REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,SEG,JOINTPRIPLT
LOGICAL*1 CGS,JS                                       PRIPLT
COMMON/TEMPVS/ TEMP1(3),TEMP(3),TEMP2(3),CJOINT(3,30),BSN(2),PRIPLT
* PLOTYZ(96,55),PLOTXZ(96,55),PLOTXY(96,55)          PRIPLT
LOGICAL*1 PLOTYZ,PLOTXZ,PLOTXY,CHARS(7),BLANK,BCHAR   PRIPLT
LOGICAL NPRT5,NPRT6,NPRT7                             PRIPLT
DATA CHARS/' ','+', '@', '!', '_','-', '*', '/', BLANK/' '/PRIPLT
DATA ISTEP/0/ , NPLTI/96/ , NPLTJ/55/                PRIPLT
C                                               PRIPLT
C DETERMINE IF PLOTTING IS TO BE DONE FOR THIS TIME STEP.  PRIPLT
C                                               PRIPLT
C ISTEP = ISTEP+1                                       PRIPLT
C NPRT5 = (NPRT(5).EQ.1)                                PRIPLT
C IF (NPRT(5).GT.1) NPRT5 = (MOD(ISTEP,NPRT(5)).EQ.1)  PRIPLT
C NPRT6 = (NPRT(6).EQ.1)                                PRIPLT
C IF (NPRT(6).GT.1) NPRT6 = (MOD(ISTEP,NPRT(6)).EQ.1)  PRIPLT
C NPRT7 = (NPRT(7).EQ.1)                                PRIPLT
C IF (NPRT(7).GT.1) NPRT7 = (MOD(ISTEP,NPRT(7)).EQ.1)  PRIPLT
C IF (.NOT.NPRT5 .AND. .NOT.NPRT6 .AND. .NOT.NPRT7) GO TO 99PRIPLT
C CALL ELTIME(1, 4)                                     PRIPLT
C                                               PRIPLT
C BLANK OUT PLOT ARRAYS.                                PRIPLT
C                                               PRIPLT
C DO 10 J=1,NPLTJ                                       PRIPLT
C PLOTYZ(1,J) = CHARS(6)                                PRIPLT
C PLOTXZ(1,J) = CHARS(6)                                PRIPLT
C PLOTXY(1,J) = CHARS(6)                                PRIPLT

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	DO 10 I=2,NPLTI	PRIPLT
	PLOTYZ(I,J) = BLANK	PRIPLT
	PLOTXZ(I,J) = BLANK	PRIPLT
	10 PLOTXY(I,J) = BLANK	PRIPLT
C		PRIPLT
C	PLOT VEHICLE REFERENCE ORIGIN USING SYMBOL(*).	PRIPLT
C		PRIPLT
	CALL PLTXYZ (SEGLP(1,NVEH),CHARS(7))	PRIPLT
C		PRIPLT
C	PLOT CG OF BODY SEGMENTS USING SEGMENT SYMBOLS.	PRIPLT
C		PRIPLT
	DO 20 I=1,NSEG	PRIPLT
	20 CALL PLTXYZ(SEGLP(1,I),CGS(I))	PRIPLT
C		PRIPLT
C	COMPUTE AND PLOT JOINT LOCATIONS USING JOINT SYMBOLS.	PRIPLT
C		PRIPLT
	IF (NJNT.EQ.0) GO TO 40	PRIPLT
	DO 31 J=1,NJNT	PRIPLT
	I = IABS(JNT(J))	PRIPLT
	IF (I.LE.0) GO TO 31	PRIPLT
	CALL DOT31(D(1,1,I),SR(1,2*J-1),TEMP)	PRIPLT
	DO 30 L=1,3	PRIPLT
	30 CJOINT(L,J) = TEMP(L)+SEGLP(L,I)	PRIPLT
	CALL PLTXYZ (CJOINT(1,J),JS(J))	PRIPLT
	31 CONTINUE	PRIPLT
	IF (NPRT(13).NE.0) WRITE (6,32) ((CJOINT(I,J),I=1,3),J=1,NJNT)	PRIPLT
	32 FORMAT ('0 JOINT POSITIONS'/(1X,9F14.4))	PRIPLT
C		PRIPLT
C	PLOT BELT ANCHOR, FIXED AND TANGENT POINTS USING SYMBOL(.).	PRIPLT
C		PRIPLT
	40 IF (NBLT.LE.0) GO TO 50	PRIPLT
	DO 43 J=1,NBLT	PRIPLT
	IF (MNBLT(J).LE.0) GO TO 43	PRIPLT
	M1 = MBLT(1,1,J)	PRIPLT
	M2 = MBLT(2,1,J)	PRIPLT
	M3 = MBLT(3,1,J)	PRIPLT
	DO 41 I=1,3	PRIPLT
	41 TEMP1(I) = BELT(I+6,J) + BD(I+3,M3)	PRIPLT
	CALL DOT31 (D(1,1,M2),TEMP1,TEMP)	PRIPLT
	CALL DOT31 (D(1,1,M1),BELT(1,J),TEMP1)	PRIPLT
	CALL DOT31 (D(1,1,M1),BELT(4,J),TEMP2)	PRIPLT
	DO 42 I=1,3	PRIPLT
	TEMP1(I) = TEMP1(I) + SEGLP(I,M1)	PRIPLT
	TEMP2(I) = TEMP2(I) + SEGLP(I,M1)	PRIPLT
	42 TEMP (I) = TEMP (I) + SEGLP(I,M2)	PRIPLT
	CALL PLTXYZ (TEMP1 ,CHARS(1))	PRIPLT
	CALL PLTXYZ (TEMP2 ,CHARS(1))	PRIPLT
	CALL PLTXYZ (TEMP ,CHARS(1))	PRIPLT
	CALL PLTXYZ (TPTS(1,J),CHARS(1))	PRIPLT
	CALL PLTXYZ (TPTS(4,J),CHARS(1))	PRIPLT

	43 CONTINUE	PRIPLT
C		PRIPLT
C	PLOT POINTS IN PLAY ON HARNESS-BELT SYSTEMS USING SYMBOL(.).	PRIPLT
C		PRIPLT
	50 IF (NHRNSS.LE.0) GO TO 60	PRIPLT
	J1 = 1	PRIPLT
	K1 = 1	PRIPLT
	DO 54 NH=1,NHRNSS	PRIPLT
	IF (NBLTPH(NH).LE.0) GO TO 54	PRIPLT
	J2 = J1 + NBLTPH(NH) - 1	PRIPLT
	DO 53 NB=J1,J2	PRIPLT
	IF (NPTPLY(NB).LE.0) GO TO 53	PRIPLT
	K2 = K1 + NPTPLY(NB) - 1	PRIPLT
	DO 52 K=K1,K2	PRIPLT
	KI = NL(1,K)	PRIPLT
	KS = IABS(IBAR(1,KI))	PRIPLT
	IF (KS.GT.100) KS = MOD(KS,100)	PRIPLT
	CALL DOT31 (D(1,1,KS),BAR(4,KI),TEMP1)	PRIPLT
	CALL DOT31 (D(1,1,KS),BAR(7,KI),TEMP2)	PRIPLT
	DO 51 I=1,3	PRIPLT
	51 TEMP(I) = SEGLP(I,KS) + TEMP1(I) + TEMP2(I)	PRIPLT
	52 CALL PLTKYZ (TEMP,CHARS(1))	PRIPLT
	K1 = K2+1	PRIPLT
	53 CONTINUE	PRIPLT
	J1 = J2+1	PRIPLT
	54 CONTINUE	PRIPLT
C		PRIPLT
C	PLOT CENTER AND END OF AXES OF ELLIPSOIDAL TARGET USING SYMBOLS	PRIPLT
C	(@) FOR CENTER, (-) FOR ENDS OF Z AXIS, (!) FOR ENDS OF X,Y AXES.	PRIPLT
C		PRIPLT
	60 IF (NBAG.EQ.0) GO TO 80	PRIPLT
	BSN(1) = 1.0	PRIPLT
	BSN(2) = -1.0	PRIPLT
	DO 68 J=1,NBAG	PRIPLT
	IF (MNBAG(J).EQ.0) GO TO 68	PRIPLT
	JB = NVEH+J	PRIPLT
	BCHAR = CHARS(5)	PRIPLT
	L2 = 2	PRIPLT
	DO 67 I=1,4	PRIPLT
	IF (I.EQ.3) BCHAR = CHARS(4)	PRIPLT
	IF (I.EQ.4) BCHAR = CHARS(3)	PRIPLT
	IF (I.EQ.4) L2 = 1	PRIPLT
	DO 67 L=1,L2	PRIPLT
	DO 64 K=1,3	PRIPLT
	64 TEMP1(K) = BD(K+3,JB)	PRIPLT
	IF (I.EQ.4) GO TO 65	PRIPLT
	TEMP1(I) = TEMP1(I) + BSN(L)*BD(I,JB)	PRIPLT
	65 CALL DOT31 (D(1,1,JB),TEMP1,TEMP2)	PRIPLT
	DO 66 K=1,3	PRIPLT
	66 TEMP2(K) = TEMP2(K) + SEGLP(K,JB)	PRIPLT

	67 CALL PLTXYZ (TEMP2,BCHAR)	PRIPLT
	68 CONTINUE	PRIPLT
C		PRIPLT
C	PRINT Y-Z , X-Z AND X-Y PLANE VIEW PLOTS.	PRIPLT
C		PRIPLT
	80 TMSC = 1000.0*TIME	PRIPLT
	IF (.NOT.NPRT5) GO TO 83	PRIPLT
	WRITE (2,81) TMSC,SEGLP(2,NVEH),SEGLP(3,NVEH)	PRIPLT
	81 FORMAT ('1 T=',F10.3,' Y0=',F10.5,' Z0=',F10.5,' Y-Z PLANE')	PRIPLT
	WRITE (2,82) PLOTYZ	PRIPLT
	82 FORMAT (2X,96A1)	PRIPLT
	83 IF (.NOT.NPRT6) GO TO 85	PRIPLT
	WRITE (2,84) TMSC,SEGLP(1,NVEH),SEGLP(3,NVEH)	PRIPLT
	84 FORMAT ('1 T=',F10.3,' X0=',F10.5,' Z0=',F10.5,' X-Z PLANE')	PRIPLT
	WRITE (2,82) PLOTXZ	PRIPLT
	85 IF (.NOT.NPRT7) GO TO 87	PRIPLT
	WRITE (2,86) TMSC,SEGLP(1,NVEH),SEGLP(2,NVEH)	PRIPLT
	86 FORMAT ('1 T=',F10.3,' X0=',F10.5,' Y0=',F10.5,' X-Y PLANE')	PRIPLT
	WRITE (2,82) PLOTXY	PRIPLT
	87 CALL ELTIME(2, 4)	PRIPLT
	99 RETURN	PRIPLT
	END	PRIPLT



	SUBROUTINE QSET(F,Y,X,DER,N)		QSET
		REV III.3 10/01/84	REVIII
C	IMPLICIT REAL*8(A-H,O-Z)		QSET
	DIMENSION F(5,3,80),Y(5,3,80),X(3,80),DER(3,80)		QSET
	DIMENSION T1(3),T2(3),T3(3),T4(3)		QSET
	DO 20 I=1,N		QSET
	E1=DSQRT(1.DO -X(1,I)**2-X(2,I)**2-X(3,I)**2)		QSET
	E1D=-(X(1,I)*DER(1,I)+X(2,I)*DER(2,I)+X(3,I)*DER(3,I))/E1		QSET
	E2=DSQRT(1.DO-Y(1,1,I)**2-Y(1,2,I)**2-Y(1,3,I)**2)		QSET
	E2D=-(Y(1,1,I)*Y(2,1,I)+Y(1,2,I)*Y(2,2,I)+Y(1,3,I)*Y(2,3,I))/E2		QSET
	UHB=X(1,I)*F(3,1,I)+X(2,I)*F(3,2,I)+X(3,I)*F(3,3,I)		QSET
	UHC=X(1,I)*F(4,1,I)+X(2,I)*F(4,2,I)+X(3,I)*F(4,3,I)		QSET
	UDB=DER(1,I)*F(3,1,I)+DER(2,I)*F(3,2,I)+DER(3,I)*F(3,3,I)		QSET
	UDD=DER(1,I)**2+DER(2,I)**2+DER(3,I)**2		QSET
	EB=(E1D**2+UDD+UHB)/E1		QSET
	EC = (1.5*(UDB-E1D*EB)+UHC+F(5,1,I)*(E1D**2+UDD))/E1		QSET
	T1(1)=X(2,I)*F(3,3,I)-X(3,I)*F(3,2,I)		QSET
	T2(1)=X(2,I)*F(4,3,I)-X(3,I)*F(4,2,I)		QSET
	T3(1)=X(2,I)*Y(1,3,I)-X(3,I)*Y(1,2,I)		QSET
	T4(1)=X(2,I)*Y(2,3,I)-X(3,I)*Y(2,2,I)		QSET
	T1(2)=X(3,I)*F(3,1,I)-X(1,I)*F(3,3,I)		QSET
	T2(2)=X(3,I)*F(4,1,I)-X(1,I)*F(4,3,I)		QSET
	T3(2)=X(3,I)*Y(1,1,I)-X(1,I)*Y(1,3,I)		QSET
	T4(2)=X(3,I)*Y(2,1,I)-X(1,I)*Y(2,3,I)		QSET
	T1(3)=X(1,I)*F(3,2,I)-X(2,I)*F(3,1,I)		QSET
	T2(3)=X(1,I)*F(4,2,I)-X(2,I)*F(4,1,I)		QSET
	T3(3)=X(1,I)*Y(1,2,I)-X(2,I)*Y(1,1,I)		QSET
	T4(3)=X(1,I)*Y(2,2,I)-X(2,I)*Y(2,1,I)		QSET
	DO 20 J=1,3		QSET
	F(3,J,I)=E1*F(3,J,I)-T1(J)+EB*X(J,I)		JTF984
	F(4,J,I)=E1*F(4,J,I)-T2(J)+EC*X(J,I)		JTF984
	Y(3,J,I)=E1*Y(1,J,I)-T3(J)-E2*X(J,I)		JTF984
20	Y(4,J,I)=E1*Y(2,J,I)-T4(J)-E2D*X(J,I)		JTF984
	RETURN		QSET
	END		QSET

	SUBROUTINE QUAT(ANG,Q)	QUAT
		REV IV 07/23/86TWOPI
C	COMPUTES QUATERNIONS FROM YAW, PITCH, ROLL ANGLES IN DEGREES	QUAT
C	IMPLICIT REAL *8(A-H,O-Z)	QUAT
	DIMENSION ANG(3),Q(4),R(4),T(3)	QUAT
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),	QUAT
	* UNITL,UNITM,UNITT,GRAVTY(3),TWOPI	TWOPI
	A = 0.5*ANG(1)*RADIAN	QUAT
	Q(1) = DCOS(A)	QUAT
	Q(2) = 0.0	QUAT
	Q(3) = 0.0	QUAT
	Q(4) = DSIN(A)	QUAT
	K = 3	QUAT
	DO 10 I = 2,3	QUAT
	A = 0.5*ANG(I)*RADIAN	QUAT
	R(1) = DCOS(A)	QUAT
	R(2) = 0.0	QUAT
	R(3) = 0.0	QUAT
	R(4) = 0.0	QUAT
	R(K) = DSIN(A)	QUAT
	DOT = Q(2)*R(2) + Q(3)*R(3) + Q(4)*R(4)	QUAT
	CALL CROSS(Q(2),R(2),T)	QUAT
	DO 5 J = 2,4	QUAT
5	Q(J) = Q(1)*R(J) + R(1)*Q(J) + T(J-1)	QUAT
	Q(1) = Q(1)*R(1) - DOT	QUAT
10	K = 2	QUAT
	SUM = DSQRT(Q(1)**2 + Q(2)**2 + Q(3)**2 + Q(4)**2)	QUAT
	DO 12 I = 1,4	QUAT
12	Q(I) = Q(I)/SUM	QUAT
	RETURN	QUAT
	END	QUAT

```

C          DOUBLE PRECISION FUNCTION RCRT(A,PL,Z,IP)                                RCRT
C          REV 03 07/19/73RCRT
C          COMPUTES THE RADIUS OF CURVATURE AT POINT Z OF ELLIPSOID A            RCRT
C          IN THE PLANE PL(I,IP) WHERE                                         RCRT
C          A: 3X3 MATRIX DEFINING ELLIPSOID.                                   RCRT
C          PL: 4X3 MATRIX CONTAINING THREE ORTHONORMAL VECTORS.              RCRT
C          Z: 3 COORDINATES OF POINT ON THE ELLIPSOID                         RCRT
C          AS MEASURED FROM CENTER OF ELLIPSOID                              RCRT
C          IP: IDENTIFIES THE NORMAL VECTOR OF PLANE IN WHICH THE             RCRT
C          RADIUS OF CURVATURE IS DESIRED.                                     RCRT
C
C          IMPLICIT REAL*8 (A-H,O-Z)                                           RCRT
C          DIMENSION A(3,3),PL(4,3),Z(3),T(5)                                  RCRT
C          DO 10 I=1,5                                                         RCRT
10 T(I) = 0.0                                                                  RCRT
C          M = IP+1                                                            RCRT
C          N = IP+2                                                            RCRT
C          IF(M.GT.3) M = M-3                                                  RCRT
C          IF(N.GT.3) N = N-3                                                  RCRT
C          DO 30 I=1,3                                                         RCRT
C          S1 = 0.                                                            RCRT
C          S2 = 0.                                                            RCRT
C          DO 20 J=1,3                                                         RCRT
C          S1 = S1+A(I,J)*PL(J,M)                                             RCRT
20 S2 = S2+A(I,J)*PL(J,N)                                                     RCRT
C          T(1) = T(1)+S1*Z(I)                                                RCRT
C          T(2) = T(2)+S2*Z(I)                                                RCRT
C          T(3) = T(3)+S1*PL(I,M)                                             RCRT
C          T(4) = T(4)+S2*PL(I,N)                                             RCRT
30 T(5) = T(5)+S1*PL(I,N)                                                     RCRT
C          W = DSQRT(T(1)**2+T(2)**2)                                          RCRT
C          T(1) = T(1)/W                                                       RCRT
C          T(2) = T(2)/W                                                       RCRT
C          RCRT = W/(T(3)*T(2)**2-2.0*T(1)*T(2)*T(5)+T(4)*T(1)**2)          RCRT
C          IF(RCRT.LT.0.0) RCRT = -RCRT                                       RCRT
C          RETURN                                                              RCRT
C          END                                                                  RCRT

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	SUBROUTINE ROT (A,L,TH)		ROT
C		REV IV	07/23/86TWOPI
C	COMPUTES ROTATION MATRIX A FOR ANGLE TH		ROT
C	ABOUT X,Y OR Z AXIS AS L = 1,2, OR 3.		ROT
C			ROT
C	ARGUMENTS:		ROT
C	A: 3X3 ROTATION MATRIX TO BE COMPUTED.		ROT
C	L: 1,2 OR 3 TO ROTATE ABOUT X,Y OR Z AXIS.		ROT
C	TH: ANGLE OF ROTATION IN RADIAN.		ROT
C			ROT
	IMPLICIT REAL*8 (A-H,O-Z)		ROT
	DIMENSION A(3,3)		ROT
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		ROT
	*                  UNITL,UNITM,UNITT,GRAVTY(3),TWOPI		TWOPI
	C=DCOS(TH)		ROT
	S=DSIN(TH)		ROT
	IF (DABS(C) .LT.EPS(8)) C=0.0		CONVER
	IF (DABS(S) .LT.EPS(8)) S=0.0		CONVER
	ONE = 1.0		ROT
	IF (1.0-DABS(C) .LT.EPS(8)) C = DSIGN(ONE,C)		CONVER
	IF (1.0-DABS(S) .LT.EPS(8)) S = DSIGN(ONE,S)		CONVER
	IF (L.EQ.2) S = -S		ROT
	DO 30 I=1,3		ROT
	IF(I.EQ.3)GO TO 20		ROT
	DO 10 J=I,2		ROT
	A(I,J+1)=0.0		ROT
	A(J+1,I)=0.0		ROT
	IF(I+J+L.NE.5)GO TO 10		ROT
	A(I,J+1)=S		ROT
	A(J+1,I)=-S		ROT
10	CONTINUE		ROT
20	A(I,I)= C		ROT
	IF(I.EQ.L)A(I,I)=1.0		ROT
30	CONTINUE		ROT
	RETURN		ROT
	END		ROT

```

SUBROUTINE ROTATE
C                                     REV IV    02/20/87HYPER
C THE PURPOSE OF THIS ROUTINE IS TO TRANSFORM THOSE VARIABLES THAT ROTATE
C HAVE BEEN SUPPLIED IN LOCAL GEOMETRIC COORDINATES TO PRINCIPAL ROTATE
C AXES COORDINATES AS INDICATED BY LPMI(I) * 0 FOR I = 1 TO NSEG. ROTATE
C
  IMPLICIT REAL*8 (A-H,O-Z) ROTATE
  COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND, ROTATE
  * NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG PAGE
  COMMON/RSAVE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30), ATBIII
  * NSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9) TTHKREF
  COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60), SLIP
  * RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90), ROTATE
  * JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30) ROTATE
  COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40) EDGE
  COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30), ROTATE
  * SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30) ROTATE
  COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6), ROTATE
  * MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6), ROTATE
  * NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30) ROTATE
  COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24), ROTATE
  * HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12), ROTATE
  * RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12), ROTATE
  * KQ1(12),KQ2(12),KQTYPE(12) ROTATE
  COMMON/DAMPER/ APSDM(3,20),APSDN(3,20),ASD(5,20),MSDM(20),MSDN(20) ROTATE
  COMMON/WINDFR/ WTIME(30),QFU(3,5),QFV(3,5),WF(3,30),IWIND(30), WINDOP
  * MWSEG(7,30),NFVSEG(6),NFVMT(5),MOWSEG(30,30) WINDOP
  COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100), ROTATE
  * XLONG(20),HTIME(2),IBAR(5,100),NL(2,100), ROTATE
  * NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5) ROTATE
  COMMON/TABLES/MKNTI,MKNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500) WINDROT
  COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30), FXHROT
  * FE(3,30),TQE(3,30),CONST(5,30) FXHROT
  COMMON/TEMPVS/ T1(3),T3(3,3),LBD(40),T2(3),T4(3,3) FXHROT
C                                     ROTATE
C TRANSFORM DIRECTION COSINE MATRICEES D FROM INPUT CARDS G.3. ROTATE
C                                     ROTATE
  LTEST = 0 ROTATE
  DO 20 J=1,30 ROTATE
  IF (J.GT.NSEG) LPMI(J) = 0 ROTATE
  IF (LPMI(J).EQ.0) GO TO 20 ROTATE
  LTEST = 1 ROTATE
  DO 12 I=1,3 ROTATE
  T1(I) = WMEG(I,J) ROTATE
  DO 12 K=1,3 ROTATE
  12 T3(I,K) = D(I,K,J) ROTATE
  CALL MAT33 (DPMI(1,1,J),T3,D(1,1,J)) ROTATE
  CALL MAT31 (DPMI(1,1,J),T1,WMEG(1,J)) ROTATE
  20 CONTINUE ROTATE
  IF (LTEST.EQ.0) GO TO 99 ROTATE

```

C		ROTATE
C	TRANSFORM SR,HT AND HB FROM INPUT CARDS B.3.	ROTATE
C		ROTATE
	IF (NJNT.LE.0) GO TO 31	ROTATE
	DO 30 J=1,NJNT	ROTATE
	I = IABS(JNT(J))	ROTATE
	M = 2	SLIP
	IF (IABS(IPIN(J)).GT.4) M = 3	SLIP
	DO 24 K=1,2	ROTATE
	IF (I.EQ.0 .OR. LPMI(I).EQ.0) GO TO 24	ROTATE
	IJ = 2*J-2+K	ROTATE
	DO 22 LI=1,3	ROTATE
	T1(LI) = SR(LI,IJ)	ROTATE
	T2(LI) = HB(LI,IJ)	FXHROT
	DO 22 LJ=1,3	ROTATE
	T4(LI,LJ) = HIR(LI,LJ,IJ+30)	FXHROT
22	T3(LI,LJ) = HT(LI,LJ,IJ)	ROTATE
	CALL MAT31 (DPMI(1,1,I),T1,SR(1,IJ))	ROTATE
	CALL MAT31 (DPMI(1,1,I),T2,HB(1,IJ))	FXHROT
	CALL MAT33 (DPMI(1,1,I),T3,HT(1,1,IJ))	ROTATE
	CALL MAT33 (DPMI(1,1,I),T4,HIR(1,1,IJ+30))	FXHROT
24	I = J+1	ROTATE
30	CONTINUE	ROTATE
C		ROTATE
C	TRANSFORM RK1,RK2 FROM INPUT CARDS D.6.	ROTATE
C		ROTATE
	31 IF (NQ.LE.0) GO TO 41	ROTATE
	K5 = 0	ROTATE
	DO 40 K=1,NQ	ROTATE
	IF (K5.EQ.1) GO TO 39	ROTATE
	KSEG = KQ1(K)	ROTATE
	IF (LPMI(KSEG).EQ.0) GO TO 36	ROTATE
	DO 35 I=1,3	ROTATE
35	T1(I) = RK1(I,K)	ROTATE
	CALL MAT31 (DPMI(1,1,KSEG),T1,RK1(1,K))	ROTATE
36	KSEG = KQ2(K)	ROTATE
	IF (LPMI(KSEG).EQ.0) GO TO 40	ROTATE
	DO 37 I=1,3	ROTATE
37	T1(I) = RK2(I,K)	ROTATE
	CALL MAT31 (DPMI(1,1,KSEG),T1,RK2(1,K))	ROTATE
39	IF (KQTYPE(K).EQ.5) K5 = 1-K5	ROTATE
40	CONTINUE	ROTATE
C		ROTATE
C	TRANSFORM APSDM,APSDN FROM INPUT CARDS D.8.	ROTATE
C		ROTATE
	41 IF (NSD.LE.0) GO TO 151	FIXROT
	DO 50 J=1,NSD	ROTATE
	KSEG = MSDM(J)	ROTATE
	IF (LPMI(KSEG).EQ.0) GO TO 44	ROTATE
	DO 43 I=1,3	ROTATE

43	T1(I) = APSDM(I,J)	ROTATE
	CALL MAT31 (DPMI(1,1,KSEG),T1,APSDM(1,J))	ROTATE
44	KSEG = MSDN(J)	ROTATE
	IF (LPMI(KSEG).EQ.0) GO TO 50	ROTATE
	DO 45 I=1,3	ROTATE
45	T1(I) = APSDN(I,J)	ROTATE
	CALL MAT31 (DPMI(1,1,KSEG),T1,APSDN(1,J))	ROTATE
50	CONTINUE	ROTATE
C		FIXROT
C	TRANSFORM QFU AND QFV FROM INPUT CARDS D.9.	FIXROT
C		FIXROT
151	NFORCE = NFVSEG(6)	FIXROT
	IF (NFORCE.LE.0) GO TO 100	WINDROT
	DO 152 J=1,NFORCE	FIXROT
	KSEG = IABS(NFVSEG(J))	FIXROT
	IF (LPMI(KSEG).EQ.0) GO TO 152	FIXROT
	DO 143 I=1,3	FIXROT
	T1(I) = QFU(I,J)	FIXROT
143	T2(I) = QFV(I,J)	FIXROT
	CALL MAT31 (DPMI(1,1,KSEG),T1,QFU(1,J))	FIXROT
	CALL MAT31 (DPMI(1,1,KSEG),T2,QFV(1,J))	FIXROT
152	CONTINUE	FIXROT
C		WINDROT
C	ROTATE WIND FORCE FUNCTIONS	WINDROT
C		WINDROT
100	IF (NWINDF.EQ.0) GOTO 51	WINDROT
	DO 101 I=1,NSEG	WINDROT
	IF (MWSEG(1,I).EQ.0) GOTO 101	WINDROT
	NT = MWSEG(5,I)	WINDROT
	DO 102 J=1,I-1	WINDROT
	IF (NT.EQ.MWSEG(5,J)) GOTO 101	WINDROT
102	CONTINUE	WINDROT
	KT = NTI(NT)	WINDROT
	RK = TAB(KT)	WINDROT
	IF (RK.NE.0) GOTO 101	WINDROT
	NSR = IDINT(TAB(KT+4))	WINDROT
	IF (NSR.EQ.0 .OR. LPMI(NSR).EQ.0) GOTO 101	WINDROT
	NENTRY = TAB(KT+5)	WINDROT
	K1 = KT+6	WINDROT
	K2 = 4*NENTRY+KT+2	WINDROT
	DO 103 K=K1,K2,4	WINDROT
	DO 104 J=1,3	WINDROT
104	T1(J) = TAB(K+J)	WINDROT
103	CALL MAT31(DPMI(1,1,NSR),T1,TAB(K+1))	WINDROT
101	CONTINUE	WINDROT
C		ROTATE
C	CHECK PLANE AND ELLIPSOID ASSIGNMENTS ON INPUT CARDS F.1.	ROTATE
C	TRANSFORM PLANE ARRAYS SET UP FROM INPUT CARD D.1.	ROTATE
C		ROTATE
51	DO 52 J=1,40	ROTATE

	LBD(J) = 0	ROTATE
52	IF (J.LE.NSEG) LBD(J) = J	ROTATE
	IF (NPL.LE.0) GO TO 61	ROTATE
	DO 60 J=1,NPL	ROTATE
	IF (MNPL(J).EQ.0) GO TO 60	ROTATE
	LPL = 0	ROTATE
	KPL = MNPL(J)	ROTATE
	DO 56 I=1,KPL	ROTATE
	M1 = MPL (1,I,J)	ROTATE
	M2 = MPL (2,I,J)	ROTATE
	M3 = MPL (3,I,J)	ROTATE
	IF (LPL.EQ.M1 .OR. LPL.EQ.0) GO TO 54	ROTATE
	WRITE (6,53) J,M1,LPL	ROTATE
53	FORMAT('0 INPUT ERROR HAS BEEN DETECTED IN SUBROUTINE ROTATE.')	ROTATE
*	' PLANE NO.',I3,' HAS BEEN ASSIGNED TO BOTH SEGMENTS NO.'	ROTATE
*	I3,' AND NO.',I3,'.'/ PROGRAM IS BEING TERMINATED.')	ROTATE
	STOP 43	ROTATE
54	LPL = M1	ROTATE
	IF (LBD(M3).EQ.M2 .OR. LBD(M3).EQ.0) GO TO 55	ROTATE
	WRITE (6,68) M3,M2,LBD(M3)	ROTATE
	STOP 44	ROTATE
55	LBD(M3) = M2	ROTATE
56	CONTINUE	ROTATE
	IF (LPMI(LPL).EQ.0) GO TO 60	ROTATE
	L = 1	EDGE
	DO 59 K=1,6	EDGE
	IF((K.EQ.3).OR.(K.EQ.6)) L = L-1	EDGE
	IF((K.EQ.4).OR.(K.EQ.5)) L = L+1	EDGE
	DO 58 I=1,3	ROTATE
	T1(I) = PL(L,J)	EDGE
58	L=L+1	EDGE
	CALL MAT31 (DPMI(1,1,LPL),T1,PL(L-3,J))	EDGE
59	L=L+1	EDGE
60	CONTINUE	ROTATE
C		ROTATE
C	CHECK ELLIPSOID ASSIGNMENTS ON INPUT CARDS F.2.	ROTATE
C	TRANSFORM BELT(L,J) FOR L=1,9 FROM INPUT CARDS D.3.	ROTATE
C		ROTATE
61	IF (NBLT.LE.0) GO TO 66	ROTATE
	DO 65 J=1,NBLT	ROTATE
	IF (MNBLT(J).EQ.0) GO TO 65	ROTATE
	KBLT = MNBLT(J)	ROTATE
	DO 62 I=1,KBLT	ROTATE
	M1 = MBLT(1,I,J)	ROTATE
	M2 = MBLT(2,I,J)	ROTATE
	M3 = MBLT(3,I,J)	ROTATE
	IF (LBD(M3).EQ.M2 .OR. LBD(M3).EQ.0) GO TO 62	ROTATE
	WRITE (6,68) M3,M2,LBD(M3)	ROTATE
	STOP 45	ROTATE
62	LBD(M3) = M2	ROTATE



	IF (LPMI(M1).EQ.0) GO TO 63	ROTATE
	DO 57 I=1,3	ROTATE
	T3(I,1) = BELT(I ,J)	ROTATE
57	T3(I,2) = BELT(I+3,J)	ROTATE
	CALL MAT31 (DPMI(1,1,M1),T3(1,1),BELT(1,J))	ROTATE
	CALL MAT31 (DPMI(1,1,M1),T3(1,2),BELT(4,J))	ROTATE
63	IF (LPMI(M2).EQ.0) GO TO 65	ROTATE
	DO 64 I=1,3	ROTATE
64	T3(I,3) = BELT(I+6,J)	ROTATE
	CALL MAT31 (DPMI(1,1,M2),T3(1,3),BELT(7,J))	ROTATE
65	CONTINUE	ROTATE
C		ROTATE
C	CHECK ELLIPSOID ASSIGNMENTS ON INPUT CARDS F.3.	ROTATE
C		ROTATE
66	DO 70 J=1,NSEG	ROTATE
	IF (MNSEG(J).EQ.0) GO TO 70	ROTATE
	KSEG = MNSEG(J)	ROTATE
	DO 69 I=1,KSEG	ROTATE
	M1 = MSEG(1,I,J)	ROTATE
	M2 = MSEG(2,I,J)	ROTATE
	M3 = MSEG(3,I,J)	ROTATE
	IF (LBD(M1).EQ.J .OR. LBD(M1).EQ.0) GO TO 67	ROTATE
	WRITE (6,68) M1,J,LBD(M1)	ROTATE
	STOP 46	ROTATE
67	LBD(M1) = J	ROTATE
	IF (LBD(M3).EQ.M2 .OR. LBD(M3).EQ.0) GO TO 69	ROTATE
	WRITE (6,68) M3,M2,LBD(M3)	ROTATE
68	FORMAT('0 INPUT ERROR HAS BEEN DETECTED IN SUBROUTINE ROTATE.')	ROTATE
	* ' ELLIPSOID NO.',I3,' HAS BEEN ASSIGNED TO BOTH SEGMENTS NO.'	ROTATE
	* I3,' AND NO.',I3,'.'/' PROGRAM IS BEING TERMINATED.'	ROTATE
	STOP 47	ROTATE
69	LBD(M3) = M2	ROTATE
70	CONTINUE	ROTATE
C		ROTATE
C	CHECK ELLIPSOID ASSIGNMENTS ON INPUT CARDS F.6.	ROTATE
C		ROTATE
	IF (NBAG.EQ.0) GO TO 174	TGMOD8
	DO 73 J=1,NBAG	ROTATE
	IF (MNBAG(J).EQ.0) GO TO 73	ROTATE
	KBAG = MNBAG(J)	ROTATE
	DO 72 I=1,KBAG	ROTATE
	M2 = MBAG(2,I,J)	ROTATE
	M3 = MBAG(3,I,J)	ROTATE
	IF (LBD(M3).EQ.M2 .OR. LBD(M3).EQ.0) GO TO 72	ROTATE
	WRITE (6,68) M3,M2,LBD(M3)	ROTATE
	STOP 50	ROTATE
72	LBD(M3) = M2	ROTATE
73	CONTINUE	ROTATE
C		TGMOD8
C	CHECK ELLIPSOID ASSIGNMENTS ON INPUT CARDS F.7.	TGMOD8

C		TGMOD8
	174 IF(NWINDF.EQ.0) GO TO 74	TGMOD8
	DO 175 J=1,NSEG	TGMOD8
	M1 = IABS(MWSEG(1,J))	TGMOD8
	IF(M1.EQ.0) GO TO 175	TGMOD8
	M2 = MWSEG(2,J)	TGMOD8
	IF(LBD(M2).EQ.M1.OR.LBD(M2).EQ.0) GO TO 172	TGMOD8
	WRITE(6,68) M2,M1,LBD(M2)	TGMOD8
	STOP 48	TGMOD8
	172 LBD(M2) = M1	TGMOD8
	175 CONTINUE	TGMOD8
C		ROTATE
C	CHECK ELLIPSOID ASSIGNMENTS ON INPUT CARDS F.8.	ROTATE
C	TRANSFORM BAR(L,K) FOR L=4,12 FROM INPUT CARDS F.8.D.	ROTATE
C		ROTATE
	74 IF (NHRNSS.EQ.0) GO TO 81	ROTATE
	J1 = 1	ROTATE
	K1 = 1	ROTATE
	DO 80 II=1,NHRNSS	ROTATE
	IF (NBLTPH(II).LE.0) GO TO 80	ROTATE
	J2 = J1 + NBLTPH(II) - 1	ROTATE
	DO 79 JJ=J1,J2	ROTATE
	IF (NPTSPB(JJ).LE.0) GO TO 79	ROTATE
	K2 = K1 + NPTSPB(JJ) - 1	ROTATE
	DO 78 K=K1,K2	ROTATE
	M2 = MOD(IBAR(1,K),100)	ROTATE
	M3 = IBAR(2,K)	ROTATE
	IF (M3.EQ.0) GO TO 88	BUTLER1
	IF (LBD(M3).EQ.M2 .OR. LBD(M3).EQ.0) GO TO 75	ROTATE
	WRITE (6,68) M3,M2,LBD(M3)	ROTATE
	STOP 51	ROTATE
	75 LBD(M3) = M2	ROTATE
	88 IF (LPMI(M2).EQ.0) GO TO 78	BUTLER1
	DO 77 J=3,9,3	ROTATE
	DO 76 I=1,3	ROTATE
	IJ = I+J	ROTATE
	76 T1(I) = BAR(IJ,K)	ROTATE
	77 CALL MAT31 (DPMI(1,1,M2),T1,BAR(J+1,K))	ROTATE
	78 CONTINUE	ROTATE
	K1 = K2+1	ROTATE
	79 CONTINUE	ROTATE
	J1 = J2+1	ROTATE
	80 CONTINUE	ROTATE
C		ROTATE
C	TRANSFORM DATA IN BD ARRAYS FOR ELLIPSOIDS THAT HAVE BEEN ASSIGNED	ROTATE
C		ROTATE
	81 DO 90 J=1,40	ROTATE
	IF (LBD(J).EQ.0) GO TO 90	ROTATE
	KSEG = LBD(J)	ROTATE
	IF (LPMI(KSEG).EQ.0) GO TO 90	ROTATE

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L = 4
IF (BD(1,J).LT.0.0) L = 5
M = 8
DO 82 I=1,3
T1(I) = BD(L,J)
L = L + 1
DO 82 K = 1,3
T3(K,I) = BD(M,J)
82 M = M + 1
CALL MAT31 (DPMI(1,1,KSEG),T1,BD(L-3,J))
IF (BD(1,J).GT.0.0) GO TO 84
CALL MAT33 (DPMI(1,1,KSEG),T3,BD(8,J))
GO TO 90
84 CALL DOTT33 (BD( 7,J),DPMI(1,1,KSEG),T3)
CALL MAT33 (DPMI(1,1,KSEG),T3,BD( 7,J))
CALL DOTT33 (BD(16,J),DPMI(1,1,KSEG),T3)
CALL MAT33 (DPMI(1,1,KSEG),T3,BD(16,J))
90 CONTINUE
99 RETURN
END

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	REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,SEG,JOINT	RSTART
	LOGICAL*1 CGS,JS	RSTART
	REAL RC7,RC7A,XDTE,XCMENT	RSTART
	DIMENSION RC7(305),RC7A(348),XDTE(3),XCMENT(40)	RSTART
	EQUIVALENCE (RC7(1),VPSTTL(1)),(RC7A(1),DATE(1))	RSTART
C 8	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),	RSTART
	* UNITL,UNITM,UNITT,GRAVTY(3),TWOPI	TWOPI
	DIMENSION RC8(35)	TWOPI
	EQUIVALENCE (RC8(1),PI)	RSTART
C 9	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),	SLIP
	* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),	RSTART
	* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)	RSTART
	DIMENSION RC9(2460),IC9(150)	SLIP
	EQUIVALENCE (RC9(1),PHI(1,1)),(IC9(1),JNT(1))	RSTART
C 10	COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6),	RSTART
	* MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6),	RSTART
	* NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30)	RSTART
	DIMENSION IC10(1614)	RSTART
	EQUIVALENCE (IC10(1),MNPL(1))	RSTART
C 11	COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),	NCFORC
	* PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBSGF	RSTART
	DIMENSION RC11(1240),IC11(9)	NCFORC
	EQUIVALENCE (RC11(1),PSF(1,1)),(IC11(1),NPANEL(1))	RSTART
C 12	COMMON/INTEST/ SGTEST(3,4,30),XTEST(3,120),SEGT(120),REGT(120)	RSTART
	REAL SEGT	RSTART
	DIMENSION RC12(720)	RSTART
	EQUIVALENCE (RC12(1),SGTEST(1,1,1))	RSTART
C 13	COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),	RSTART
	* HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),	RSTART
	* RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),	RSTART
	* KQ1(12),KQ2(12),KQTYPE(12)	RSTART
	DIMENSION RC13(72),IC13(36),RC13A(1212),RC13H(348)	RSTART
	EQUIVALENCE (RC13(1),RK1(1,1)),(IC13(1),KQ1(1)),	RSTART
	* (RC13A(1),A13(1,1,1)),(RC13H(1),HHT(1,1,1))	RSTART
C 14	COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)	DIMENB
	DIMENSION IC14(1304)	BUTLER2
	EQUIVALENCE (IC14(1),MXNTI)	RSTART
C 15	COMMON/COMAIN/VAR(240),DER(240),DT,HO,HMAX,HMIN,RSTIME,	RSTART
	* ISTEP,NSTEPS,NDINT,NEQ,IRSIN,IRSOUT	RSTART
	DIMENSION RC15(485),IC15(6)	RSTART
	EQUIVALENCE (RC15(1),VAR(1)),(IC15(1),ISTEP)	RSTART
C 16		RSTART

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COMMON/CDINT/ UU(4),GH(3,4), RSTART
* E(3,240),FF(5,240),GG(5,240),Y(5,240),U(5,240). RSTART
* H,HPRINT,HS,TPRINT,TSTART,ICNT,IDBL,IFLAG RSTART
C NOTE: FF REPLACES F FROM SUBROUTINE DINT. RSTART
DIMENSION RC16(5541),IC16(3) RSTART
EQUIVALENCE (RC16(1),UU(1)),(IC16(1),ICNT) RSTART
C 17 COMMON/DAMPER/ APSDM(3,20),APSDN(3,20),ASD(5,20),MSDM(20),MSDN(20) RSTART
DIMENSION RC17(220),IC17(40) RSTART
EQUIVALENCE (RC17(1),APSDM(1,1)),(IC17(1),MSDM(1)) RSTART
C 18 COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30), RSTART
* FE(3,30),TQE(3,30),CONST(5,30) JDRIFT
DIMENSION RC18(1320) JDRIFT
EQUIVALENCE (RC18(1),HIR(1,1,1)) RSTART
C 19 COMMON/TEMPVI/ CREST,TTI(3),R1I(3),R2I(3),JSTOP(4,2,30) RSTART
DIMENSION RC19(10),IC19(180) RSTART
EQUIVALENCE (RC19(1),CREST),(IC19(1),JSTOP(1,1,1)) RSTART
C 20 COMMON/CYDATA/ CYTD(5),CYP(5),CYSP(5),CYT0(5),CYV0(5),CYCD(5), RSTART
* CYK(5),CYR(5),CYAT(5),CYPV(5),CYCD0(5),CYA0(5), RSTART
* CYP0(5),CYSS(5),CYL0(5),CYC(5),CYRH00(5),CYVMAX(5), RSTART
* CYORFC(5),CYRHO(5),CYT(5),CYP(5),CYV(5) RSTART
DIMENSION RC20A(95),RC20B(20) RSTART
EQUIVALENCE (RC20A(1),CYTD(1)),(RC20B(1),CYRHO(1)) RSTART
C 21 COMMON/RSAVE/ XSG(3,20,3),DPMI(3,3,30),LPMI(30), RSTART
* NSG(9),MSG(20,9),MCG,MCGIN(24,5),KREF(20,9) ATBIII
DIMENSION RC21(450),IC21(520) TTHKREF
EQUIVALENCE (RC21(1),XSG(1,1,1)),(IC21(1),LPMI(1)) RSTART
C 22 COMMON/FLXBLE/ HF(4,12,8),B42(3,3,24),V4(3,8),NFLEX(3,8) RSTART
DIMENSION RC22(624),IC22(24) RSTART
EQUIVALENCE (RC22(1),HF(1,1,1)),(IC22(1),NFLEX(1,1)) RSTART
C 23 COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100), RSTART
* XLONG(20),HTIME(2),IBAR(5,100),NL(2,100), RSTART
* NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5) RSTART
DIMENSION RC23(1922),IC23(765) RSTART
EQUIVALENCE (RC23(1),BAR(1,1)),(IC23(1),IBAR(1,1)) RSTART
C 24 COMMON/WINDFR/ WTIME(30),QFU(3,5),QFV(3,5),WF(3,30),IWIND(30), RSTART
* MWSEG(7,30),NFVSEG(6),NFVNT(5),MOWSEG(30,30) WINDOP
DIMENSION RC24(150),IC24(1151) WINDOP
EQUIVALENCE (RC24(1),WTIME(1)),(IC24(1),IWIND(1)) RSTART
C REAL AOLD4,AAOLD4 RSTART
DIMENSION COMMON(24),INDEX(3) RSTART
DATA COMMON /8HCONTRL ,8HCNTRSF ,8HVPOSTN ,8HSGMNTS , RSTART

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*           8HCMATRX ,8HABDATA ,8HTITLES ,8HCNSNTS ,           RSTART
*           8HDESCRP ,8HJBARTZ ,8HFORCES ,8HINTEST ,           RSTART
*           8HCSTRNT ,8HTABLES ,8HCOMAIN ,8HCDINT ,           RSTART
*           8HDAMPER ,8HCEULER ,8HTEMPVI ,8HCYDATA ,           RSTART
*           8HRSAVE ,8HFLXBLE ,8HHRNESS ,8HWINDFR /           RSTART
DATA BLANK/8H /           RSTART
CALL ELTIME(1,25)           RSTART
GO TO (100,200,300,400,500),IF           RSTART
C           RSTART
C           1. READ INPUT & INITIALIZATION RECORD FROM OLD RESTART TAPE. RSTART
C           RSTART
100 READ (IT) IC1, PL, RC3, IC3, NSYM, RC6A, IFULL, XDTE, XCOMMENT, RSTART
*           RC7, CGS, JS, RC8, RC9, IC9, IC10, NPANEL, SGTEST, RSTART
*           RC13, IC13, IC14, DT, HO, HMAX, HMIN, NSTEPS, NDINT, RSTART
*           RC17, IC17, IEULER, IC19, RC20A, RC21, IC21, HF, IC22, RSTART
*           RC23, IC23, RC24, IC24 RSTART
WRITE (6,101) IT,XDTE,XCOMMENT RSTART
101 FORMAT('O INPUT DATA HAS BEEN READ IN FROM UNIT NO.',I4// RSTART
*           10X,3A4//10X,20A4/10X,20A4) RSTART
GO TO 999 RSTART
C           RSTART
C           2. WRITE INPUT & INITIALIZATION RECORD ONTO NEW RESTART TAPE. RSTART
C           RSTART
200 WRITE (IT) IC1, PL, RC3, IC3, NSYM, RC6A, IFULL, DATE, COMENT, RSTART
*           RC7, CGS, JS, RC8, RC9, IC9, IC10, NPANEL, SGTEST, RSTART
*           RC13, IC13, IC14, DT, HO, HMAX, HMIN, NSTEPS, NDINT, RSTART
*           RC17, IC17, IEULER, IC19, RC20A, RC21, IC21, HF, IC22, RSTART
*           RC23, IC23, RC24, IC24 RSTART
GO TO 999 RSTART
C           RSTART
C           3. READ TIME POINT RECORD FROM OLD RESTART TAPE. RSTART
C           RSTART
300 READ (IT) TIME, BELT, TPTS, BD, RC4, RC5B, RC6B, IFULL, IPIN, RSTART
*           RC11, IC11, XTEST, SEGT, REGT, RC13H, KQTYPE, TAB, RSTART
*           VAR, DER, NEQ, RC16, IC16, IEULER, RC18, IC19, RC20B, RSTART
*           RC21, IC21, V4, RC23, NL, NPTPLY, WTIME, IWIND RSTART
CALL OUTPUT(1) RSTART
GO TO 999 RSTART
C           RSTART
C           5. WRITE TIME POINT RECORD ONTO NEW RESTART TAPE. RSTART
C           RSTART
500 WRITE (IT) TIME, BELT, TPTS, BD, RC4, RC5B, RC6B, IFULL, IPIN, RSTART
*           RC11, IC11, XTEST, SEGT, REGT, RC13H, KQTYPE, TAB, RSTART
*           VAR, DER, NEQ, RC16, IC16, IEULER, RC18, IC19, RC20B, RSTART
*           RC21, IC21, V4, RC23, NL, NPTPLY, WTIME, IWIND RSTART
GO TO 999 RSTART
C           RSTART
C           4. READ NEW INPUT DATA FROM INPUT STREAM FOR RESTART. RSTART
C           RSTART
400 READ (5,399) AVAR,INDEX,ITYPE,RR,II,AA,RROLD,IIOLD,AAOLD RSTART

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399	FORMAT(A8,4I4,2(F8.0,I8,A8))	RSTART
	CALL SEARCH(AVAR,INDEX,NCOM,ITEM)	RSTART
	IF (NCOM.LE.0) GO TO 490	RSTART
	IF (NCOM.GT.24) GO TO 999	RSTART
	IF (ITYPE.GT.3) GO TO 490	RSTART
	GO TO ( 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12,	RSTART
*	13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24) , NCOM	RSTART
C	COMMON /CONTRL/	RSTART
1	IF (ITEM.GT.1) GO TO 401	RSTART
	IF (ITYPE.NE.1) GO TO 490	RSTART
	ROLD = TIME	RSTART
	TIME = RR	RSTART
	GO TO 492	RSTART
401	IF (ITEM.GT.52) GO TO 490	PAGE
	IF (ITYPE.NE.2) GO TO 490	RSTART
	IOLD = IC1(ITEM-1)	RSTART
	IC1(ITEM-1) = II	RSTART
	GO TO 494	RSTART
C	COMMON /CNTSRF/	RSTART
2	IF (ITEM.GT.1888) GO TO 490	EDGE
	IF (ITYPE.NE.1) GO TO 490	RSTART
	ROLD = RC2(ITEM)	RSTART
	RC2(ITEM) = RR	RSTART
	GO TO 492	RSTART
C	COMMON /VPOSTN/	RSTART
3	IF (ITEM.GT.18084) GO TO 403	VEHICL
	IF (ITYPE.NE.1) GO TO 490	RSTART
	ROLD = RC3(ITEM)	RSTART
	RC3(ITEM) = RR	RSTART
	GO TO 492	RSTART
403	IF (ITEM.GT.18096) GO TO 490	VEHICL
	IF (ITYPE.NE.2) GO TO 490	RSTART
	IOLD = IC3(ITEM-18084)	VEHICL
	IC3(ITEM-18084) = II	VEHICL
	GO TO 494	RSTART
C	COMMON /SGMNTS/	RSTART
4	IF (ITEM.GT.900 ) GO TO 404	RSTART
	IF (ITYPE.NE.1) GO TO 490	RSTART
	ROLD = RC4(ITEM)	RSTART
	RC4(ITEM) = RR	RSTART
	GO TO 492	RSTART
404	IF (ITEM.GT.930 ) GO TO 490	RSTART
	IF (ITYPE.NE.2) GO TO 490	RSTART
	IOLD = NSYM(ITEM-900)	RSTART
	NSYM(ITEM-900) = II	RSTART
	GO TO 494	RSTART
C	COMMON /CMATRX/	RSTART
5	IF (ITEM.GT.1776) GO TO 490	SLIP
	IF (ITYPE.NE.1) GO TO 490	RSTART
	ROLD = RC5A(ITEM)	RSTART



	RC5A(ITEM) = RR	RSTART
	GO TO 492	RSTART
C	COMMON /ABDATA/	RSTART
	6 IF (ITEM.GT.881 ) GO TO 406	RSTART
	IF (ITYPE.NE.1) GO TO 490	RSTART
	ROLD = RC6A(ITEM)	RSTART
	RC6A(ITEM) = RR	RSTART
	GO TO 492	RSTART
	406 IF (ITEM.GT.887 ) GO TO 490	RSTART
	IF (ITYPE.NE.2) GO TO 490	RSTART
	IOLD = IFULL(ITEM-881)	RSTART
	IFULL(ITEM-881) = II	RSTART
	GO TO 494	RSTART
C	COMMON /TITLES/ NOTE: NO PROVISION FOR CGS OR JS.	RSTART
	7 IF (ITEM.GT.348 ) GO TO 490	RSTART
	IF (ITYPE.NE.3) GO TO 490	RSTART
	AOLD = RC7A(ITEM)	RSTART
	RC7A(ITEM) = AA	RSTART
	GO TO 496	RSTART
C	COMMON /CNSNTS/	RSTART
	8 IF (ITEM.GT.35 ) GO TO 490	TWOPI
	IF (ITEM.GT.31 ) GO TO 408	RSTART
	IF (ITEM.LE.28 ) GO TO 408	RSTART
	IF (ITYPE.NE.3) GO TO 490	RSTART
	AOLD = RC8(ITEM)	RSTART
	RC8(ITEM) = AA	RSTART
	GO TO 496	RSTART
	408 IF (ITYPE.NE.1) GO TO 490	RSTART
	ROLD = RC8(ITEM)	RSTART
	RC8(ITEM) = RR	RSTART
	GO TO 492	RSTART
C	COMMON /DESCRP/	RSTART
	9 IF (ITEM.GT.2460) GO TO 409	SLIP
	IF (ITYPE.NE.1) GO TO 490	RSTART
	ROLD = RC9(ITEM)	RSTART
	RC9(ITEM) = RR	RSTART
	GO TO 492	RSTART
	409 IF (ITEM.GT.2610) GO TO 490	SLIP
	IF (ITYPE.NE.2) GO TO 490	RSTART
	IOLD = IC9(ITEM-2460)	SLIP
	IC9(ITEM-2460) = II	SLIPRT
	GO TO 494	RSTART
C	COMMON /JBARTZ/	RSTART
	10 IF (ITEM.GT.1614) GO TO 490	RSTART
	IF (ITYPE.NE.2) GO TO 490	RSTART
	IOLD = IC10(ITEM)	RSTART
	IC10(ITEM) = II	RSTART
	GO TO 494	RSTART
C	COMMON /FORCES/	RSTART
	11 IF (ITEM.GT.1240) GO TO 411	NCFORC

	IF (ITYPE.NE.1) GO TO 490	RSTART
	ROLD = RC11(ITEM)	RSTART
	RC11(ITEM) = RR	RSTART
	GO TO 492	RSTART
411	IF (ITEM.GT.1249) GO TO 490	NCFORC
	IF (ITYPE.NE.2) GO TO 490	RSTART
	IOLD = IC11(ITEM-1240)	NCFORC
	IC11(ITEM-1240) = II	NCFORC
	GO TO 494	RSTART
C	COMMON /INTEST/	RSTART
12	IF (ITEM.GT.720 ) GO TO 412	RSTART
	IF (ITYPE.NE.1) GO TO 490	RSTART
	ROLD = RC12(ITEM)	RSTART
	RC12(ITEM) = RR	RSTART
	GO TO 492	RSTART
412	IF (ITEM.GT.840 ) GO TO 512	RSTART
	IF (ITYPE.NE.3) GO TO 490	RSTART
	AOLD = SEGT(ITEM-720)	RSTART
	SEGT(ITEM-720) = AA	RSTART
	GO TO 496	RSTART
512	IF (ITEM.GT.960 ) GO TO 490	RSTART
	IF (ITYPE.NE.3) GO TO 490	RSTART
	AOLD = REGT(ITEM-840)	RSTART
	REGT(ITEM-840) = AA	RSTART
	GO TO 496	RSTART
C	COMMON /CSTRNT/	RSTART
13	IF (ITEM.GT.1212) GO TO 413	RSTART
	IF (ITYPE.NE.1) GO TO 490	RSTART
	ROLD = RC13A(ITEM)	RSTART
	RC13A(ITEM) = RR	RSTART
	GO TO 492	RSTART
413	IF (ITEM.GT.1248) GO TO 490	RSTART
	IF (ITYPE.NE.2) GO TO 490	RSTART
	IOLD = IC13(ITEM-1212)	RSTART
	IC13(ITEM-1212) = II	RSTART
	GO TO 494	RSTART
C	COMMON /TABLES/	RSTART
14	IF (ITEM.GT.1304 ) GO TO 414	BUTLER2
	IF (ITYPE.NE.2) GO TO 490	RSTART
	IOLD = IC14(ITEM)	RSTART
	IC14(ITEM) = II	RSTART
	GO TO 494	RSTART
414	IF (ITEM.GT.5804) GO TO 490	MISC
	IF (ITYPE.NE.1) GO TO 490	RSTART
	ROLD = TAB(ITEM-1304)	BUTLER2
	TAB(ITEM-1304) = RR	BUTLER2
	GO TO 492	RSTART
C	COMMON /COMAIN/	RSTART
15	IF (ITEM.GT.485 ) GO TO 415	RSTART
	IF (ITYPE.NE.1) GO TO 490	RSTART

	ROLD = RC15(ITEM)	RSTART
	RC15(ITEM) = RR	RSTART
	GO TO 492	RSTART
415	IF (ITEM.GT.491 ) GO TO 490	RSTART
	IF (ITYPE.NE.2) GO TO 490	RSTART
	IOLD = IC15(ITEM-485)	RSTART
	IC15(ITEM-485) = II	RSTART
	GO TO 494	RSTART
C	COMMON /CDINT /	RSTART
16	IF (ITEM.GT.5541) GO TO 416	RSTART
	IF (ITYPE.NE.1) GO TO 490	RSTART
	ROLD = RC16(ITEM)	RSTART
	RC16(ITEM) = RR	RSTART
	GO TO 492	RSTART
416	IF (ITEM.GT.5544) GO TO 490	RSTART
	IF (ITYPE.NE.2) GO TO 490	RSTART
	IOLD = IC16(ITEM-5541)	RSTART
	IC16(ITEM-5541) = II	RSTART
	GO TO 494	RSTART
C	COMMON /DAMPER/	RSTART
17	IF (ITEM.GT.220 ) GO TO 417	RSTART
	IF (ITYPE.NE.1) GO TO 490	RSTART
	ROLD = RC17(ITEM)	RSTART
	RC17(ITEM) = RR	RSTART
	GO TO 492	RSTART
417	IF (ITEM.GT.260 ) GO TO 490	RSTART
	IF (ITYPE.NE.2) GO TO 490	RSTART
	IOLD = IC17(ITEM-220)	RSTART
	IC17(ITEM-220) = II	RSTART
	GO TO 494	RSTART
C	COMMON /CEULER/	RSTART
18	IF (ITEM.GT.30 ) GO TO 418	RSTART
	IF (ITYPE.NE.2) GO TO 490	RSTART
	IOLD = IEULER(ITEM)	RSTART
	IEULER(ITEM) = II	RSTART
	GO TO 494	RSTART
418	IF (ITEM.GT.1350) GO TO 490	JDRIFT
	IF (ITYPE.NE.1) GO TO 490	RSTART
	ROLD = RC18(ITEM-30)	RSTART
	RC18(ITEM-30) = RR	RSTART
	GO TO 492	RSTART
C	COMMON /TEMPVI/	RSTART
19	IF (ITEM.GT.10 ) GO TO 419	RSTART
	IF (ITYPE.NE.1) GO TO 490	RSTART
	ROLD = RC19(ITEM)	RSTART
	RC19(ITEM) = RR	RSTART
	GO TO 492	RSTART
419	IF (ITEM.GT.190 ) GO TO 490	RSTART
	IF (ITYPE.NE.2) GO TO 490	RSTART
	IOLD = IC19(ITEM-10)	RSTART

	IC19(ITEM-10) = II	RSTART
	GO TO 494	RSTART
C	COMMON/CYDATA/	RSTART
20	IF (ITEM.GT.115 ) GO TO 490	RSTART
	IF (ITYPE.NE.1 ) GO TO 490	RSTART
	ROLD = RC20A(ITEM)	RSTART
	RC20A(ITEM) = RR	RSTART
	GO TO 492	RSTART
C	COMMON /RSAVE/	RSTART
21	IF (ITEM.GT.450 ) GO TO 421	RSTART
	IF (ITYPE.NE.1 ) GO TO 490	RSTART
	ROLD = RC21(ITEM)	RSTART
	RC21(ITEM) = RR	RSTART
	GO TO 492	RSTART
421	IF (ITEM.GT.970 ) GO TO 490	TTHKREF
	IF (ITYPE.NE.2 ) GO TO 490	RSTART
	IOLD = IC21(ITEM-450)	RSTART
	IC21(ITEM-450) = II	RSTART
	GO TO 494	RSTART
C	COMMON /FLXBLE/	RSTART
22	IF (ITEM.GT.624 ) GO TO 422	RSTART
	IF (ITYPE.NE.1 ) GO TO 490	RSTART
	ROLD = RC22(ITEM)	RSTART
	RC22(ITEM) = RR	RSTART
	GO TO 492	RSTART
422	IF (ITEM.GT.648 ) GO TO 490	RSTART
	IF (ITYPE.NE.2 ) GO TO 490	RSTART
	IOLD = IC22(ITEM-624)	RSTART
	IC22(ITEM-624) = II	RSTART
	GO TO 494	RSTART
C	COMMON /HRNESS/	RSTART
23	IF (ITEM.GT.1922) GO TO 423	RSTART
	IF (ITYPE.NE.1 ) GO TO 490	RSTART
	ROLD = RC23(ITEM)	RSTART
	RC23(ITEM) = RR	RSTART
	GO TO 492	RSTART
423	IF (ITEM.GT.2687) GO TO 490	RSTART
	IF (ITYPE.NE.2 ) GO TO 490	RSTART
	IOLD = IC23(ITEM-1922)	RSTART
	IC23(ITEM-1922) = II	RSTART
	GO TO 494	RSTART
C	COMMON /WINDFR/	RSTART
24	IF (ITEM.GT.150 ) GO TO 424	WINDOP
	IF (ITYPE.NE.1 ) GO TO 490	RSTART
	ROLD = RC24(ITEM)	RSTART
	RC24(ITEM) = RR	RSTART
	GO TO 492	RSTART
424	IF (ITEM.GT.1301) GO TO 490	WINDOP
	IF (ITYPE.NE.2 ) GO TO 490	RSTART
	IOLD = IC24(ITEM-150)	WINDOP

	IC24(ITEM-150) = II	WINDOP
	GO TO 494	RSTART
C		RSTART
C	ERROR MESSAGE - TERMINATE PROGRAM.	RSTART
C		RSTART
	490 WRITE (6,491) AVAR,INDEX,NCOM,ITEM,ITYPE,RR,II,AA	RSTART
	491 FORMAT('0 SUBROUTINE RSTART INPUT ERROR'//	RSTART
	* ' AVAR= ',A8,' INDEX=',I3I6,' NCOM=',I6,' ITEM=',I6,	RSTART
	* ' ITYPE=',I6,' RR=',G15.8,' II=',I8,' AA= ',A8//	RSTART
	* ' PROGRAM IS BEING TERMINATED.')	RSTART
	STOP 2	RSTART
C		RSTART
C	PRINT MESSAGE FOR REAL VARIABLES.	RSTART
C		RSTART
	492 WRITE (6,493) AVAR,INDEX,COMMON(NCOM),ROLD,RR	RSTART
	493 FORMAT('0',A6,'(',I4,',',I4,',',I4,') OF COMMON/',A6,'/',	RSTART
	* ' HAS BEEN CHANGED FROM ',G15.8,' TO ',G15.8)	RSTART
	IF (RROLD.EQ.0.0) GO TO 400	RSTART
	IF (DABS(RROLD-ROLD).LE.0.00001*RROLD) GO TO 400	RSTART
	WRITE (6,383) RROLD	RSTART
	383 FORMAT(' INPUT VALUE FOR RROLD WAS ',G15.8//)	RSTART
	GO TO 490	RSTART
C		RSTART
C	PRINT MESSAGE FOR INTEGER VARIABLES.	RSTART
C		RSTART
	494 WRITE (6,495) AVAR,INDEX,COMMON(NCOM),IOLD,II	RSTART
	495 FORMAT('0',A6,'(',I4,',',I4,',',I4,') OF COMMON/',A6,'/',	RSTART
	* ' HAS BEEN CHANGED FROM ', I8,' TO ', I8)	RSTART
	IF (IIOLD.EQ.0) GO TO 400	RSTART
	IF (IOLD.EQ.IIOLD) GO TO 400	RSTART
	WRITE (6,385) IIOLD	RSTART
	385 FORMAT(' INPUT VALUE FOR IIOLD WAS ',I8//)	RSTART
	GO TO 490	RSTART
C		RSTART
C	PRINT MESSAGE FOR ALPHANUMERIC VARIABLES.	RSTART
C		RSTART
	496 WRITE (6,497) AVAR,INDEX,COMMON(NCOM),AOLD,AA	RSTART
	497 FORMAT('0',A6,'(',I4,',',I4,',',I4,') OF COMMON/',A6,'/',	RSTART
	* ' HAS BEEN CHANGED FROM ', A8,' TO ', A8)	RSTART
	IF (AAOLD.EQ.BLANK) GO TO 400	RSTART
	AAOLD4 = AAOLD	RSTART
	AOLD4 = AOLD	RSTART
	IF (AOLD4.EQ.AAOLD4) GO TO 400	RSTART
	WRITE (6,387) AAOLD	RSTART
	387 FORMAT(' INPUT VALUE FOR AAOLD WAS ',A8//)	RSTART
	GO TO 490	RSTART
	999 CALL ELTIME(2,25)	RSTART
	RETURN	RSTART
	END	RSTART

	SUBROUTINE SEARCH(AVAR,INDEX,NCOM,ITEM)	SEARCH
C		REV IV 07/24/86 SLIP
C	CALL BY SUBROUTINE RSTART TO COMPUTE NCOM & ITEM FROM AVAR &	SEARCH
C	INDEX. RETURNS NCOM=0 FOR ERROR AND NCOM=50 FOR BLANK.	SEARCH
C		SEARCH
	IMPLICIT REAL*8(A-H,O-Z)	SEARCH
	DIMENSION BVAR(264),KOUNT(25),NDIM(3,264),NJ(3),NK(3),INDEX(3)	SLIP
	DIMENSION C1 ( 17) , NC1 ( 51)	PAGE
	DIMENSION C2 ( 4) , NC2 ( 12)	SEARCH
	DIMENSION C3 ( 10) , NC3 ( 30)	SEARCH
	DIMENSION C4 ( 9) , NC4 ( 27)	SEARCH
	DIMENSION C5 ( 9) , NC5 ( 27)	SLIP
	DIMENSION C6 ( 30) , NC6 ( 90)	SEARCH
	DIMENSION C7 ( 11) , NC7 ( 33)	SEARCH
	DIMENSION C8 ( 10) , NC8 ( 30)	TWOPI
	DIMENSION C9 ( 15) , NC9 ( 45)	SEARCH
	DIMENSION C10( 11) , NC10( 33)	SEARCH
	DIMENSION C11( 10) , NC11( 30)	SEARCH
	DIMENSION C12( 4) , NC12( 12)	SEARCH
	DIMENSION C13( 16) , NC13( 48)	SEARCH
	DIMENSION C14( 7) , NC14( 21)	SEARCH
	DIMENSION C15( 13) , NC15( 39)	SEARCH
	DIMENSION C16( 15) , NC16( 45)	SEARCH
	DIMENSION C17( 5) , NC17( 15)	SEARCH
	DIMENSION C18( 7) , NC18( 21)	SEARCH
	DIMENSION C19( 5) , NC19( 15)	SEARCH
	DIMENSION C20( 23) , NC20( 69)	SEARCH
	DIMENSION C21( 8) , NC21( 24)	CHGIII
	DIMENSION C22( 4) , NC22( 12)	SEARCH
	DIMENSION C23( 12) , NC23( 36)	SEARCH
	DIMENSION C24( 9) , NC24( 27)	WINDOP
C		SEARCH
	EQUIVALENCE (C1 (1),BVAR( 1)) , (NC1 (1),NDIM(1, 1))	SEARCH
	EQUIVALENCE (C2 (1),BVAR( 18)) , (NC2 (1),NDIM(1, 18))	PAGE
	EQUIVALENCE (C3 (1),BVAR( 22)) , (NC3 (1),NDIM(1, 22))	PAGE
	EQUIVALENCE (C4 (1),BVAR( 32)) , (NC4 (1),NDIM(1, 32))	PAGE
	EQUIVALENCE (C5 (1),BVAR( 41)) , (NC5 (1),NDIM(1, 41))	PAGE
	EQUIVALENCE (C6 (1),BVAR( 50)) , (NC6 (1),NDIM(1, 50))	SLIP
	EQUIVALENCE (C7 (1),BVAR( 80)) , (NC7 (1),NDIM(1, 80))	SLIP
	EQUIVALENCE (C8 (1),BVAR( 91)) , (NC8 (1),NDIM(1, 91))	SLIP
	EQUIVALENCE (C9 (1),BVAR(101)) , (NC9 (1),NDIM(1,101))	SLIP
	EQUIVALENCE (C10(1),BVAR(116)) , (NC10(1),NDIM(1,116))	SLIP
	EQUIVALENCE (C11(1),BVAR(127)) , (NC11(1),NDIM(1,127))	SLIP
	EQUIVALENCE (C12(1),BVAR(137)) , (NC12(1),NDIM(1,137))	SLIP
	EQUIVALENCE (C13(1),BVAR(141)) , (NC13(1),NDIM(1,141))	SLIP
	EQUIVALENCE (C14(1),BVAR(157)) , (NC14(1),NDIM(1,157))	SLIP
	EQUIVALENCE (C15(1),BVAR(164)) , (NC15(1),NDIM(1,164))	SLIP
	EQUIVALENCE (C16(1),BVAR(177)) , (NC16(1),NDIM(1,177))	SLIP
	EQUIVALENCE (C17(1),BVAR(192)) , (NC17(1),NDIM(1,192))	SLIP
	EQUIVALENCE (C18(1),BVAR(197)) , (NC18(1),NDIM(1,197))	SLIP

	EQUIVALENCE (C19(1),BVAR(204)) , (NC19(1),NDIM(1,204))	SLIP
	EQUIVALENCE (C20(1),BVAR(209)) , (NC20(1),NDIM(1,209))	SLIP
	EQUIVALENCE (C21(1),BVAR(232)) , (NC21(1),NDIM(1,232))	SLIP
	EQUIVALENCE (C22(1),BVAR(240)) , (NC22(1),NDIM(1,240))	SLIP
	EQUIVALENCE (C23(1),BVAR(244)) , (NC23(1),NDIM(1,244))	SLIP
	EQUIVALENCE (C24(1),BVAR(256)) , (NC24(1),NDIM(1,256))	SLIP
C		SEARCH
	DATA NVAR/264/ , KOM/24/ , BLANK/8H /	SLIP
	DATA KOUNT/1,18,22,32,41,50,80,91,101,116,127,137,141,157,	SLIP
	* 164,177,192,197,204,209,232,240,244,256,265/	SLIP
C		SEARCH
C	1 COMMON/CONTRL/	SEARCH
C		SEARCH
	DATA C1 / 8HTIME ,8HNSEG ,8HNJNT ,8HNPL ,8HNBTL ,	SEARCH
	* 8HNBAG ,8HNVEH ,8HNGRND ,8HNS ,8HNQ ,	SEARCH
	* 8HNSD ,8HNFLX ,8HNNRNS ,8HNWINDF ,8HNJNTF ,	SEARCH
	* 8HNPRT ,8HNPG /	PAGE
	DATA NC1 / 0,0,0 , 0,0,0 , 0,0,0 , 0,0,0 , 0,0,0 ,	SEARCH
	* 0,0,0 , 0,0,0 , 0,0,0 , 0,0,0 , 0,0,0 ,	SEARCH
	* 0,0,0 , 0,0,0 , 0,0,0 , 0,0,0 , 0,0,0 ,	SEARCH
	* 36,0,0 , 0,0,0 /	PAGE
C		SEARCH
C	2 COMMON/CNTRF/	SEARCH
C		SEARCH
	DATA C2 / 8HPL ,8HBELT ,8HTPTS ,8HBD /	SEARCH
	DATA NC2 / 24,30,0 , 20,8,0 , 6,8,0 , 24,40,0 /	EDGE
C		SEARCH
C	3 COMMON/VPOSTN/	SEARCH
C		SEARCH
	DATA C3 / 8HZPLT ,8HSPLT ,8HAXV ,8HVATAB ,8HVTO ,	SEARCH
	* 8HVDT ,8HTIMEV ,8HOMEGV ,8HNVTAB ,8HINDXV /	SEARCH
	DATA NC3 / 3,0,0 , 3,0,0 , 3,6,0 , 6,501,6 , 6,0,0 ,	VEHICL
	* 6,0,0 , 6,0,0 , 6,0,0 , 6,0,0 , 6,0,0 /	SEARCH
C		SEARCH
C	4 COMMON/SGMNTS/	SEARCH
C		SEARCH
	DATA C4 / 8HD ,8HWMEG ,8HWMEGD ,8HU1 ,8HU2 ,	SEARCH
	* 8HSEGLP ,8HSEGLV ,8HSEGLA ,8HNSYM /	SEARCH
	DATA NC4 / 3,3,30 , 3,30,0 , 3,30,0 , 3,30,0 , 3,30,0 ,	SEARCH
	* 3,30,0 , 3,30,0 , 3,30,0 , 30,0,0 /	SEARCH
C		SEARCH
C	5 COMMON/CMATRX/	SEARCH
C		SEARCH
	DATA C5 / 8HV1 ,8HV2 ,8HV3 ,8HB12 ,8HA22 ,	SEARCH
	* 8HF ,8HTQ ,8HWJ ,8HA11 /	SLIP
	DATA NC5 / 3,30,0 , 3,30,0 , 3,12,0 , 3,3,60 , 3,3,60 ,	SEARCH
	* 3,30,0 , 3,30,0 , 30,0,0 , 3,3,60 /	SLIP
C		SEARCH
C	6 COMMON/ABDATA/	SEARCH
C		SEARCH

	DATA C6 /	8HZDEP	,8HDBR	,8HDPVCTR	,8HDEPLOY	,8HAB	, SEARCH
*		8HB	,8HZR	,8HBF	,8HRR	,8HVBAGG	, SEARCH
*		8HVSCS	,8HSPRK	,8HCK	,8HCMASS	,8HCYMIN	, SEARCH
*		8HCYMOUT	,8HBAGPV	,8HPD	,8HVBAG	,8HVOLBP	, SEARCH
*		8HPCYV	,8HPCYMIN	,8HPVBAG	,8HTV1	,8HTV2	, SEARCH
*		8HSWITCH	,8HPYMOUT	,8HSCALE	,8HPREVT	,8HIFULL	/ SEARCH
	DATA NC6 /	3,5,0	, 3,3,5	, 3,5,0	, 3,5,0	, 3,5,0	, SEARCH
*		9,4,5	, 3,4,5	, 3,4,5	, 9,4,5	, 5,0,0	, SEARCH
*		5,0,0	, 5,0,0	, 5,0,0	, 5,0,0	, 5,0,0	, SEARCH
*		5,0,0	, 5,0,0	, 5,0,0	, 5,0,0	, 5,0,0	, SEARCH
*		5,0,0	, 5,0,0	, 5,0,0	, 3,4,5	, 3,10,5	, SEARCH
*		5,0,0	, 5,0,0	, 5,0,0	, 0,0,0	, 6,0,0	/ SEARCH
C							SEARCH
C	7	COMMON/TITLES/					SEARCH
C							SEARCH
	DATA C7 /	8HDATE	,8HCOMENT	,8HVPSTTL	,8HBDYTTL	,8HBLTTTL	, SEARCH
*		8HPLTTL	,8HBAGTTL	,8HSEG	,8HJOINT	,8HCGS	, SEARCH
*		8HJS	/				SEARCH
	DATA NC7 /	3,0,0	, 40,0,0	, 20,0,0	, 5,0,0	, 5,8,0	, SEARCH
*		5,30,0	, 5,6,0	, 30,0,0	, 30,0,0	, 30,0,0	, SEARCH
*		30,0,0	/				SEARCH
C							SEARCH
C	8	COMMON/CNSNTS/					SEARCH
C							SEARCH
	DATA C8 /	8HPI	,8HRADIAN	,8HG	,8HTHIRD	,8HEPS	, SEARCH
*		8HUNITL	,8HUNITM	,8HUNITT	,8HGRAVTY	,8HTWOPI	/ TWOPI
	DATA NC8 /	0,0,0	, 0,0,0	, 0,0,0	, 0,0,0	, 24,0,0	, SEARCH
*		0,0,0	, 0,0,0	, 0,0,0	, 3,0,0	, 0,0,0	/ TWOPI
C							SEARCH
C	9	COMMON/DESCRP/					SEARCH
C							SEARCH
	DATA C9 /	8HPI	,8HW	,8HRW	,8HSR	,8HHA	, SEARCH
*		8HHB	,8HRPHI	,8HHT	,8HSPRING	,8HVISC	, SEARCH
*		8HJNT	,8HJPIN	,8HJSING	,8HJGLOB	,8HJOINTF	/ SEARCH
	DATA NC9 /	3,30,0	, 30,0,0	, 30,0,0	, 4,60,0	, 3,60,0	, SLIP
*		3,60,0	, 3,30,0	, 3,3,60	, 5,90,0	, 7,90,0	, SEARCH
*		30,0,0	, 30,0,0	, 30,0,0	, 30,0,0	, 30,0,0	/ SEARCH
C							SEARCH
C	10	COMMON/JBARTZ/					SEARCH
C							SEARCH
	DATA C10/	8HMNPL	,8HMNBLT	,8HMNSEG	,8HMNBAG	,8HMPL	, SEARCH
*		8HMBLT	,8HMSEG	,8HMBAG	,8HNTPL	,8HNTBLT	, SEARCH
*		8HNTSEG	/				SEARCH
	DATA NC10/	30,0,0	, 8,0,0	, 30,0,0	, 6,0,0	, 3,5,30	, SEARCH
*		3,5,8	, 3,5,30	, 3,10,6	, 5,30,0	, 5,8,0	, SEARCH
*		5,30,0	/				SEARCH
C							SEARCH
C	11	COMMON/FORCES/					SEARCH
C							SEARCH
	DATA C11/	8HPSF	,8HBSF	,8HSSF	,8HBAGSF	,8HPRJNT	, SEARCH



	*	8HNPANEL	,8HNPSF	,8HNBSF	,8HNSSF	,8HNBGSF	/	SEARCH
		DATA NC11/	7,70,0	, 4,20,0	, 10,40,0	, 3,20,0	, 7,30,0	, NCFORC
	*		5,0,0	, 0,0,0	, 0,0,0	, 0,0,0	, 0,0,0	/ SEARCH
C								SEARCH
C	12	COMMON/INTEST/						SEARCH
C								SEARCH
		DATA C12/	8HSGTEST	,8HXTEST	,8HSEGT	,8HREGT	/	SEARCH
		DATA NC12/	3,4,30	, 3,120,0	, 120,0,0	, 120,0,0	/	SEARCH
C								SEARCH
C	13	COMMON/CSTRNT/						SEARCH
C								SEARCH
		DATA C13/	8HA13	,8HA23	,8HB31	,8HB32	,8HHHT	, SEARCH
	*		8HRK1	,8HRK2	,8HQQ	,8HTQQ	,8HRQQ	, SEARCH
	*		8HHQQ	,8HSQQ	,8HCFQQ	,8HKQ1	,8HKQ2	, SEARCH
	*		8HKQTYPE	/				SEARCH
		DATA NC13/	3,3,24	, 3,3,24	, 3,3,24	, 3,3,24	, 3,3,12	, SEARCH
	*		3,12,0	, 3,12,0	, 3,12,0	, 3,12,0	, 3,12,0	, SEARCH
	*		3,12,0	, 12,0,0	, 12,0,0	, 12,0,0	, 12,0,0	, SEARCH
	*		12,0,0	/				SEARCH
C								SEARCH
C	14	COMMON/TABLES/						SEARCH
C								SEARCH
		DATA C14/	8HMXTI	,8HMXTB	,8HMXTB1	,8HMXTB2	,8HNTI	, SEARCH
	*		8HNTAB	,8HTAB	/			SEARCH
		DATA NC14/	0,0,0	, 0,0,0	, 0,0,0	, 0,0,0	, 50,0,0	, SEARCH
	*		1250,0,0	, 4500,0,0/				BUTLER2
C								SEARCH
C	15	COMMON/COMAIN/						SEARCH
C								SEARCH
		DATA C15/	8HVAR	,8HDER	,8HDT	,8HHO	,8HHMAX	, SEARCH
	*		8HHMIN	,8HRSTIME	,8HISTEP	,8HNSTEPS	,8HNDINT	, SEARCH
	*		8HNEQ	,8HIRSIN	,8HIRSOUT	/		SEARCH
		DATA NC15/	240,0,0	, 240,0,0	, 0,0,0	, 0,0,0	, 0,0,0	, SEARCH
	*		0,0,0	, 0,0,0	, 0,0,0	, 0,0,0	, 0,0,0	, SEARCH
	*		0,0,0	, 0,0,0	, 0,0,0	/		SEARCH
C								SEARCH
C	16	COMMON/CDINT /						SEARCH
C								SEARCH
		DATA C16/	8HUU	,8HGH	,8HE	,8HFF	,8HGG	, SEARCH
	*		8HY	,8HU	,8HH	,8HHPRINT	,8HHS	, SEARCH
	*		8HTPRINT	,8HTSTART	,8HICNT	,8HIDBL	,8HIFLAG	/ SEARCH
		DATA NC16/	4,0,0	, 3,4,0	, 3,240,0	, 5,240,0	, 5,240,0	, SEARCH
	*		5,240,0	, 5,240,0	, 0,0,0	, 0,0,0	, 0,0,0	, SEARCH
	*		0,0,0	, 0,0,0	, 0,0,0	, 0,0,0	, 0,0,0	/ SEARCH
C								SEARCH
C	17	COMMON/DAMPER/						SEARCH
C								SEARCH
		DATA C17/	8HAPSDM	,8HAPSDN	,8HASD	,8HMSDM	,8HMSDN	/ SEARCH
		DATA NC17/	3,20,0	, 3,20,0	, 5,20,0	, 20,0,0	, 20,0,0	/ SEARCH
C								SEARCH

C	18	COMMON/CEULER/					SEARCH
C							SEARCH
		DATA C18/ 8HIEULER	,8HHIR	,8HANG	,8HANGD	,8HFE	, SEARCH
	*	8HTQE	,8HCONST	/			SEARCH
		DATA NC18/ 30,0,0	, 3,3,90	, 3,30,0	, 3,30,0	, 3,30,0	, JDRIFT
	*	3,30,0	, 5,30,0	/			JDRIFT
C							SEARCH
C	19	COMMON/TEMPVI/					SEARCH
C							SEARCH
		DATA C19/ 8HCREST	,8HTTI	,8HR1I	,8HR2I	,8HJSTOP	/ SEARCH
		DATA NC19/ 0,0,0	, 3,0,0	, 3,0,0	, 3,0,0	, 4,2,30	/ SEARCH
C							SEARCH
C	20	COMMON/CYDATA/					SEARCH
C							SEARCH
		DATA C20/ 8HCYTD	,8HCYPA	,8HCYSP	,8HCYT0	,8HCYV0	, SEARCH
	*	8HCYCD	,8HCYK	,8HCYR	,8HCYAT	,8HCYPV	, SEARCH
	*	8HCYCD0	,8HCYAO	,8HCYPO	,8HCYSS	,8HCYLO	, SEARCH
	*	8HCYC	,8HCYRHO0	,8HCYVMAX	,8HCYORFC	,8HCYRHO	, SEARCH
	*	8HCYT	,8HCYRHP	,8HCYV	/		SEARCH
		DATA NC20/ 5,0,0	, 5,0,0	, 5,0,0	, 5,0,0	, 5,0,0	, SEARCH
	*	5,0,0	, 5,0,0	, 5,0,0	, 5,0,0	, 5,0,0	, SEARCH
	*	5,0,0	, 5,0,0	, 5,0,0	, 5,0,0	, 5,0,0	, SEARCH
	*	5,0,0	, 5,0,0	, 5,0,0	, 5,0,0	, 5,0,0	, SEARCH
	*	5,0,0	, 5,0,0	, 5,0,0	/		SEARCH
C							SEARCH
C	21	COMMON/RSAVE/					SEARCH
C							SEARCH
		DATA C21/ 8HXSG	,8HDPMI	,8HLPMI	,8HNSG	,8HMSG	, SEARCH
	*	8HMC	,8HMC	,8HKREF	/		CHGIII
		DATA NC21/ 3,20,3	, 3,3,30	, 30,0,0	, 9,0,0	, 20,9,0	, WINDOP
	*	1,0,0	, 24,5,0	, 20,9,0	/		TTHKREF
C							SEARCH
C	22	COMMON/FLXBLE/					SEARCH
C							SEARCH
		DATA C22/ 8HHF	,8HB42	,8HV4	,8HNFLEX	/	SEARCH
		DATA NC22/ 4,12,8	, 3,3,24	, 3,8,0	, 3,8,0	/	SEARCH
C							SEARCH
C	23	COMMON/HRNESS/					SEARCH
C							SEARCH
		DATA C23/ 8HBAR	,8HBB	,8HBBDOT	,8HPLOSS	,8HXLONG	, SEARCH
	*	8HHTIME	,8HIBAR	,8HNL	,8HNPTSPB	,8HNPTPLY	, SEARCH
	*	8HNTHRNS	,8HNBLTPH	/			SEARCH
		DATA NC23/ 15,100,0	, 100,0,0	, 100,0,0	, 2,100,0	, 20,0,0	, SEARCH
	*	2,0,0	, 5,100,0	, 2,100,0	, 20,0,0	, 20,0,0	, SEARCH
	*	20,0,0	, 5,0,0	/			SEARCH
C							SEARCH
C	24	COMMON/WINDFR/					SEARCH
		DATA C24/ 8HWTIME	,8HQFU	,8HQFV	,8HWF	,8HIWIND	, WINDOP
	*	8HMWSEG	,8HNFVSEG	,8HNFVNT	,8HMOWSEG	/	WINDOP
		DATA NC24/ 30,0,0	, 3, 5,0	, 3, 5,0	, 3,30,0	, 30,0,0	, WINDOP

	*	7,30,0 , 6,0,0 , 5,0,0 , 30,30,0 /	WINDOP
		NCOM = 50	SEARCH
		IF (AVAR.EQ.BLANK) GO TO 99	SEARCH
C			SEARCH
C		SEARCH FOR VARIABLE NO. IV.	SEARCH
C			SEARCH
		NCOM = 0	SEARCH
		DO 10 IV=1,NVAR	SEARCH
		IF (AVAR.EQ.BVAR(IV)) GO TO 12	SEARCH
10		CONTINUE	SEARCH
		GO TO 99	SEARCH
C			SEARCH
C		SEARCH FOR COMMON NO. IC.	SEARCH
C			SEARCH
12		DO 20 IC=1,KOM	SEARCH
		IF (IV.GE.KOUNT(IC).AND.IV.LT.KOUNT(IC+1)) GO TO 22	SEARCH
20		CONTINUE	SEARCH
		GO TO 99	SEARCH
C			SEARCH
C		COMPUTE ITEM NO. FOR VARIABLE IV IN COMMON IC.	SEARCH
C			SEARCH
22		K1 = KOUNT(IC)	SEARCH
		K2 = IV-1	SEARCH
		ITEM = 1	SEARCH
		IF (K1.EQ.IV) GO TO 25	SEARCH
		DO 24 K=K1,K2	SEARCH
		NI = 1	SEARCH
		DO 23 I=1,3	SEARCH
		IF (NDIM(I,K).NE.0) NI=NI*NDIM(I,K)	SEARCH
23		CONTINUE	SEARCH
24		ITEM = ITEM+NI	SEARCH
25		DO 26 I=1,3	SEARCH
		IF (INDEX(I).EQ.0 .AND. NDIM(I,IV).NE.0) GO TO 99	SEARCH
		IF (NDIM(I,IV).EQ.0 .AND. INDEX(I).GT.1) GO TO 99	SEARCH
		NJ(I) = MAXO(INDEX(I)-1,0)	SEARCH
		NK(I) = MAXO(NDIM(I,IV),1)	SEARCH
		IF (NJ(I).GE.NK(I)) GO TO 99	SEARCH
26		CONTINUE	SEARCH
		ITEM = ITEM+NJ(1)+NJ(2)*NK(1)+NJ(3)*NK(2)*NK(1)	SEARCH
		NCOM = IC	SEARCH
99		RETURN	SEARCH
		END	SEARCH



	GO TO 25		HYPER
C	OLD ELLIPSOIDS		HYPER
	20 IF(NS.LT.0.0)TB = -TB		HYPER
	CALL DOTT33(BD(7,NN),DMNT,TEMP)		EDGE
	CALL MAT33(DMNT,TEMP,B)		EDGE
	CALL INTERS(BD(7,MM),B,R,TB,RM,TAB(LT+22),TM)		SEGSEG
C		A B R Z C AZ	EDGE
C	INTERS SOLVES (CA + B)Z = BR, TB = SQRT(Z.AZ)		EDGE
C			EDGE
	25 MCF = NTAB(NT+1)		HYPER
	NCF = -MCF		SEGSEG
	IF(NCF.GT.0)CFQQ(NCF) = -999.		SEGSEG
C			EDGE
C	CHECK FOR INTERSECTION		EDGE
C			EDGE
	IF(TB.GE.1.0)GO TO 75		HYPER
	S1 = 0.0		SEGSEG
	S2 = 0.0		SEGSEG
	DO 30 I = 1,3		HYPER
	RI = R(I)		SEGSEG
	IF(NS.LT.0)RI = RM(I) + TB*(RM(I) - R(I))		SEGSEG
	S1 = S1 + RI**2		SEGSEG
30	S2 = S2 + TM(I)**2		HYPER
	AMR = DSQRT(S2)		SEGSEG
	P = (1.0/TB - 1.0)*DSQRT(S1)		SEGSEG
	J = 3		HYPER
	IF(BD(1,MM).LT.0.0)J = 4		HYPER
	DO 35 I = 1,3		HYPER
	J = J + 1		HYPER
	IF((BD(1,MM).LT.0.0).OR.(BD(1,NN).LT.0.0))RM(I) = TB*RM(I)		HYPER
	TM(I) = -TM(I)/AMR		SEGSEG
	T2(I) = RM(I) - R(I)		SEGSEG
	RN(I) = T2(I) + RLN(I)		SEGSEG
35	RLM(I) = RM(I) + BD(J,MM)		HYPER
	CALL DOT31(DMNT,RN,RLN)		SEGSEG
	CALL PLSEGF(M,N,NT)		SEGSEG
C			EDGE
C	STORE PRINT DATA		EDGE
C			EDGE
	SSF(1,NSSF) = P		SEGSEG
	DO 40 I = 1,3		HYPER
	SSF(I+4,NSSF) = RLM(I)		EDGE
40	SSF(I+7,NSSF) = RLN(I)		HYPER
	IF(LPMI(M).NE.0)CALL DOT31(DPMI(1,1,M),RLM,SSF(5,NSSF))		EDGE
	IF(LPMI(N).NE.0)CALL DOT31(DPMI(1,1,N),RLN,SSF(8,NSSF))		EDGE
	IF(MCF.LT.0)GO TO 45		HYPER
	SSF(2,NSSF) = FM		SEGSEG
	TF2FM2 = TF**2 - FM**2		SEGSEG
	IF(TF2FM2.LT.0.0)TF2FM2 = 0.0		SEGSEG
	SSF(3,NSSF) = DSQRT(TF2FM2)		SEGSEG

	SSF(4,NSSF) = TF	SEGSEG
	GO TO 75	HYPER
C		EDGE
C	ROLL-SLIDE	EDGE
45	DO 50 I = 1,3	HYPER
50	SSF(I+1,NSSF) = T(I)	HYPER
	IF((BD(1,MM).LT.0.0).OR.(BD(1,NN).LT.0.0)) STOP 29	HYPER
	ANR = XDY(TM,B,T2)	SEGSEG
	CALL CROSS(TM,WNM,T2)	SEGSEG
	CALL MAT31(B,VR,T1)	SEGSEG
	TB = TM(1)*T1(1) + TM(2)*T1(2) + TM(3)*T1(3)	EDGE
	DO 60 I = 1,3	HYPER
	DO 55 J = 1,3	HYPER
	K = I + 3*(J+1)	SEGSEG
	TT4(I,J) = BD(K,MM)/AMR + B(I,J)/ANR	SEGSEG
55	TT5(I,J) = TT4(I,J)	HYPER
	TT4(I,4) = T2(I) - (T1(I) - TB*TM(I))/ANR	EDGE
60	TT5(I,4) = TM(I)	HYPER
	CALL DSMSOL(TT4,3,3)	SEGSEG
	CALL DSMSOL(TT5,3,3)	SEGSEG
	S1 = TM(1)*TT4(1,4) + TM(2)*TT4(2,4) + TM(3)*TT4(3,4)	EDGE
	S2 = (TM(1)*TT5(1,4) + TM(2)*TT5(2,4) + TM(3)*TT5(3,4))/S1	EDGE
	DO 65 I = 1,3	HYPER
	RMD(I) = TT4(I,4) - S2*TT5(I,4)	EDGE
65	RND(I) = RND(I) + VR(I)	HYPER
	CALL CROSS(DMNWN,RND,T1)	EDGE
	CALL CROSS(WMEG(1,MM),RMD,T2)	EDGE
	CALL MAT31(B,RND,T3)	EDGE
	CALL CROSS(DMNWN,TM,T4)	EDGE
	S1 = TM(1)*T3(1) + TM(2)*T3(2) + TM(3)*T3(3)	EDGE
	SQQ(NCF) = 0.0	SEGSEG
	DO 70 I = 1,3	HYPER
	T1(I) = T1(I) - T2(I)	EDGE
70	SQQ(NCF) = SQQ(NCF) + TM(I)*T1(I) - VR(I)*(T4(I) + (T3(I) - S1*TM(I))/ANR)	HYPER
	CALL DOT31(D(1,1,M),T1,RQQ(1,NCF))	EDGE
75	CALL ELTIME(2,23)	HYPER
	RETURN	SEGSEG
	END	SEGSEG



	T1(K) = SR(K,2*J-1)	SLIP
	T2(K) = SR(K,2*J )	SLIP
	IF (IABS(IPIN(J)).LT.5) GO TO 31	SLIP
	IF (IEULER(J).EQ.-1) GO TO 31	SLIP
	T1(K) = T1(K) + SR(4,2*J-1)*HT(K,3,2*J-1)	SLIP
31	V1(K,J) = 0.0	SETUP1
	I = IABS(JNT(J))	SETUP1
	IF (I.LE.0) GO TO 40	SETUP1
C		SETUP1
C	FOR EACH JOINT SET	SETUP1
C	B12(2J-1) = B12(J,I ) = -D(I)' * SR(2J-1) X	SETUP1
C	B12(2J ) = B12(J,J+1) = D(J+1)' * SR(2J) X	SETUP1
C		SETUP1
	B12(1,1,2*J-1) = D(3,1,I)*T1(2) - D(2,1,I)*T1(3)	SLIP
	B12(2,1,2*J-1) = D(3,2,I)*T1(2) - D(2,2,I)*T1(3)	SLIP
	B12(3,1,2*J-1) = D(3,3,I)*T1(2) - D(2,3,I)*T1(3)	SLIP
	B12(1,2,2*J-1) = D(1,1,I)*T1(3) - D(3,1,I)*T1(1)	SLIP
	B12(2,2,2*J-1) = D(1,2,I)*T1(3) - D(3,2,I)*T1(1)	SLIP
	B12(3,2,2*J-1) = D(1,3,I)*T1(3) - D(3,3,I)*T1(1)	SLIP
	B12(1,3,2*J-1) = D(2,1,I)*T1(1) - D(1,1,I)*T1(2)	SLIP
	B12(2,3,2*J-1) = D(2,2,I)*T1(1) - D(1,2,I)*T1(2)	SLIP
	B12(3,3,2*J-1) = D(2,3,I)*T1(1) - D(1,3,I)*T1(2)	SLIP
C		SETUP1
	B12(1,1,2*J ) = D(2,1,J+1)*T2(3) - D(3,1,J+1)*T2(2)	SLIP
	B12(2,1,2*J ) = D(2,2,J+1)*T2(3) - D(3,2,J+1)*T2(2)	SLIP
	B12(3,1,2*J ) = D(2,3,J+1)*T2(3) - D(3,3,J+1)*T2(2)	SLIP
	B12(1,2,2*J ) = D(3,1,J+1)*T2(1) - D(1,1,J+1)*T2(3)	SLIP
	B12(2,2,2*J ) = D(3,2,J+1)*T2(1) - D(1,2,J+1)*T2(3)	SLIP
	B12(3,2,2*J ) = D(3,3,J+1)*T2(1) - D(1,3,J+1)*T2(3)	SLIP
	B12(1,3,2*J ) = D(1,1,J+1)*T2(2) - D(2,1,J+1)*T2(1)	SLIP
	B12(2,3,2*J ) = D(1,2,J+1)*T2(2) - D(2,2,J+1)*T2(1)	SLIP
	B12(3,3,2*J ) = D(1,3,J+1)*T2(2) - D(2,3,J+1)*T2(1)	SLIP
C		SETUP1
C	NOTE THAT FOR EACH JOINT	SETUP1
C	A21(M,N) = B12(N,M)	SETUP1
C		SETUP1
C	FOR EACH JOINT SET	SETUP1
C	V1(J) = -D(I)'*W(I)X( W(I)XSR(2J-1) )	SETUP1
C	+D(J+1)'*W(J+1)X( W(J+1)XSR(2J) )	SETUP1
C		SETUP1
	CALL CROSS(WMEG(1,I),T1,T)	SLIP
	CALL CROSS(WMEG(1,I),T,S)	SETUP1
	CALL DOT31(D(1,1,I),S,V1(1,J))	SETUP1
	CALL CROSS(WMEG(1,J+1),T2,T)	SLIP
	CALL CROSS(WMEG(1,J+1),T,S)	SETUP1
	CALL DOT31(D(1,1,J+1),S,T)	SETUP1
	DO 32 K=1,3	SLIP
32	V1(K,J) = T(K) - V1(K,J)	SLIP
	IF (IABS(IPIN(J)).LT.5) GO TO 40	SLIP
	IF (IEULER(J).EQ.-1) GO TO 40	SLIP



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CALL DOT31(D(1,1,I),HT(1,3,2*J-1),T4) SLIP
CALL CROSS(WMEG(1,I),HT(1,3,2*J-1),T5) SLIP
CALL DOT31(D(1,1,I),T5,T6) SLIP
V1T = V1(1,J)*T4(1) + V1(2,J)*T4(2) + V1(3,J)*T4(3) SLIP
SR2 = 2.0*SR(4,2*J) SLIP
DO 34 K = 1,3 SLIP
V1(K,J) = V1(K,J) - V1T*T4(K) - SR2*T6(K) SLIP
S1=T4(1)*B12(1,K,2*J-1)+T4(2)*B12(2,K,2*J-1)+T4(3)*B12(3,K,2*J-1) SLIP
S2=T4(1)*B12(1,K,2*J) +T4(2)*B12(2,K,2*J) +T4(3)*B12(3,K,2*J) SLIP
DO 33 L = 1,3 SLIP
A11(K,L,J) = -T4(K)*T4(L) SLIP
B12(L,K,2*J-1) = B12(L,K,2*J-1) - S1*T4(L) SLIP
33 B12(L,K,2*J) = B12(L,K,2*J) - S2*T4(L) SLIP
34 A11(K,K,J) = 1.0 + A11(K,K,J) SLIP
40 CONTINUE SETUP1
IF (NPRT(11).NE.0) WRITE (6,41) ((V1(I,J),I=1,3),J=1,NJNT) SETUP1
41 FORMAT(' V1 ARRAY'/(1X,1P9D14.4)) SETUP1
C SETUP1
C IF IPIN(M)=1, SET V2(M)=(WN.HN-WM.HM)DN'WNXHN SETUP1
C SETUP1
DO 50 J=1,NJNT SETUP1
DO 43 K=1,3 SETUP1
43 V2(K,J) = 0.0 SETUP1
IF (IPIN(J).LT.1) GO TO 50 SLIP
IF (IPIN(J).GT.1.AND.IPIN(J).LT.6) GOTO 50 SLIP
I = IABS(JNT(J)) SETUP1
CALL CROSS (WMEG(1,I),HB(1,2*J-1),T) SETUP1
CALL DOT31 (D(1,1,I),T,T1) SETUP1
C CALL CROSS (WMEG(1,J+1),HB(1,2*J),T) SETUP1
C CALL DOT31 (D(1,1,J+1),T,T2) SETUP1
S1 = WMEG(1,I)*HB(1,2*J-1) SETUP1
* + WMEG(2,I)*HB(2,2*J-1) SETUP1
* + WMEG(3,I)*HB(3,2*J-1) SETUP1
S2 = WMEG(1,J+1)*HB(1,2*J) SETUP1
* + WMEG(2,J+1)*HB(2,2*J) SETUP1
* + WMEG(3,J+1)*HB(3,2*J) SETUP1
DO 44 K=1,3 SETUP1
C 44 V2(K,J) = S1*T1(K) - S2*T2(K) SETUP1
44 V2(K,J) = (S1-S2)*T1(K) SETUP1
50 CONTINUE SETUP1
98 CALL ELTIME(2,10) SETUP1
RETURN SETUP1
END SETUP1

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C	SET UP A13,A23 AND V3 ARRAYS FOR DAUX33.	SETUP2
C		SETUP2
	50 IF (NQ.EQ.0) GO TO 98	SETUP2
	DO 70 K=1,NQ	SETUP2
	IF (KQTYPE(K).LT.0) GO TO 70	SETUP2
	IF (KQTYPE(K).EQ.5) GO TO 70	SETUP2
	M = KQ1(K)	SETUP2
	N = KQ2(K)	SETUP2
	IF (KQTYPE(K).EQ.2 .OR. KQTYPE(K).EQ.4) GO TO 53	SETUP2
C		SETUP2
C	FOR KQTYPE = 1 OR 3, SET HHT = I	SETUP2
C		SETUP2
	DO 52 J=1,3	SETUP2
	DO 51 I=1,3	SETUP2
	51 HHT(I,J,K) = 0.0	SETUP2
	52 HHT(J,J,K) = 1.0	SETUP2
	IF (KQTYPE(K).NE.6) GO TO 61	SETUP2
C		SETUP2
C	FOR KQTYPE=6, SET HHT= I-TT'	SETUP2
C		SETUP2
	DO 60 J=1,3	SETUP2
	DO 60 I=1,3	SETUP2
	60 HHT(I,J,K) = HHT(I,J,K) - TQQ(I,K)*TQQ(J,K)	SETUP2
	GO TO 61	SETUP2
	53 IF (KQTYPE(K).NE.2) GO TO 56	SETUP2
C		SETUP2
C	FOR KQTYPE=2, COMPUTE HH AND HHT.	SETUP2
C		SETUP2
	CALL DOT31(D(1,1,M),RK1(1,K),T1)	SETUP2
	CALL DOT31(D(1,1,N),RK2(1,K),T2)	SETUP2
	S1 = 0.0	SETUP2
	DO 54 I=1,3	SETUP2
	HH(I) = SEGLP(I,M)+T1(I) - SEGLP(I,N)-T2(I)	SETUP2
	54 S1 = S1 + HH(I)**2	SETUP2
	SQS1 = DSQRT(S1)	SETUP2
	DO 55 I=1,3	SETUP2
	HH(I) = HH(I)/SQS1	SETUP2
	55 IF (DABS(HH(I)).LE.EPS(12)) HH(I) = 0.0	SETUP2
	CALL DOT31(HH,HH,HHT(1,1,K))	SETUP2
	56 IF (KQTYPE(K).NE.4) GO TO 61	SETUP2
C		SETUP2
C	FOR KQTYPE = 4, SET HHT = HHT	SETUP2
C		SETUP2
	CALL DOT31(HQQ(1,K),HQQ(1,K),HHT(1,1,K))	SETUP2
C		SETUP2
C	SET A13(2K-1) = HHT	SETUP2
C	AND A13(2K) = -HHT	SETUP2
C		SETUP2
	61 DO 62 J=1,3	SETUP2
	DO 62 I=1,3	SETUP2

	A13(I,J,2*K-1) = HHT(I,J,K)	SETUP2
62	A13(I,J,2*K ) = -HHT(I,J,K)	SETUP2
C		SETUP2
C	SET A23(2K-1) = (R1X)(D1)A13(2K-1)	SETUP2
C	AND A23(2K) = (R2X)(D2)A13(2K)	SETUP2
C		SETUP2
	CALL MAT33(D(1,1,M),A13(1,1,2*K-1),TT1)	SETUP2
	CALL MAT33(D(1,1,N),A13(1,1,2*K ),TT2)	SETUP2
	DO 63 J=1,3	SETUP2
	CALL CROSS(RK1(1,K),TT1(1,J),A23(1,J,2*K-1) )	SETUP2
63	CALL CROSS(RK2(1,K),TT2(1,J),A23(1,J,2*K ) )	SETUP2
	IF (KQTYPE(K).EQ.4) GO TO 72	SETUP2
C		SETUP2
C	FOR KQTYPE = 1,2 OR 3, SET B31 = A13' AND B32 = A23'	SETUP2
C		SETUP2
	DO 71 I=1,3	SETUP2
	DO 71 J=1,3	SETUP2
	B31(I,J,2*K-1) = A13(J,I,2*K-1)	SETUP2
	B31(I,J,2*K ) = A13(J,I,2*K )	SETUP2
	B32(I,J,2*K-1) = A23(J,I,2*K-1)	SETUP2
71	B32(I,J,2*K ) = A23(J,I,2*K )	SETUP2
	GO TO 76	SETUP2
C		SETUP2
C	FOR KQTYPE = 4, SET B31(2K-1) = HTT	SETUP2
C	B31(2K ) = -HTT	SETUP2
C	B32 = (B31)(D')(RX)'	SETUP2
C		SETUP2
	72 CALL DOT31(HQQ(1,K),TQQ(1,K),B31(1,1,2*K-1))	SETUP2
	DO 73 I=1,3	SETUP2
	DO 73 J=1,3	SETUP2
73	B31(I,J,2*K) = -B31(I,J,2*K-1)	SETUP2
	CALL DOT33(D(1,1,M),B31(1,1,2*K-1),B32(1,1,2*K-1))	SETUP2
	CALL DOT33(D(1,1,N),B31(1,1,2*K ),B32(1,1,2*K ))	SETUP2
	DO 74 J=1,3	SETUP2
	CALL CROSS(RK1(1,K),B32(1,J,2*K-1),TT1(1,J))	SETUP2
74	CALL CROSS(RK2(1,K),B32(1,J,2*K ),TT2(1,J))	SETUP2
	DO 75 I=1,3	SETUP2
	DO 75 J=1,3	SETUP2
	B32(I,J,2*K-1) = TT1(J,I)	SETUP2
75	B32(I,J,2*K ) = TT2(J,I)	SETUP2
C		SETUP2
C	COMPUTE V3 = D2'(W2X(W2XR2)) - D1'(W1X(W1XR1))	SETUP2
C		SETUP2
	76 CALL CROSS(WMEG(1,M),RK1(1,K),T3)	SETUP2
	CALL CROSS (WMEG(1,M),T3,T4)	SETUP2
	CALL DOT31 (D(1,1,M),T4,T5)	SETUP2
	CALL CROSS (WMEG(1,N),RK2(1,K),T6)	SETUP2
	CALL CROSS (WMEG(1,N),T6,T7)	SETUP2
	CALL DOT31 (D(1,1,N),T7,T8)	SETUP2
	DO 64 I=1,3	SETUP2

	64	V3(I,K) = T8(I) - T5(I)	SETUP2
		IF (KQTYPE(K).NE.2) GO TO 67	SETUP2
C			SETUP2
C		RECOMPUTE V3 FOR KQTYPE=2.	SETUP2
C			SETUP2
		CALL DOT31 (D(1,1,M),T3,T9 )	SETUP2
		CALL DOT31 (D(1,1,N),T6,T10)	SETUP2
		S2 = 0.0	SETUP2
		DO 65 I=1,3	SETUP2
		T11(I) = SEGLV(I,M)+T9(I) - SEGLV(I,N)-T10(I)	SETUP2
	65	S2 = S2 + T11(I)**2	SETUP2
		S3 = HH(1)*V3(1,K) + HH(2)*V3(2,K) + HH(3)*V3(3,K)	SETUP2
		S4 = S3-S2/SQS1	SETUP2
		DO 66 I=1,3	SETUP2
	66	V3(I,K) = S4*HH(I)	SETUP2
	67	IF (KQTYPE(K).NE.3.AND.KQTYPE(K).NE.6) GO TO 77	SETUP2
C			SETUP2
C		FOR KQTYPE=3 OR 6, ADD R DOT TERM FROM PLELP OR SEGSEG TO V3.	SETUP2
C			SETUP2
		DO 68 I=1,3	SETUP2
	68	V3(I,K) = V3(I,K) + RQQ(I,K)	SETUP2
		IF (KQTYPE(K).NE.6) GO TO 70	SETUP2
C			SETUP2
C		FOR KQTYPE=6, SET V3 = (I-TT')(V3+RQQ)	SETUP2
C			SETUP2
		VQQ = V3(1,K)*TQQ(1,K) + V3(2,K)*TQQ(2,K) + V3(3,K)*TQQ(3,K)	SETUP2
		DO 69 I=1,3	SETUP2
	69	V3(I,K) = V3(I,K) - VQQ*TQQ(I,K)	SETUP2
	77	IF (KQTYPE(K).NE.4) GO TO 70	SETUP2
C			SETUP2
C		FOR KQTYPE = 4, ADD R TERM FROM PLELP OR SEGSEG TO V3.	SETUP2
C			SETUP2
		S3 = TQQ(1,K)*V3(1,K) + TQQ(2,K)*V3(2,K) + TQQ(3,K)*V3(3,K)	SETUP2
		S4 = S3+SQQ(K)	SETUP2
		DO 78 I=1,3	SETUP2
	78	V3(I,K) = S4*HQQ(I,K)	SETUP2
	70	CONTINUE	SETUP2
C			SETUP2
C		SPECIAL SETUP FOR TENSION ELEMENTS (KQTYPE = 5).	SETUP2
C			SETUP2
		N = 0	SETUP2
	79	N = N+1	SETUP2
		IF (N.GE.NQ) GO TO 98	SETUP2
		IF (KQTYPE(N).NE.5) GO TO 79	SETUP2
		DO 81 I=1,3	SETUP2
		DO 80 J=1,3	SETUP2
		A13(I,J,2*N-1) = 0.0	SETUP2
		A13(I,J,2*N ) = 0.0	SETUP2
		A23(I,J,2*N ) = 0.0	SETUP2
		B31(I,J,2*N-1) = 0.0	SETUP2

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      B31(I,J,2*N ) = 0.0
      A13(I,J,2*N+1) = 0.0
      A13(I,J,2*N+2) = 0.0
      A23(I,J,2*N+1) = 0.0
      B31(I,J,2*N+1) = 0.0
      B31(I,J,2*N+2) = 0.0
      HHT(I,J,N ) = 0.0
80 HHT(I,J,N+1 ) = 0.0
      A13(I,I,2*N-1) = 1.0
      B31(I,I,2*N-1) = RK1(1,N+1)
      B31(I,I,2*N ) = RK1(3,N+1)
      A13(I,I,2*N+2) = 1.0
      B31(I,I,2*N+1) = RK1(3,N+1)
81 B31(I,I,2*N+2) = RK1(2,N+1)
      N1 = KQ1(N)
      N2 = KQ2(N)
      DO 82 K=1,3
      CALL CROSS(RK1(1,N),D(1,K,N1),A23(1,K,2*N-1))
82 CALL CROSS(RK2(1,N),D(1,K,N2),A23(1,K,2*N+2))
      DO 83 I=1,3
      DO 83 J=1,3
      B32(I,J,2*N-1) = RK1(1,N+1)*A23(J,I,2*N-1)
      B32(I,J,2*N ) = RK1(3,N+1)*A23(J,I,2*N+2)
      B32(I,J,2*N+1) = RK1(3,N+1)*A23(J,I,2*N-1)
83 B32(I,J,2*N+2) = RK1(2,N+1)*A23(J,I,2*N+2)
      CALL CROSS(WMEG(1,N1),RK1(1,N),WCRM)
      CALL CROSS(WMEG(1,N2),RK2(1,N),WCRN)
      CALL DOT31(D(1,1,N1),RK1(1,N),RM)
      CALL DOT31(D(1,1,N2),RK2(1,N),RN)
      CALL DOT31(D(1,1,N1),WCRM,WCM)
      CALL DOT31(D(1,1,N2),WCRN,WCN)
      BA = 0.0
      DO 84 I=1,3
      RBA(I) = SEGLP(I,N2) + RN(I) - SEGLP(I,N1) - RM(I)
      RBAD(I) = SEGLV(I,N2) + WCN(I) - SEGLV(I,N1) - WCM(I)
84 BA = BA + RBA(I)**2
      BA = DSQRT(BA)
      FORCE = 0.0
      IF (BA.GT.RK2(3,N+1)) FORCE = RK2(1,N+1)*(1.0-RK2(3,N+1)/BA)
      DO 85 I=1,3
      V3(I,N) = RK2(2,N+1)*RBAD(I) + FORCE*RBA(I)
85 V3(I,N+1) = -V3(I,N)
      CALL CROSS(WMEG(1,N1),WCRM,WWCM)
      CALL CROSS(WMEG(1,N2),WCRN,WWCN)
      CALL DOT31(D(1,1,N1),WWCM,WWM)
      CALL DOT31(D(1,1,N2),WWCN,WWN)
      DO 86 I=1,3
      V3(I,N ) = V3(I,N ) - RK1(1,N+1)*WWM(I) - RK1(3,N+1)*WWN(I)
86 V3(I,N+1) = V3(I,N+1) - RK1(3,N+1)*WWM(I) - RK1(2,N+1)*WWN(I)
      N = N+1

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GO TO 79  
98 CALL ELTIME(2,26)  
RETURN  
END

SETUP2  
SETUP2  
SETUP2  
SETUP2

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SUBROUTINE SINPUT                                SINPUT
C                                               REV IV    02/20/87HYPER
C READS AND PRINTS THE INPUT CARDS THAT DESCRIBE THE PHYSICAL SINPUT
C DIMENSIONS OF THE PLANES REPRESENTING THE VEHICLE PANELS AND OF SINPUT
C THE RESTRAINT BELTS. ALSO PROCESSES THOSE DATA CARDS THAT DESCRIBESINPUT
C ADDITIONAL CONTACT ELLIPSOIDS, CONSTRAINTS, BODY SEGMENT SYMMETRY SINPUT
C OPTIONS AND SPRING DAMPER FUNCTIONS.          SINPUT
C                                               SINPUT
C IMPLICIT REAL*8 (A-H,O-Z)                     SINPUT
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND, SINPUT
* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG    PAGE
COMMON/CNTRSF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40) EDGE
COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),SINPUT
* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)        SINPUT
COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24), SINPUT
* HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),SINPUT
* RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),              SINPUT
* KQ1(12),KQ2(12),KQTYPE(12)                         SINPUT
COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5), SINPUT
* BLTTTL(5,8),PLTTL(5,30),BAGTTL(5,6),SEG(30),        SINPUT
* JOINT(30),CGS(30),JS(30)                            SINPUT
REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,SEG,JOINT SINPUT
LOGICAL*1 CGS,JS,LP4                                  HYPER
COMMON/DAMPER/ APSDM(3,20),APSDN(3,20),ASD(5,20),MSDM(20),MSDN(20) SINPUT
COMMON/WINDFR/ WTIME(30),QFU(3,5),QFV(3,5),WF(3,30),IWIND(30), WINDOP
* MWSEG(7,30),NFVSEG(6),NFVNT(5),MOWSEG(30,30)        WINDOP
COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),            SINPUT
* UNITL,UNITM,UNITT,GRAVTY(3),TWOPI                  TWOPI
COMMON/TEMPVS/ P1(3),P2(3),P3(3),P4(3),DE(3,3)      HYPER
DIMENSION IDYPR(3)                                   SINPUT
DATA IDYPR/3,2,1/                                    SINPUT
DATA MAXBD/40/                                       CHGIII
DATA NPLMAX/30/,NBLTMX/8/,NBAGMX/5/,NELPMX/40/,NQMAX/12/, MISC
* NSDMAX/20/,NHRNSM/5/,NWINDM/50/,NJNTFM/50/,NFORCM/5/ MISC
C                                               SINPUT
C INPUT CARD D.1                                    SINPUT
C                                               SINPUT
READ (5,11) NPL,NBLT,NBAG,NELP,NQ,NSD,NHRNSS,NWINDF,NJNTF,NFORCESINPUT
11 FORMAT(12I6)                                       SINPUT
WRITE (6,16) NPG,NPL,NBLT,NBAG,NELP,NQ,NSD,NHRNSS,NWINDF,NJNTF, PAGE
* NFORCE                                              PAGE
NPG=NPG+1                                             PAGE
16 FORMAT('1 NPL NBLT NBAG NELP NQ NSD NHRNSS',PAGE
* ' NWINDF NJNTF NFORCE',43X,'PAGE',15/10I8,40X,'CARD D.1')PAGE
IF (NPL.GT.NPLMAX) STOP 65                            CHGIII
IF (NBLT.GT.NBLTMX) STOP 66                            MISC
IF (NBAG.GT.NBAGMX) STOP 67                            MISC
IF (NELP.GT.NELPMX) STOP 68                            MISC
IF (NQ.GT.NQMAX) STOP 69                              CHGIII
IF (NSD.GT.NSDMAX) STOP 70                            CHGIII

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	IF (NHRNSS.GT.NHRNSM) STOP 71	MISC
	IF (NWINDF.GT.NWINDM) STOP 72	MISC
	IF (NJNTF.GT.NJNTFM) STOP 73	MISC
	IF (NFORCE.GT.NFORCM) STOP 74	MISC
	IF (NPL.EQ.0) GO TO 15	SINPUT
	IPAGE = 0	SINPUT
	DO 20 J=1,NPL	SINPUT
C		SINPUT
C	READ AND PRINT CARDS D.2.A,D.2.B AND D.2.C FOR THE JTH PLANE.	SINPUT
C		SINPUT
	READ (5,23) JJ,(PLTTL(I,J),I = 1,5),P1,P2,P3	SINPUT
	23 FORMAT (I4,4X,5A4/(3F12.0))	SINPUT
	IF (JJ.NE.J) WRITE (6,24) JJ,J	SINPUT
	24 FORMAT (' PLANE INDEX INPUT ERROR,',2I4)	SINPUT
	IF (JJ.NE.J) STOP 10	SINPUT
	IF (MOD(J,7).EQ.1.AND.IPAGE.EQ.0) WRITE (6,12) IPAGE	PAGE
	IF (MOD(J,7).EQ.1.AND.IPAGE.EQ.1) WRITE (6,112) IPAGE,NPG	PAGE
	IF (MOD(J,7).EQ.1.AND.IPAGE.EQ.1) NPG=NPG+1	PAGE
	112 FORMAT(I1,' PLANE INPUTS',109X,'PAGE',I5/120X,'CARDS D.2')	PAGE
	12 FORMAT(I1,' PLANE INPUTS',106X,'CARDS D.2')	SINPUT
	IPAGE = 1	SINPUT
	WRITE (6,25) J, (PLTTL(I,J),I = 1,5),P1,P2,P3	SINPUT
	25 FORMAT('0 PLANE NO.',I4,4X,5A4//17X,'X',11X,'Y',11X,'Z'/	SINPUT
	* ' POINT 1 ' ,3F12.4/	SINPUT
	* ' POINT 2 ' ,3F12.4/	SINPUT
	* ' POINT 3 ' ,3F12.4)	SINPUT
C		SINPUT
C	PROGRAM NOW ASSUMES THE FINITE PLANE IS A PARALLELOGRAM IN SHAPE	SINPUT
C	WHERE THE INPUT POINTS P1,P2,P3 ARE 3 OF THE CORNERS SUCH THAT	SINPUT
C	EDGE P1-P2 IS LESS THAN 180 DEGREES CLOCKWISE (AS VIEWED BY THE	SINPUT
C	OCCUPANT) FROM THE EDGE P1-P3.	SINPUT
C		SINPUT
C	SET UP PL ARRAY AS REQUIRED BY SUBROUTINE PLELP	SINPUT
C		SINPUT
C	PL(1,J) = A0      NORMAL EQUATION OF JTH PLACE	SINPUT
C	PL(2,J) = B0      A0*X + B0*Y + C0*Z = D0	SINPUT
C	PL(3,J) = C0	SINPUT
C	PL(4,J) = D0	SINPUT
C		SINPUT
C	PL(5,J)	SINPUT
C	PL(6,J)            POINT 1	EDGE
C	PL(7,J)	SINPUT
C		SINPUT
C	PL(8,J) =A1	SINPUT
C	PL(9,J) =B1      NORMAL EQUATION OF 1ST BOUNDARY PLANE	SINPUT
C	PL(10,J)=C1      A1*X + B1*Y + C1*Z = D1	SINPUT
C	PL(11,J)=D1      AND E1 IS LENGTH OF PLANE FROM BOUNDARY.	SINPUT
C	PL(12,J)=E1	SINPUT
C		SINPUT
C	PL(13,J)=A2	SINPUT

C	PL(14,J)=B2	NORMAL EQUATION OF 2ND BOUNDARY PLANE	SINPUT
C	PL(15,J)=C2	$A2*X + B2*Y + C2*Z = D2$	SINPUT
C	PL(16,J)=D2	AND E2 IS LENGTH OF PLANE FROM BOUNDARY.	SINPUT
C	PL(17,J)=E2		SINPUT
C			SINPUT
C	PL(18,J)		EDGE
C	PL(19,J)	POINT 2 - POINT 1	EDGE
C	PL(20,J)		EDGE
C			EDGE
C	PL(21,J)		EDGE
C	PL(22,J)	POINT 3 - POINT 1	EDGE
C	PL(23,J)		EDGE
C			EDGE
C	PL(24,J)	NOT CURRENTLY USED	EDGE
	S22 = 0.0		SINPUT
	S23 = 0.0		SINPUT
	S33 = 0.0		SINPUT
	DO 26 I = 1,3		SINPUT
	P2(I) = P2(I)-P1(I)		SINPUT
	P3(I) = P3(I)-P1(I)		SINPUT
	PL(I+ 4,J) = P1(I)		EDGE
	PL(I+17,J) = P2(I)		EDGE
	PL(I+20,J) = P3(I)		EDGE
	S22 = S22 + P2(I)*P2(I)		SINPUT
	S23 = S23 + P2(I)*P3(I)		SINPUT
26	S33 = S33 + P3(I)*P3(I)		SINPUT
	S2 = DSQRT(S22)		SINPUT
	S3 = DSQRT(S33)		SINPUT
	CALL CROSS(P2,P3,PL(1,J))		SINPUT
	S1 = 0.0		SINPUT
	DO 27 I=1,3		SINPUT
27	S1 = S1 + PL(I,J)**2		SINPUT
	S1 = DSQRT(S1)		SINPUT
	DO 28 I=1,3		SINPUT
	PL(I,J) = PL(I,J)/S1		SINPUT
	PL(I+7 ,J) = (S33*P2(I) - S23*P3(I)) / (S1*S3)		SINPUT
28	PL(I+12,J) = (S22*P3(I) - S23*P2(I)) / (S1*S2)		SINPUT
	PL( 4,J) = P1(1)*PL( 1,J) + P1(2)*PL( 2,J) + P1(3)*PL( 3,J)		SINPUT
	PL(11,J) = P1(1)*PL( 8,J) + P1(2)*PL( 9,J) + P1(3)*PL(10,J)		SINPUT
	PL(12,J) = P2(1)*PL( 8,J) + P2(2)*PL( 9,J) + P2(3)*PL(10,J)		SINPUT
	PL(16,J) = P1(1)*PL(13,J) + P1(2)*PL(14,J) + P1(3)*PL(15,J)		SINPUT
20	PL(17,J) = P3(1)*PL(13,J) + P3(2)*PL(14,J) + P3(3)*PL(15,J)		SINPUT
15	IF (NBLT.EQ.0) GO TO 35		SINPUT
	DO 30 J=1,NBLT		SINPUT
C			SINPUT
C	READ AND PRINT CARDS D.3.A, D.3.B AND D.3.C FOR THE JTH BELT.		SINPUT
C			SINPUT
	READ (5,13) (BLTTTL(I,J),I = 1,5),(BELT(I,J),I = 1,11)		SINPUT
13	FORMAT (5A4/(6F12.0))		SINPUT
	IF (MOD(J,5).EQ.1) WRITE (6,21) NPG		PAGE

	IF (MOD(J,5).EQ.1) NPG=NPG+1	PAGE
21	FORMAT('1 BELT INPUTS',110X,'PAGE',I5/120X,'CARDS D.3')	PAGE
30	WRITE (6,14) J,(BLTTTL(I,J),I = 1,5),(BELT(I,J),I = 1,11)	SINPUT
14	FORMAT('0 BELT NO.',I4,4X,5A4//	SINPUT
	* 30X,'ANCHOR POINT A',46X,'ANCHOR POINT B'//	SINPUT
	* 2(16X,'X',19X,'Y',19X,'Z',3X)/6F20.3//	SINPUT
	* 26X,'FIXED POINT ON SEGMENT',45X,'SLACK(+)'//	SINPUT
	* 16X,'X',19X,'Y',19X,'Z',17X,'BLANK',13X,'LENGTH(-)'/5F20.3)	SINPUT
C		SINPUT
C	CALL AIRBG1 ROUTINE IF REQUIRED FOR AIRBAG INPUT	SINPUT
C		SINPUT
35	IF (NBAG.NE.0) CALL AIRBG1	SINPUT
	IF (NELP.LE.0) GO TO 51	SINPUT
C		SINPUT
C	READ AND PRINT CARDS D.5 FOR ELLIPSOID INPUT, IF ANY.	SINPUT
C	NOTE: NELP IS THE NO. OF ELLIPSOIDS TO BE SUPPLIED HERE, NOT THE	SINPUT
C	NO. OF ELLIPSOIDS IN THE PROGRAM, SINCE THE FIRST NSEG	SINPUT
C	ELLIPSOIDS WERE SUPPLIED ON CARDS B.2.A - B.2.I. HOWEVER	SINPUT
C	THEY MAY BE REPLACED HERE IF DESIRED.	SINPUT
C		SINPUT
	WRITE (6,41) NPG,UNITL,UNITL	PAGE
	NPG=NPG+1	PAGE
41	FORMAT('1 ADDITIONAL ELLIPSOID INPUT',95X,'PAGE',I5/120X,	PAGE
	* 'CARDS D.5'/17X,'SEMIAXES ('A4,')',18X,'OFFSET ('A4,')',	PAGE
	* 20X,'ROTATION (DEG)',15X,'POWER'//	HYPER
	* .3X,'NO.',2(8X,'X',8X,'Y',8X,'Z',6X),7X,'YAW',7X,'PITCH',5X,	SINPUT
	* 'ROLL'//)	SINPUT
	DO 50 MM=1,NELP	SINPUT
	READ (5,42) M,P1,P2,P3,P4	HYPER
42	FORMAT(I6,9F6.0,3F4.0)	HYPER
	IF (M.GT.MAXBD) STOP 63	CHGIII
C		CHGIII
C	PREVENT EXTRA ELLIPSOIDS FROM CHANGING AIRBAG ELLIPSOIDS	CHGIII
C		CHGIII
	IF (M.GT.NVEH.AND.M.LT.NGRND) WRITE (6,330)	CHGIII
330	FORMAT(3X,'THE EXTRA CONTACT ELLIPSOID NUMBER IS THE SAME AS AN AIC	CHGIII
	*RBAG ELLIPSOID')	CHGIII
	IF (M.GT.NVEH.AND.M.LT.NGRND) STOP 64	CHGIII
	WRITE (6,43) M,P1,P2,P3,P4	HYPER
43	FORMAT(I6,3(3X,3F9.3,3X),3F6.0)	HYPER
	CALL DRCYPR (DE,P3,IDYPR)	SINPUT
	N = 1	HYPER
	LP4 = .FALSE.	HYPER
	DO 39 J = 1,3	HYPER
39	IF (P4(J).GT.2.0) LP4 = .TRUE.	HYPER
	IF (LP4) N = 2	HYPER
	DO 46 I = 1,3	HYPER
	BD(N ,M) = P1(I)	HYPER
	BD(N+3,M) = P2(I)	HYPER
	IF (LP4) GO TO 46	HYPER

	DO 45 J=1,3	SINPUT
	SUM1 = 0.0	SINPUT
	SUM2 = 0.0	SINPUT
	DO 44 L=1,3	SINPUT
	SUM1 = SUM1 + DE(L,I)/P1(L)**2*DE(L,J)	SINPUT
44	SUM2 = SUM2 + DE(L,I)*P1(L)**2*DE(L,J)	SINPUT
	K = 3*I + J + 3	SINPUT
	BD(K ,M) = SUM1	SINPUT
45	BD(K+9,M) = SUM2	SINPUT
46	N = N + 1	HYPER
	IF (.NOT.LP4) GO TO 50	HYPER
	BD(1,M) = -P4(1)	HYPER
	N = 8	HYPER
	DO 48 J = 1,3	HYPER
	BD(J+19,M) = P4(J)	HYPER
	IF (BD(J+19,M).EQ.0.0) BD(J+19,M) = BD(20,M)	HYPER
	BD(J+16,M) = 1.0/BD(J+1,M)**2	HYPER
	DO 48 I = 1,3	HYPER
	BD(N,M) = DE(I,J)	HYPER
48	N = N + 1	HYPER
	BD(23,M) = 0.0	HYPER
	IF (BD(20,M).NE.BD(21,M)) BD(23,M) = 1.0	HYPER
	IF (BD(21,M).NE.BD(22,M)) BD(23,M) = 1.0	HYPER
	IF (BD(22,M).NE.BD(20,M)) BD(23,M) = 1.0	HYPER
50	CONTINUE	SINPUT
C		SINPUT
C	READ AND PRINT CARDS D.6 FOR CONSTRAINT INPUT, IF ANY.	SINPUT
C		SINPUT
	51 IF (NQ.LE.0) GO TO 70	SINPUT
	DO 60 K=1,NQ	SINPUT
	READ (5,52) KQTYPE(K),KQ1(K),KQ2(K), (RK1(I,K),I=1,3)	SINPUT
	* , (RK2(I,K),I=1,3)	SINPUT
52	FORMAT(3I6,6F6.0)	SINPUT
	IF (K.EQ.1) WRITE (6,53) NPG,UNITL,UNITL	PAGE
	IF (K.EQ.1) NPG=NPG+1	PAGE
53	FORMAT('1 CONSTRAINT INPUT',105X,'PAGE',I5/120X,'CARDS D.6'/	PAGE
	* ' TYPE SEGMENT SEGMENT POINT ON 1ST SEGMENT ('	SINPUT
	* A4,')', ' POINT ON 2ND SEGMENT (' ,A4,')'/'	SINPUT
	* ' NO. NO. 1 NO. 2 X Y Z	SINPUT
	* X Y Z'//)	SINPUT
	WRITE (6,54) KQTYPE(K),KQ1(K),KQ2(K), (RK1(I,K),I=1,3)	SINPUT
	* , (RK2(I,K),I=1,3)	SINPUT
54	FORMAT(I6,2I9,2(6X,3F9.3) )	SINPUT
60	CONTINUE	SINPUT
C		SINPUT
C	CARD D.7 BODY SEGMENT SYMMETRY INPUT	SINPUT
C		SINPUT
	70 READ (5,71) (NSYM(J),J=1,NSEG)	SINPUT
	71 FORMAT(18I4)	SINPUT
	DO 103 J=1,NSEG	TGMOD2

	LJ = NSYM(J)	TGMOD2
	IF(IABS(LJ).GT.NSEG) GO TO 107	TGMOD2
	IF(LJ) 104,103,105	TGMOD2
105	LK = NSYM(LJ)	TGMOD2
	IF(IABS(LK).GT.NSEG) GO TO 107	TGMOD2
	IF(LK.NE.J) GO TO 106	TGMOD2
	GO TO 103	TGMOD2
104	JJ = -J	TGMOD2
	LJ = -LJ	TGMOD2
	LK = NSYM(LJ)	TGMOD2
	IF(IABS(LK).GT.NSEG) GO TO 107	TGMOD2
	IF((LK.NE.JJ).OR.(NSYM(J).EQ.JJ)) GO TO 106	TGMOD2
	GO TO 103	TGMOD2
106	STOP 96	TGMOD2
107	STOP 97	TGMOD2
103	CONTINUE	TGMOD2
	WRITE(6,72) (J,J=1,NSEG)	SINPUT
	WRITE(6,73) (NSYM(J),J=1,NSEG)	SINPUT
72	FORMAT('0 BODY SEGMENT SYMMETRY INPUT',91X,'CARD D.7'//	SINPUT
*	' SEG NO.',30I4)	SINPUT
73	FORMAT('0 NSYM(J)',30I4)	SINPUT
	NSEG1 = NSEG+1	SINPUT
	DO 74 J=NSEG1,NGRND	SINPUT
74	NSYM(J) = 0	SINPUT
	IF (NSD.LE.0) GO TO 90	SINPUT
C		SINPUT
C	CARD D.8 SPRING DAMPERS FUNCTION INPUT.	SINPUT
C		SINPUT
	DO 79 J=1,NSD	SINPUT
79	READ (5,80) MSDM(J),MSDN(J),(APSDM(I,J),I=1,3),	SINPUT
*	(APSDN(I,J),I=1,3),(ASD(I,J),I=1,5)	SINPUT
80	FORMAT(2I3,11F6.0)	SINPUT
	WRITE (6,81) UNITL	SINPUT
81	FORMAT('0',5X,'SPRING DAMPERS FUNCTION INPUT',82X,'CARDS D.8'//	SINPUT
*	18X,'COORDINATES OF ATTACHMENT POINTS ('A4,')'//	SINPUT
*	5X,'SEGMENT',9X,'SEGMENT M',16X,'SEGMENT N',15X,	SINPUT
*	'SPRING FORCE FUNCTION',12X,'DAMPING FORCE FUNCTION'//	AFREVS
*	' NO. M N',2(6X,'X',7X,'Y',7X,'Z',2X),7X,'D0',9X,'A1',11X,	SINPUT
*	'A2',13X,'B1',10X,'B2' // )	SINPUT
	DO 82 J=1,NSD	SINPUT
82	WRITE (6,83) J,MSDM(J),MSDN(J),(APSDM(I,J),I=1,3),	SINPUT
*	(APSDN(I,J),I=1,3),(ASD(I,J),I=1,5)	SINPUT
83	FORMAT(I3,2I4,2(1X,3F8.2),F11.2,2F12.3,F15.3,F12.3)	SINPUT
C		SINPUT
C	CARDS D.9 FORCE AND/OR TORQUE FUNCTIONS.	CHGIII
C		SINPUT
90	NFVSEG(6)= NFORCE	SINPUT
	IF (NFORCE.LE.0) GO TO 99	SINPUT
	WRITE (6,91)	SINPUT
91	FORMAT ('0',6X,'FORCE AND/OR TORQUE FUNCTION INPUTS',78X,'CARDS D.CHGIII	

*9'//,	5X,'NO.',	5X,'SEG',	5X,'FCN',	13X,'X',	9X,'Y',	9X,'Z',	CHGIII
*	13X,'YAW',	6X,'PITCH',	6X,'ROLL' //				SINPUT
	DO 95	J=1,NFORCE					SINPUT
	READ (5,92)	NFVSEG(J),NFVNT(J),P1,P2					SINPUT
92	FORMAT (2I6,6F10.0)						SINPUT
	WRITE (6,93)	J,NFVSEG(J),NFVNT(J),P1,P2					SINPUT
93	FORMAT (3I8,6X,3F10.3,6X,3F10.3)						SINPUT
	CALL DRCYPR	(DE,P2,IDYPR)					SINPUT
	DO 94	I=1,3					SINPUT
94	QFU(I,J) =	DE(1,I)					FIXSPT
95	CALL CROSS	(P1,QFU(1,J),QFV(1,J))					SINPUT
99	RETURN						SINPUT
	END						SINPUT

```

SUBROUTINE SLPLOT (X, NX, XO, XN, XL, XSIZE, XLAB, NXLB,           SLPLOT
*                  Y, NY, YO, YN, YL, YSIZE, YLAB, NYLB,       SLPLOT
*                  NPTS, NYY, NDY, PLAB1, NPLB1, PLAB2, NPLB2)  SLPLOT
REV III.2 08/08/84REVIII

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ARGUMENTS:

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X(NPTS)          - ARRAY OF NPTS ABSCISSAS TO BE PLOTTED.      SLPLOT
Y(NDY,NYY)       - ARRAY OF NPTS*NYY ORDINATES TO BE PLOTTED.  SLPLOT
NX,NY            - POSITIVE - NO. OF LINEAR SUBDIVISIONS.      SLPLOT
                  NEGATIVE - NO. OF LOGARITHMIC DECADES.      SLPLOT
XO,YO           - AXES ORIGINS (POWER OF TEN IF NX,NY NEGATIVE). SLPLOT
XN,YN           - AXES END VALUES (REQUIRED IF NX,NY POSITIVE). SLPLOT
XL,YL           - LENGTH (INCHES) OF X,Y AXES.                SLPLOT
XSIZE,YSIZE     - PAPER SIZE (INCHES) IN X,Y DIRECTIONS.     SLPLOT
XLAB,YLAB       - X,Y AXES LABELS (ALPHANUMERIC ARRAYS).     SLPLOT
NXLB,NYLB       - NO. OF CHARACTERS IN X,Y LABELS.            SLPLOT
NPTS            - NO. OF POINTS IN X ARRAY AND EACH Y ARRAY.  SLPLOT
NYY             - NO. OF Y ARRAYS TO BE PLOTTED VS. X ARRAY.  SLPLOT
NDY             - FIRST DIMENSION OF Y ARRAY IN CALLING ROUTINE. SLPLOT
                  (NDY MUST BE .GE. NPTS)                      SLPLOT
PLAB1,PLAB2     - 1ST & 2ND LINES OF PLOT ID LABELS (ALPHANUMERIC). SLPLOT
NPLB1,NPLB2     - NO. OF CHARACTERS IN PLOT ID LABELS.        SLPLOT

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NOTE: PLOTS WILL BE TRUNCATED AS FOLLOWS:

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NX,NY POSITIVE - XO,YO .LE. X,Y .LE. XN,YN                    SLPLOT
NX,NY NEGATIVE - XO,YO .LE. X,Y .LE. XN*10**(-NX),YO*10**(-NY) SLPLOT

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DIMENSION X(NPTS),Y(NDY,NYY),XLAB(1),YLAB(1),PLAB1(1),PLAB2(1) SLPLOT

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NOTE: THIS ROUTINE HAS BEEN WRITTEN FOR THE PLOTTING FACILITIES AT CALSPAN. THE FOLLOWING ITEMS ARE KNOWN TO BE CONTRARY TO THE NORMAL CALCOMP PROCEDURES AND SHOULD BE EXAMINED BY USERS AT OTHERS COMPUTER SYSTEMS AND CHANGES MADE ACCORDINGLY.

1. AT CALSPAN THE PLOTTED CHARACTERS GENERATED BY SUBROUTINE SYMBOL HAVE A WIDTH OF 6/7 TIMES THE HEIGHT. FOR THE CALCOMP ROUTINES THE WIDTH IS EQUAL TO THE HEIGHT. THE STATEMENT 'WIDTHF = 6.0/7.0' SHOULD BE CHANGED TO 'WIDTHF = 1.0'.
2. THE ONLY INITIALIZATION REQUIRED AT CALSPAN IS THE STATEMENT 'CALL PLOT (0.0,0.0,0)' TO ESTABLISH A NEW PAGE, INCLUDING THE FIRST PAGE. THIS IS FOLLOWED BY 'CALL PLOT (XO,YO,-3)' TO SET THE PLOT ORIGIN ON THE PAGE. PROPER PLOT INITIALIZATION SHOULD BE DONE HERE AND IN SUBROUTINE POSTPR (AFTER STATEMENT NO. 30) AS REQUIRED BY THE USER'S PLOTTING FACILITY.
3. THE STATEMENT 'CALL NEWPEN(2)' SHOULD BE EXAMINED OR DELETED.
4. THE STATEMENT 'CALL EFLOT' AFTER STATEMENT NO. 50 IN POSTPR IS REQUIRED AT CALSPAN TO CLOSE OUT THE PLOT FILES. THIS

C	SHOULD BE CHANGED TO CONFORM TO THE REQUIREMENTS OF THE	SLPLOT
C	USER'S PLOTTING FACILITIES.	SLPLOT
C		SLPLOT
C	5. THE NECESSARY JOB CONTROL LANGUAGE FOR PLOTTING IS NECESSARY.	SLPLOT
C		SLPLOT
C	6. THE ONLY CALCOMP ROUTINES NEEDED ARE SYMBOL, NUMBER AND PLOT.	SLPLOT
C		SLPLOT
	LOGICAL NXPOS, NXNEG, NYPOS, NYNEG	SLPLOT
	DATA HN/0.07/, HL/0.105/	SLPLOT
	WIDTHF = 1.0	REDIMN
	WN = WIDTHF*HN	SLPLOT
	WL = WIDTHF*HL	SLPLOT
C	** PLOT PAGE INITIALIZATION **	SLPLOT
	CALL PLOT (0.0,0.0,-3)	CHANGE
	XP = 0.5*(XSIZE-(XL-0.5))	SLPLOT
	YP = 0.5*(YSIZE-(YL-1.0))	SLPLOT
	CALL PLOT (XP,YP,-3)	SLPLOT
	NXPOS = NX.GT.0	SLPLOT
	NXNEG = NX.LT.0	SLPLOT
	NYPOS = NY.GT.0	SLPLOT
	NYNEG = NY.LT.0	SLPLOT
C	** PLOT AXES AND ID LABELS. **	SLPLOT
	XP = 0.0	SLPLOT
	YP = 0.0	SLPLOT
	IF (.NOT.NXPOS) GO TO 12	SLPLOT
C	** LINEAR X AXIS **	SLPLOT
	CALL LINAXS (XP, YP, 0.0, NX, XL)	SLPLOT
	XB = XL/(XN-X0)	SLPLOT
C	** LINEAR X AXIS NUMERICS **	SLPLOT
	DX = XL/FLOAT(NX)	SLPLOT
	EX = X0	SLPLOT
	DD = (XN-X0)/FLOAT(NX)	SLPLOT
	ND = 0.99 - ALOG10(ABS(DD))	SLPLOT
	IF (ND.LE.0) ND = -1	SLPLOT
	IX = 0	SLPLOT
	YC = YP - 2.0*HN	SLPLOT
11	AX = ABS(EX)	SLPLOT
	NF = 0	SLPLOT
	IF (AX.GE.10.0) NF = ALOG10(AX)	SLPLOT
	NS = 0	SLPLOT
	IF (EX.LT.0.0) NS = 1	SLPLOT
	SP = NS+NF+2*ND	SLPLOT
	XC = XP - 0.5*SP*WN	SLPLOT
	CALL NUMBER (XC, YC, HN, EX, 0.0, ND)	SLPLOT
	XP = XP + DX	SLPLOT
	EX = EX + DD	SLPLOT
	IX = IX + 1	SLPLOT
	IF (ABS(EX).GT.ABS(0.1*DD)) GO TO 18	SLPLOT
	IF (IX.GT.NX) GO TO 12	SLPLOT
	CALL PLOT (XP, YP+YL,3)	SLPLOT



	CALL PLOT (XP, YP ,2)	SLPLOT
18	IF (IX.LE.NX) GO TO 11	SLPLOT
12	IF (.NOT.NXNEG) GO TO 14	SLPLOT
C	** LOG X AXIS **	SLPLOT
	CALL LOGAXS (XP, YP, 0.0, -NX, XL)	SLPLOT
	XB = XL/ALOG(10.0**(-NX))	SLPLOT
	XA = -XB*ALOG(X0)	SLPLOT
C	** LOG X AXIS NUMERICS **	SLPLOT
	DX = XL/FLOAT(-NX)	SLPLOT
	EX = ALOG10(X0)	SLPLOT
	IX = 0	SLPLOT
13	CALL NUMBER (XP-1.0*WN, YP-2.5*HN, HN, 10.0, 0.0, -1)	SLPLOT
	CALL NUMBER (XP+1.0*WN, YP-2.0*HN, HN, EX, 0.0, -1)	SLPLOT
	XP = XP + DX	SLPLOT
	EX = EX + 1.0	SLPLOT
	IX = IX - 1	SLPLOT
	IF (IX.GE.NX) GO TO 13	SLPLOT
14	IF (NXLB.LE.0) GO TO 15	SLPLOT
C	** X AXIS LABEL **	SLPLOT
	XPX = (XL-FLOAT(NXLB)*WL)/2.0	SLPLOT
	YPX = YP-4.0*HN-HL	SLPLOT
	CALL SYMBOL(XPX, YPX, HL, XLAB, 0.0, NXLB)	SLPLOT
15	IF (NPLB1.LE.0) GO TO 16	SLPLOT
C	** PLOT LABEL - 1ST LINE **	SLPLOT
	XP1 = (XL-FLOAT(NPLB1)*WL)/2.0	SLPLOT
	YP1 = YP-4.0*HN-4.0*HL	SLPLOT
	CALL SYMBOL(XP1, YP1, HL, PLAB1, 0.0, NPLB1)	SLPLOT
16	IF (NPLB2.LE.0) GO TO 20	SLPLOT
C	** PLOT LABEL - 2ND LINE **	SLPLOT
	XP2 = (XL-FLOAT(NPLB2)*WL)/2.0	SLPLOT
	YP2 = YP-4.0*HN-6.0*HL	SLPLOT
	CALL SYMBOL(XP2, YP2, HL, PLAB2, 0.0, NPLB2)	SLPLOT
20	XP = 0.0	SLPLOT
C	** COMPLETE AXIS GRID **	SLPLOT
	IF (NYPOS) CALL LINAXS (XL, YP, 90.0, NY, YL)	SLPLOT
	IF (NYNEG) CALL LOGAXS (XL, YP, 90.0, -NY, YL)	SLPLOT
	IF (NXPOS) CALL LINAXS (XL, YL, 180.0, NX, XL)	SLPLOT
	IF (NXNEG) CALL LOGAXS (XL, YL, 180.0, -NX, -XL)	SLPLOT
	IF (.NOT.NYPOS) GO TO 22	SLPLOT
C	** LINEAR Y AXIS **	SLPLOT
	CALL LINAXS (XP, YL, -90.0, NY, YL)	SLPLOT
	YB = YL/(YN-Y0)	SLPLOT
C	** LINEAR Y AXIS NUMERICS **	SLPLOT
	DY = YL/FLOAT(NY)	SLPLOT
	EY = Y0	SLPLOT
	DD = (YN-Y0)/FLOAT(NY)	SLPLOT
	ND = 0.99 - ALOG10(ABS(DD))	SLPLOT
	IF (ND.LE.0) ND = -1	SLPLOT
	IY = 0	SLPLOT
	XC = XP - 1.0*HN	SLPLOT

21	AY = ABS(EY)	SLPLOT
	NF = 0	SLPLOT
	IF (AY.GE.10.0) NF = ALOG10(AY)	SLPLOT
	NS = 0	SLPLOT
	IF (EY.LT.0.0) NS = 1	SLPLOT
	SP = NS+NF+2+ND	SLPLOT
	YC = YP - 0.5*SP*WN	SLPLOT
	CALL NUMBER (XC, YC, HN, EY, 90.0, ND)	SLPLOT
	YP = YP + DY	SLPLOT
	EY = EY + DD	SLPLOT
	IY = IY + 1	SLPLOT
	IF (ABS(EY).GT.ABS(0.1*DD)) GO TO 19	SLPLOT
	IF (IY.GT.NY) GO TO 22	SLPLOT
	CALL PLOT (XP+XL, YP, 3)	SLPLOT
	CALL PLOT (XP, YP, 2)	SLPLOT
19	IF (IY.LE.NY) GO TO 21	SLPLOT
22	IF (.NOT.NYNEG) GO TO 24	SLPLOT
C	** LOG Y AXIS **	SLPLOT
	CALL LOGAXS (XP, YL, -90.0, -NY, -YL)	SLPLOT
	YB = YL/ALOG(10.0**(-NY))	SLPLOT
	YA = -YB*ALOG(YO)	SLPLOT
C	** LOG Y AXIS NUMERICS **	SLPLOT
	DY = YL/FLOAT(-NY)	SLPLOT
	EY = ALOG10(YO)	SLPLOT
	IY = 0	SLPLOT
23	CALL NUMBER (XP-1.0*HN, YP-1.0*WN, HN, 10.0, 90.0, -1)	SLPLOT
	CALL NUMBER (XP-1.5*HN, YP+1.0*WN, HN, EY, 90.0, -1)	SLPLOT
	YP = YP + DY	SLPLOT
	EY = EY + 1.0	SLPLOT
	IY = IY - 1	SLPLOT
	IF (IY.GE.NY) GO TO 23	SLPLOT
24	IF (NYLB.LE.0) GO TO 25	SLPLOT
C	** Y AXIS LABEL **	SLPLOT
	XPY = XP-4.0*HN	SLPLOT
	YPY = (YL-FLOAT(NYLB)*WL)/2.0	SLPLOT
	CALL SYMBOL(XPY, YPY, HL, YLAB, 90.0, NYLB)	SLPLOT
25	CONTINUE	SLPLOT
C	** PLOT DATA ARRAYS **	SLPLOT
	NSYM = 24	SLPLOT
	IS = NPTS/NSYM	SLPLOT
	IF (IS.EQ.0) IS = 1	VARTTH
	XOMIN = X0/1000.0	SLPLOT
	YOMIN = Y0/1000.0	SLPLOT
	DO 40 J=1, NYY	SLPLOT
	IPEN = 3	SLPLOT
	DO 39 I=1, NPTS	SLPLOT
	X1 = X2	SLPLOT
	Y1 = Y2	SLPLOT
	IF (NXPOS) X2 = XB*(X(I) - X0)	SLPLOT
	IF (NYPOS) Y2 = YB*(Y(I,J) - Y0)	SLPLOT

	IF (NXNEG) X2 = XA + XB*ALOG(AMAX1(X(I) ,XOMIN))	SLPLOT
	IF (NYNEG) Y2 = YA + YB*ALOG(AMAX1(Y(I,J),YOMIN))	SLPLOT
	IF (Y2.LT.0.0 .OR. Y2.GT.YL) GO TO 33	SLPLOT
	IF (X2.LT.0.0 .OR. X2.GT.XL) GO TO 33	SLPLOT
	IF (IPEN.EQ.3) GO TO 33	SLPLOT
	CALL PLOT (X2,Y2,IPEN)	SLPLOT
C	**    PLOT NYSM SYMBOLS    **	SLPLOT
	IF (NYY.EQ.1 .OR. MOD(I,IS).NE.0) GO TO 39	SLPLOT
	IF (MOD((I/IS)-1,NYY)+1.EQ.J) CALL SYMBOL (X2,Y2,0.14,J,0.0,-2)	SLPLOT
	GO TO 39	SLPLOT
33	IF (I.EQ.1) GO TO 39	SLPLOT
	DX = X2 - X1	SLPLOT
	IF (DX.NE.0.0) GO TO 34	SLPLOT
	AX0 = 1.0	SLPLOT
	AXL = 0.0	SLPLOT
	IF (X1.GE.0.0) AX0 = 0.0	SLPLOT
	IF (X1.LE.XL ) AXL = 1.0	SLPLOT
	GO TO 35	SLPLOT
34	AX0 = -X1 /DX	SLPLOT
	AXL = (XL-X1)/DX	SLPLOT
35	AX1 = AMIN1(AX0,AXL)	SLPLOT
	AX2 = AMAX1(AX0,AXL)	SLPLOT
	DY = Y2 - Y1	SLPLOT
	IF (DY.NE.0.0) GO TO 36	SLPLOT
	AY0 = 1.0	SLPLOT
	AYL = 0.0	SLPLOT
	IF (Y1.GE.0.0) AY0 = 0.0	SLPLOT
	IF (Y1.LE.YL ) AYL = 1.0	SLPLOT
	GO TO 37	SLPLOT
36	AY0 = -Y1 /DY	SLPLOT
	AYL = (YL-Y1)/DY	SLPLOT
37	AY1 = AMIN1(AY0,AYL)	SLPLOT
	AY2 = AMAX1(AY0,AYL)	SLPLOT
	A1 = AMAX1(AX1,AY1,0.0)	SLPLOT
	A2 = AMIN1(AX2,AY2,1.0)	SLPLOT
	IF (A1.GE.A2 ) GO TO 39	SLPLOT
	XP = X1 + A1*DX	SLPLOT
	YP = Y1 + A1*DY	SLPLOT
	CALL PLOT(XP,YP,IPEN)	SLPLOT
	IPEN = 2	SLPLOT
	XP = X1 + A2*DX	SLPLOT
	YP = Y1 + A2*DY	SLPLOT
	CALL PLOT(XP,YP,IPEN)	SLPLOT
	IF (A2.NE.1.0) IPEN = 3	SLPLOT
39	CONTINUE	SLPLOT
40	CONTINUE	SLPLOT
	RETURN	SLPLOT
	END	SLPLOT



```

C      SUBROUTINE SOLVR(A1,A2,A3,A4,A5,A6,A7,A8,P,RX,RZ)          SOLVR
C                                     REV III.2 08/08/84REVI III
C      IMPLICIT REAL*8 (A-H,O-Z)                                SOLVR
C      *****                                                SOLVR
C      *****                                                SOLVR
C      THIS SUBROUTINE WILL SOLVE A SET OF SIMULTANEOUS EQUATIONS SOLVR
C      TO FIND COMPONETS OF VECTOR R THAT SATISFY THE PROPERTIES NEEDED SOLVR
C      TO DETURMINE THE EQUATION OF THE PROJECTED ELLIPSE.      SOLVR
C      SEE WRITEUP.                                             SOLVR
C      *****                                                SOLVR
C      *****                                                SOLVR
C      DIMENSION P(3)                                          SOLVR
C      B=A1*P(1)+A2*P(2)+A3*P(3)                               SOLVR
C      D=A4*P(1)+A5*P(2)+A6*P(3)                               SOLVR
C      T1=A7*(D/B)**2+A6-2.0*A8*D/B                             SOLVR
C      T2=2.0*A7*D/(B)**2-2.0*A8/B                             SOLVR
C      T3=A7*(1/B)**2-1                                         SOLVR
C      RZ=(-T2+DSQRT(T2**2-4.0*T1*T3))/(2.0*T1)                SOLVR
C      RX=-D*RZ/B-1.0/B                                         SOLVR
C      RETURN                                                  SOLVR
C      END                                                      SOLVR

```



FD = 0.0	SPDAMP
IF (ASD(1,I).LT.0.0) GO TO 21	SLIP
DDO = DEL-ASD(1,I)	SPDAMP
IF (DDO.LE.0.0 .AND. ASD(2,I).LE.0.0) GO TO 41	SPDAMP
FS = DDO*(DABS(ASD(2,I)) + DABS(DDO)*ASD(3,I))	SPDAMP
FD = DMV*(ASD(4,I)+DABS(DMV)*ASD(5,I))	SPDAMP
GO TO 29	SPDAMP
21 DDO = DEL+ASD(1,I)	SPDAMP
JF1 = ASD(2,I)	SPDAMP
IF (JF1.EQ.0) GO TO 22	SPDAMP
JF2 = NTI(JF1)	SPDAMP
IF (DDO.GT.0.0 .OR. ASD(3,I).EQ.0.0) FS = EVALFD(DDO,JF2,1)	SPDAMP
22 JF3 = ASD(4,I)	SPDAMP
IF (JF3.EQ.0) GO TO 29	SPDAMP
JF4 = NTI(JF3)	SPDAMP
IF (DDO.GT.0.0 .OR. ASD(3,I).EQ.0.0) FD = EVALFD(DMV,JF4,1)	SLIP
29 DO 30 K=1,3	SPDAMP
30 TOTF(K) = (FS+FD)*DUNIT(K)	SPDAMP
C	SPDAMP
C	AND ADD THE RESULTING FORCE AND TORQUE TO THE U1 AND U2 ARRAYS.
C	SPDAMP
CALL MAT31(D(1,1,M),TOTF,T5)	SPDAMP
CALL MAT31(D(1,1,N),TOTF,T6)	SPDAMP
CALL CROSS(APSDM(1,I),T5,T7)	SPDAMP
CALL CROSS(APSDN(1,I),T6,T8)	SPDAMP
DO 40 K=1,3	SPDAMP
U1(K,M) = U1(K,M) - TOTF(K)	SPDAMP
U1(K,N) = U1(K,N) + TOTF(K)	SPDAMP
U2(K,M) = U2(K,M) - T7(K)	SPDAMP
40 U2(K,N) = U2(K,N) + T8(K)	SPDAMP
41 IBSF = 3-2*MOD(I,2)	SPDAMP
NBSF = NBSFO + (I+1)/2	SPDAMP
BSF(IBSF ,NBSF) = DEL	SPDAMP
BSF(IBSF+1,NBSF) = FD + FS	SPDAMP
90 CONTINUE	SPDAMP
CALL ELTIME(2,32)	SPDAMP
RETURN	SPDAMP
END	SPDAMP

```

C      SUBROUTINE SPLINE (X,Y,F,N,L)
C
C      REV 19      05/14/79
C
C      ROUTINE TO FIT A SET OF POLYNOMIALS OF DEGREE L
C      TO A SET OF GIVEN DATA POINTS (X(I),Y(I),I=1,N)
C
C      FUNCTION IS OF FORM:
C
C      Y = F(2,K) + F(3,K)*DX + F(4,K)*DX**2 + F(5,K)*DX**3
C
C      WHERE: DX = XX - F(1,K)
C      F(1,K) .LE. XX .LT. F(1,K+1) ; (SETS K)
C      IF (XX.GT.F(1,N)) ; USE K=N, CONSTANT FIT TO Y(N)
C      IF (XX.LT.F(1,1)) ; EXTRAPOLATED FIT FOR K=1
C
C      F(1,I) = X(I) ,      I=1,N
C      F(2,I) = Y(I) ,      I=1,N
C
C      DEGREE L      CONTINUITY
C      0      F(3,I) = F(4,I) = F(5,I) = 0 , I=1,N      NONE
C      1      F(4,I) = F(5,I) = 0 ,      I=1,N      Y
C      2      F(5,I) = 0 ,      I=1,N      Y,Y'
C      3      CUBIC SPLINE      Y,Y',Y''
C
C      F(K,N)=0 FOR K=3,5 IN ALL CASES
C
C      FOR L=2 AND L=3 THE CHANGES IN THE L'TH DERIVATIVES ARE MINIMIZED
C
C      SPECIAL CASES:
C      N=1 ;      TREATED AS L=0
C      N=2 ;      TREATED AS L=MIN(L,1)
C      L<0 ;      TREATED AS L=0
C      L>3 ;      TREATED AS L=3
C
C      STORAGE REQUIRED X(N),Y(N),F(5,N); SET BY CALLING PROGRAM
C
C      USAGE:
C      ALL COMPUTATIONS AND REAL VARIABLES ARE DOUBLE PRECISION
C      GIVEN: L,N, (X(I),Y(I),I=1,N)
C      CALL SPLINE (X,Y,F,N,L) ; SETS F
C
C      TO EVALUATE FUNCTION AND DERIVATIVES AT POINT XX
C
C      DO 10 K=1,N
C      IF (K.EQ.N) GO TO 11
C      IF (XX.LT.F(1,K+1)) GO TO 11
C 10 CONTINUE
C 11 DX = XX - F(1,K)
C      YY = F(2,K) + DX*(F(3,K)+DX*(F(4,K)+DX*F(5,K)))

```



C	YD = F(3,K) + DX*(2.0*F(4,K)+3.0*DX*F(5,K))	SPLINE
C	YDD = 2.0*F(4,K) + 6.0*DX*F(5,K)	SPLINE
C	YDDD = 6.0*F(5,K)	SPLINE
C	YDDDD = 0.0	SPLINE
CC		SPLINE
CC	FUNCTIONAL VALUE IN YY, DERIVATIVES IN YD'S	SPLINE
CC	REPEAT FOR NEXT VALUE OF XX	SPLINE
C		SPLINE
C	AUTHOR: DR. JOHN T. FLECK	SPLINE
C		SPLINE
	IMPLICIT REAL*8 (A-H,O-Z)	SPLINE
	DIMENSION X(N),Y(N),F(5,N),C(2,3)	SPLINE
	DO 20 I=1,N	SPLINE
	F(1,I) = X(I)	SPLINE
	DO 10 K=2,5	SPLINE
10	F(K,I) = 0.0	SPLINE
	IF (L.LT.3) F(2,I) = Y(I)	SPLINE
20	IF (L.GT.0 .AND. I.LT.N) F(3,I) = (Y(I+1)-Y(I))/(X(I+1)-X(I))	SPLINE
	IF (L.LT.2 .OR. N.LT.3) GO TO 99	SPLINE
	IF (L.GE.3) GO TO 50	SPLINE
	D1 = X(2) - X(1)	SPLINE
	SS = 0.0	SPLINE
	DS = 0.0	SPLINE
	DO 30 I=3,N	SPLINE
	F(4,I-1) = F(3,I-1) - F(3,I-2) - F(4,I-2)	SPLINE
	DX1 = X(I) - X(I-1)	SPLINE
	DX2 = X(I-1) - X(I-2)	SPLINE
	DD = D1/DX1 + D1/DX2	SPLINE
	SS = SS + DD*DD	SPLINE
	DS = DS + DD*(F(4,I-1)/DX1 - F(4,I-2)/DX2)	SPLINE
30	D1 = -D1	SPLINE
	F(4,1) = DS/SS	SPLINE
	DX = (X(2)-X(1))*F(4,1)	SPLINE
	F(3,1) = F(3,1) - DX	SPLINE
	DO 40 I=3,N	SPLINE
	XX = F(4,I-1) - DX	SPLINE
	F(3,I-1) = F(3,I-1) - XX	SPLINE
	F(4,I-1) = XX/(X(I)-X(I-1))	SPLINE
40	DX = -DX	SPLINE
	GO TO 99	SPLINE
C		SPLINE
C	CUBIC SPLINE	SPLINE
C		SPLINE
50	DO 51 I=2,N	SPLINE
	IF (I.EQ.N) GO TO 51	SPLINE
	F(4,I) = 3.0*(F(3,I)-F(3,I-1))	SPLINE
	F(5,I) = 2.0*(X(I+1)-X(I-1))	SPLINE
51	F(3,I-1) = 0.0	SPLINE
	F(2,N) = -1.0	SPLINE
	F(3,1) = -1.0	SPLINE

	DO 60 I=3,N	SPLINE
	DX = X(I-1) - X(I-2)	SPLINE
	IF (I.GT.3) DX = DX/F(5,I-2)	SPLINE
	DO 60 K=3,5	SPLINE
60	F(K,I-1) = F(K,I-1) - F(K,I-2)*DX**((K-1)/2)	SPLINE
	DO 70 I=3,N	SPLINE
	NI = N-I	SPLINE
	DX = X(NI+3) - X(NI+2)	SPLINE
	DO 70 K=2,4	SPLINE
70	F(K,NI+2) = (F(K,NI+2) - DX*F(K,NI+3))/F(5,NI+2)	SPLINE
	DO 71 J=1,2	SPLINE
	DO 71 K=J,3	SPLINE
	C(J,K) = 0.0	SPLINE
	DO 71 I=3,N	SPLINE
	DX1 = X(I) - X(I-1)	SPLINE
	DX2 = X(I-1) - X(I-2)	SPLINE
71	C(J,K) = C(J,K) + ( (F(J+1,I) - F(J+1,I-1))/DX1	SPLINE
*	- (F(J+1,I-1) - F(J+1,I-2))/DX2)	SPLINE
*	* ( (F(K+1,I) - F(K+1,I-1))/DX1	SPLINE
*	- (F(K+1,I-1) - F(K+1,I-2))/DX2)	SPLINE
	DEN = C(1,1)*C(2,2) - C(1,2)*C(1,2)	SPLINE
	F(4,1) = (C(1,1)*C(2,3) - C(1,2)*C(1,3))/DEN	SPLINE
	F(4,N) = (C(2,2)*C(1,3) - C(1,2)*C(2,3))/DEN	SPLINE
	DO 72 I=3,N	SPLINE
72	F(4,I-1) = F(4,I-1) - F(4,1)*F(3,I-1) - F(4,N)*F(2,I-1)	SPLINE
	D1 = X(2) - X(1)	SPLINE
	F(3,1) = (Y(2)-Y(1))/D1 - (2.0*F(4,1)+F(4,2))*D1/3.0	SPLINE
	F(2,1) = Y(1)	SPLINE
	DO 80 I=2,N	SPLINE
	F(2,I) = Y(I)	SPLINE
	DX = X(I) - X(I-1)	SPLINE
	IF (I.LT.N) F(3,I) = F(3,I-1) + (F(4,I)+F(4,I-1))*DX	SPLINE
80	F(5,I-1) = (F(4,I)-F(4,I-1))/(3.0*DX)	SPLINE
	F(4,N) = 0.0	SPLINE
99	RETURN	SPLINE
	END	SPLINE

```

DOUBLE PRECISION FUNCTION SPRNGF(T,D,ZD,SPR,JSTOP)          SPRNGF
C                                                              REV IV    07/23/86TWOPI
C COMPUTES NONLINEAR SPRING TORQUE FOR JOINTS AS A FUNCTION OF ANGLESPRNGF
C ACTUALLY ROUTINE RETURNS TORQUE/ABS(SIN THETA)          SPRNGF
C                                                              SPRNGF
C ARGUMENTS:                                              SPRNGF
C     T      : COS THETA WHERE THETA IS ANGLE OF JOINT (0<THETA<PI) SPRNGF
C     D      : ABS(SIN THETA)                               SPRNGF
C     ZD     : -THETA DOT * SIN THETA                     SPRNGF
C     SPR    : ARRAY OF 5 VALUES DESCRIBING FUNCTION EVALUATION SPRNGF
C     JSTOP  : INDICATOR TO BE SET TO ONE IF JOINT IS IN STOP SPRNGF
C                                                              SPRNGF
C IMPLICIT REAL*8 (A-H,O-Z)                               SPRNGF
COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),               SPRNGF
*              UNITL,UNITM,UNITT,GRAVITY(3),TWOPI       TWOPI
DIMENSION SPR(5)                                         SPRNGF
C                                                              SPRNGF
C     RESET T=1 IF T>1 (HAD & HBD IN VISPR)              SPRNGF
C                                                              SPRNGF
C     IF (T.GT.1.0) T = 1.0                               SPRNGF
C     IF (T.LT.-1.0) T = -1.0                             SPRNGF
C     Z = DACOS(T)                                         SPRNGF
C     U = EPS(1)*D                                         SPRNGF
C     Q = 0.0                                              SPRNGF
C     IF (D.NE.0.0) Q = -ZD/U                              SPRNGF
C     IF (Q.GT.1.0) Q = 1.0                               SPRNGF
C     IF (Q.LT.-1.0) Q = -1.0                             SPRNGF
C     X = 0.5*(1.0+SPR(4) + Q*(1.0-SPR(4)) )              SPRNGF
C     Y = 0.0                                              SPRNGF
C     IF (D.NE.0.0) Y = Z/D                               SPRNGF
C     Q = 1.0                                              SPRNGF
C     IF (DABS(Z).LT.EPS(4)) Y = DSIGN(Q,Z)               SPRNGF
C     SPRNGF = Y*SPR(1)                                    SPRNGF
C     JSTOP = 0                                           SPRNGF
C     IF (SPR(5).GT.0.0) GO TO 10                          SPRNGF
C     SPRNGF = X*SPRNGF                                    SPRNGF
C     GO TO 11                                             SPRNGF
10 IF (Z.LT.SPR(5)) GO TO 11                               SPRNGF
C     JSTOP = 1                                           SPRNGF
C     Z = Z-SPR(5)                                         SPRNGF
C     SPRNGF = SPRNGF + X/D*(SPR(2)+Z*SPR(3))*Z**2       SPRNGF
11 CONTINUE                                               SPRNGF
C     RETURN                                              SPRNGF
C     END                                                 SPRNGF

```

	SUBROUTINE TRIGFS		TRIGFS
C		REV 19	08/05/78TRIGFS
	IMPLICIT REAL*8 (A-H,O-Z)		TRIGFS
	COMMON/CDINT/ UU(4),GH(3,4),		TRIGFS
	* E(3,240), F(5,240),GG(5,240),Y(5,240),U(5,240),		TRIGFS
	* H,HPRINT,HS,TPRINT,TSTART,ICNT,IDBL,IFLAG		TRIGFS
	BETA = 0.0		TRIGFS
	IF (HS.NE.0.0) BETA = (H/HS)**2		TRIGFS
	R1 = HS/H		TRIGFS
	R2 = 1.0+BETA*R1		TRIGFS
	GH(3,1) = 2.0/(H*R2)		TRIGFS
	GH(2,1) = GH(3,1)*(BETA-1.0)		TRIGFS
	GH(1,1) = GH(3,1)* BETA		TRIGFS
	GH(1,2) = 4.0*BETA/(R2*H**2)		TRIGFS
	GH(3,2) = GH(1,2)* R1		TRIGFS
	GH(2,2) = GH(1,2)*(R1+1.0)		TRIGFS
	GH(3,3) = 1.0/H		TRIGFS
	GH(2,3) = 4.0*GH(3,3)		TRIGFS
	GH(1,3) = 3.0*GH(3,3)		TRIGFS
	GH(3,4) = 2.0/H**2		TRIGFS
	GH(2,4) = 2.0*GH(3,4)		TRIGFS
	GH(1,4) = GH(3,4)		TRIGFS
	UU(1) = 2.0/H		TRIGFS
	UU(2) = 0.0		TRIGFS
	UU(3) = 0.5*H		TRIGFS
	UU(4) = 0.25*H**2		TRIGFS
	IF (HS.EQ.0.0) GO TO 99		TRIGFS
	UU(1) = BETA*(4.25+2.25/R1)		TRIGFS
	UU(2) = BETA*(2.25+1.25/R1)/R1		TRIGFS
	UAU = 1.0+UU(1)+UU(2)		TRIGFS
	UU(1) = 2.0*UU(1)/(UAU*H)		TRIGFS
	UU(2) = 4.0*UU(2)/(UAU*H**2)		TRIGFS
99	RETURN		TRIGFS
	END		TRIGFS



C

```
20 XTIME = TIME
   DO 22 K=1,30
   DO 22 J=1,3
   DO 21 I=1,3
21 XD(I,J,K) = D(I,J,K)
22 XSEGLP(J,K) = SEGLP(J,K)
   DO 25 K=1,NSEG
   IF (LPMI(K).EQ.0) GO TO 25
   CALL DOT33 (DPMI(1,1,K),D(1,1,K),T3)
   DO 24 I=1,3
   DO 24 J=1,3
24 XD(I,J,K) = T3(I,J)
25 CONTINUE
   WRITE (1) XTIME,XSEGLP,XD
99 RETURN
   END
```

```
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
UNIT1
```

```

SUBROUTINE UPDATE(I)
CALLLED BY SUBROUTINE DINT
(I=1) AT THE START OF A NEW STEP TO SETUP ANY NEW CONDITIONS
      TO BE VALID FOR ENTIRE INTEGRATION STEP
      A. UPDATE FORCE DEFLECTION FUNCTIONS(SUBROUTINE UPDFDC)
      B. TEST FOR LOCKED JOINTS
NOTE: ARGUMENT I WILL BE SET TO -1 TO RESET INTEGRATOR.
(I=2) AT THE END OF EACH SUCCESSFUL INTEGRATION STEP TO
      COMPLETE CALCULATIONS FOR OUTPUT (SUBROUTINE AIRBG3).
IMPLICIT REAL*8(A-H,O-Z)
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,
*              NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG
COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),
*              SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)
COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),
*              RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),
*              JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)
COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),
*              F(3,30),TQ(3,30),WJ(30),A11(3,3,30)
COMMON/JBARTZ/ MNPL( 30),MNBLT( 8),MNSEG( 30),MNBAG( 6),
*              MPL(3,5,30),MBLT(3,5,8),MSEG(3,5,30),MBAG(3,10,6),
*              NTPL( 5,30),NTBLT( 5,8),NTSEG( 5,30)
COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)
COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),
*              PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF
COMMON/CSTRNT/ A13(3,3,24),A23(3,3,24),B31(3,3,24),B32(3,3,24),
*              HHT(3,3,12),RK1(3,12),RK2(3,12),QQ(3,12),TQQ(3,12),
*              RQQ(3,12),HQQ(3,12),SQQ(12),CFQQ(12),
*              KQ1(12),KQ2(12),KQTYPE(12)
COMMON/TEMPVI/ CREST,TTI(3),R1I(3),R2I(3),JSTOP(4,2,30)
COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30),
*              FE(3,30),TQE(3,30),CONST(5,30)
COMMON/HRNESS/ BAR(15,100),BB(100),BBDOT(100),PLOSS(2,100),
*              XLONG(20),HTIME(2),IBAR(5,100),NL(2,100),
*              NPTSPB(20),NPTPLY(20),NTHRNS(20),NBLTPH(5)
DIMENSION TQTEST(3),LOCK(8,3),T(3)
DATA LOCK/-8, 6, 5, 7,-3,-2,-4, 1,
*          6,-8, 4,-3, 7,-1,-5, 2,
*          5, 4,-8,-2,-1, 7,-6, 3/
CALL AIRBG3 FOR AIRBAG, IF ANY.
IF (NBAG.NE.0) CALL AIRBG3(I)
IF (I.EQ.2) GO TO 42
CALL ELTIME (1,7)
IF (NPL.LE.0) GO TO 13

```

C		UPDATE
C	CALL UPDFDC FOR EACH ALLOWED PLANE-SEGMENT CONTACT.	UPDATE
C		UPDATE
	NPSF = 0	UPDATE
	DO 12 J=1,NPL	UPDATE
	NK = MNPL(J)	UPDATE
	IF (NK.LE.0) GO TO 12	UPDATE
	DO 11 K = 1, NK	UPDATE
	NPSF = NPSF+1	UPDATE
	NT = NTPL(K,J)	UPDATE
	NF = NTAB(NT+5)	UPDATE
	CALL UPDFDC(NT)	UPDATE
	IF (NT.GT.0.OR.TAB(NF+3).EQ.0.0) GO TO 11	UPDATE
	CALL IMPULS(1,K,J)	UPDATE
	I = -1	UPDATE
	11 CONTINUE	UPDATE
	12 CONTINUE	UPDATE
	13 IF (NBLT.LE.0) GO TO 16	UPDATE
C		UPDATE
C	CALL UPDFDC FOR EACH ALLOWED BELT-SEGMENT CONTACT.	UPDATE
C		UPDATE
	DO 15 J=1,NBLT	UPDATE
	NK = MNBLT(J)	UPDATE
	IF (NK.LE.0) GO TO 15	UPDATE
	DO 14 K = 1,NK	UPDATE
	NT = NTBLT(K,J)	UPDATE
	NF = NTAB(NT+5)	UPDATE
	NT6 = NT+6	UPDATE
	CALL UPDFDC(NT)	UPDATE
C		UPDATE
C	AND FOR 2ND FUNCTION, IF FULL BELT FRICTION.	UPDATE
C		UPDATE
	14 IF (NF.NE.0) CALL UPDFDC(NT6)	UPDATE
	15 CONTINUE	UPDATE
C		UPDATE
C	CALL UPDFDC FOR EACH ALLOWED SEGMENT-SEGMENT CONTACT.	UPDATE
C		UPDATE
	16 NSSF = 0	UPDATE
	DO 18 J=1,NSEG	UPDATE
	NK = MNSEG(J)	UPDATE
	IF (NK.LE.0) GO TO 18	UPDATE
	DO 17 K = 1,NK	UPDATE
	NSSF = NSSF+1	UPDATE
	NT = NTSEG(K,J)	UPDATE
	NF = NTAB(NT+5)	UPDATE
	CALL UPDFDC(NT)	UPDATE
	IF (NT.GT.0.OR.TAB(NF+3).EQ.0.0) GO TO 17	UPDATE
	CALL IMPULS(3,K,J)	UPDATE
	I = -1	UPDATE
	17 CONTINUE	UPDATE



18	CONTINUE	UPDATE
	IF (NHRNSS.LE.0) GO TO 71	UPDATE
C		UPDATE
C	CALL UPDFDC FOR EACH BELT OF HARNESS-BELT SYSTEMS.	UPDATE
C		UPDATE
	CALL HPTURB	UPDATE
	J1 = 1	UPDATE
	K1 = 1	UPDATE
	DO 70 II=1,NHRNSS	UPDATE
	IF (NBLTPH(II).LE.0) GO TO 70	UPDATE
	J2 = J1 + NBLTPH(II) - 1	UPDATE
	DO 69 J=J1,J2	UPDATE
	IF (NPTPLY(J).LE.0) GO TO 69	UPDATE
	NT = NTHRNS(J)	UPDATE
	CALL UPDFDC(NT)	UPDATE
	K2 = K1 + NPTPLY(J) - 1	UPDATE
	DO 68 K=K1,K2	UPDATE
	KI = NL(1,K)	UPDATE
	NT = IBAR(3,KI)	UPDATE
	CALL UPDFDC(NT)	UPDATE
68	CONTINUE	UPDATE
	K1 = K2+1	UPDATE
69	CONTINUE	UPDATE
	J1 = J2+1	UPDATE
70	CONTINUE	UPDATE
71	IF (NJNT.LE.0) GO TO 37	UPDATE
C		UPDATE
C	CHECK FOR IMPULSE ON JOINT STOPS	UPDATE
C	TO BE CALLED IF IN JOINT STOP (JSTOP(1)=1) THIS TIME STEP	UPDATE
C	BUT NOT IN IN JOINT STOP (JSTOP(2)=0) AT PREVIOUS TIME.	UPDATE
C		UPDATE
	DO 21 K=1,NJNT	UPDATE
	IF (JNT(K).EQ.0) GO TO 21	UPDATE
	IF (IABS(IPIN(K)).NE.4 .AND. VISC(7,3*K-2).EQ.0.0) GO TO 20	UPDATE
	DO 19 J=1,3	UPDATE
	K3J = 3*K-3+J	UPDATE
	IF (IABS(IPIN(K)).NE.4) K3J=3*K-2	UPDATE
	IF (IABS(IPIN(K)).EQ.4 .AND. VISC(7,K3J).EQ.0.0) GO TO 19	UPDATE
	IF (JSTOP(J,1,K).NE.1.OR.JSTOP(J,2,K).NE.0) GO TO 19	UPDATE
	CALL IMPULS(4,J,K)	UPDATE
	I = -1	UPDATE
19	JSTOP(J,2,K) = JSTOP(J,1,K)	UPDATE
20	IF (IGLOB(K).EQ.0) GO TO 21	UPDATE
	NT = IGLOB(K)	UPDATE
	MT = NTAB(NT+5)	UPDATE
	NT1 = NTAB(NT+2)	UPDATE
	NTAB(NT+2) = 0	UPDATE
	CALL UPDFDC(NT)	UPDATE
	NT = IABS(NT)	UPDATE
	NTAB(NT+2) = NT1	UPDATE



	IPINJ = -IPIN(J)	UPDATE
	WRITE (6,27) TMSEC,J,IPINJ,IPIN(J)	UPDATE
27	FORMAT('0 AT TIME =',F9.3,' MSEC, IPIN(',I2,	BUTLER1
	* ' ) HAS BEEN CHANGED FROM',I3,' TO',I3)	BUTLER1
28	CONTINUE	UPDATE
C		UPDATE
C	TEST TO LOCK OR UNLOCK EULER JOINTS AXES.	UPDATE
C	USE SAME TEST AS ABOVE BUT ON EACH AXIS SERARATELY.	UPDATE
C		UPDATE
C	IF LOCK(IEULER,K) IS NEGATIVE, AXIS K IS LOCKED;	UPDATE
C	TO UNLOCK AXIS SET IEULER TO -LOCK(IEULER,K).	UPDATE
C		UPDATE
C	IF LOCK(IEULER,K) IS POSITIVE, AXIS K IS UNLOCKED;	UPDATE
C	TO LOCK AXIS SET IEULER TO LOCK(IEULER,K).	UPDATE
C		UPDATE
	DO 36 J=1,NJNT	UPDATE
	IF (IABS(IPIN(J)).NE.4) GO TO 36	UPDATE
	JEULER = IEULER(J)	UPDATE
	CALL DOT31(HIR(1,1,J),TQ(1,J),TQTEST)	UPDATE
	DO 31 K=1,3	UPDATE
	K3J = 3*J-3+K	UPDATE
	NLOCK = LOCK(JEULER,K)	UPDATE
	IF (NLOCK.GT.0) GO TO 29	UPDATE
	IF (VISC(4,K3J).EQ.0.0) GO TO 31	UPDATE
	IF (DABS(TQTEST(K)).LE.VISC(4,K3J)) GO TO 31	UPDATE
	JEULER = -NLOCK	UPDATE
	HA(K,2*J-1) = TQTEST(K)	UPDATE
	GO TO 31	UPDATE
29	IF (HA(K,2*J).EQ.0.0) HA(K,2*J-1) = 0.0	UPDATE
	IF (VISC(5,K3J).EQ.0.0) GO TO 30	UPDATE
	IF (DABS(TQTEST(K)).LT.VISC(5,K3J)) JEULER = NLOCK	UPDATE
	GO TO 31	UPDATE
30	IF (VISC(6,K3J).EQ.0.0) GO TO 31	UPDATE
	IF (DABS(ANGD(K,J)).LT.VISC(6,K3J)) JEULER = NLOCK	UPDATE
31	CONTINUE	UPDATE
	IF (JEULER.EQ.IEULER(J)) GO TO 36	UPDATE
	TMSEC = 1000.0*TIME	UPDATE
	WRITE (6,32) TMSEC,J,IEULER(J),JEULER	UPDATE
32	FORMAT('0 AT TIME =',F9.3,' MSEC, IEULER(',I2,	BUTLER1
	* ' ) HAS BEEN CHANGED FROM',I3,' TO',I3)	BUTLER1
	IF (JEULER.EQ.8) GO TO 35	UPDATE
	IF (IEULER(J).EQ.7) GO TO 35	UPDATE
	IF (IEULER(J).EQ.6 .AND. (JEULER.EQ.2.OR.JEULER.EQ.1)) GO TO 35	UPDATE
	IF (IEULER(J).EQ.5 .AND. (JEULER.EQ.3.OR.JEULER.EQ.1)) GO TO 35	UPDATE
	IF (IEULER(J).EQ.4 .AND. (JEULER.EQ.3.OR.JEULER.EQ.2)) GO TO 35	UPDATE
	MODE = -1	UPDATE
	K = JEULER	UPDATE
	IF (K.GT.3) GO TO 33	UPDATE
	IF (K.EQ.2) GO TO 34	UPDATE
	K4 = 4-K	UPDATE

CALL CROSS (HIR(1,K4,J),HIR(1,2,J),T)	UPDATE
IEULER(J) = 8	UPDATE
IPIN(J) = 4	UPDATE
CALL IMPLS2(MODE,J,T)	UPDATE
I = -1	UPDATE
GO TO 35	UPDATE
33 MODE = 1	UPDATE
K = K-3	UPDATE
IF (K.GT.3) MODE=0	UPDATE
34 IEULER(J) = 8	UPDATE
IPIN(J) = 4	UPDATE
CALL IMPLS2(MODE,J,HIR(1,K,J))	UPDATE
I = -1	UPDATE
35 IEULER(J) = JEULER	UPDATE
IPIN(J) = 4	UPDATE
IF (IEULER(J).NE.8) IPIN(J) = -4	UPDATE
C GET SINE AND COSINE OF NUTATION IF IEULER GOES TO STATE 2	JDRIFT
CALL EJOINT(-1,J)	JDRIFT
IF(JEULER.NE.2) GOTO 36	JDRIFT
TQM=ANG(2,J)+CONST(2,J)	JDRIFT
CONST(4,J) = DCOS(TQM)	JDRIFT
CONST(5,J) = DSIN(TQM)	JDRIFT
36 CONTINUE	UPDATE
DO 90 J = 1,NJNT	SLIP
IF (IABS(IPIN(J)).LE.4) GO TO 90	SLIP
IF (IEULER(J).GE.0) GO TO 90	SLIP
IF (CONST(1,J).EQ.0.0.AND.CONST(2,J).EQ.0.0) GO TO 90	SLIP
M = JNT(J)	SLIP
FTEST = XDY(HT(1,3,2*J-1),D(1,1,M),F(1,J))	SLIP
IF (FTEST.GE.CONST(1,J).AND.FTEST.LE.CONST(2,J)) GO TO 90	SLIP
IEULER(J) = 0	SLIP
TMSEC = 1000.0*TIME	SLIP
WRITE (6,88) TMSEC,J	SLIP
88 FORMAT(/'0 AT TIME = ',F9.3,' MSEC, JOINT ',I3,' HAS BEEN',	SLIP
* ' UNLOCKED AND ALLOWED TO SLIP.'/)	SLIP
90 CONTINUE	SLIP
C F IS THE FORCE ON SEGMENT J+1, - F IS ON SEGMENT M	SLIP
C	UPDATE
37 IF (NQ.LE.0) GO TO 41	UPDATE
DO 40 K=1,NQ	UPDATE
IF (KQTYPE(K).LT.3) GO TO 40	UPDATE
IF (KQTYPE(K).GT.4) GO TO 40	UPDATE
IF (CFQQ(K).LT.0.0) KQTYPE(K) = -KQTYPE(K)	UPDATE
IF (CFQQ(K).LT.0.0) GO TO 39	UPDATE
C	UPDATE
C TEST IF ROLLING CONSTRAINT SHOULD BE SLIDING AND VICE VERSA.	UPDATE
C	UPDATE
QN = -XDY(TQQ(1,K),HHT(1,1,K),QQ(1,K))	UPDATE
IF (NPRT(24).NE.0) WRITE (6,38) KQTYPE(K),KQ1(K),KQ2(K),	UPDATE
* (RK1(II,K),II=1,3),(RK2(II,K),II=1,3),	UPDATE

```

*           (HHT(II,J,K),J=1,3),II=1,3), UPDATE
*           (QQ(II,K),II=1,3),(TQQ(II,K),II=1,3),(RQQ(II,K),II=1,3), UPDATE
*           (HQQ(II,K),II=1,3),SQQ(K),CFQQ(K),QN UPDATE
38 FORMAT('O UPDATE ROLL-SLIDE TEST'/(2X,9G14.6)) UPDATE
   IF (QN.LT.0.0) KQTYPE(K) = -4 UPDATE
   IF (QN.LT.0.0) GO TO 39 UPDATE
   QDOTQ = QQ(1,K)**2 + QQ(2,K)**2 + QQ(3,K)**2 UPDATE
   QT = DSQRT(QDOTQ-QN**2) UPDATE
   IF (KQTYPE(K).EQ.3 .AND. QT.LE.CFQQ(K)*QN) GO TO 40 UPDATE
   IF (KQTYPE(K).EQ.4 .AND. QT.GE.0.9*CFQQ(K)*QN) GO TO 40 UPDATE
   KQTYPE(K) = 7-KQTYPE(K) UPDATE
39 CALL OUTPUT(0) UPDATE
   CALL SETUP2 UPDATE
   CALL DAUX(K) UPDATE
   IF (NPRT(24).NE.0) CALL OUTPUT(1) UPDATE
   IF (NPRT( 3).NE.0) CALL PRINT (6HUPDATE) UPDATE
   I = -1 UPDATE
40 CONTINUE UPDATE
41 CALL ELTIME(2,7) UPDATE
42 RETURN UPDATE
   END UPDATE

```

```

SUBROUTINE UPDFDC (M)                                UPDFDC
C                                                     REV III.2 08/08/84REVIII
C UPDATE FORCE DEFLECTION CURVE DEFINITION THAT IS DEFINED UPDFDC
C IN LOCATION M OF NTAB ARRAY. SUBROUTINE ASSUMES THAT UPDFDC
C A SUCCESSFUL INTEGRATION STEP HAS JUST BEEN COMPLETED AND UPDFDC
C WILL COMPUTE ENTIRE CURVE DEFINITION TO BE VALID FOR NEXT STEP. UPDFDC
C                                                     UPDFDC
C IMPLICIT REAL*8(A-H,O-Z)                            UPDFDC
COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500)DIMENB
C L = NTAB(M)                                         UPDFDC
C IF (L.EQ.0) GO TO 99                                UPDFDC
C D = TAB(L)                                          UPDFDC
C IF (D.LT.0.0) D = 0.0                               UPDFDC
C DLAST = TAB(L+1)                                   UPDFDC
C IF (D.EQ.DLAST) GO TO 99                            UPDFDC
C DCUBIC = TAB(L+6)                                  UPDFDC
C IF (D.EQ.DCUBIC) GO TO 98                           UPDFDC
C AREA = TAB(L+2)                                    UPDFDC
C RLAST = TAB(L+3)                                   UPDFDC
C GLAST = TAB(L+4)                                   UPDFDC
C DG = TAB(L+5)                                       UPDFDC
C DGO = DG                                           UPDFDC
C DREF = TAB(L+7)                                     UPDFDC
C DMAX = TAB(L+8)                                     UPDFDC
C DINER = TAB(L+9)                                   UPDFDC
C FDMAX = TAB(L+10)                                  UPDFDC
C DCO = TAB(L+18)                                    UPDFDC
C LQ = L+11                                          UPDFDC
C LC = L+14                                          UPDFDC
C IF (NTAB(M+1).LT.0) GO TO 98                        UPDFDC
C IF (D-DCUBIC) 10,98,20                             UPDFDC
C                                                     UPDFDC
C D < DCUBIC, DEFINE NEW CUBIC                       UPDFDC
C  $Y(X) = A0 + A1*(X-X1) + A2*(X-X1)**2 + A3*(X-X1)**3$  UPDFDC
C WHOSE DERIVATIVE IS                               UPDFDC
C  $Y'(X) = A1 + 2*A2*(X-X1) + 3*A3*(X-X1)**2$  UPDFDC
C                                                     UPDFDC
10 X1 = DMAX1 (D,DG)                                  UPDFDC
X2 = DREF                                             UPDFDC
C                                                     UPDFDC
C IF INERTIAL SPIKE EXISTS AND IF DIMAX < DREF , DROP INERTIAL SPIKEUPDFDC
NI = NTAB(M+2)                                       UPDFDC
IF (NI.GT.0.AND.TAB(NI+3).GT.0.0.AND.DREF.GT.TAB(NI+3))NTAB(M+2)=0UPDFDC
DX = X2-X1                                           UPDFDC
X = X1-DG                                           UPDFDC
Y1 = TAB(LQ) + X *(TAB(LQ+1)+X *TAB(LQ+2))          UPDFDC
Y1P = TAB(LQ+1)+2.0*X *TAB(LQ+2)                   UPDFDC
X2DOT = 0.0                                          UPDFDC
CALL FRCDFL (X2,X2DOT,M,0,Y2P,ELOSS)                 UPDFDC
CALL FRCDFL (X2,X2DOT,M,1,Y2 ,ELOSS)                UPDFDC

```



```

C      DCUBIC < D < DREF, DEFINE NEW QUADRATIC FROM CUBIC CURVE.          UPDFDC
C                                                                              UPDFDC
21 X = D-DCO                                                                UPDFDC
   Y2 = TAB(LC)+X*(TAB(LC+1)+X*(TAB(LC+2)+X*TAB(LC+3)))                    UPDFDC
   X1 = DCUBIC - DG                                                         UPDFDC
   AREA = X1*(TAB(LQ)+X1*(TAB(LQ+1)/2.0+X1*TAB(LQ+2)/3.0))                UPDFDC
* + X*(TAB(LC)+X*(TAB(LC+1)/2.0+X*(TAB(LC+2)/3.0+X*TAB(LC+3)/4.0)) UPDFDC
   X = DCUBIC - DCO                                                         UPDFDC
   IF (X.NE.0.0) AREA = AREA                                               UPDFDC
* - X*(TAB(LC)+X*(TAB(LC+1)/2.0+X*(TAB(LC+2)/3.0+X*TAB(LC+3)/4.0)) UPDFDC
   GO TO 31                                                                  UPDFDC
C                                                                              UPDFDC
C      DREF < D, DEFINE NEW QUADRATIC FROM BASE CURVE.                    UPDFDC
C                                                                              UPDFDC
C      IF DINER < D , REMOVE INERTIAL SPIKE                               UPDFDC
C                                                                              UPDFDC
30 IF (NTAB(M+2).GT.0 .AND. D.GE.DINER)  NTAB(M+2) = 0                    UPDFDC
   NR = NTAB(M+3)                                                           UPDFDC
   RLAST = 1.0                                                             UPDFDC
   IF (NR.GT.0 ) RLAST = EVALFD(D,NR,1)                                    UPDFDC
   IF (RLAST.NE.1.0) GO TO 39                                              UPDFDC
C                                                                              UPDFDC
C      R = 1, USE BASE CURVE FOR UNLOADING                                UPDFDC
C                                                                              UPDFDC
   DG = 0.0                                                                UPDFDC
   DCUBIC = 0.0                                                            UPDFDC
   DREF = 0.0                                                              UPDFDC
   A0 = 0.0                                                                UPDFDC
   A1 = 0.0                                                                UPDFDC
   A2 = 0.0                                                                UPDFDC
   GO TO 32                                                                UPDFDC
39 NG = NTAB(M+4)                                                           UPDFDC
   GLAST = 0.0                                                             UPDFDC
   IF (NG.GT.0 ) GLAST = EVALFD(D,NG,1)                                    UPDFDC
   NB = NTAB(M+1)                                                          UPDFDC
   DO = TAB(NB)                                                            UPDFDC
   DG = DO + GLAST*(D-DO)                                                  UPDFDC
   Y2 = EVALFD(D, NB,1)                                                   UPDFDC
   NI = NTAB(M+2)                                                         UPDFDC
   IF (NI.GT.0) Y2 = Y2+EVALFD(D,NI,1)                                    UPDFDC
   AREA = EVALFD(D,NB,2)                                                  UPDFDC
   DREF = D                                                                UPDFDC
31 DCUBIC = D                                                              UPDFDC
   X1 = DG                                                                UPDFDC
   X2 = D                                                                  UPDFDC
   DX = X2-X1                                                             UPDFDC
   Y1 = 0.0                                                                UPDFDC
   RAREA = RLAST*AREA                                                      UPDFDC
C                                                                              UPDFDC
C      COMPUTE UNLOADING QUADRATIC COEFFICIENTS SUCH THAT                UPDFDC

```



C	ENDPOINT DERIVATES ARE NON-NEGATIVE.	UPDFDC
C		UPDFDC
	A0 = 0.0	UPDFDC
	A1 = 2.0/DX*(3.0*RAREA/DX-Y2)	UPDFDC
	IF (A1.LT.0.0) A1 = 0.0	UPDFDC
	A2 = (Y2/DX-A1)/DX	UPDFDC
	IF (A2.GE.0.0) GO TO 32	UPDFDC
	A1 = Y2/DX	UPDFDC
	A2 = 0.0	UPDFDC
C		UPDFDC
C	RESTORE TAB VALUES THAT MAY HAVE BEEN CHANGED	UPDFDC
C		UPDFDC
32	TAB(L+2) = AREA	UPDFDC
	TAB(L+3) = RLAST	UPDFDC
	TAB(L+4) = GLAST	UPDFDC
	TAB(L+5) = DG	UPDFDC
	TAB(L+6) = DCUBIC	UPDFDC
	TAB(L+7) = DREF	UPDFDC
	TAB(LQ) = A0	UPDFDC
	TAB(LQ+1) = A1	UPDFDC
	TAB(LQ+2) = A2	UPDFDC
98	TAB(L+1) = D	UPDFDC
	IF (D.GT.DG0 .AND. DLAST.LE.DG0) M=-M	UPDFDC
99	RETURN	UPDFDC
	END	UPDFDC

```

SUBROUTINE VEHPOS                                VEHPOS
C                                                    REV IV    07/23/86TWOPI
C COMPUTES COMPONENTS OF VEHICLE ACCELERATIONS ONLY AS A FUNCTION VEHPOS
C OF TIME USING DATA AND TABLES PRODUCED BY SUBROUTINE VINPUT. VEHPOS
C                                                    VEHPOS
C IMPLICIT REAL*8 (A-H,O-Z) VEHPOS
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND, VEHPOS
* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG PAGE
COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30), VEHPOS
* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30) VEHPOS
COMMON/VPOSTN/ ZPLT(3),SPLT(3),AXV(3,6),VATAB(6,501,6), VEHICL
* VTO(6),VDT(6),TIMEV(6),OMEGV(6),NVTAB(6),INDXV(6) VEHPOS
COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24), VEHPOS
* UNITL,UNITM,UNITT,GRAVTY(3),TWOPI TWOPI
DIMENSION AX(3) VEHPOS
T = TIME VEHPOS
M = 1 VEHPOS
15 DO 16 I=1,3 VEHPOS
16 AX(I) = AXV(I,M) VEHPOS
ATO = VTO(M) VEHPOS
ADT = VDT(M) VEHPOS
VTIME = TIMEV(M) VEHPOS
OMEG = OMEGV(M) VEHPOS
NATAB = NVTAB(M) VEHPOS
K = INDXV(M) VEHPOS
IF(NATAB.NE.0) GO TO 20 VEHPOS
C VEHPOS
C HALF-SINE WAVE DECELERATION VEHPOS
C VEHPOS
IF(T.GT.VTIME) T=VTIME VEHPOS
WT = OMEG*T VEHPOS
SWT = DSIN(WT) VEHPOS
DO 10 I=1,3 VEHPOS
AW = AX(I)*OMEG VEHPOS
SEGLA(I,K) = -AW*OMEG*SWT VEHPOS
10 WMEGD(I,K) = 0.0 VEHPOS
GO TO 99 VEHPOS
20 IF (NATAB.LT.0) GO TO 30 VEHPOS
C VEHPOS
C UNIDIRECTIONAL DECELERATION VEHPOS
C VEHPOS
IF (T.LT.VTIME) GO TO 21 VEHPOS
C VEHPOS
C TIME POINT EXCEEDS TABLE, USE LAST VALUES OF ACCELERATION. VEHPOS
C VEHPOS
ACO = VATAB(1,NATAB,M) VEHPOS
GO TO 25 VEHPOS
C VEHPOS
C USE QUADRATIC INTERPOLATION FROM TABLES FOR CURRENT VALUE OF VEHPOS
C TIME TO BE CONSISTENT WITH SIMPSON INTEGRATION OF TABLES. VEHPOS

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SUBROUTINE VINPUT                                VINPUT
C                                                    REV IV   07/24/86SLIP
C PERFORMS CARD INPUT AND COMPUTES DATA AND TABLES REQUIRED BY VINPUT
C SUBROUTINE VEHPOS TO INTEGRATE THE CRASH VEHICLE MOTION FOR ONE OFVINPUT
C THREE PERMISSABLE OPTIONS: VINPUT
C   (1) HALF SINE-WAVE LINEAR DECELERATION IMPULSE VINPUT
C   (2) UNIDIRECTIONAL LINEAR DECELERATION TABULAR INPUT VINPUT
C   (3) OMNIDIRECTIONAL LINEAR AND ANGULAR ACCELERATION TABULAR VINPUT
C INPUT (6 DEGREES OF FREEDOM VEHICLE MOTION) VINPUT
C
IMPLICIT REAL*8 (A-H,O-Z) VINPUT
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND, VINPUT
* NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG PAGE
COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30), VINPUT
* SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30) VINPUT
COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60), SLIP
* RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90), VINPUT
* JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30) VINPUT
COMMON/VPOSTN/ ZPLT(3),SPLT(3),AXV(3,6),VATAB(6,501,6), VINPUT
* VT0(6),VDT(6),TIMEV(6),OMEGV(6),NVTAB(6),INDXV(6) VINPUT
COMMON/TEMPVS/ XO(3),XDOT0(3),XCOMP(3),XVCOMP(3),ANGLE(3), VINPUT
* ATAB(15,501),DVEH(3,3),VMEG(3),VMEGD(3), VINPUT
* XACOMP(3),THET(3),AX(3),F(5,101),XYZ(103,6),TT(103),CHGIII
* VIPS,VMPH,ATO,ADT,VTIME,OMEG,NATAB VINPUT
* ,SP(5,101,4),Q1(101,4),A1(3),W1(4),QD(4),QC(4) JTF984
COMMON/INTEST/ SGTEST(3,4,30),XTEST(3,120),SEGT(120),REGT(120) VINPUT
REAL SEGT VINPUT
COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24), VINPUT
* UNITL,UNITM,UNITT,GRAVITY(3),TWOPI TWOPI
COMMON/TITLES/ DATE(3),COMENT(40),VPSTTL(20),BDYTTL(5), VINPUT
* BLTTTL(5,8),PLTTL(5,30),BAGTTL(5,6),SEG(30), VINPUT
* JOINT(30),CGS(30),JS(30) VINPUT
REAL DATE,COMENT,VPSTTL,BDYTTL,BLTTTL,PLTTL,BAGTTL,SEG,JOINT VINPUT
LOGICAL*1 CGS,JS VINPUT
DIMENSION IDYPR(3) VINPUT
REAL VEH(6),GRND VINPUT
DATA VEH/4HVEH1,4HVEH2,4HVEH3,4HVEH4,4HVEH5,4HVEH /,GRND/4HGRND/ VINPUT
DATA IDYPR/3,2,1/ VINPUT
DATA MXTAB2/99/,MXTAB3/501/,MXTAB4/101/ MISC
C
C READ AND PRINT CONTENTS OF CARDS C.1 AND C.2 VINPUT
C
NVEH = NSEG VINPUT
NVH = 0 VINPUT
DO 11 I=1,6 VINPUT
11 INDXV(I) = 0 VINPUT
12 READ (5,13) VPSTTL VINPUT
13 FORMAT (20A4) VINPUT
READ(5,14) ANGLE,VIPS,VTIME,XO,NATAB,ATO,ADT,MSEG VINPUT
14 FORMAT(8F6.0,I6,2F6.0,I6) VINPUT

```

	INTAB = IABS(NATAB)	CHGIII
	IF (NATAB.GT.0.AND.INTAB.GT.MXTAB2) STOP 79	MISC
	WRITE (6,15) NPG,VPSTTL,ANGLE,VIPS,VTIME,XO,NATAB,ATO,ADT,MSEG	PAGE
	NPG = NPG+1	PAGE
15	FORMAT('1 VEHICLE DECELERATION INPUTS',94X,'PAGE',I5/120X,	PAGE
	* 'CARDS C'/3X,20A4//	PAGE
	* 7X,'YAW',9X,'PITCH',7X,'ROLL',8X,'VIPS',8X,'VTIME',7X,'XO(X)',VINPUT	
	* 7X,'XO(Y)',7X,'XO(Z)',2X,'NATAB',6X,'ATO',9X,'ADT',4X,'MSEG'/VINPUT	
	* 8F12.3,I5,2X,2F12.6,I5)	VINPUT
	DA1 = ANGLE(1)*RADIAN	VINPUT
	DA2 = ANGLE(2)*RADIAN	VINPUT
	AX(3) = DCOS(DA2)	VINPUT
	AX(1) = DCOS(DA1)*AX(3)	VINPUT
	AX(2) = DSIN(DA1)*AX(3)	VINPUT
	AX(3) = DSIN(DA2)	VINPUT
	IF(NATAB.NE.0) GO TO 18	VINPUT
C		VINPUT
C	HALF-SINE WAVE DECELERATION	VINPUT
C		VINPUT
	OMEG = PI/VTIME	VINPUT
	AT = 0.5*VIPS/OMEG	VINPUT
	IF (VIPS.LT.0.0) VIPS = 0.0	VINPUT
	DO 16 I=1,3	VINPUT
	XACOMP(I) = 0.0	VINPUT
	XDOT0(I) = VIPS*AX(I)	VINPUT
16	AX(I) = AT*AX(I)	VINPUT
	WRITE (6,17) VIPS,UNITL,UNITT,ANGLE,VTIME,UNITT	VINPUT
17	FORMAT('0 PASSENGER COMPARTMENT DISPLACEMENT HISTORY'/	VINPUT
	* ' ANALYTICAL HALF-SINE WAVE DECELERATION'/	VINPUT
	* ' VO=',F8.3,1X,A4,'/',A4,', OBLIQUE ANGLES =',3F7.2,	VINPUT
	* ' DEGREES, TIME DURATION =',F7.3,1X,A4//)	VINPUT
	GO TO 28	VINPUT
18	IF (NATAB.LT.0) GO TO 31	VINPUT
C		VINPUT
C	FOR UNIDIRECTIONAL VEHICLE MOTION	VINPUT
C	READ LINEAR DECELERATION TABLES FROM CARDS C.3	VINPUT
C		VINPUT
	READ (5,19) (ATAB(1,I),I=1,NATAB)	VINPUT
19	FORMAT (12F6.0)	VINPUT
C		VINPUT
C	EXTEND TABLE IF NECESSARY SUCH THAT NATAB IS ODD AND	VINPUT
C	LAST ENTRY NEED NOT BE ZERO. IF TABLE SIZE IS EXCEEDED ON TIME,	VINPUT
C	VALUE OF LAST ENTRY WILL BE USED.	VINPUT
C		VINPUT
	IF (MOD(NATAB,2).EQ.1) GO TO 20	VINPUT
	ATAB(1,NATAB+1) = ATAB(1,NATAB)	VINPUT
	NATAB = NATAB+1	VINPUT
20	VTIME = ADT * DFLOAT(NATAB-1)	VINPUT
C		VINPUT
C	USING SIMPSON'S INTEGRATION, COMPUTE VELOCITY AND DISPLACEMENT	VINPUT

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C      TABLE FOR NATAB EQUALLY SPACED (ADT) TIME POINTS.          VINPUT
C      FOR I=1,NATAB                                                VINPUT
C      ATAB(1,I) = LINEAR DECELERATION (G'S)                       VINPUT
C      ATAB(2,I) = LINEAR VELOCITY (L UNITS/T UNITS)               VINPUT
C      ATAB(3,I) = LINEAR DISPLACEMENT (L UNITS)                   VINPUT
C                                                                    VINPUT
C      ATAB(2,1) = VIPS                                             VINPUT
C      ATAB(3,1) = 0.0                                              VINPUT
C      DA1 = ADT/3.0                                                VINPUT
C      DA2 = ADT/12.0                                              VINPUT
C      UNITS = -G                                                  VINPUT
C      DO 22 J=2,3                                                  VINPUT
C      DO 21 I=2,NATAB,2                                           VINPUT
C      F1 = ATAB(J-1,I-1) * UNITS                                  VINPUT
C      F2 = ATAB(J-1,I ) * UNITS                                  VINPUT
C      F3 = ATAB(J-1,I+1) * UNITS                                  VINPUT
C      ATAB(J,I ) = ATAB(J,I-1) + DA2*(5.0*F1+8.0*F2-F3)         VINPUT
21 ATAB(J,I+1) = ATAB(J,I-1) + DA1*( F1+4.0*F2+F3)               VINPUT
22 UNITS = 1.0                                                    VINPUT
C                                                                    VINPUT
C      PRINT TABLES                                              VINPUT
C                                                                    VINPUT
C      WRITE (6,23) (UNITL,UNITT,UNITL,I=1,2)                      VINPUT
23 FORMAT('0 UNIDIRECTIONAL VEHICLE POSITION TABLES'//           VINPUT
*      2('      TIME      ACC      VELOCITY      POSITION  ')/    VINPUT
*      2('      (MSEC)      (G)      (',A4,',',A4,',')',5X,'(',A4,',')',4X)/VINPUT
C      DO 26 J=1,50                                                VINPUT
C      IF (J.GT.NATAB) GO TO 26                                     VINPUT
C      T1 = (ATO + DFLOAT(J-1)*ADT)*1000.0                        VINPUT
C      IF (J+50.LE.NATAB) GO TO 25                                 VINPUT
C      WRITE (6,24) T1,(ATAB(I,J),I=1,3)                          VINPUT
24 FORMAT(2(F11.5,F10.2,F13.4,F13.5,3X))                          VINPUT
C      GO TO 26                                                    VINPUT
25 T2 = (ATO + DFLOAT(J+49)*ADT)*1000.0                          VINPUT
C      WRITE (6,24) T1,(ATAB(I,J),I=1,3),T2,(ATAB(I,J+50),I=1,3) VINPUT
26 CONTINUE                                                       VINPUT
C                                                                    VINPUT
C      INITIALIZATION                                             VINPUT
C                                                                    VINPUT
C      DO 27 I=1,3                                                 VINPUT
C      XACOMP(I) = -G*AX(I)*ATAB(1,1)                             VINPUT
27 XDOTO(I) = VIPS*AX(I)                                          VINPUT
28 DO 30 I=1,3                                                     VINPUT
C      DO 29 J=1,3                                                 VINPUT
29 DVEH(I,J) = 0.0                                               VINPUT
C      DVEH(I,I) = 1.0                                             VINPUT
C      VMEGD(I) = 0.0                                              VINPUT
30 VMEG(I) = 0.0                                                 VINPUT
C      GO TO 64                                                    VINPUT
C                                                                    VINPUT

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C	FOR OMNIDIRECTIONAL (6 DEGREES OF FREEDOM) VEHICLE MOTION	VINPUT
C	READ LINEAR DECELERATION AND ANGULAR ACCELERATION TABLES	VINPUT
C	FROM CARDS C.2.B AND C.4.	CHGIII
C		VINPUT
	31 MATAB = -NATAB	VINPUT
	READ (5,32) LTYPE,LFIT,NPTS,(VMAG(I),I=1,3)	VINPUT
	32 FORMAT (3I6,22X,3F10.0)	VINPUT
	IF (MATAB.GT.MXTAB3) STOP 80	MISC
	IF (LTYPE.EQ.2.AND.LFIT.LT.1) STOP 82	CHGIII
	IF (LTYPE.EQ.1.AND.LFIT.LT.2) STOP 83	VEHICL
	IF (LTYPE.GT.0) GO TO 34	VINPUT
	READ (5,33) ((ATAB(I,J),I=1,3),(ATAB(I,J),I=10,12),J=1,MATAB)	VINPUT
	33 FORMAT (10X,6F10.0)	VINPUT
	ISKIP = 0	VINPUT
	GO TO 46	VINPUT
C		CHGIII
C	FOR SPLINE FIT VEHICLE MOTION	CHGIII
C	READ DATA FROM CARDS C.5.	CHGIII
C		CHGIII
	34 LPTS = LTYPE-1 + NPTS	VINPUT
	IF (NPTS.GT.MXTAB3) STOP 84	MISC
	READ (5,35) (TT(I),(XYZ(I,J),J=1,6),I=1,LPTS)	VINPUT
	35 FORMAT (7F10.0)	VINPUT
	WRITE (6,36) LTYPE,LFIT,NPTS	CHGIII
	36 FORMAT ('O SPLINE FIT TABULAR INPUT'//	CHGIII
	* 3X,'LTYPE =',I6,' LFIT =',I6,' NPTS =',I6/)	CHGIII
	IF (LTYPE.EQ.2) WRITE(6,701) UNITL,UNITT,TT(1),(XYZ(1,J),J=1,6)	CHGIII
	IF (LTYPE.EQ.3) WRITE(6,702) UNITL,UNITT,TT(1),(XYZ(1,J),J=1,6),	CHGIII
	* UNITL,UNITT,UNITT,TT(2),(XYZ(2,J),J=1,6)	CHGIII
	701 FORMAT(32X,'INITIAL LINEAR POSITION (' ,A4,')',17X,'INITIAL ANGULACHGIII	
	*R POSITION (DEG)',/,3X,'TIME(' ,A4,')=' ,F9.4,3X,2('X=' ,F10.3,2X,	JTF984
	* 'Y=' ,F10.3,2X,'Z=' ,F10.3,8X),/)	CHGIII
	702 FORMAT(32X,'INITIAL LINEAR POSITION (' ,A4,')',17X,'INITIAL ANGULACHGIII	
	*R POSITION (DEG)',/,3X,'TIME(' ,A4,')=' ,F9.4,3X,2('X=' ,F10.3,2X,	JTF984
	* 'Y=' ,F10.3,2X,'Z=' ,F10.3,8X),/,30X,'INITIAL LINEAR VELOCITY (' ,CHGIII	
	* A4,'/' ,A4,')',12X,'INITIAL ANGULAR VELOCITY (DEG/' ,A4,')',	CHGIII
	*/,3X,'TIME(' ,A4,')=' ,F9.4,3X,2('X=' ,F10.2,2X,'Y=' ,	CHGIII
	* F10.2,2X,'Z=' ,F10.2,8X),/)	CHGIII
	IF (LTYPE.EQ.1) WRITE(6,703) UNITL,UNITT	CHGIII
	IF (LTYPE.EQ.2) WRITE(6,704) UNITL,UNITT,UNITT,UNITT	CHGIII
	IF (LTYPE.EQ.3) WRITE(6,705) UNITT,UNITT	VEHICL
	703 FORMAT(29X,'LINEAR POSITION (' ,A4,')',21X,'ANGULAR POSITION (DECHGIII	
	*G)',/,5X,'TIME(' ,A4,')',11X,'X',11X,'Y',11X,'Z',18X,'YAW',8X,	VEHICL
	*'PITCH',8X,'ROLL')	VEHICL
	704 FORMAT(26X,'LINEAR VELOCITY (' ,A4,')/' ,A4,')',16X,	CHGIII
	* 'ANGULAR VELOCITY (DEG/' ,A4,')',/,5X,'TIME(' ,A4,')',	CHGIII
	* 11X,2('X',11X,'Y',11X,'Z',19X))	CHGIII
	705 FORMAT(26X,'LINEAR DECELERATION (G''S)',15X,	VEHICL
	* 'ANGULAR ACCELERATION (DEG/' ,A4,')**2)',/,5X,'TIME(' ,A4,')',	CHGIII
	* 11X,2('X',11X,'Y',11X,'Z',19X))	CHGIII

IF (LTYPE.EQ.1) WRITE(6,706) (TT(I),(XYZ(I,J),J=1,6),I=1,LPTS)	CHGIII
IF (LTYPE.EQ.2) WRITE(6,706) (TT(I),(XYZ(I,J),J=1,6),I=2,LPTS)	CHGIII
IF (LTYPE.EQ.3) WRITE(6,706) (TT(I),(XYZ(I,J),J=1,6),I=3,LPTS)	CHGIII
706 FORMAT(1X,F12.5,6X,3F12.3,8X,3F12.3)	CHGIII
DO 37 I=1,3	VINPUT
XO(I) = XYZ(1,I)	VINPUT
XDOTO(I) = XYZ(2,I)	VINPUT
VMEG(I) = XYZ(2,I+3)	VINPUT
37 ANGLE(I) = XYZ(1,I+3)	JTF984
IMJ = 6	JTF984
IF(LTYPE.EQ.1)IMJ = 3	JTF984
DO 45 II=1,IMJ	JTF984
CALL SPLINE (TT(LTYPE),XYZ(LTYPE,II),F,NPTS,LFIT)	VINPUT
I = II	VINPUT
IF (II.GT.3) I = II + 6	VINPUT
IF(LTYPE.EQ.1) XDOTO(I) = F(3,1)	JTF984
UNITS = 1.0	JTF984
IF (LTYPE.LT.3 .AND. II.LE.3) UNITS = -1.0/G	VINPUT
K1 = 1	VINPUT
DO 45 J=1,MATAB	VINPUT
TTT = ATO + DFLOAT(J-1)*ADT	VINPUT
DO 39 L=K1,NPTS	JTF984
K = L	JTF984
IF (TTT.LT.F(1,L+1)) GO TO 40	VINPUT
39 CONTINUE	VINPUT
40 K1 = K	VINPUT
DX = TTT - F(1,K)	VINPUT
IF (LTYPE-2) 41,42,43	BUTLERI
41 ACC = 2.0*F(4,K) + 6.0*DX*F(5,K)	VINPUT
GO TO 44	VINPUT
42 ACC = F(3,K) + DX*(2.0*F(4,K)+3.0*DX*F(5,K))	VINPUT
GO TO 44	VINPUT
43 ACC = F(2,K) + DX*(F(3,K)+DX*(F(4,K)+DX*F(5,K)))	VINPUT
44 ATAB(I,J) = ACC*UNITS	VINPUT
45 CONTINUE	VINPUT
ISKIP = 1	VINPUT
IF(LTYPE.NE.1)GO TO 46	JTF984
C CODE FOR OMEGA ROUTINE: COMPUTE ATAB(I,J),I=10,11,12 J = 1,MATAB	JTF984
DO 80 I = 1,NPTS	JTF984
DO 91 K = 1,3	JTF984
91 A1(K) = XYZ(I,K+3)	JTF984
CALL QUAT(A1,W1)	JTF984
DO 76 K = 1,4	JTF984
76 Q1(I,K) = W1(K)	JTF984
IF(I.EQ.1)GO TO 80	JTF984
TA = 0.0	JTF984
TB = 0.0	JTF984
DO 77 K = 1,4	JTF984
TA = TA + DABS(Q1(I,K) - Q1(I-1,K))	JTF984
77 TB = TB + DABS(Q1(I,K) + Q1(I-1,K))	JTF984



	IF(TA.LE.TB)GO TO 80	JTF984
	DO 78 K = 1,4	JTF984
78	Q1(I,K) = -Q1(I,K)	JTF984
80	CONTINUE	JTF984
	DO 82 K = 1,4	JTF984
82	CALL SPLINE(TT,Q1(1,K),SP(1,1,K),NPTS,LFIT)	JTF984
	DO 90 J = 1,MATAB	JTF984
	TTT = ATO + DFLOAT(J-1)*ADT	JTF984
	K1 = 1	JTF984
	DO 83 L = K1,NPTS	JTF984
	K = L	JTF984
83	IF(TTT.LT.SP(1,L+1,1))GO TO 84	JTF984
84	K1 = K	JTF984
	DX = TTT - SP(1,K,1)	JTF984
	DO 85 L = 1,4	JTF984
	W1(L) = SP(2,K,L)+DX*(SP(3,K,L)+DX*(SP(4,K,L)+DX*SP(5,K,L)))	JTF984
	QD(L) = 2.0*SP(4,K,L) + 6.0*DX*SP(5,K,L)	JTF984
85	IF(J.EQ.1)QC(L) = SP(3,K,L)+DX*(2.0*SP(4,K,L)+DX*3.0*SP(5,K,L))	MISC
	CCC = 2.0/RADIAN	JTF984
	IF(J.GT.1)GO TO 88	JTF984
	CALL CROSS(QC(2),W1(2),A1)	JTF984
	DO 86 K = 1,3	JTF984
86	VMEG(K) = CCC*(W1(1)*QC(K+1) - QC(1)*W1(K+1) + A1(K))	JTF984
	CALL DRCQUA(DVEH,W1)	JTF984
	CALL YPRDEG(DVEH,ANGLE)	JTF984
88	CALL CROSS(QD(2),W1(2),QC(2))	JTF984
	DO 89 K = 2,4	JTF984
89	ATAB(K+8,J) = CCC*(W1(1)*QD(K)-QD(1)*W1(K) + QC(K))	JTF984
90	CONTINUE	JTF984
46	DO 55 J=1,MATAB	VINPUB
	IF (MOD(J,45).NE.1) GO TO 49	VINPUB
C		VINPUB
C	PRINT PAGE HEADING AT START OF EACH 45 TIME POINTS.	VINPUB
C		VINPUB
	IPAGE = (J-1)/45 + 1	VINPUB
	IF (ISKIP.EQ.1) WRITE (6,75) NPG	PAGE
	IF (ISKIP.EQ.1) NPG=NPG+1	PAGE
75	FORMAT('1',122X,'PAGE',I5)	PAGE
	WRITE (6,48) VPSTTL,IPAGE,UNITL,UNITT,UNITL	PAGE
48	FORMAT('0 VEHICLE LINEAR TIME HISTORY',3X,20A4,3X,	PAGE
	* 'PAGE NO.',I3//	VINPUB
	* 4X,'TIME',12X,'LINEAR DECELERATIONS (G'S)',	VINPUB
	* 11X,'LINEAR VELOCITIES ('A4','/'A4,')',	VINPUB
	* 11X,'LINEAR DISPLACEMENTS ('A4,')' /	VINPUB
	* 3X,'(MSEC)',3(11X,'X',11X,'Y',11X,'Z',3X) / )	VINPUB
	ISKIP = 1	VINPUB
49	IF (J.GT.1) GO TO 52	VINPUB
C		VINPUB
C	INTEGRATION INITIALIZATION FOR TIME = 0.	VINPUB
C		VINPUB

	DO 50 I=1,3	VINPUT
	ATAB(I+6,J) = XO(I)	VINPUT
50	ATAB(I+12,J) = VMEG(I)	JTF984
	CALL DRCYPR (DVEH,ANGLE,IDYPR)	VINPUT
	DO 51 I=1,3	VINPUT
	IF (LTYPE.EQ.0) XDOTO(I) = VIPS*DVEH(1,I)	VINPUT
51	ATAB(I+3,J) = XDOTO(I)	VINPUT
	GO TO 54	VINPUT
52	DO 53 I=1,3	VINPUT
C		VINPUT
C	INTEGRATE LINEAR VELOCITY AND DISPLACEMENT.	VINPUT
C		VINPUT
	ATAB(I+3,J) = ATAB(I+3,J-1)-G*ADT/2.0*(ATAB(I,J-1)+ATAB(I,J))	VINPUT
53	ATAB(I+6,J) = ATAB(I+6,J-1)	VINPUT
	* +ADT*(ATAB(I+3,J-1)-G*ADT/6.0*(2.0*ATAB(I,J-1)+ATAB(I,J)))	VINPUT
54	T1 = (ATO + DFLOAT(J-1)*ADT)*1000.0	VINPUT
55	WRITE(6,56) T1,(ATAB(I,J),I=1,9)	VINPUT
56	FORMAT(F9.3,3(3X,3F12.3))	VINPUT
	DO 61 J=1,MATAB	VINPUT
	IF (MOD(J,45).NE.1) GO TO 58	VINPUT
C		VINPUT
C	PRINT PAGE HEADING AT START OF EACH 45 TIME POINTS.	VINPUT
C		VINPUT
	IPAGE = (J-1)/45 + 1	VINPUT
	WRITE (6,57) VPSTTL,NPG,IPAGE,UNITT,UNITT	PAGE
	NPG=NPG+1	PAGE
57	FORMAT('1 VEHICLE ANGULAR TIME HISTORY',3X,20A4,10X,'PAGE',15/	PAGE
	* 116X,'PAGE NO.',13/	PAGE
	* 4X,'TIME', 7X,'ANGULAR ACCELERATIONS (DEG/','A4,'**2)',	VINPUT
	* 7X,'ANGULAR VELOCITIES (DEG/','A4,')',	VINPUT
	* 11X,'ANGULAR DISPLACEMENTS (DEG)' /	VINPUT
	* 3X,'(MSEC)',2(11X,'X',11X,'Y',11X,'Z',3X),	VINPUT
	* 10X,'YAW',8X,'PITCH',8X,'ROLL' /)	VINPUT
58	IF(J.EQ.1) GO TO 60	VINPUT
C		VINPUT
C	INTEGRATE ANGULAR VELOCITY AND DISPLACEMENT.	VINPUT
C		VINPUT
	DO 59 I=1,3	VINPUT
	ATAB(I+12,J) = ATAB(I+12,J-1)+(ATAB(I+9,J-1)+ATAB(I+9,J))*ADT/2.0	VINPUT
59	THET(I) = ADT*(ATAB(I+12,J-1)+(2.0*ATAB(I+9,J-1)+ATAB(I+9,J))*ADT	VINPUT
	*/6.0)*RADIAN	VINPUT
	CALL DSETD(DVEH,THET,THT)	VINPUT
60	CALL YPRDEG(DVEH,THET)	VINPUT
	T1 = (ATO + DFLOAT(J-1)*ADT)*1000.0	VINPUT
61	WRITE (6,56) T1,(ATAB(I,J),I=10,15),THET	VINPUT
C		VINPUT
C	PROGRAM INITIALIZATION FOR TIME = 0.	VINPUT
C		VINPUT
	CALL DRCYPR (DVEH,ANGLE,IDYPR)	VINPUT
	DO 63 I=1,3	VINPUT

	XACOMP(I) = -G*ATAB(I,1)	VINPUT
	VMEG(I) = ATAB(I+12,1)*RADIAN	VINPUT
63	VMEGD(I) = ATAB(I+9,1)*RADIAN	VINPUT
64	J = MSEG	VINPUT
	IF (MSEG.EQ.0) GO TO 65	VINPUT
	IF (MSEG.LE.NSEG) GO TO 66	VINPUT
	IF (MSEG.NE.NVEH+1) STOP 6	VINPUT
65	NVEH = NVEH+1	VINPUT
	J = NVEH	VINPUT
C		VINPUT
C	SETUP FOR ALL PRESCRIBED SEGMENT MOTION.	VINPUT
C		VINPUT
66	NVH = NVH+1	VINPUT
	ISING(J) = -1	VINPUT
	IF (MSEG.GT.NSEG) SEG(J) = VEH(NVH)	VINPUT
	RW(J) = 0.0	VINPUT
	DO 67 I=1,3	VINPUT
	RPHI (I,J) = 0.0	VINPUT
	SEGLA(I,J) = VMEGD(I)	VINPUT
	WMEGD(I,J) = XACOMP(I)	VINPUT
67	AXV(I,NVH) = AX(I)	VINPUT
	VTO(NVH) = ATO	VINPUT
	VDT(NVH) = ADT	VINPUT
	OMEGV(NVH) = OMEG	VINPUT
	TIMEV(NVH) = VTIME	VINPUT
	NVTAB(NVH) = NATAB	VINPUT
	INDXV(NVH) = J	VINPUT
	NJ = IABS(NATAB)	VINPUT
	IF (NJ.LE.0) GO TO 69	VINPUT
	DO 68 K=1,NJ	VINPUT
	DO 68 I=1,3	VINPUT
	VATAB(I,K,NVH) = ATAB(I,K)	VINPUT
68	VATAB(I+3,K,NVH) = ATAB(I+9,K)	VINPUT
69	IF (J.LE.NSEG) GO TO 72	VINPUT
C		VINPUT
C	SETUP FOR NEW VEHICLE (SEGMENT) MOTION.	VINPUT
C		VINPUT
	W(J) = 0.0	VINPUT
	RW(J) = 0.0	VINPUT
	DO 71 I=1,3	VINPUT
	DO 70 K=1,3	VINPUT
	D(I,K,J) = DVEH(I,K)	VINPUT
70	SGTEST(I,K,J) = 0.0	VINPUT
	SGTEST(I,4,J) = 0.0	VINPUT
	SEGLP(I,J) = XO(I)	VINPUT
	SEGLV(I,J) = XDOTO(I)	VINPUT
	WMEG (I,J) = VMEG(I)	VINPUT
	PHI (I,J) = 0.0	VINPUT
71	RPHI (I,J) = 0.0	VINPUT
72	IF (MSEG.NE.0) GO TO 12	VINPUT

	SEG(NVEH) = VEH(6)	VINPUT
C		VINPUT
C	SET UP SEGMENT DATA FOR GROUND	VINPUT
C		VINPUT
	NGRND = NVEH+1	VINPUT
	IF (NGRND.GT.30 .OR. NVH.GT.6) STOP 7	VINPUT
	SEG(NGRND) = GRND	VINPUT
	J = NGRND	VINPUT
	ISING(J) = -1	VINPUT
	W(J) = 0.0	VINPUT
	RW(J) = 0.0	VINPUT
	DO 74 I=1,3	VINPUT
	DO 73 K=1,3	VINPUT
	D(I,K,J) = 0.0	VINPUT
73	SGTEST(I,K,J) = 0.0	VINPUT
	D(I,I,J) = 1.0	VINPUT
	SGTEST(I,4,J) = 0.0	VINPUT
	SEGLP(I,J) = 0.0	VINPUT
	SEGLV(I,J) = 0.0	VINPUT
	SEGLA(I,J) = 0.0	VINPUT
	WMEG (I,J) = 0.0	VINPUT
	WMEGD(I,J) = 0.0	VINPUT
	PHI (I,J) = 0.0	VINPUT
74	RPHI (I,J) = 0.0	VINPUT
	RETURN	VINPUT
	END	VINPUT

	DOUBLE PRECISION FUNCTION VISCOS(ZD,VISC,HA)		VISCOS
C		REV 19	10/23/78VISCOS
C	COMPUTES SUM OF COULOMB AND VISCOUS TORQUES		VISCOS
C	AT JOINTS AS A FUNCTION OF THETA DOT.		VISCOS
C	ACTUALLY ROUTINE RETURNS SUM/ZD.		VISCOS
C			VISCOS
C	ARGUMENTS:		VISCOS
C	ZD : !THETA DOT! WHERE THETA IS THE ANGLE OF THE JOINT.		VISCOS
C	VISC: ARRAY OF 5 VALUES DESCRIBING FUNCTION EVALUATION.		VISCOS
C			VISCOS
	IMPLICIT REAL*8 (A-H,O-Z)		VISCOS
	DIMENSION VISC(5)		VISCOS
	Z = ZD		VISCOS
	IF (ZD.LT.VISC(3)) Z = VISC(3)/(2.0-ZD/VISC(3))		VISCOS
	HA = (Z-ZD)/Z		VISCOS
	VISCOS = VISC(1)+VISC(2)/Z		VISCOS
	RETURN		VISCOS
	END		VISCOS

	SUBROUTINE VISPR(IJ,NJ)		VISPR
C		REV IV	02/01/88MISDOT
C	COMPUTES VISCOS AND SPRING TORQUES AT THE JOINTS		VISPR
C	AND ADDS THEM TO THE U2 ARRAY.		VISPR
C	ARGUMENTS:		VISPR
C	NJ = 0 - REGULAR COMPUTATION FOR ALL JOINTS		VISPR
C	* 0 - COMPUTE ONLY FOR JOINT NJ IMPULSE		VISPR
C			VISPR
C	IJ = 1 IMPULSE FOR FLEXURE ONLY		VISPR
C	= 2 IMPULSE FOR TORSION ONLY		VISPR
C	= 4 IMPULSE FOR GLOBALGRAPHIC ONLY		VISPR
C			VISPR
	IMPLICIT REAL*8 (A-H,O-Z)		VISPR
	COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,		VISPR
*	NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG		PAGE
	COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30),		VISPR
*	SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)		VISPR
	COMMON/DESCRP/ PHI(3,30),W(30),RW(30),SR(4,60),HA(3,60),HB(3,60),		SLIP
*	RPHI(3,30),HT(3,3,60),SPRING(5,90),VISC(7,90),		VISPR
*	JNT(30),IPIN(30),ISING(30),IGLOB(30),JOINTF(30)		VISPR
	COMMON/CMATRX/ V1(3,30),V2(3,30),V3(3,12),B12(3,3,60),A22(3,3,60),		VISPR
*	F(3,30),TQ(3,30),WJ(30),A11(3,3,30)		SLIP
	COMMON/FORCES/PSF(7,70),BSF(4,20),SSF(10,40),BAGSF(3,20),		NCFORC
*	PRJNT(7,30),NPANEL(5),NPSF,NBSF,NSSF,NBGSF		VISPR
	COMMON/CEULER/ IEULER(30),HIR(3,3,90),ANG(3,30),ANGD(3,30),		JDRIFT
*	FE(3,30),TQE(3,30),CONST(5,30)		JDRIFT
	COMMON/TEMPVI/ CREST,TTI(3),R1I(3),R2I(3),JSTOP(4,2,30)		VISPR
	COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),		VISPR
*	UNITL,UNITM,UNITT,GRAVTY(3),TWOPI		TWOPI
	COMMON/TEMPVS/ T3(3),T6(3),T7(3),T8(3),T9(3),		VISPR
*	WIJ(3),ANGL(3),DH1(3,3),HD3(3,3),		VISPR
*	HAD,HBD,WIJM,CV,CSA,CSB,TQC		VISPR
	IF (NJNT.LE.0) GO TO 99		VISPR
	CALL ELTIME(1,13)		VISPR
	IF (NPRT(12).NE.0) WRITE (6,11) TIME,NPG		PAGE
	IF (NPRT(12).NE.0) NPG=NPG+1		PAGE
11	FORMAT('1 VISPR COMPUTATIONS FOR TIME = ',F12.6,80X,'PAGE',I5)		PAGE
	J1 = 1		VISPR
	J2 = NJNT		VISPR
	IF (NJ.EQ.0) GO TO 13		VISPR
	J1 = NJ		VISPR
	J2 = NJ		VISPR
13	DO 90 J=J1,J2		VISPR
	DO 12 L=1,3		VISPR
	T3(L) = 0.0		VISPR
	T6(L) = 0.0		VISPR
	ANGL(L) = 0.0		VISPR
12	TQ(L,J) = 0.0		VISPR
	WJ(J) = 0.0		VISPR

```

C
C DO NOT COMPUTE TORQUES FOR NULL, LOCKED OR EULER JOINTS.
C
I = IABS(JNT(J))
IF (I.LE.0) GO TO 90
CALL DOT33 (D(1,1,J+1),HT(1,1,2*J),HIR(1,1,J))
IF (IABS(IPIN(J)).EQ.4) GO TO 90
C
ZERO T1-T9 ARRAYS AND HAD,HBD,WIJM,CV,CS4,CSB AND TQC.
C
WIJM = 0.0
HAC = 0.0
CV = 0.0
CSA = 0.0
CSB = 0.0
TQC = 0.0
CALL DOT33 (D(1,1,I),HT(1,1,2*J-1),DH1)
CALL DOT33 (DH1,HIR(1,1,J),HD3)
DO 220 L=1,3
DO 220 K=1,3
IF(DABS(HD3(L,K)).LT.EPS(10)) HD3(L,K) = 0.D0
220 CONTINUE
HAD = HD3(3,3)
IF (HAD.GT. 1.0) HAD = 1.0
IF (HAD.LT.-1.0) HAD = -1.0
ANGL(1) = DACOS(HAD)
IF ((HD3(2,3).NE.0.0 .OR. HD3(1,3).NE.0.0).AND.IABS(IPIN(J)).NE.7) SLIP
*ANGL(2) = DATAN2(HD3(2,3),HD3(1,3))
ANGL(3) = DATAN2(HD3(2,1)-HD3(1,2),HD3(1,1)+HD3(2,2))
IF(NPRT(12).NE.0.AND.IPIN(J).LT.0) WRITE (6,739) J,I,ANGL,
* ((D(L,K,J+1),K=1,3), (HT(L,K,2*J),K=1,3), (HIR(L,K,J),K=1,3),L=1,3),
* ((D(L,K,I),K=1,3), (HT(L,K,2*J-1),K=1,3), (DH1(L,K),K=1,3),L=1,3),
* ((HD3(L,K),K=1,3),L=1,3)
739 FORMAT(1H0,'J= ',I2,1X,'I= ',I2,3(2X,D14.7),/,
* 2(3(9(1X,D13.6),/),/),3(3(2X,D18.12),/))
IF (IPIN(J).LT.0) GO TO 41
IF (NJ.NE.0.AND.IJ.EQ.4) GO TO 27
C
CONVERT TO INERTIAL REFERENCE SYSTEM
C T1= D(I)*HA(NJ) T4=D(J+1)*HA(MJ)
C T3= D(I)*WMEG(I) T6=D(J+1)*WMEG(J+1)
C
HAD = COS TA = T1.T4
C WIJ = T3-T6
C WJ = !WIJ!
C
DO 20 L=1,3
DO 15 M=1,3
T3(L) = T3(L)+ D(M,L,I)* WMEG(M,I)
15 T6(L) = T6(L)+ D(M,L,J+1)* WMEG(M,J+1)

```

	WIJ(L) = T3(L) - T6(L)	VISPR
20	WIJM = WIJM + WIJ(L)**2	VISPR
	WIJM = DSQRT(WIJM)	VISPR
	IF (WIJM.LE.EPS(12)) WIJM = 0.0	MISDOT
	WJ(J) = WIJM	VISPR
C		VISPR
C	T7 = T1 X T4	VISPR
C	HAC = !T7!	VISPR
C		VISPR
	CALL CROSS (DH1(1,3),HIR(1,3,J),T7)	VISPR
	HACC = T7(1)**2 + T7(2)**2 + T7(3)**2	VISPR
	HAC = DSQRT(HACC)	VISPR
C		VISPR
C	COMPUTE CV, THE MAGNITUDE OF VISCOUS AND COULOMB TORQUE/WIJM	VISPR
C	RA = +SGN TA DOT = -WIJ.T7	VISPR
C	AND CSA, THE MAGNITUDE OF FLEXURE TORQUE/HAC	VISPR
C		VISPR
	CV = VISCOS(WIJM,VISC(1,3*J-2),HA2)	VISPR
	IF (NJ.EQ.0) HA(2,2*J) = HA2	VISPR
	CREST = VISC(7,3*J-2)	VISPR
	RA = -(WIJ(1)*T7(1) + WIJ(2)*T7(2) + WIJ(3)*T7(3))	VISPR
	IF (HAC.LT.EPS(12)) RA=0.0	MISDOT
	IF (HAC.GE.EPS(12)) RA=RA/HAC	MISDOT
	JSTP = 0	VISPR
	IF (IPIN(J).EQ.7) GOTO 25	SLIP
	IF (JOINTF(J).EQ.0) CSA = EFUNCT(ANGL(1),RA,SPRING(1,3*J-2),JSTP)	VISPR
	IF (JOINTF(J).NE.0) CSA = FINTERP(ANGL(1),ANGL(2),JOINTF(J))	VISPR
	IF (HAC.LT.EPS(12)) CSA=0.0	MISDOT
	IF (HAC.GE.EPS(12)) CSA=CSA/HAC	MISDOT
25	IF (NJ.EQ.0) JSTOP(1,1,J) = JSTP	SLIP
	IF (IPIN(J).EQ.1) GO TO 34	VISPR
	IF (IPIN(J).EQ.6) GOTO 34	SLIP
C		VISPR
C	RB = +SGN TB DOT = -WIJ.T8	VISPR
C	COMPUTE CSB, THE MAGNITUDE OF TORSIONAL TORQUE/HBC	VISPR
C		VISPR
	RB = -(WIJ(1)*HIR(1,3,J) + WIJ(2)*HIR(2,3,J) + WIJ(3)*HIR(3,3,J))	VISPR
	CSB = EFUNCT(ANGL(3),RB,SPRING(1,3*J-1),JSTP)	VISPR
	IF (NJ.EQ.0) JSTOP(2,1,J) = JSTP	VISPR
	IF (NJ.GT.0) GO TO 34	VISPR
C		VISPR
C	COMPUTE EFFECT OF GLOBALGRAPHIC JOINT STOP (IPIN=3)	VISPR
C		VISPR
27	IF (IPIN(J).NE.3) GO TO 34	VISPR
	CALL GLOBAL (J,HD3(1,3),DH1,TQC,T9,ANGL)	VISPR
C		VISPR
C	COMPUTE TOTAL TORQUE IN INERTIAL REFERENCE BY	VISPR
C	TQ = -CV*WIJ + CSA*T7 + CSB*T8 + TQC*T9	VISPR
C		VISPR
34	IF (NJ.EQ.0) GO TO 35	JDRIFT



	CV = 0.0	VISPR
	IF (IJ.NE.1) CSA = 0.0	VISPR
	IF (IJ.NE.2) CSB = 0.0	VISPR
	IF (IJ.NE.4) TQC = 0.0	VISPR
35	IF (HA(2,2*J).EQ.0.0) GO TO 36	JDRIFT
	CALL MAT31 (HIR(1,1,J),HA(1,2*J-1),TQ(1,J))	VISPR
	DO 38 L=1,3	VISPR
38	TQ(L,J) = HA(2,2*J)*TQ(L,J)	VISPR
36	DO 37 L=1,3	VISPR
	TQ(L,J) = TQ(L,J) -CV*WIJ(L) +CSA*T7(L) +CSB*HIR(L,3,J) +TQC*T9(L)	VISPR
37	TTI(L) = TQ(L,J)	VISPR
	IF (NPRT(12).NE.0) WRITE (6,39)	VISPR
	* J, CV, CSA, CSB, HAC, RA, RB, (TQ(L,J), L=1,3),	VISPR
	* WIJ, T7, ANGL, DH1, HD3,	VISPR
	* ((HIR(L,K,J), L=1,3), K=1,3)	VISPR
39	FORMAT (1H0,I3,3F14.3,6F14.6/(4X,9F14.6))	VISPR
C		VISPR
C	ADD TORQUE CONVERTED TO LOCAL REFERENCE BY	VISPR
C	U2I = U2I + DI*TQ	VISPR
C	U2J = U2J - DJ*TQ	VISPR
C		VISPR
	DO 40 L=1,3	VISPR
	DO 40 M=1,3	VISPR
	U2(L,I) = U2(L,I) + D(L,M,I)*TQ(M,J)	VISPR
40	U2(L,J+1) = U2(L,J+1) - D(L,M,J+1)*TQ(M,J)	VISPR
C		VISPR
C	STORE DATA FOR OUTPUT ROUTINE INTO PRJNT ARRAY.	VISPR
C		VISPR
41	PRJNT(1,J) = IPIN(J)	VISPR
	PRJNT(2,J) = ANGL(1)	VISPR
	PRJNT(3,J) = ANGL(2)	VISPR
	PRJNT(4,J) = ANGL(3)	VISPR
	PRJNT(5,J) = (CSA*HAC)**2 + CSB**2	VISPR
	PRJNT(6,J) = (CV*WIJM)**2	VISPR
	PRJNT(7,J) = TQ(1,J)**2 + TQ(2,J)**2 + TQ(3,J)**2	VISPR
90	CONTINUE	VISPR
	CALL ELTIME(2,13)	VISPR
99	RETURN	VISPR
	END	VISPR

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SUBROUTINE WINDY(MMM,MM,N,NN,NT)                                WINDY
                                                                REV IV   07/23/86TWOPI
C                                                                WINDY
C COMPUTES FORCES AND TORQUES ADDING THEM TO THE U1 AND U2 ARRAYS WINDY
C OF WIND BLAST FORCES DETERMINED BY FUNCTION STORED IN TAB(NT) WINDY
C ON ELLIPSOID (MM) ATTACHED TO BODY SEGMENT (M) WHICH EXTENDS WINDY
C THROUGH THE INTERSECTING PLANE (NN) ATTACHED TO SEGMENT (N). WINDY
C                                                                WINDY
C   IMPLICIT REAL*8 (A-H,O-Z)                                  WINDY
COMMON/CONTRL/ TIME,NSEG,NJNT,NPL,NBLT,NBAG,NVEH,NGRND,        WINDY
*   NS,NQ,NSD,NFLX,NHRNSS,NWINDF,NJNTF,NPRT(36),NPG           PAGE
COMMON/SGMNTS/ D(3,3,30),WMEG(3,30),WMEGD(3,30),U1(3,30),U2(3,30), WINDY
*   SEGLP(3,30),SEGLV(3,30),SEGLA(3,30),NSYM(30)              WINDY
COMMON/TABLES/MXNTI,MXNTB,MXTB1,MXTB2,NTI(50),NTAB(1250),TAB(4500) DIMENB
COMMON/WINDFR/ WTIME(30),QFU(3,5),QFV(3,5),WF(3,30),IWIND(30), WINDOP
*   MWSEG(7,30),NFVSEG(6),NFVNT(5),MOWSEG(30,30)              WINDOP
COMMON/CNTRSRF/ PL(24,30),BELT(20,8),TPTS(6,8),BD(24,40)     EDGE
COMMON/CNSNTS/ PI,RADIAN,G,THIRD,EPS(24),                     WINDY
*   UNITL,UNITM,UNITT,GRAVTY(3),TWOPI                          TWOPI
COMMON/TEMPVS/ DMNT(3,3),XMN(3),XMM(3),TM(3),BET,BTS,P,FT(3), WINDOP
*   FF(3),AF(3),FAF,TF,BREF,SCALE,TRACER,AREA,RLM(3),          WINDOP
*   TQM(3),RM(3),DD(3,3),DDD(3,3),R(3,3),DVP(3,3),            WINDOP
*   SI(3,15),R2(2,3),TTF(3),FFT(3),AM(3,3),VP(3),             WINDOP
*   SS(3),SM(3),SN1(3),AS(3),BTE,XNORM,TEMP,                  WINDOP
*   X,Y,AI(3,3,15),RYC,AMDA1,AMDA2,B1,B2,RXC                  WINDOP
                                                                WINDOP
C   MMM=0   CALCULATE NFORCE                                  WINDOP
C   MMM>0   WIND FORCE CALCULATED USING ENTIRE AREA METHOD      WINDOP
C   MMM<0   WIND FORCE CALCULATED USING GRID METHOD             WINDOP
C                                                       (ALLOWS BLOCKING SEGMENTS) WINDOP
C                                                                WINDOP
C   DATA NSTEPS/4/                                           WINDOP
C   CALL ELTIME(1,37)                                         WINDY
C   M=IABS(MMM)                                               WINDOP
C   IF (MMM.EQ.0) GO TO 50                                     WINDOP
                                                                WINDY
C   COMPUTE PENETRATION DISTANCE; IF NEGATIVE, RETURN.       WINDY
C                                                                WINDY
C   CALL DOTT33 (D(1,1,M),D(1,1,N),DMNT)                     WINDY
C   DO 10 I=1,3                                               WINDY
10  XMN(I) = SEGLP(I,M) - SEGLP(I,N)                          WINDY
C   CALL MAT31 (D(1,1,M),XMN,XMM)                             WINDY
C   CALL MAT31 (DMNT,PL(1,NN),TM)                             WINDY
C   BET = PL(4,NN)                                            WINDY
C   DO 11 I=1,3                                               WINDY
11  BET = BET - TM(I)*(BD(I+3,MM)+XMM(I))                      WINDY
C   CALL MAT31 (BD(16,MM),TM,RM)                             WINDY
C   BTS = TM(1)*RM(1) + TM(2)*RM(2) + TM(3)*RM(3)           WINDY
C   BTE = -DSQRT(BTS)                                         WINDY
C   P = BET - BTE                                             WINDY
C   IF (P.LT.0.0) GO TO 99                                     WINDY

```

C		WINDY
C	FETCH OR STORE INITIAL PENETRATION TIME.	WINDY
C		WINDY
	IWIND(M) = M	WINDY
	IF (TIME.LE.WTIME(M)) WTIME(M) = TIME	WINDY
	FTIME = TIME - WTIME(M)	WINDY
C		WINDY
C	GET DRAG COEFFICIENT CD FROM TABLE NTC FOR TIME = FTIME.	WINDOP
C		WINDOP
	CD=1.0	WINDOP
	NTC=MWSEG(6,M)	WINDOP
	IF (NTC.EQ.0) GOTO 20	WINDOP
	KT=NTI(NTC)	WINDOP
	NENTRY=TAB(KT+5)	WINDOP
	K1=KT+10	WINDOP
	K2=4*NENTRY+KT+2	WINDOP
	IF (NENTRY.EQ.1) GOTO 18	WINDOP
	DO 17 K=K1,K2,4	WINDOP
	IF (FTIME.GT.TAB(K)) GOTO 17	WINDOP
	KK=K	WINDOP
	R1=(TAB(K)-FTIME)/(TAB(K)-TAB(K-4))	WINDOP
	GOTO 19	WINDOP
17	CONTINUE	WINDOP
18	KK=K2	WINDOP
	R1=0.0	WINDOP
19	R22=1.0-R1	WINDOP
	K=KK+1	WINDOP
	CD=R22*TAB(K)+R1*TAB(K-4)	WINDOP
C		WINDOP
C	GET FORCE VECTOR FT	WINDOP
C		WINDOP
C	RK=0    TIME DEPENDENT WIND FORCE FROM TABLE	WINDOP
C	RK*0    VELOCITY DEPENDENT WIND FORCE	WINDOP
C		WINDOP
20	KT = NTI(NT)	WINDOP
	RK=TAB(KT)	WINDOP
	IF (RK.EQ.0.0) GOTO 13	WINDOP
	C=TAB(KT+1)	WINDOP
	PR=TAB(KT+2)	WINDOP
	NSV=IDINT(TAB(KT+3))	WINDOP
	NSR=IDINT(TAB(KT+4))	WINDOP
	DO 12 I=1,3	WINDOP
	V=SEGLV(I,NSV)-SEGLV(I,NSR)	WINDOP
12	FT(I)=DSIGN(0.5D0,-V)*CD*RK*PR*V**2/C**2	WINDOP
	GOTO 14	WINDOP
13	NSR=IDINT(TAB(KT+4))	WINDOP
	NENTRY = TAB(KT+5)	WINDY
	K1 = KT+10	WINDY
	K2 = 4*NENTRY + KT+2	WINDY
	IF (NENTRY.EQ.1) GO TO 31	WINDY

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DO 30 K=K1,K2,4                                WINDY
IF (FTIME.GT.TAB(K)) GO TO 30                   WINDY
KK = K                                           WINDY
R1 = (TAB(K)-FTIME)/(TAB(K)-TAB(K-4))           WINDY
GO TO 32                                         WINDY
30 CONTINUE                                      WINDY
31 KK = K2                                       WINDY
R1 = 0.0                                         WINDY
32 R22= 1.0 - R1                                  WINDOP
DO 33 I=1,3                                      WINDY
K= KK+I                                          WINDY
33 FT(I)=(R22*TAB(K) + R1*TAB(K-4))*CD          WINDOP
IF (NSR.EQ.0) GOTO 14                            WINDOP
CALL DOT31(D(1,1,NSR),FT,FF)                    WINDOP
DO 21 I=1,3                                      WINDOP
21 FT(I)=FF(I)                                    WINDOP
14 IF (MMM.LT.0) GOTO 15                          WINDOP
C                                                  WINDY
C COMPUTE PRESENTED AREA TO WIND FORCE.           WINDY
C                                                  WINDY
CALL MAT31 (D(1,1,M),FT,FF)                      WINDY
CALL MAT31 (BD(7,MM),FF,AF)                       WINDY
FAF = FF(1)*AF(1) + FF(2)*AF(2) + FF(3)*AF(3)   WINDY
IF (FAF.LE.0.0) GO TO 99                          WINDY
TF = TM(1)*FF(1) + TM(2)*FF(2) + TM(3)*FF(3)   WINDY
BREF=0.0                                           WINDY
TEMP=BTS-TF*TF/FAF                                WINDY
IF (TEMP.GT.0.0) BREF =DSQRT(TEMP)                WINDY
SCALE = (-BET+BREF)/(-BTE+BREF)                  WINDY
IF (SCALE.GE.1.0) GO TO 99                        WINDY
IF (SCALE.LT.0.0) SCALE = 0.0                    WINDY
TRACER = (BD( 7,MM)-AF(1)**2/FAF)*(BD(11,MM)-AF(2)**2/FAF) WINDY
*          + (BD( 7,MM)-AF(1)**2/FAF)*(BD(15,MM)-AF(3)**2/FAF) WINDY
*          + (BD(11,MM)-AF(2)**2/FAF)*(BD(15,MM)-AF(3)**2/FAF) WINDY
*          - (BD( 8,MM)-AF(1)*AF(2)/FAF)**2       WINDY
*          - (BD( 9,MM)-AF(1)*AF(3)/FAF)**2       WINDY
*          - (BD(12,MM)-AF(2)*AF(3)/FAF)**2       WINDY
AREA = (1.0-SCALE**2) * PI / DSQRT(TRACER)        WINDY
C                                                  WINDY
C ADD FORCE AND TORQUES TO U1 AND U2 ARRAYS FOR SEGMENT M. WINDY
C                                                  WINDY
SCALE = SCALE/BTE                                 WINDY
DO 36 I=1,3                                       WINDY
RLM(I) = RM(I)*SCALE + BD(I+3,MM)                WINDY
FT (I) = FT(I)*AREA                              WINDY
36 FF (I) = FF(I)*AREA                            WINDY
CALL CROSS (RLM,FF,TQM)                          WINDY
DO 39 I=1,3                                       WINDY
WF(I,M)=FT(I)                                    WINDY
U1(I,M) = U1(I,M) + FT(I)                        WINDY

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39	U2(I,M) = U2(I,M) + TQM(I)	WINDY
	IF (NPRT(14).NE.0) WRITE (6,41) TIME,M,P,AREA,FT,TQM	WINDY
41	FORMAT(' WIND FORCE',F14.6,I6,2F10.3,3X,3F12.5,3X,3F12.5)	WINDY
	GO TO 99	WINDY
C		WINDY
C	USE GRID TO CALCULATE WIND FORCE	WINDOP
C	VP - ORIGIN OF WIND	WINDOP
C		WINDOP
15	AREAT=0.0	WINDOP
	DO 16 I=1,3	WINDOP
	TTF(I)=0.0	WINDOP
	TQM(I)=0.0	WINDOP
16	VP(I) = -FT(I)*10000.0	WINDOP
	TEMP=FT(1)**2+FT(2)**2+FT(3)**2	WINDOP
	IF (TEMP.EQ.0.0) GOTO 99	WINDOP
	CALL MAT31(D(1,1,M),FT,FF)	WINDOP
	TEMP = 0.0	WINDOP
	IF (FT(1).NE.0.0.OR.FT(2).NE.0.0) GOTO 150	WINDOP
C		WINDOP
C	CALCULATE DIRECTION COSINE MATRIX FOR VP COORD. SYS.	WINDOP
C		WINDOP
	DO 140 I=1,3	WINDOP
	DO 140 J=1,3	WINDOP
140	DVP(I,J)=0.0	WINDOP
	DVP(1,2)=1.0	WINDOP
	DVP(2,1)=1.0	WINDOP
	DVP(3,3)=-1.0	WINDOP
	GO TO 141	WINDOP
150	CONTINUE	WINDOP
	DO 110 I=1,3	WINDOP
110	TEMP=TEMP+FT(I)*FT(I)	WINDOP
	TEMP = DSQRT(TEMP)	WINDOP
	XNORM = DSQRT(FT(1)*FT(1)/TEMP**2+FT(2)*FT(2)/TEMP**2)	WINDOP
	DVP(1,1) = FT(2)/(XNORM*TEMP)	WINDOP
	DVP(1,2) = -FT(1)/(XNORM*TEMP)	WINDOP
	DVP(1,3) = 0.0	WINDOP
	DVP(2,1) = FT(1)*FT(3)/(XNORM*TEMP*TEMP)	WINDOP
	DVP(2,2) = FT(2)*FT(3)/(XNORM*TEMP*TEMP)	WINDOP
	DVP(2,3) = -XNORM	WINDOP
	DO 130 I=1,3	WINDOP
130	DVP(3,I) = FT(I)/TEMP	WINDOP
141	CONTINUE	WINDOP
	MOELP = MWSEG(7,M)	WINDOP
C		WINDOP
C	PROJECT MM ELLIPSOID UNTO VP-PLANE	WINDOP
C	AS - PROJECTED ELLIPSE MATRIX	WINDOP
C		WINDOP
	CALL DOTT33(D(1,1,M),DVP,DD)	WINDOP
	CALL MAT33(BD(7,MM),DD,DDD)	WINDOP
	CALL DOT33(D(1,1,M),DDD,DD)	WINDOP

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CALL MAT33(DVP,DD,AM)
DO 101 K=1,3
101 SS(K)=SEGLP(K,M)+BD(K+3,MM)-VP(K)
CALL MAT31(DVP,SS,SM)
DO 114 K=1,3
IF (DABS(SM(K)).LT.EPS(5)) SM(K)=DSIGN(EPS(5),SM(K))
114 CONTINUE
CALL SOLVR(AM(1,1),AM(2,1),AM(3,1),AM(1,3),AM(2,3),AM(3,3),
* AM(1,1),AM(1,3),SM,R(1,1),R(3,1))
CALL SOLVR(AM(1,2),AM(2,2),AM(3,2),AM(1,3),AM(2,3),AM(3,3),
* AM(2,2),AM(2,3),SM,R(2,2),R(3,2))
CALL SOLVR(AM(1,1)+AM(1,2),AM(2,1)+AM(2,2),AM(3,1)+AM(3,2),
* AM(1,3),AM(2,3),AM(3,3),AM(1,1)+2.0*AM(1,2)+AM(2,2),
* AM(1,3)+AM(2,3),SM,R(1,3),R(3,3))
R(2,1)=0.0
R(1,2)=0.0
R(2,3)=R(1,3)
DO 102 K=1,3
DO 102 J=1,2
102 R2(J,K)=R(J,K)
CALL SOLVA(R2,AS(1),AS(2),AS(3))
C
C GET MAJOR & MINOR AXES OF PROJECTED ELLIPSE
C
TEMP=(AS(1)+AS(2))**2-4.0*(AS(1)*AS(2)-AS(3)**2)
IF (TEMP.LT.0.0) TEMP=0.0
TEMP = DSQRT(TEMP)
AMDA1=(AS(1)+AS(2)+TEMP)/2.0
AMDA2=(AS(1)+AS(2)-TEMP)/2.0
R2(1,1)=AS(3)
R2(2,1)=AMDA1-AS(1)
R2(1,2)=AMDA2-AS(2)
R2(2,2)=AS(3)
AMDA1=DABS(AMDA1)
AMDA2=DABS(AMDA2)
B1=DSQRT(1.0/(AMDA1*(R2(1,1)**2+R2(1,2)**2)))
B2=DSQRT(1.0/(AMDA2*(R2(2,1)**2+R2(2,2)**2)))
R2(1,1)=R2(1,1)*B1
R2(1,2)=R2(1,2)*B2
R2(2,1)=R2(2,1)*B1
R2(2,2)=R2(2,2)*B2
C
C GET BLOCKING ELLIPSOIDS IN VP COORD. SYS.
C
DO 103 MI=1,MOELP
I=MOWSEG(M,MI*2-1)
II=MOWSEG(M,MI*2)
CALL DOT33(D(1,1,I),DVP,DD)
CALL MAT33(BD(7,II),DD,DDD)
CALL DOT33(D(1,1,I),DDD,DD)

```



	TM(3)=AI(1,1,IM)*X**2+AI(2,2,IM)*Y**2+2.0*AI(1,2,IM)*X*Y-1.0	WINDOP
	TEMP=TM(2)**2-4.0*TM(1)*TM(3)	WINDOP
	IF (TEMP.LT.0.0) GOTO 109	WINDOP
	B1=(-TM(2)+DSQRT(TEMP))/(2.0*TM(1))	WINDOP
	B2=(-TM(2)-DSQRT(TEMP))/(2.0*TM(1))	WINDOP
	IF (B2.LT.B1) B1=B2	WINDOP
	SNZ=B1+SI(3,IM)	WINDOP
	IF (SNZ.LT.SN1(3)) GOTO 106	WINDOP
109	CONTINUE	WINDOP
	CALL DOT31(DVP,RM,SS)	WINDOP
	CALL MAT31(D(1,1,M),SS,RM)	WINDOP
C		WINDOP
C	SUM FORCES & TORQUES	WINDOP
C		WINDOP
	AREAT=AREAT+AREA	WINDOP
	DO 111 K=1,3	WINDOP
	TTF(K)=FT(K)*AREA+TTF(K)	WINDOP
	RM(K)=RM(K)+BD(K+3,MM)	WINDOP
111	FFT(K)=FF(K)*AREA	WINDOP
	CALL CROSS(RM,FFT,TM)	WINDOP
	DO 112 K=1,3	WINDOP
112	TQM(K)=TQM(K)+TM(K)	WINDOP
106	CONTINUE	WINDOP
105	CONTINUE	WINDOP
C		WINDOP
C	ADD FORCE & TORQUE TO U1 & U2 ARRAYS FOR SEGMENT M	WINDOP
C		WINDOP
	IF (NPRT(14).NE.0) WRITE(6,200) TIME,M,AREAT,TTF,TQM	WINDOP
200	FORMAT(' WIND FORCE',F14.6,I6,13X,F10.3,3F12.5,3X,3F12.5)	WINDOP
	DO 113 I=1,3	WINDOP
	WF(I,M)=TTF(I)	WINDOP
	U1(I,M)=U1(I,M)+TTF(I)	WINDOP
113	U2(I,M)=U2(I,M)+TQM(I)	WINDOP
	GO TO 99	WINDOP
C		WINDOP
C	M = 0: CALCULATE FORCE FUNCTIONS.	WINDOP
C		WINDY
50	NFORCE = NFVSEG(6)	WINDY
	DO 60 J=1,NFORCE	WINDY
	NFS = IABS(NFVSEG(J))	WINDY
	NFT = IABS(NFVNT(J))	WINDY
	KFT = NTI(NFT)	WINDY
	FRCE = EVALFD(TIME,KFT,1)	WINDY
	IF (NFVSEG(J).GT.0) GO TO 52	WINDY
	DO 51 I=1,3	WINDY
51	U2(I,NFS) = U2(I,NFS) + FRCE*QFU(I,J)	WINDY
	GO TO 60	WINDY
52	CALL DOT31(D(1,1,NFS),QFU(1,J),TM)	WINDY
	DO 53 I=1,3	WINDY
	U1(I,NFS) = U1(I,NFS) + FRCE*TM(I)	WINDY



53 U2(I,NFS) = U2(I,NFS) + FRCE\*QFV(I,J)  
60 CONTINUE  
99 CALL ELTIME (2,37)  
RETURN  
END

WINDY  
WINDY  
WINDY  
WINDY  
WINDY

C	DOUBLE PRECISION FUNCTION XDY(X,D,Y)	REV IV	07/23/86JTF786	XDY
C	FUNCTION ROUTINE TO COMPUTE X.DY OR Y.D'X			XDY
C	IMPLICIT REAL*8(A-H,O-Z)			XDY
	DIMENSION X(3),D(3,3),Y(3)			XDY
	XDY = 0.0			XDY
	DO 10 I=1,3			XDY
	10 XDY = XDY + X(I)*(D(I,1)*Y(1)+D(I,2)*Y(2)+D(I,3)*Y(3))			JTF786
	RETURN			XDY
	END			XDY



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## REFERENCES

1. Fleck, J.T., Butler, F.E. and Vogel, SD.L., "An Improved Three Dimensional Computer Simulation of Crash Victims," NHTSA Report Nos. DOT-HS-801-507 through 510, April 1975, Vols. 1-4.
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4. Fleck, J.T., Butler, F.E., and DeLeys, N.J., "Validation of the Crash Victim Simulator," Calspan Report Nos. ZS-5881-V-1 through 4, DOT-HS-806-279 through 282, 1982, Vols 1-4 (NTIS No. PC E99, PB 86-212420).
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6. Leetch, B.D., Bowman, W.L., "Articulated Total Body (ATB) VIEW Program Software Report," Report Nos. AMRL-TR-81-111, Vols 1 & 2, June 1983 (NTIS Nos. AD-B075 161 & 162).



The first part of the document discusses the importance of maintaining accurate records of all transactions. It emphasizes that every entry should be supported by a valid receipt or invoice. This ensures transparency and allows for easy verification of the data.

In the second section, the author details the various methods used to collect and analyze the data. This includes both manual data entry and the use of specialized software tools. The goal is to ensure that the data is not only collected accurately but also analyzed in a way that provides meaningful insights.

The third part of the document focuses on the results of the analysis. It presents a series of charts and graphs that illustrate the trends and patterns in the data. These visual aids are crucial for identifying key areas of concern and opportunity.

Finally, the document concludes with a series of recommendations based on the findings. These suggestions are designed to help the organization improve its operations, reduce costs, and increase efficiency. The author stresses that these changes should be implemented gradually and monitored closely to ensure their effectiveness.

Prepared by: [Name]

